S K Mondal’s

Strength of Materials

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Note

"Asked Objective Questions" is the total collection of questions from:-
20 yrs IES (2010-1992) [Engineering Service Examination]
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Every effort has been made to see that there are no errors (typographical or otherwise) in the material presented. However, it is still possible that there are a few errors (serious or otherwise). I would be thankful to the readers if they are brought to my attention at the following e-mail address: swapan_mondal_01@yahoo.co.in

S K Mondal
1. Stress and Strain

## Theory at a Glance (for IES, GATE, PSU)

### 1.1 Stress (σ)

When a material is subjected to an external force, a resisting force is set up within the component. The internal resistance force per unit area acting on a material or intensity of the forces distributed over a given section is called the stress at a point.

- It uses original cross section area of the specimen and also known as engineering stress or conventional stress.

Therefore, \( \sigma = \frac{P}{A} \)

- \( P \) is expressed in Newton (N) and \( A \), original area, in square meters (m\(^2\)), the stress \( \sigma \) will be expresses in N/m\(^2\). This unit is called Pascal (Pa).

- As Pascal is a small quantity, in practice, multiples of this unit is used.
  
  \[ 1 \text{ kPa} = 10^3 \text{ Pa} = 10^3 \text{ N/ m}^2 \quad (\text{kPa} = \text{Kilo Pascal}) \]
  
  \[ 1 \text{ MPa} = 10^6 \text{ Pa} = 10^6 \text{ N/ m}^2 = 1 \text{ N/mm}^2 \quad (\text{MPa} = \text{Mega Pascal}) \]
  
  \[ 1 \text{ GPa} = 10^9 \text{ Pa} = 10^9 \text{ N/ m}^2 \quad (\text{GPa} = \text{Giga Pascal}) \]

**Let us take an example:** A rod 10 mm × 10 mm cross-section is carrying an axial tensile load 10 kN. In this rod the tensile stress developed is given by

\[
(\sigma_t) = \frac{P}{A} = \frac{10 \text{kN}}{(10 \text{mm} \times 10 \text{mm})} = \frac{10 \times 10^3 \text{N}}{100 \text{mm}^2} = 100 \text{N/mm}^2 = 100 \text{MPa}
\]

- The resultant of the internal forces for an axially loaded member is normal to a section cut perpendicular to the member axis.

- The force intensity on the shown section is defined as the normal stress.

\[
\sigma = \lim_{\Delta A \to 0} \frac{\Delta F}{\Delta A} \quad \text{and} \quad \sigma_{avg} = \frac{P}{A}
\]

- **Tensile stress (\( \sigma_t \))**

If \( \sigma > 0 \) the stress is tensile. i.e. The fibres of the component tend to elongate due to the external force. A member subjected to an external force tensile P and tensile stress distribution due to the force is shown in the given figure.
Chapter-1 Stress and Strain

- **Compressive stress** ($\sigma_c$)
  
  If $\sigma < 0$ the stress is compressive. i.e. The fibres of the component tend to shorten due to the external force. A member subjected to an external compressive force $P$ and compressive stress distribution due to the force is shown in the given figure.

- **Shear stress** ($\tau$)
  
  When forces are transmitted from one part of a body to other, the stresses developed in a plane parallel to the applied force are the shear stress. Shear stress acts parallel to plane of interest. Forces $P$ is applied transversely to the member $AB$ as shown. The corresponding internal forces act in the plane of section C and are called shearing forces. The corresponding average shear stress $\tau = \frac{P}{\text{Area}}$

1.2 Strain ($\varepsilon$)

The displacement per unit length (dimensionless) is known as strain.

- **Tensile strain** ($\varepsilon_t$)

  The elongation per unit length as shown in the figure is known as tensile strain.

  \[ \varepsilon_t = \frac{\Delta L}{L_0} \]

  It is engineering strain or conventional strain.

  Here we divide the elongation to original length not actual length ($L_0 + \Delta L$)

  Let us take an example: A rod 100 mm in original length. When we apply an axial tensile load 10 kN the final length of the rod after application of the load is 100.1 mm. So in this rod tensile strain is developed and is given by

  \[ (\varepsilon_t) = \frac{\Delta L}{L_0} = \frac{L - L_0}{L_0} = \frac{100.1\text{mm} - 100\text{mm}}{100\text{mm}} = 0.001 \text{ (Dimensionless) Tensile} \]

- **Compressive strain** ($\varepsilon_c$)

  If the applied force is compressive then the reduction of length per unit length is known as compressive strain. It is negative. Then $\varepsilon_c = (-\Delta L)/L_0$

  Let us take an example: A rod 100 mm in original length. When we apply an axial compressive load 10 kN the final length of the rod after application of the load is 99 mm. So in this rod a compressive strain is developed and is given by
Shear Strain (\(\gamma\)): When a force \(P\) is applied tangentially to the element shown. Its edge displaced to dotted line. Where \(\delta\) is the lateral displacement of the upper face of the element relative to the lower face and \(L\) is the distance between these faces.

Then the shear strain is \(\gamma = \frac{\delta}{L}\)

Let us take an example: A block 100 mm \(\times\) 100 mm base and 10 mm height. When we apply a tangential force 10 kN to the upper edge it is displaced 1 mm relative to lower face.

Then the direct shear stress in the element\(\tau = \frac{10\, kN}{100\, mm \times 100\, mm} = \frac{10 \times 10^3 \, N}{100\, mm \times 100\, mm} = 10^2 \, N/m^2 = 1 \, MPa\)

And shear strain in the element \(\gamma = \frac{1\, mm}{10\, mm} = 0.1\) Dimensionless

1.3 True stress and True Strain

The true stress is defined as the ratio of the load to the cross section area at any instant.\(\sigma_T = \frac{\text{load}}{\text{Instantaneous area}} = \sigma (1 + \varepsilon)\)

Where \(\sigma\) and \(\varepsilon\) is the engineering stress and engineering strain respectively.

True strain\(\varepsilon_T = \int \frac{dL}{L} = \ln \left(\frac{L}{L_0}\right) = \ln (1 + \varepsilon) = \ln \left(\frac{A_f}{A_0}\right) = 2 \ln \left(\frac{d_f}{d}\right)\)

or engineering strain \(\varepsilon = e^\gamma - 1\)

The volume of the specimen is assumed to be constant during plastic deformation. \([\because A_0L_0 = AL]\) It is valid till the neck formation.

Comparison of engineering and the true stress-strain curves shown below
The true stress-strain curve is also known as the flow curve.

True stress-strain curve gives a true indication of deformation characteristics because it is based on the instantaneous dimension of the specimen.

In engineering stress-strain curve, stress drops down after necking since it is based on the original area.

In true stress-strain curve, the stress however increases after necking since the cross-sectional area of the specimen decreases rapidly after necking.

The flow curve of many metals in the region of uniform plastic deformation can be expressed by the simple power law.

\[ \sigma_T = K(\varepsilon_T)^n \]

Where \( K \) is the strength coefficient

- \( n \) is the strain hardening exponent
- \( n = 0 \) perfectly plastic solid
- \( n = 1 \) elastic solid

For most metals, \( 0.1 < n < 0.5 \)

**Relation between the ultimate tensile strength and true stress at maximum load**

The ultimate tensile strength \( (\sigma_u) \) = \( \frac{P_{\text{max}}}{A_o} \)

The true stress at maximum load \( (\sigma_T)_T = \frac{P_{\text{max}}}{A} \)

And true strain at maximum load \( (\varepsilon)_T = \ln \left( \frac{A_o}{A} \right) \) or \( \frac{A_o}{A} = e^{\varepsilon} \)

Eliminating \( P_{\text{max}} \) we get, \( (\sigma_u)_T = \frac{P_{\text{max}}}{A} = \frac{P_{\text{max}}}{A_o} \times \frac{A_o}{A} = \sigma_u e^{\varepsilon} \)

Where \( P_{\text{max}} \) = maximum force and \( A_o \) = Original cross section area

\( A \) = Instantaneous cross section area

**Let us take two examples:**

(I.) Only elongation no neck formation

In the tension test of a rod shown initially it was \( A_o = 50 \text{ mm}^2 \) and \( L_o = 100 \text{ mm} \). After the application of load it’s \( A = 40 \text{ mm}^2 \) and \( L = 125 \text{ mm} \).

Determine the true strain using changes in both length and area.

**Answer:** First of all we have to check that does the member forms neck or not? For that check \( A_o L_o = A L \) or not?

Here \( 50 \times 100 = 40 \times 125 \) so no neck formation is there. Therefore true strain

(If no neck formation occurs both area and gauge length can be used for a strain calculation.)
(II.) Elongation with neck formation
A ductile material is tested such and necking occurs then the final gauge length is $L=140$ mm and the final minimum cross sectional area is $A = 35$ mm$^2$. Though the rod shown initially it was $A_o = 50$ mm$^2$ and $L_o = 100$ mm. Determine the true strain using changes in both length and area.

**Answer:** First of all we have to check that does the member forms neck or not? For that check $A_o L_o = AL$ or not?
Here $A_o L_o = 50 \times 100 = 5000$ mm$^3$ and $AL=35 \times 140 = 4200$ mm$^3$. So neck formation is there. Note here $A_o L_o > AL$.
Therefore true strain
\[
(\varepsilon_r) = \ln \left( \frac{A_o}{A} \right) = \ln \left( \frac{50}{35} \right) = 0.357
\]
But not $\left( \varepsilon_r = \frac{L}{L_o} = \ln \left( \frac{140}{100} \right) = 0.336 \right.$ (it is wrong)

### 1.4 Hook’s law
According to Hook’s law the stress is directly proportional to strain i.e. normal stress ($\sigma$) $\propto$ normal strain ($\varepsilon$) and shearing stress ($\tau$) $\propto$ shearing strain ($\gamma$).

\[
\sigma = E\varepsilon \quad \text{and} \quad \tau = G\gamma
\]
The co-efficient $E$ is called the **modulus of elasticity** i.e. its resistance to elastic strain. The co-efficient $G$ is called the **shear modulus of elasticity** or **modulus of rigidity**.

### 1.5 Volumetric strain ($\varepsilon_v$)
A relationship similar to that for length changes holds for three-dimensional (volume) change. For volumetric strain ($\varepsilon_v$), the relationship is $\left( \varepsilon_v \right) = (V-V_0)/V_0$ or $\left( \varepsilon_v \right) = \Delta V/V_0 = \frac{P}{K}$

- Where $V$ is the final volume, $V_0$ is the original volume, and $\Delta V$ is the volume change.
- Volumetric strain is a ratio of values with the same units, so it also is a dimensionless quantity.
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- AV/V = volumetric strain = ε_x + ε_y + ε_z = ε_1 + ε_2 + ε_3

- **Dilation**: The hydrostatic component of the total stress contributes to deformation by changing the area (or volume, in three dimensions) of an object. Area or volume change is called dilation and is positive or negative, as the volume increases or decreases, respectively. \( \varepsilon = \frac{p}{K} \) Where p is pressure.

1.6 Young’s modulus or Modulus of elasticity \( (E) = \frac{PL}{A\delta} = \frac{\sigma}{\varepsilon} \)

1.7 Modulus of rigidity or Shear modulus of elasticity \( (G) = \frac{\tau}{\gamma} = -\frac{PL}{A\delta} \)

1.8 Bulk Modulus or Volume modulus of elasticity \( (K) = \frac{\Delta p}{\Delta \nu} = \frac{\Delta p}{\Delta \nu} \)

1.10 Relationship between the elastic constants \( E, G, K, \mu \)

\[
E = 2G(1+\mu) = 3K(1-2\mu) = \frac{9KG}{3K+G}
\]

[VIMP]

Where K = Bulk Modulus, \( \mu = \) Poisson’s Ratio, \( E= \) Young’s modulus, \( G= \) Modulus of rigidity

- For a linearly elastic, isotropic and homogeneous material, the number of elastic constants required to relate stress and strain is two. i.e. any two of the four must be known.

- If the material is non-isotropic (i.e. anisotropic), then the elastic modulii will vary with additional stresses appearing since there is a coupling between shear stresses and normal stresses for an anisotropic material.

**Let us take an example**: The modulus of elasticity and rigidity of a material are 200 GPa and 80 GPa, respectively. Find all other elastic modulus.

**Answer**: Using the relation \( E = 2G(1+\mu) = 3K(1-2\mu) = \frac{9KG}{3K+G} \) we may find all other elastic modulus easily

Poisson’s Ratio \( (\mu) \):

\[
1+\mu = \frac{E}{2G} \quad \Rightarrow \mu = \frac{E}{2G} - 1 = \frac{200}{2\times80} - 1 = 0.25
\]

Bulk Modulus \( (K) \):

\[
3K = \frac{E}{1-2\mu} \quad \Rightarrow K = \frac{E}{3(1-2\mu)} = \frac{200}{3(1-2	imes0.25)} = 133.33 \text{GPa}
\]

1.11 Poisson’s Ratio \( (\mu) \)

\[
\frac{\text{Transverse strain or lateral strain}}{\text{Longitudinal strain}} = \frac{-\varepsilon_y}{\varepsilon_x}
\]

(Under unidirectional stress in x-direction)

- The theory of isotropic elasticity allows Poisson’s ratios in the range from -1 to 1/2.

- Poisson’s ratio in various materials
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<table>
<thead>
<tr>
<th>Material</th>
<th>Poisson’s ratio</th>
</tr>
</thead>
<tbody>
<tr>
<td>Steel</td>
<td>0.25 – 0.33</td>
</tr>
<tr>
<td>C.I</td>
<td>0.23 – 0.27</td>
</tr>
<tr>
<td>Concrete</td>
<td>0.2</td>
</tr>
<tr>
<td>Rubber</td>
<td>0.48 – 0.5</td>
</tr>
<tr>
<td>Cork</td>
<td>Nearly zero</td>
</tr>
<tr>
<td>Novel foam</td>
<td>negative</td>
</tr>
</tbody>
</table>

- We use cork in a bottle as the cork easily inserted and removed, yet it also withstand the pressure from within the bottle. Cork with a Poisson’s ratio of nearly zero, is ideal in this application.

1.12 For bi-axial stretching of sheet

\[
\varepsilon_1 = \ln \left( \frac{L_1}{L_{o1}} \right) \quad \text{L}_o - \text{Original length}
\]

\[
\varepsilon_2 = \ln \left( \frac{L_2}{L_{o2}} \right) \quad \text{L}_f - \text{Final length}
\]

Final thickness \((t_f) = \frac{\text{Initial thickness}(t_o)}{e^{\varepsilon_1} \times e^{\varepsilon_2}}\)

1.13 Elongation

- A prismatic bar loaded in tension by an axial force \(P\)

For a prismatic bar loaded in tension by an axial force \(P\). The elongation of the bar can be determined as

\[
\delta = \frac{PL}{AE}
\]

Let us take an example: A Mild Steel wire 5 mm in diameter and 1 m long. If the wire is subjected to an axial tensile load 10 kN find its extension of the rod. \((E = 200 \text{ GPa})\)

Answer: We know that \((\delta) = \frac{PL}{AE}\)

Here given, Force \((P) = 10 \text{ kN} = 10 \times 1000 \text{N}\)

Length \((L) = 1 \text{ m}\)

Area \((A) = \frac{\pi d^2}{4} = \frac{\pi \times (0.005)^2}{4} \text{m}^2 = 1.963 \times 10^{-5} \text{m}^2\)

Modulus of Elasticity \((E) = 200 \text{ GPa} = 200 \times 10^9 \text{N/m}^2\)

Therefore Elongation \((\delta) = \frac{PL}{AE} = \frac{(10 \times 1000) \times 1}{(1.963 \times 10^{-5}) \times (200 \times 10^9)} \text{m} = 2.55 \times 10^{-3} \text{ m} = 2.55 \text{ mm}\)

- Elongation of composite body

Elongation of a bar of varying cross section \(A_1, A_2, \ldots, A_n\) of lengths \(l_1, l_2, \ldots, l_n\) respectively.

\[
\delta = \frac{P}{E} \left[ \frac{l_1}{A_1} + \frac{l_2}{A_2} + \frac{l_3}{A_3} + \ldots + \frac{l_n}{A_n} \right]
\]
Let us take an example: A composite rod is 1000 mm long, its two ends are 40 mm\(^2\) and 30 mm\(^2\) in area and length are 300 mm and 200 mm respectively. The middle portion of the rod is 20 mm\(^2\) in area and 500 mm long. If the rod is subjected to an axial tensile load of 1000 N, find its total elongation. (E = 200 GPa).

Answer: Consider the following figure

![Composite Rod Diagram](image)

Given, Load \(P = 1000 \text{ N}\)

- Area: \(A_1 = 40 \text{ mm}^2\), \(A_2 = 20 \text{ mm}^2\), \(A_3 = 30 \text{ mm}^2\)
- Length: \(l_1 = 300 \text{ mm}\), \(l_2 = 500 \text{ mm}\), \(l_3 = 200 \text{ mm}\)
- \(E = 200 \text{ GPa} = 200 \times 10^9 \text{ N/m}^2 = 200 \times 10^3 \text{ N/mm}^2\)

Therefore, Total extension of the rod

\[
\delta = \frac{P}{E} \left[ \frac{l_1}{A_1} + \frac{l_2}{A_2} + \frac{l_3}{A_3} \right]
\]

\[
= \frac{1000 \text{ N}}{200 \times 10^3 \text{ N/mm}^2} \times \left[ \frac{300 \text{ mm}}{40 \text{ mm}^2} + \frac{500 \text{ mm}}{20 \text{ mm}^2} + \frac{200 \text{ mm}}{30 \text{ mm}^2} \right]
\]

\[
= 0.196 \text{ mm}
\]

- Elongation of a tapered body

Elongation of a tapering rod of length ‘L’ due to load ‘P’ at the end

\[
\delta = \frac{4PL}{\pi Ed_1d_2}
\]

(d\(_1\) and d\(_2\) are the diameters of smaller & larger ends)

You may remember this in this way, \(\delta = \frac{PL}{E \left( \frac{\pi}{4} d_1d_2 \right)} \) i.e. \(\delta = \frac{PL}{EA_{eq}}\)

Let us take an example: A round bar, of length L, tapers uniformly from small diameter \(d_1\) at one end to bigger diameter \(d_2\) at the other end. Show that the extension produced by a tensile axial load \(P\) is

\[
\delta = \frac{4PL}{\pi d_1d_2E}
\]

If \(d_2 = 2d_1\), compare this extension with that of a uniform cylindrical bar having a diameter equal to the mean diameter of the tapered bar.

Answer: Consider the figure below \(d_1\) be the radius at the smaller end. Then at a X cross section XX located at a distance \(X\) from the smaller end, the value of diameter ‘\(d_X\)’ is equal to
\[ \frac{d_x}{2} = \frac{d_1}{2} + \frac{x}{L} \left( \frac{d_2 - d_1}{2} \right) \]

or \[ d_x = d_1 + \frac{x}{L} (d_2 - d_1) \]

\[ = d_1 (1 + kx) \quad \text{Where} \quad k = \frac{d_2 - d_1}{L} \times \frac{1}{d_i} \]

We now taking a small strip of diameter 'd_x' and length 'd_x' at section XX.

Elongation of this section 'd_x' length

\[ d(\delta) = \frac{PL}{AE} = \frac{P \, dx}{\left( \frac{\pi d_i^4}{4} \right) \times E} = \frac{4P \, dx}{\pi \cdot \left( d_i (1 + kx) \right)^2 \times E} \]

Therefore total elongation of the taper bar

\[ \delta = \int d(\delta) = \int_{x=0}^{x=L} \frac{4P \, dx}{\pi E d_i \left( 1 + kx \right)^2} \]

\[ = \frac{4PL}{\pi E d_i d_2} \]

**Comparison:** Case-I: Where \( d_2 = 2d_1 \)

\[ \text{Elongation (\delta_i)} = \frac{4PL}{\pi Ed_i \times 2d_i} = \frac{2PL}{\pi Ed_i^2} \]

Case –II: Where we use Mean diameter

\[ d_m = \frac{d_1 + d_2}{2} = \frac{d_1 + 2d_1}{2} = \frac{3d_1}{2} \]

\[ \text{Elongation of such bar (\delta_h)} = \frac{PL}{AE} = \frac{P \, L}{\pi \left( \frac{3}{2} d_1 \right)^2 \times E} \]

\[ = \frac{16PL}{9\pi Ed_i^2} \]

\[ \text{Extension of taper bar} = \frac{2}{16} = \frac{9}{8} \]

\[ \text{Extension of uniform bar} \]
**Elongation of a body due to its self weight**

(i) Elongation of a uniform rod of length ‘L’ due to its own weight ‘W’

\[ \delta = \frac{WL}{2AE} \]

The deformation of a bar under its own weight as compared to that when subjected to a direct axial load equal to its own weight will be half.

(ii) Total extension produced in rod of length ‘L’ due to its own weight ‘\( \omega \)’ per with length.

\[ \delta = \frac{\omega L^2}{2EA} \]

(iii) Elongation of a conical bar due to its self weight

\[ \delta = \frac{pgL^2}{6E} = \frac{WL}{2A_{\text{max}}E} \]

1.14 Structural members or machines must be designed such that the working stresses are less than the ultimate strength of the material.

\[
\text{Working stress} \left( \sigma_w \right) = \frac{\sigma_f}{n} \quad n=1.5 \text{ to } 2 \\
= \frac{\sigma_{\text{ult}}}{n_t} \quad n_t = 2 \text{ to } 3 \\
= \frac{\sigma_p}{n} \quad \sigma_p = \text{Proof stress}
\]

1.15 Factor of Safety: \( n = \frac{\sigma_y \text{ or } \sigma_p \text{ or } \sigma_{\text{ult}}}{\sigma_w} \)

1.16 Thermal or Temperature stress and strain

- When a material undergoes a change in temperature, it either elongates or contracts depending upon whether temperature is increased or decreased of the material.
- If the elongation or contraction is not restricted, i.e., free then the material does not experience any stress despite the fact that it undergoes a strain.
- The strain due to temperature change is called thermal strain and is expressed as,

\[ \varepsilon = \alpha \left( \Delta T \right) \]

- Where \( \alpha \) is co-efficient of thermal expansion, a material property, and \( \Delta T \) is the change in temperature.
- The free expansion or contraction of materials, when restrained induces stress in the material and it is referred to as thermal stress.
\[ \sigma_t = \alpha E (\Delta T) \]

Where, \( E \) = Modulus of elasticity

- Thermal stress produces the same effect in the material similar to that of mechanical stress. A compressive stress will produce in the material with increase in temperature and the stress developed is tensile stress with decrease in temperature.

**Let us take an example:** A rod consists of two parts that are made of steel and copper as shown in figure below. The elastic modulus and coefficient of thermal expansion for steel are 200 GPa and \( 11.7 \times 10^{-6} \) per °C respectively and for copper 70 GPa and \( 21.6 \times 10^{-6} \) per °C respectively. If the temperature of the rod is raised by 50°C, determine the forces and stresses acting on the rod.

![Diagram of the rod](image)

**Answer:** If we allow this rod to freely expand then free expansion

\[
\delta_f = \alpha (\Delta T) L \\
= (11.7 \times 10^{-6}) \times 50 \times 500 + (21.6 \times 10^{-6}) \times 50 \times 750 \\
= 1.1025 \text{ mm (Compressive)}
\]

But according to diagram only free expansion is 0.4 mm.

Therefore restrained deflection of rod = 1.1025 mm – 0.4 mm = 0.7025 mm

Let us assume the force required to make their elongation vanish be \( P \) which is the reaction force at the ends.

\[
\delta = \left( \frac{PL}{AE} \right)_{\text{Steel}} + \left( \frac{PL}{AE} \right)_{\text{Cu}}
\]

or

\[
0.7025 = \frac{P \times 500}{\frac{\pi}{4} \times (0.075)^2} \times (200 \times 10^9) + \frac{P \times 750}{\frac{\pi}{4} \times (0.050)^2} \times (70 \times 10^9)
\]

or \( P = 116.6 \text{ kN} \)

Therefore, compressive stress on steel rod

\[ \sigma_{\text{Steel}} = \frac{P}{A_{\text{Steel}}} = \frac{116.6 \times 10^3}{\frac{\pi}{4} \times (0.075)^2} \text{ N/m}^2 = 26.39 \text{ MPa} \]

And compressive stress on copper rod

\[ \sigma_{\text{Cu}} = \frac{P}{A_{\text{Cu}}} = \frac{116.6 \times 10^3}{\frac{\pi}{4} \times (0.050)^2} \text{ N/m}^2 = 59.38 \text{ MPa} \]
1.17 Thermal stress on Brass and Mild steel combination

A brass rod placed within a steel tube of exactly same length. The assembly is making in such a way that elongation of the combination will be same. To calculate the stress induced in the brass rod, steel tube when the combination is raised by \( t \)°C then the following analogy have to do.

(a) Original bar before heating.

(b) Expanded position if the members are allowed to expand freely and independently after heating.

(c) Expanded position of the compound bar i.e. final position after heating.

- Compatibility Equation:
  \[
  \delta = \delta_s + \delta_{sf} = \delta_{bt} - \delta_{bf}
  \]
- Equilibrium Equation:
  \[
  \sigma_s A_s = \sigma_b A_b
  \]

Assumption:
1. \( L = L_s = L_b \)
2. \( \alpha_b > \alpha_s \)
3. Steel – Tension
   Brass – Compression

Where, \( \delta = \) Expansion of the compound bar = \( AD \) in the above figure.

\( \delta_s = \) Free expansion of the steel tube due to temperature rise \( t \)°C = \( \alpha_s L t \)

\( = AB \) in the above figure.

\( \delta_{sf} = \) Expansion of the steel tube due to internal force developed by the unequal expansion.

\( = BD \) in the above figure.

\( \delta_{bt} = \) Free expansion of the brass rod due to temperature rise \( t \)°C = \( \alpha_b L t \)

\( = AC \) in the above figure.

\( \delta_{bf} = \) Compression of the brass rod due to internal force developed by the unequal expansion.

\( = BD \) in the above figure.

And in the equilibrium equation

Tensile force in the steel tube = Compressive force in the brass rod

Where, \( \sigma_s = \) Tensile stress developed in the steel tube.

\( \sigma_b = \) Compressive stress developed in the brass rod.

\( A_s = \) Cross section area of the steel tube.

\( A_b = \) Cross section area of the brass rod.

Let us take an example: See the Conventional Question Answer section of this chapter and the question is “Conventional Question IES-2008” and it’s answer.
1.18 Maximum stress and elongation due to rotation

(i) \( \sigma_{\text{max}} = \frac{\rho \omega^2 L^2}{8} \) and \( (\delta L) = \frac{\rho \omega^2 L^3}{12E} \)

(ii) \( \sigma_{\text{max}} = \frac{\rho \omega^2 L^2}{2} \) and \( (\delta L) = \frac{\rho \omega^2 L^3}{3E} \)

For remember: You will get (ii) by multiplying by 4 of (i)

1.18 Creep

When a member is subjected to a constant load over a long period of time it undergoes a slow permanent deformation and this is termed as “creep”. This is dependent on temperature. Usually at elevated temperatures creep is high.

- The materials have its own different melting point; each will creep when the homologous temperature > 0.5. Homologous temp = \( \frac{\text{Testing temperature}}{\text{Melting temperature}} > 0.5 \)

A typical creep curve shows three distinct stages with different creep rates. After an initial rapid elongation \( \varepsilon_0 \), the creep rate decrease with time until reaching the steady state.

1) **Primary creep** is a period of transient creep. The creep resistance of the material increases due to material deformation.

2) **Secondary creep** provides a nearly constant creep rate. The average value of the creep rate during this period is called the minimum creep rate. A stage of balance between competing.

**Strain hardening** and **recovery** (softening) of the material.

3) **Tertiary creep** shows a rapid increase in the creep rate due to effectively reduced cross-sectional area of the specimen leading to creep rupture or failure. In this stage intergranular cracking and/or formation of voids and cavities occur.

**Creep rate** = \( c_1 \sigma^{c_2} \)

Creep strain at any time = zero time strain intercept + creep rate \( \times \)Time

\[ = \varepsilon_0 + c_1 \sigma^{c_2} \times t \]

Where, \( c_1, c_2 \) are constants \( \sigma = \text{stress} \)

1.19 If a load \( P \) is applied suddenly to a bar then the stress & strain induced will be **double** than those obtained by an equal load applied gradually.

1.20 Stress produced by a load \( P \) in falling from height \( 'h' \)
\[ \sigma_d = \sigma \left[ \frac{1}{1 + \frac{2h}{L}} \right] \sigma, \]

\[ \varepsilon \] being stress & strain produced by static load \( P \) & \( L = \) length of bar.

\[ = \frac{A}{P} \left[ 1 + \frac{2AEh}{PL} \right] \]

1.21 Loads shared by the materials of a compound bar made of bars \( x \) & \( y \) due to load \( W \),

\[ P_x = W \cdot \frac{A_x E_x}{A_x E_x + A_y E_y} \]

\[ P_y = W \cdot \frac{A_y E_y}{A_x E_x + A_y E_y} \]

1.22 Elongation of a compound bar, \( \delta = \frac{PL}{A_x E_x + A_y E_y} \)

1.23 Tension Test

i) **True elastic limit**: based on micro-strain measurement at strains on order of \( 2 \times 10^{-6} \). Very low value and is related to the motion of a few hundred dislocations.

ii) **Proportional limit**: the highest stress at which stress is directly proportional to strain.

iii) **Elastic limit**: is the greatest stress the material can withstand without any measurable permanent strain after unloading. Elastic limit > proportional limit.

iv) **Yield strength** is the stress required to produce a small specific amount of deformation. The offset yield strength can be determined by the stress corresponding to the intersection of the stress-strain curve and a line parallel to the elastic line offset by a strain of 0.2 or 0.1%. \((\varepsilon = 0.002 \text{ or } 0.001)\).
v) **Tensile strength or ultimate tensile strength (UTS)** $\sigma_u$ is the maximum load $P_{\text{max}}$ divided by the original cross-sectional area $A_o$ of the specimen.

vi) **% Elongation**, $\frac{L_f - L_o}{L_o}$, is chiefly influenced by uniform elongation, which is dependent on the strain-hardening capacity of the material.

vii) **Reduction of Area**: $q = \frac{A_o - A_f}{A_o}$

- Reduction of area is more a measure of the deformation required to produce failure and its chief contribution results from the necking process.
- Because of the complicated state of stress state in the neck, values of reduction of area are dependent on specimen geometry, and deformation behaviour, and they should not be taken as true material properties.
- RA is the most structure-sensitive ductility parameter and is useful in detecting quality changes in the materials.

viii) **Stress-strain response**

![Stress-strain graphs](image)

1.24 **Elastic strain and Plastic strain**

The strain present in the material after unloading is called the residual strain or plastic strain and the strain disappears during unloading is termed as recoverable or elastic strain.

Equation of the straight line CB is given by

$$\sigma = \varepsilon_{\text{total}} \times E - \varepsilon_{\text{plastic}} \times E = \varepsilon_{\text{elastic}} \times E$$

Carefully observe the following figures and understand which one is Elastic strain and which one is Plastic strain.
Let us take an example: A 10 mm diameter tensile specimen has a 50 mm gauge length. The load corresponding to the 0.2% offset is 55 kN and the maximum load is 70 kN. Fracture occurs at 60 kN. The diameter after fracture is 8 mm and the gauge length at fracture is 65 mm. Calculate the following properties of the material from the tension test.

(i) % Elongation

(ii) Reduction of Area (RA) %

(iii) Tensile strength or ultimate tensile strength (UTS)

(iv) Yield strength

(v) Fracture strength

(vi) If $E = 200 \text{ GPa}$, the elastic recoverable strain at maximum load

(vii) If the elongation at maximum load (the uniform elongation) is 20%, what is the plastic strain at maximum load?

**Answer:**

Given, Original area $A_b = \frac{\pi}{4} \times (0.010)^2 \text{ m}^2 = 7.854 \times 10^{-5} \text{ m}^2$

Area at fracture $A_f = \frac{\pi}{4} \times (0.008)^2 \text{ m}^2 = 5.027 \times 10^{-5} \text{ m}^2$

Original gauge length ($L_0$) = 50 mm

Gauge length at fracture ($L$) = 65 mm

Therefore

(i) % Elongation $= \frac{L - L_0}{L_0} \times 100\% = \frac{65 - 50}{50} \times 100\% = 30\%$

(ii) Reduction of area (RA) $= q = \frac{A_b - A_f}{A_b} \times 100\% = \frac{7.854 - 5.027}{7.854} \times 100\% = 36\%$

(iii) Tensile strength or Ultimate tensile strength (UTS), $\sigma_u = \frac{P_{max}}{A_b} = \frac{70 \times 10^3}{7.854 \times 10^{-5}} \text{ N/m}^2 = 891 \text{ MPa}$

(iv) Yield strength $\left(\sigma_y\right) = \frac{P_y}{A_b} = \frac{55 \times 10^3}{7.854 \times 10^{-5}} \text{ N/m}^2 = 700 \text{ MPa}$

(v) Fracture strength $\left(\sigma_F\right) = \frac{P_{Fracture}}{A_b} = \frac{60 \times 10^3}{7.854 \times 10^{-5}} \text{ N/m}^2 = 764 \text{ MPa}$

(vi) Elastic recoverable strain at maximum load $\left(\varepsilon_E\right) = \frac{P_{max}}{E} \frac{A_b}{A_b} = \frac{891 \times 10^6}{200 \times 10^9} = 0.0045$
1.25 Elasticity
This is the property of a material to regain its original shape after deformation when the external forces are removed. When the material is in elastic region the strain disappears completely after removal of the load. The stress-strain relationship in elastic region need not be linear and can be non-linear (example rubber). The maximum stress value below which the strain is fully recoverable is called the elastic limit. It is represented by point A in figure. All materials are elastic to some extent but the degree varies, for example, both mild steel and rubber are elastic materials but steel is more elastic than rubber.

1.26 Plasticity
When the stress in the material exceeds the elastic limit, the material enters into plastic phase where the strain can no longer be completely removed. Under plastic conditions materials ideally deform without any increase in stress. A typical stress strain diagram for an elastic-perfectly plastic material is shown in the figure. Mises-Henky criterion gives a good starting point for plasticity analysis.

1.27 Strain hardening
If the material is reloaded from point C, it will follow the previous unloading path and line CB becomes its new elastic region with elastic limit defined by point B. Though the new elastic region CB resembles that of the initial elastic region OA, the internal structure of the material in the new state has changed. The change in the microstructure of the material is clear from the fact that the ductility of the material has come down due to strain hardening. When the material is reloaded, it follows the same path as that of a virgin material and fails on reaching the ultimate strength which remains unaltered due to the intermediate loading and unloading process.
1.28 Stress reversal and stress-strain hysteresis loop

We know that fatigue failure begins at a local discontinuity and when the stress at the discontinuity exceeds elastic limit there is plastic strain. The cyclic plastic strain results crack propagation and fracture.

When we plot the experimental data with reversed loading and the true stress strain hysteresis loops is found as shown below.

Due to cyclic strain the elastic limit increases for annealed steel and decreases for cold drawn steel. Here the stress range is $\Delta \sigma$. $\Delta \varepsilon_p$ and $\Delta \varepsilon_e$ are the plastic and elastic strain ranges, the total strain range being $\Delta \varepsilon$. Considering that the total strain amplitude can be given as

$$\Delta \varepsilon = \Delta \varepsilon_p + \Delta \varepsilon_e$$
Stress in a bar due to self-weight

GATE-1. Two identical circular rods of same diameter and same length are subjected to same magnitude of axial tensile force. One of the rods is made out of mild steel having the modulus of elasticity of 206 GPa. The other rod is made out of cast iron having the modulus of elasticity of 100 GPa. Assume both the materials to be homogeneous and isotropic and the axial force causes the same amount of uniform stress in both the rods. The stresses developed are within the proportional limit of the respective materials. Which of the following observations is correct? [GATE-2003]

(a) Both rods elongate by the same amount
(b) Mild steel rod elongates more than the cast iron rod
(c) Cast iron rod elongates more than the mild steel rod
(d) As the stresses are equal strains are also equal in both the rods

GATE-1. Ans. (c) $\Delta L = \frac{PL}{AE}$ or $\Delta L \propto \frac{1}{E}$ [As P, L and A is same]

GATE-2. A steel bar of 40 mm $\times$ 40 mm square cross-section is subjected to an axial compressive load of 200 kN. If the length of the bar is 2 m and $E = 200$ GPa, the elongation of the bar will be: [GATE-2006]

(a) 1.25 mm  (b) 2.70 mm  (c) 4.05 mm  (d) 5.40 mm

GATE-2. Ans. (a) $\Delta L = \frac{PL}{AE} = \frac{(200 \times 1000) \times 2}{(0.04 \times 0.04) \times 200 \times 10^6} = 1.25$ mm

True stress and true strain

GATE-3. The ultimate tensile strength of a material is 400 MPa and the elongation up to maximum load is 35%. If the material obeys power law of hardening, then the true stress-true strain relation (stress in MPa) in the plastic deformation range is: [GATE-2006]

(a) $\sigma = 540 \varepsilon^{0.30}$  (b) $\sigma = 775 \varepsilon^{0.30}$  (c) $\sigma = 540 \varepsilon^{0.35}$  (d) $\sigma = 775 \varepsilon^{0.35}$

GATE-3. Ans. (c)

A true stress – true strain curve in tension $\sigma = k\varepsilon^n$

k = Strength co-efficient = 400 $\times$ (1.35) = 540 MPa

n = Strain – hardening exponent = 0.35

Elasticity and Plasticity

GATE-4. An axial residual compressive stress due to a manufacturing process is present on the outer surface of a rotating shaft subjected to bending. Under a given
bending load, the fatigue life of the shaft in the presence of the residual compressive stress is: [GATE-2008]
(a) Decreased
(b) Increased or decreased, depending on the external bending load
(c) Neither decreased nor increased
(d) Increased

GATE-4. Ans. (d)

A cantilever-loaded rotating beam, showing the normal distribution of surface stresses. (i.e., tension at the top and compression at the bottom)

The residual compressive stresses induced.

Net stress pattern obtained when loading a surface treated beam. The reduced magnitude of the tensile stresses contributes to increased fatigue life.

GATE-5. A static load is mounted at the centre of a shaft rotating at uniform angular velocity. This shaft will be designed for [GATE-2002]
(a) The maximum compressive stress (static)  (b) The maximum tensile stress (static)
(c) The maximum bending moment (static)  (d) Fatigue loading

GATE-5. Ans. (d)

GATE-6. Fatigue strength of a rod subjected to cyclic axial force is less than that of a rotating beam of the same dimensions subjected to steady lateral force because [GATE-1992]
(a) Axial stiffness is less than bending stiffness
(b) Of absence of centrifugal effects in the rod
(c) The number of discontinuities vulnerable to fatigue are more in the rod
(d) At a particular time the rod has only one type of stress whereas the beam has both the tensile and compressive stresses.

GATE-6. Ans. (d)

**Relation between the Elastic Modulii**

GATE-7. A rod of length $L$ and diameter $D$ is subjected to a tensile load $P$. Which of the following is sufficient to calculate the resulting change in diameter?
(a) Young’s modulus  (b) Shear modulus  [GATE-2008]
(c) Poisson's ratio  (d) Both Young’s modulus and shear modulus
GATE-7. Ans. (d) For longitudinal strain we need Young's modulus and for calculating transverse strain we need Poisson's ratio. We may calculate Poisson's ratio from \( E = 2G(1 + \mu) \) for that we need shear modulus.

GATE-8. In terms of Poisson's ratio (\( \mu \)) the ratio of Young's Modulus (E) to Shear Modulus (G) of elastic materials is

\[ \frac{E}{G} = \frac{1}{2(1 - \mu)} \]

GATE-8. Ans. (a)

GATE-9. The relationship between Young's modulus (E), Bulk modulus (K) and Poisson's ratio (\( \mu \)) is given by:

(a) \( E = 3K(1 - 2\mu) \)  
(b) \( K = 3E(1 - 2\mu) \)  
(c) \( E = 3K(1 - \mu) \)  
(d) \( K = 3E(1 - \mu) \)

GATE-9. Ans. (a) Remember \( E = 2G(1 + \mu) = 3K(1 - 2\mu) = \frac{9KG}{3K + G} \)

Stresses in compound strut

GATE-10. In a bolted joint two members are connected with an axial tightening force of 2200 N. If the bolt used has metric threads of 4 mm pitch, then torque required for achieving the tightening force is

(a) 0.7Nm  
(b) 1.0 Nm  
(c) 1.4Nm  
(d) 2.8Nm

GATE-10. Ans. (c) \( T = F \times r = 2200 \times \frac{0.004}{2\pi} \text{Nm} = 1.4\text{Nm} \)

GATE-11. The figure below shows a steel rod of 25 mm² cross-sectional area. It is loaded at four points, K, L, M and N.

Assume \( E_{\text{steel}} = 200 \text{ GPa} \). The total change in length of the rod due to loading is:

(a) 1 \( \mu \)m  
(b) -10 \( \mu \)m  
(c) 16 \( \mu \)m  
(d) -20 \( \mu \)m

GATE-11. Ans. (b) First draw FBD of all parts separately then

\[ \text{Total change in length} = \sum \frac{PL}{AE} \]

GATE-12. A bar having a cross-sectional area of 700mm² is subjected to axial loads at the positions indicated. The value of stress in the segment QR is:

\[ \text{[GATE-2006]} \]
Chapter-1 Stress and Strain

GATE-12. Ans. (a)

GATE-13. Ans. (a) No calculation needed it is pre-compressed by 100 mm from its free state. So it can’t move more than 100 mm. choice (b), (c) and (d) out.

GATE-14. Ans. (d) Frictional force required = 2000 N

Force needed to produce 2000N frictional force at Y-Y section = \[
\frac{2000}{0.1} = 20000 N
\]

So for each side we need \((F_Y) = 10000 \text{ N force}\)
Taking moment about PIN

\[ F_y \times 50 = F \times 100 \quad \text{or} \quad F = \frac{F_y \times 50}{100} = \frac{10000 \times 50}{100} = 5000 \text{N} \]

GATE-15. A uniform, slender cylindrical rod is made of a homogeneous and isotropic material. The rod rests on a frictionless surface. The rod is heated uniformly. If the radial and longitudinal thermal stresses are represented by \( \sigma_r \) and \( \sigma_z \), respectively, then [GATE-2005]

(a) \( \sigma_r = 0, \sigma_z = 0 \)  \quad (b) \( \sigma_r \neq 0, \sigma_z = 0 \)  \quad (c) \( \sigma_r = 0, \sigma_z \neq 0 \)  \quad (d) \( \sigma_r \neq 0, \sigma_z \neq 0 \)

GATE-15. Ans. (a) Thermal stress will develop only when you prevent the material to contrast/elongate. As here it is free no thermal stress will develop.

### Tensile Test

GATE-16. A test specimen is stressed slightly beyond the yield point and then unloaded. Its yield strength will \[ \text{GATE-1995} \]

(a) Decrease  \quad (b) Increase  \quad (c) Remains same  \quad (d) Becomes equal to ultimate tensile strength

GATE-16. Ans. (b)

GATE-17. Under repeated loading a material has the stress-strain curve shown in figure, which of the following statements is true?

(a) The smaller the shaded area, the better the material damping
(b) The larger the shaded area, the better the material damping
(c) Material damping is an independent material property and does not depend on this curve
(d) None of these \[ \text{GATE-1999} \]

GATE-17. Ans. (a)

### Previous 20-Years IES Questions

#### Stress in a bar due to self-weight

IES-1. A solid uniform metal bar of diameter \( D \) and length \( L \) is hanging vertically from its upper end. The elongation of the bar due to self weight is: \[ \text{IES-2005} \]

(a) Proportional to \( L \) and inversely proportional to \( D^2 \)
(b) Proportional to \( L^2 \) and inversely proportional to \( D^2 \)
(c) Proportional of \( L \) but independent of \( D \)
(d) Proportional of \( U \) but independent of \( D \)
Chapter-1 Stress and Strain

IES-1. Ans. (a) \[ \delta = \frac{WL}{2AE} = \frac{WL}{2 \times \frac{\pi D^2}{4} \times E} \]

\[ \therefore \delta \times L \quad \& \quad \delta \times \frac{1}{D^2} \]

IES-2. The deformation of a bar under its own weight as compared to that when subjected to a direct axial load equal to its own weight will be: [IES-1998]
(a) The same   (b) One-fourth   (c) Half   (d) Double

IES-2. Ans. (c)

IES-3. A rigid beam of negligible weight is supported in a horizontal position by two rods of steel and aluminum, 2 m and 1 m long having values of cross-sectional areas 1 cm² and 2 cm² and E of 200 GPa and 100 GPa respectively. A load P is applied as shown in the figure [IES-2002]

\[ \text{Steel} \quad 2 \text{m} \]

\[ \text{Aluminium} \quad 1 \text{m} \]

\[ \text{Rigid Beam} \]

If the rigid beam is to remain horizontal then
(a) The forces on both sides should be equal
(b) The force on aluminum rod should be twice the force on steel
(c) The force on the steel rod should be twice the force on aluminum
(d) The force P must be applied at the centre of the beam

IES-3. Ans. (b)

Bar of uniform strength

IES-4. Which one of the following statements is correct? [IES 2007]
A beam is said to be of uniform strength, if
(a) The bending moment is the same throughout the beam
(b) The shear stress is the same throughout the beam
(c) The deflection is the same throughout the beam
(d) The bending stress is the same at every section along its longitudinal axis

IES-4. Ans. (d)

IES-5. Which one of the following statements is correct? [IES-2006]
Beams of uniform strength vary in section such that
(a) bending moment remains constant  (b) deflection remains constant
(c) maximum bending stress remains constant  (d) shear force remains constant

IES-5. Ans. (c)

IES-6. For bolts of uniform strength, the shank diameter is made equal to [IES-2003]
(a) Major diameter of threads  (b) Pitch diameter of threads
(c) Minor diameter of threads  (d) Nominal diameter of threads

IES-6. Ans. (c)

IES-7. A bolt of uniform strength can be developed by [IES-1995]
(a) Keeping the core diameter of threads equal to the diameter of unthreaded portion of the bolt
(b) Keeping the core diameter smaller than the diameter of the unthreaded portion
Elongation of a Taper Rod

IES-8. Two tapering bars of the same material are subjected to a tensile load P. The lengths of both the bars are the same. The larger diameter of each of the bars is D. The diameter of the bar A at its smaller end is D/2 and that of the bar B is D/3. What is the ratio of elongation of the bar A to that of the bar B? [IES-2006]
(a) 3 : 2  (b) 2 : 3  (c) 4 : 9  (d) 1 : 3

IES-8. Ans. (b)

\[ \frac{\delta_A}{\delta_B} = \frac{\frac{D}{3}}{\frac{D}{2}} = \frac{2}{3} \]

IES-9. A bar of length L tapers uniformly from diameter 1.1 D at one end to 0.9 D at the other end. The elongation due to axial pull is computed using mean diameter D. What is the approximate error in computed elongation? [IES-2004]
(a) 10%  (b) 5%  (c) 1%  (d) 0.5%

IES-9. Ans. (c)

Actual elongation of the bar \( \delta_{\text{act}} = \frac{PL}{\frac{\pi}{4} d_2 d E} \)
Calculated elongation of the bar \( \delta_{\text{cal}} = \frac{PL}{\pi d^2 E} \)
\[ \text{Error} \% = \left( \frac{\delta_{\text{act}}}{\delta_{\text{cal}}} - 1 \right) \times 100 = \left( 1 \times 1.1D \times 0.9D - 1 \right) \times 100\% = 1\% \]

IES-10. The stretch in a steel rod of circular section, having a length 'l' subjected to a tensile load 'P' and tapering uniformly from a diameter \( d_1 \) at one end to a diameter \( d_2 \) at the other end, is given [IES-1995]
(a) \( \frac{Pl}{4Ed_1 d_2} \)  (b) \( \frac{pl\pi}{Ed_1 d_2} \)  (c) \( \frac{pl\pi}{4Ed_1 d_2} \)  (d) \( \frac{4pl}{\pi Ed_1 d_2} \)

IES-10. Ans. (d)

Actual elongation of the bar \( \delta_{\text{act}} = \frac{PL}{\frac{\pi}{4} d_1 d_2 E} \)

IES-11. A tapering bar (diameters of end sections being \( d_1 \) and \( d_2 \) a bar of uniform cross-section 'd' have the same length and are subjected the same axial pull. Both the bars will have the same extension if 'd' is equal to [IES-1998]
(a) \( \frac{d_1 + d_2}{2} \)  (b) \( \sqrt{d_1 d_2} \)  (c) \( \sqrt{\frac{d_1 d_2}{2}} \)  (d) \( \sqrt{\frac{d_1 + d_2}{2}} \)

IES-11. Ans. (b)

Poisson's ratio

IES-12. In the case of an engineering material under unidirectional stress in the x-direction, the Poisson's ratio is equal to (symbols have the usual meanings) [IAS 1994, IES-2000]
IES-12. Ans. (a)

IES-13. Which one of the following is correct in respect of Poisson's ratio (v) limits for an isotropic elastic solid? [IES-2004]
(a) $-\infty \leq v \leq \infty$  
(b) $1/4 \leq v \leq 1/3$  
(c) $-1 \leq v \leq 1/2$  
(d) $-1/2 \leq v \leq 1/2$

IES-13. Ans. (c) Theoretically $-1 < \mu < 1/2$ but practically $0 < \mu < 1/2$

IES-14. Match List-I (Elastic properties of an isotropic elastic material) with List-II (Nature of strain produced) and select the correct answer using the codes given below the Lists: [IES-1997]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Young's modulus</td>
<td>1. Shear strain</td>
</tr>
<tr>
<td>B. Modulus of rigidity</td>
<td>2. Normal strain</td>
</tr>
<tr>
<td>C. Bulk modulus</td>
<td>3. Transverse strain</td>
</tr>
<tr>
<td>D. Poisson's ratio</td>
<td>4. Volumetric strain</td>
</tr>
</tbody>
</table>

Codes: A B C D
(a) 1 2 3 4  
(b) 2 1 3 4  
(c) 2 1 4 3  
(d) 1 2 4 3

IES-14. Ans. (c)

IES-15. If the value of Poisson's ratio is zero, then it means that [IES-1994]
(a) The material is rigid.  
(b) The material is perfectly plastic.  
(c) There is no longitudinal strain in the material  
(d) The longitudinal strain in the material is infinite.

IES-15. Ans. (a) If Poisson's ratio is zero, then material is rigid.

IES-16. Which of the following is true ($\mu =$ Poisson's ratio) [IES-1992]
(a) $0 < \mu < 1/2$  
(b) $1 < \mu < 0$  
(c) $1 < \mu < -1$  
(d) $\infty < \mu \ll -\infty$

IES-16. Ans. (a)

**Elasticity and Plasticity**

IES-17. If the area of cross-section of a wire is circular and if the radius of this circle decreases to half its original value due to the stretch of the wire by a load, then the modulus of elasticity of the wire be: [IES-1993]
(a) One-fourth of its original value  
(b) Halved  
(c) Doubled  
(d) Unaffected

IES-17. Ans. (d) Note: Modulus of elasticity is the property of material. It will remain same.

IES-18. The relationship between the Lamé's constant '\( \lambda \)', Young's modulus 'E' and the Poisson's ratio '\( \mu \)': [IES-1997]
(a) $\lambda = \frac{E\mu}{(1+\mu)(1-2\mu)}$  
(b) $\lambda = \frac{E\mu}{(1+2\mu)(1-\mu)}$  
(c) $\lambda = \frac{E\mu}{1+\mu}$  
(d) $\lambda = \frac{E\mu}{(1-\mu)}$

IES-18. Ans. (a)

IES-19. Which of the following pairs are correctly matched? [IES-1994]
1. Resilience.............. Resistance to deformation.
2. Malleability ............ Shape change.
4. Plasticity .............. Permanent deformation.

Select the correct answer using the codes given below:

Codes:  
(a) 2, 3 and 4  
(b) 1, 2 and 3  
(c) 1, 2 and 4  
(d) 1, 3 and 4

IES-19. Ans. (a) Strain energy stored by a body within elastic limit is known as resilience.
Creep and fatigue

IES-20. What is the phenomenon of progressive extension of the material i.e., strain increasing with the time at a constant load, called? [IES 2007]
(a) Plasticity  (b) Yielding  (c) Creeping  (d) Breaking
IES-20. Ans. (c)

IES-21. The correct sequence of creep deformation in a creep curve in order of their elongation is: [IES-2001]
(a) Steady state, transient, accelerated  (b) Transient, steady state, accelerated
(c) Transient, accelerated, steady state  (d) Accelerated, steady state, transient
IES-21. Ans. (b)

IES-22. The highest stress that a material can withstand for a specified length of time without excessive deformation is called [IES-1997]
(a) Fatigue strength  (b) Endurance strength  (c) Creep strength  (d) Creep rupture strength
IES-22. Ans. (c)

IES-23. Which one of the following features improves the fatigue strength of a metallic material? [IES-2000]
(a) Increasing the temperature  (b) Scratching the surface  (c) Overstressing  (d) Under stressing
IES-23. Ans. (d)

IES-24. Consider the following statements: [IES-1993]
For increasing the fatigue strength of welded joints it is necessary to employ
Of the above statements
(a) 1 and 2 are correct  (b) 2 and 3 are correct  (c) 1 and 3 are correct  (d) 1, 2 and 3 are correct
IES-24. Ans. (c) A polished surface by grinding can take more number of cycles than a part with rough surface. In Hammer peening residual compressive stress lower the peak tensile stress

Relation between the Elastic Modulii

IES-25. For a linearly elastic, isotropic and homogeneous material, the number of elastic constants required to relate stress and strain is: [IAS 1994; IES-1998]
(a) Two  (b) Three  (c) Four  (d) Six
IES-25. Ans. (a)

IES-26. E, G, K and μ represent the elastic modulus, shear modulus, bulk modulus and Poisson’s ratio respectively of a linearly elastic, isotropic and homogeneous material. To express the stress-strain relations completely for this material, at least [IES-2006]
(a) E, G and μ must be known  (b) E, K and μ must be known
(c) Any two of the four must be known  (d) All the four must be known
IES-26. Ans. (c)

IES-27. The number of elastic constants for a completely anisotropic elastic material which follows Hooke’s law is: [IES-1999]
(a) 3  (b) 4  (c) 21  (d) 25
IES-27. Ans. (c)

IES-28. What are the materials which show direction dependent properties, called? [IES 2007]
(a) Homogeneous materials  (b) Viscoelastic materials
(c) Isotropic materials  (d) Anisotropic materials
IES-28. Ans. (d)

IES-29. An orthotropic material, under plane stress condition will have: [IES-2006]
IES-29. Ans. (d)

IES-30. Match List-I (Properties) with List-II (Units) and select the correct answer using the codes given below the lists: [IES-2001]

<table>
<thead>
<tr>
<th>List I</th>
<th>List II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Dynamic viscosity</td>
<td>1. Pa</td>
</tr>
<tr>
<td>B. Kinematic viscosity</td>
<td>2. m²/s</td>
</tr>
<tr>
<td>C. Torsional stiffness</td>
<td>3. Ns/m²</td>
</tr>
<tr>
<td>D. Modulus of rigidity</td>
<td>4. N/m</td>
</tr>
</tbody>
</table>

Codes: A B C D  A B C D  A B C D
(a) 3 2 4 1  (b) 5 2 4 3  (c) 3 4 2 3

IES-30. Ans. (a)

IES-31. Young's modulus of elasticity and Poisson's ratio of a material are $1.25 \times 10^5$ MPa and 0.34 respectively. The modulus of rigidity of the material is: [IAS 1994, IES-1995, 2001, 2002, 2007]

(a) $0.4025 \times 10^5$ Mpa  
(b) $0.4664 \times 10^5$ Mpa  
(c) $0.8375 \times 10^5$ Mpa  
(d) $0.9469 \times 10^5$ Mpa

IES-31. Ans. (b)

$$E = 2G(1+\mu) \text{ or } 1.25 \times 10^5 = 2G(1+0.34) \text{ or } G = 0.4664 \times 10^5 \text{ MPa}$$

IES-32. In a homogenous, isotropic elastic material, the modulus of elasticity $E$ in terms of $G$ and $K$ is equal to [IAS-1995, IES - 1992]

(a) $G + 3K$  
(b) $\frac{3G + K}{9K}$  
(c) $\frac{9KG}{G + 3K}$  
(d) $\frac{9KG}{K + 3G}$

IES-32. Ans. (c)

IES-33. What is the relationship between the linear elastic properties Young's modulus $(E)$, rigidity modulus $(G)$ and bulk modulus $(K)$? [IES-2008]

(a) $\frac{1}{E} = \frac{9}{K} + \frac{3}{G}$  
(b) $\frac{3}{E} = \frac{9}{K} + \frac{1}{G}$  
(c) $\frac{9}{E} = \frac{3}{K} + \frac{1}{G}$  
(d) $\frac{9}{E} = \frac{1}{K} + \frac{3}{G}$

IES-33. Ans. (d)

$$E = 2G(1+\mu) = 3K(1-2\mu) = \frac{9KG}{3K + G}$$

IES-34. What is the relationship between the linear elastic properties Young's modulus $(E)$, rigidity modulus $(G)$ and bulk modulus $(K)$? [IES-2009]

(a) $E = \frac{KG}{9K + G}$  
(b) $E = \frac{9KG}{K + 3G}$  
(c) $E = \frac{9KG}{K + 3G}$  
(d) $E = \frac{9KG}{3K + G}$

IES-34. Ans. (d)

$$E = 2G(1+\mu) = 3K(1-2\mu) = \frac{9KG}{3K + G}$$

IES-35. If $E$, $G$ and $K$ denote Young's modulus, Modulus of rigidity and Bulk Modulus, respectively, for an elastic material, then which one of the following can be possibly true? [IES-2005]

(a) $G = 2K$  
(b) $G = E$  
(c) $K = E$  
(d) $G = K = E$

IES-35. Ans.(c)

$$E = 2G(1+\mu) = 3K(1-2\mu) = \frac{9KG}{3K + G}$$

the value of $\mu$ must be between 0 to 0.5 so $E$ never equal to $G$ but if $\mu = \frac{1}{3}$ then $E = k$ so ans. is c

IES-36. If a material had a modulus of elasticity of $2.1 \times 10^6$ kgf/cm² and a modulus of rigidity of $0.8 \times 10^6$ kgf/cm²² then the approximate value of the Poisson's ratio of the material would be: [IES-1993]

(a) 0.26  
(b) 0.31  
(c) 0.47  
(d) 0.5
IES-36. Ans. (b) Use \( E = 2G(1 + \mu) \)

IES-37. The modulus of elasticity for a material is 200 GN/m² and Poisson’s ratio is 0.25. What is the modulus of rigidity? \([\text{IES-2004}]\)

(a) 80 GN/m²  
(b) 125 GN/m²  
(c) 250 GN/m²  
(d) 320 GN/m²

IES-37. Ans. (a) \( E = 2G(1 + \mu) \) or \( G = \frac{E}{2(1 + \mu)} = \frac{200}{2 \times (1 + 0.25)} = 80 \text{ GN/m}^2 \)

IES-38. Consider the following statements: \([\text{IES-2009}]\)

1. Two-dimensional stresses applied to a thin plate in its own plane represent the plane stress condition.
2. Under plane stress condition, the strain in the direction perpendicular to the plane is zero.
3. Normal and shear stresses may occur simultaneously on a plane.

Which of the above statements is/are correct?

(a) 1 only  
(b) 1 and 2  
(c) 2 and 3  
(d) 1 and 3

IES-38. Ans. (d) Under plane stress condition, the strain in the direction perpendicular to the plane is not zero. It has been found experimentally that when a body is stressed within elastic limit, the lateral strain bears a constant ratio to the linear strain. \([\text{IES-2009}]\)

Stresses in compound strut

IES-39. Eight bolts are to be selected for fixing the cover plate of a cylinder subjected to a maximum load of 980·175 kN. If the design stress for the bolt material is 315 N/mm², what is the diameter of each bolt? \([\text{IES-2008}]\)

(a) 10 mm  
(b) 22 mm  
(c) 30 mm  
(d) 36 mm

IES-39. Ans. (b) Total load \( P = 8 \times \sigma \times \frac{\pi d^2}{4} \) or \( d = \sqrt{\frac{P}{2\pi \sigma}} = \sqrt{\frac{980175}{2\pi \times 315}} = 22.25 \text{ mm} \)

IES-40. For a composite consisting of a bar enclosed inside a tube of another material when compressed under a load ‘w’ as a whole through rigid collars at the end of the bar. The equation of compatibility is given by (suffixes 1 and 2) refer to bar and tube respectively \([\text{IES-1998}]\)

\( W_1 + W_2 = W \)  
(\( b \)) \( W_1 + W_2 = \text{Const.} \)  
(\( c \)) \( \frac{W_1}{A_1E_1} = \frac{W_2}{A_2E_2} \)  
(\( d \)) \( \frac{W_1}{A_1E_1} = \frac{W_2}{A_2E_2} \)

IES-40. Ans. (c) Compatibility equation insists that the change in length of the bar must be compatible with the boundary conditions. Here (a) is also correct but it is equilibrium equation.

IES-41. When a composite unit consisting of a steel rod surrounded by a cast iron tube is subjected to an axial load. \([\text{IES-2000}]\)

Assertion (A): The ratio of normal stresses induced in both the materials is equal to the ratio of Young’s moduli of respective materials.

Reason (R): The composite unit of these two materials is firmly fastened together at the ends to ensure equal deformation in both the materials.

(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is not the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true

IES-41. Ans. (a)

IES-42. The figure below shows a steel rod of 25 mm² cross sectional area. It is loaded at four points, K, L, M and N. \([\text{GATE-2004, IES 1995, 1997, 1998}]\)
Assume $E_{\text{steel}} = 200$ GPa. The total change in length of the rod due to loading is (a) 1 μm (b) -10 μm (c) 16 μm (d) -20 μm

IES-42. Ans. (b) First draw FBD of all parts separately then

Total change in length = \[
\sum \frac{PL}{AE}
\]

IES-43. The reactions at the rigid supports at A and B for the bar loaded as shown in the figure are respectively.
(a) 20/3 kN, 10/3 kN
(b) 10/3 kN, 20/3 kN
(c) 5 kN, 5 kN
(d) 6 kN, 4 kN

IES-43. Ans. (a) Elongation in AC = length reduction in CB

\[
\frac{R_A \times 1}{AE} = \frac{R_B \times 2}{AE}
\]

And $R_A + R_B = 10$

IES-44. Which one of the following is correct?

When a nut is tightened by placing a washer below it, the bolt will be subjected to
(a) Compression only  (b) Tension  (c) Shear only  (d) Compression and shear

IES-44. Ans. (b)

IES-45. Which of the following stresses are associated with the tightening of nut on a bolt?  
1. Tensile stress due to the stretching of bolt
2. Bending stress due to the bending of bolt
3. Crushing and shear stresses in threads
4. Torsional shear stress due to frictional resistance between the nut and the bolt.

Select the correct answer using the codes given below
Codes:  (a) 1, 2 and 4 (b) 1, 2 and 3 (c) 2, 3 and 4 (d) 1, 3 and 4

IES-45. Ans. (d)

**Thermal effect**

IES-46. A 100 mm × 5 mm × 5 mm steel bar free to expand is heated from 15°C to 40°C. What shall be developed?  
(a) Tensile stress  (b) Compressive stress  (c) Shear stress  (d) No stress

IES-46. Ans. (d) If we resist to expand then only stress will develop.

IES-47. Which one of the following statements is correct?  
If a material expands freely due to heating, it will develop
IES-47. Ans. (d)

IES-48. A cube having each side of length a, is constrained in all directions and is heated uniformly so that the temperature is raised to T°C. If α is the thermal coefficient of expansion of the cube material and E the modulus of elasticity, the stress developed in the cube is:

\[
\frac{\alpha TE}{\gamma} \quad \frac{\alpha TE}{(1-2\gamma)} \quad \frac{\alpha TE}{2\gamma} \quad \frac{\alpha TE}{(1+2\gamma)}
\]

IES-48. Ans. (b)

IES-49. Consider the following statements:

Thermal stress is induced in a component in general, when
1. A temperature gradient exists in the component
2. The component is free from any restraint
3. It is restrained to expand or contract freely

Which of the above statements are correct?
(a) 1 and 2    (b) 2 and 3  (c) 3 alone   (d) 2 alone

IES-49. Ans. (c)

IES-50. A steel rod 10 mm in diameter and 1m long is heated from 20°C to 120°C, E = 200 GPa and α = 12 × 10^{-6} per °C. If the rod is not free to expand, the thermal stress developed is:

(a) 120 MPa (tensile)     (b) 240 MPa (tensile)  
(c) 120 MPa (compressive)    (d) 240 MPa (compressive)

IES-50. Ans. (d)

\[\sigma = 3\alpha T\]

IES-51. A cube with a side length of 1 cm is heated uniformly 1° C above the room temperature and all the sides are free to expand. What will be the increase in volume of the cube? (Given coefficient of thermal expansion is α per °C)

(a) 3 cm³  (b) 2 cm³  (c) a cm³  (d) zero

IES-51. Ans. (a)

IES-52. A bar of copper and steel form a composite system. They are heated to a temperature of 40 °C. What type of stress is induced in the copper bar?

(a) Tensile    (b) Compressive  (c) Both tensile and compressive   (d) Shear

IES-52. Ans. (b)

IES-53. α=12.5×10^{-6}/°C,  E = 200GPa If the rod fitted strongly between the supports as shown in the figure, is heated, the stress induced in it due to 20°C rise in temperature will be:

(a) 0.07945 MPa     (b) -0.07945 MPa  
(c) -0.03972 MPa    (d) 0.03972 MPa

IES-53. Ans. (d)
IES-53. Ans. (b) Let compression of the spring = \( x \) m
Therefore spring force = \( kx \) kN
Expansion of the rod due to temperature rise = \( L\alpha\Delta t \)

Reduction in the length due to compression force = \( \frac{(kx) \times L}{AE} \)

Now \( L\alpha\Delta t = \frac{(kx) \times L}{AE} = x \)

Or \( x = \frac{0.5 \times 12.5 \times 10^{-6} \times 20}{1 + \frac{50 \times 0.5}{\pi \times 0.010^2 \times 200 \times 10^6}} = 0.125 \text{mm} \)

\( \therefore \) Compressive stress = \( \frac{kx}{A} = \frac{50 \times 0.125}{\frac{\pi \times 0.010^2}{4}} = -0.07945 \text{MPa} \)

IES-54. The temperature stress is a function of [IES-1992]
The correct answer is:
(a) 1 and 2 only  (b) 1 and 3 only  (c) 2 and 3 only  (d) 1, 2 and 3

IES-54. Ans. (d) Stress in the rod due to temperature rise = \( (\alpha\Delta t) \times E \)

Impact loading

IES-55. Assertion (A): Ductile materials generally absorb more impact loading than a brittle material [IES-2004]
Reason (R): Ductile materials generally have higher ultimate strength than brittle materials
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is not the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-55. Ans. (c)

IES-56. Assertion (A): Specimens for impact testing are never notched. [IES-1999]
Reason (R): A notch introduces tri-axial tensile stresses which cause brittle fracture.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-56. Ans. (d) A is false but R is correct.
Chapter-1 Stress and Strain S K Mondal’s

Tensile Test

IES-57. During tensile-testing of a specimen using a Universal Testing Machine, the parameters actually measured include [IES-1996] (a) True stress and true strain (b) Poisson’s ratio and Young’s modulus (c) Engineering stress and engineering strain (d) Load and elongation

IES-57. Ans. (d)

IES-58. In a tensile test, near the elastic limit zone [IES-2006] (a) Tensile stress increases at a faster rate (b) Tensile stress decreases at a faster rate (c) Tensile stress increases in linear proportion to the stress (d) Tensile stress decreases in linear proportion to the stress

IES-58. Ans. (b)

IES-59. Match List-I (Types of Tests and Materials) with List-II (Types of Fractures) and select the correct answer using the codes given below the lists:

List-I (Types of Tests and Materials) List-II (Types of Fractures) [IES-2002; IAS-2004]
A. Tensile test on CI 1. Plain fracture on a transverse plane
B. Torsion test on MS 2. Granular helecoidal fracture
C. Tensile test on MS 3. Plain granular at 45° to the axis
D. Torsion test on CI 4. Cup and Cone
5. Granular fracture on a transverse plane

Codes:
(a) 4 2 3 1 (c) 4 1 3 2
(b) 5 1 4 2 (d) 5 2 4 1

IES-59. Ans. (d)

IES-60. Which of the following materials generally exhibits a yield point? [IES-2003] (a) Cast iron (b) Annealed and hot-rolled mild steel (c) Soft brass (d) Cold-rolled steel

IES-60. Ans. (b)

IES-61. For most brittle materials, the ultimate strength in compression is much large then the ultimate strength in tension. The is mainly due to [IES-1992] (a) Presence of flaws and microscopic cracks or cavities (b) Necking in tension (c) Severity of tensile stress as compared to compressive stress (d) Non-linearity of stress-strain diagram

IES-61. Ans. (a)

IES-62. What is the safe static tensile load for a M36 × 4C bolt of mild steel having yield stress of 280 MPa and a factor of safety 1.5? [IES-2005] (a) 285 kN (b) 190 kN (c) 142.5 kN (d) 95 kN

IES-62. Ans. (b) \( \sigma_c = \frac{W}{\pi d^2} \) or \( W = \sigma_c \times \frac{\pi d^2}{4} \);

\[
W_{safe} = \frac{W}{f_0s} = \frac{\sigma_c \times \pi \times d^2}{f_0s \times 4} = \frac{280 \times \pi \times 36^2}{1.5 \times 4}N = 190kN
\]

IES-63. Which one of the following properties is more sensitive to increase in strain rate? [IES-2000] (a) Yield strength (b) Proportional limit (c) Elastic limit (d) Tensile strength

IES-63. Ans. (b)
A steel hub of 100 mm internal diameter and uniform thickness of 10 mm was heated to a temperature of 300°C to shrink-fit it on a shaft. On cooling, a crack developed parallel to the direction of the length of the hub. Consider the following factors in this regard:

1. Tensile hoop stress
2. Tensile radial stress
3. Compressive hoop stress
4. Compressive radial stress

The cause of failure is attributable to

(a) 1 alone   (b) 1 and 3   (c) 1, 2 and 4   (d) 2, 3 and 4

IES-64. Ans. (a) A crack parallel to the direction of length of hub means the failure was due to tensile hoop stress only.

If failure in shear along 45° planes is to be avoided, then a material subjected to uniaxial tension should have its shear strength equal to at least

(a) Tensile strength (b) Compressive strength (c) Half the difference between the tensile and compressive strengths. (d) Half the tensile strength.

IES-65. Ans. (d)

Select the proper sequence


(a) 2, 3, 1, 4   (b) 2, 1, 3, 4   (c) 1, 3, 2, 4   (d) 1, 2, 3, 4

IES-66. Ans. (d)

Stress in a bar due to self-weight

A heavy uniform rod of length ‘L’ and material density ‘g’ is hung vertically with its top end rigidly fixed. How is the total elongation of the bar under its own weight expressed?

(a) \( \frac{2\delta L^2 g}{E} \)   (b) \( \frac{\delta L^2 g}{E} \)   (c) \( \frac{\delta L^2 g}{\sqrt{2E}} \)   (d) \( \frac{\delta L^2 g}{2E} \)

IAS-1. Ans. (d) Elongation due to self weight = \( \frac{WL}{2AE} = \frac{(\delta ALg)L}{2AE} = \frac{\delta L^2 g}{2E} \)

A rod of length ‘l’ and cross-section area ‘A’ rotates about an axis passing through one end of the rod. The extension produced in the rod due to centrifugal forces is (w is the weight of the rod per unit length and \( \omega \) is the angular velocity of rotation of the rod).

(a) \( \frac{\omega nw^2 l^2}{gE} \)   (b) \( \frac{\omega^2 wl^3}{3gE} \)   (c) \( \frac{\omega^2 wl^3}{gE} \)   (d) \( \frac{3gE}{\omega^2 wl^3} \)

IAS-2. Ans. (b)
Elongation of a Taper Rod
IAS-3. A rod of length, "l" tapers uniformly from a diameter "D₁" to a diameter "D₂" and carries an axial tensile load of "P". The extension of the rod is \( \frac{P}{4\pi E D D_2} \) \( \frac{E D D_2}{\pi} \). \[ \text{IAS-1996} \]
(a) \( \frac{4\pi P L}{\pi E D D_2} \)  
(b) \( \frac{4\pi P L}{\pi D D_2} \)  
(c) \( \frac{\pi E P L}{4D_1 D_2} \)  
(d) \( \frac{\pi P L}{4E D_1 D_2} \)
IAS-3. Ans. (a) The extension of the taper rod = \( \frac{P}{4\pi D_2} \).

Poisson’s ratio
IAS-4. In the case of an engineering material under unidirectional stress in the x-direction, the Poisson's ratio is equal to (symbols have the usual meanings) \[ \text{IAS 1994, IES-2000} \]
(a) \( \frac{\varepsilon_x}{\varepsilon_x} \)  
(b) \( \frac{\varepsilon_y}{\sigma_y} \)  
(c) \( \frac{\sigma_x}{\sigma_y} \)  
(d) \( \frac{\sigma_y}{\varepsilon_x} \)
IAS-4. Ans. (a)

IAS-5. Assertion (A): Poisson’s ratio of a material is a measure of its ductility.
Reason (R): For every linear strain in the direction of force, Poisson's ratio of the material gives the lateral strain in directions perpendicular to the direction of force. \[ \text{IAS-1999} \]
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is not the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IAS-5. Ans. (d)

IAS-6. Assertion (A): Poisson’s ratio is a measure of the lateral strain in all direction perpendicular to and in terms of the linear strain. \[ \text{IAS-1997} \]
Reason (R): The nature of lateral strain in a uni-axially loaded bar is opposite to that of the linear strain.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is not the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IAS-6. Ans. (b)

Elasticity and Plasticity
IAS-7. A weight falls on a plunger fitted in a container filled with oil thereby producing a pressure of 1.5 N/mm² in the oil. The Bulk Modulus of oil is 2800 N/mm². Given this situation, the volumetric compressive strain produced in the oil will be:
(a) \( 400 \times 10^{-6} \)  
(b) \( 800 \times 10^{6} \)  
(c) \( 268 \times 10^{6} \)  
(d) \( 535 \times 10^{-6} \)
IAS-7. Ans. (d) Bulk modulus of elasticity \( (K) = \frac{P}{\varepsilon_y} \) or \( \varepsilon_y = \frac{P}{K} = \frac{1.5}{2800} = 535 \times 10^{-6} \)

Relation between the Elastic Modulii
IAS-8. For a linearly elastic, isotropic and homogeneous material, the number of elastic constants required to relate stress and strain is:
(a) Two  
(b) Three  
(c) Four  
(d) Six
IAS-8. Ans. (a)
The independent elastic constants for a homogenous and isotropic material are
(a) E, G, K, v (b) E, G, K (c) E, G, v (d) E, G [IAS-1995]

IAS-9. Ans. (d)

The unit of elastic modulus is the same as those of [IAS 1994]
(a) Stress, shear modulus and pressure (b) Strain, shear modulus and force
(c) Shear modulus, stress and force (d) Stress, strain and pressure.

IAS-10. Ans. (a)

Young's modulus of elasticity and Poisson's ratio of a material are \(1.25 \times 10^5\) MPa and 0.34 respectively. The modulus of rigidity of the material is:

IAS-11. Ans. (b) \(E = 2G(1 + \mu)\) or \(1.25 \times 10^5 = 2G(1+0.34)\) or \(G = 0.4664 \times 10^5\) MPa

Young's modulus of elasticity and Poisson's ratio of a material are 1.25 \(\times 10^5\) MPa and 0.34 respectively. The modulus of rigidity of the material is:

IAS-11. Ans. (a)

\( \mu = \frac{E}{2G} = \frac{3k (1-2\mu)}{2G} \) or \(0.25 = \frac{3k (1-2\mu)}{2G} \)

The Young's modulus of elasticity of a material is 2.5 times its modulus of rigidity. The Poisson's ratio for the material will be:

IAS-12. Ans. (a) \(E = 2G(1+\mu)\) \(\Rightarrow 1+\mu = \frac{E}{2G}\) \(\Rightarrow \mu = \frac{E}{2G} - 1 = \left( \frac{2.5}{2} - 1 \right) = 0.25\)

In a homogenous, isotropic elastic material, the modulus of elasticity in terms of G and K is equal to

IAS-13. Ans. (c)

\( \frac{G+3K}{9K} \) or \( \frac{3G+K}{9K} \) or \( \frac{G+3K}{9K} \) or \( \frac{3G+K}{9K} \)

The Elastic Constants E and K are related as \((\mu = \text{the Poisson’s ratio})\) [IAS-1996]

IAS-14. Ans. (b) \(E = 2G(1 + \mu) = 3k (1-2\mu)\)

For an isotropic, homogeneous and linearly elastic material, which obeys Hooke’s law, the number of independent elastic constant is:

IAS-15. Ans. (b)

(a) 1 (b) 2 (c) 3 (d) 6

\(E = 2G(1 + \mu) = 3K (1-3\mu) = \frac{9KG}{3K + G}\)

\(E = \frac{2G(1+\mu)}{3K (1-3\mu)}\)

The moduli of elasticity and rigidity of a material are 200 GPa and 80 GPa, respectively. What is the value of the Poisson's ratio of the material? [IAS-2007]

IAS-16. Ans. (c) \(E = 2G(1+\mu)\) or \(\mu = \frac{E}{2G} - 1 = \frac{200}{2 \times 80} - 1 = 0.25\)

Stresses in compound strut

IAS-17. The reactions at the rigid supports at A and B for the bar loaded as shown in the figure are respectively.

IAS-17. Ans. (d) 20/3 kN, 10/3 kN (b) 10/3 kN, 20/3 kN (c) 5 kN, 5 kN (d) 6 kN, 4 kN
IAS-17. Ans. (a) Elongation in $AC = \text{length reduction in } CB$

$$\frac{R_A \times 1}{AE} = \frac{R_B \times 2}{AE}$$

And $R_A + R_B = 10$

Thermal effect

IAS-18. A steel rod 10 mm in diameter and 1m long is heated from 20°C to 120°C, $E = 200$ GPa and $\alpha = 12 \times 10^{-6}$ per °C. If the rod is not free to expand, the thermal stress developed is: [IAS-2003, IES-1997, 2000, 2006]

(a) 120 MPa (tensile)    (b) 240 MPa (tensile)
(c) 120 MPa (compressive) (d) 240 MPa (compressive)

IAS-18. Ans. (d) $63E t 12 10 200 10 120 20 240MPa$

It will be compressive as elongation restricted.

IAS-19. A steel rod of diameter 1 cm and 1 m long is heated from 20°C to 120°C. Its $\alpha = 12 \times 10^{-6} / K$ and $E=200$ GN/m². If the rod is free to expand, the thermal stress developed in it is: [IAS-2002]

(a) $12 \times 10^4$ N/m² (b) 240 kN/m² (c) zero (d) infinity

IAS-19. Ans. (c) Thermal stress will develop only if expansion is restricted.

IAS-20. Which one of the following pairs is NOT correctly matched? [IAS-1999]

(E = Young's modulus, $\alpha = \text{Coefficient of linear expansion, } T = \text{Temperature rise, } A = \text{Area of cross-section, } l= \text{Original length})$

(a) Temperature strain with permitted expansion $\delta$ ..... $(\alpha Tl - \delta)$
(b) Temperature stress ..... $\alpha TE$
(c) Temperature thrust ..... $\alpha TEA$
(d) Temperature stress with permitted expansion ..... $E(\alpha Tl - \delta)$

IAS-20. Ans. (a) Dimensional analysis gives (a) is wrong

Impact loading

IAS-21. Match List I with List II and select the correct answer using the codes given below the lists: [IAS-1995]

<table>
<thead>
<tr>
<th>List I (Property)</th>
<th>List II (Testing Machine)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Tensile strength</td>
<td>1. Rotating Bending Machine</td>
</tr>
<tr>
<td>B. Impact strength</td>
<td>2. Three-Point Loading Machine</td>
</tr>
<tr>
<td>C. Bending strength</td>
<td>3. Universal Testing Machine</td>
</tr>
<tr>
<td>D. Fatigue strength</td>
<td>4. Izod Testing Machine</td>
</tr>
</tbody>
</table>

Codes: A B C D
(a) 4 3 2 1
(b) 3 2 1 4
(c) 2 1 4 3
(d) 3 4 2 1

IAS-21. Ans. (d)
A mild steel specimen is tested in tension up to fracture in a Universal Testing Machine. Which of the following mechanical properties of the material can be evaluated from such a test? [IAS-2007]

1. Modulus of elasticity  
2. Yield stress  
3. Ductility  
4. Tensile strength  
5. Modulus of rigidity  
Select the correct answer using the code given below:
(a) 1, 3, 5 and 6  
(b) 2, 3, 4 and 6  
(c) 1, 2, 5 and 6  
(d) 1, 2, 3 and 4

IAS-22. Ans. (d)

In a simple tension test, Hooke's law is valid upto the [IAS-1998]
(a) Elastic limit  
(b) Limit of proportionality  
(c) Ultimate stress  
(d) Breaking point  
IAS-23. Ans. (b)

Lueder' lines on steel specimen under simple tension test is a direct indication of yielding of material due to slip along the plane [IAS-1997]
(a) Of maximum principal stress  
(b) Off maximum shear  
(c) Of loading  
(d) Perpendicular to the direction of loading  
IAS-24. Ans. (b)

The percentage elongation of a material as obtained from static tension test depends upon the [IAS-1998]
(a) Diameter of the test specimen  
(b) Gauge length of the specimen  
(c) Nature of end-grips of the testing machine  
(d) Geometry of the test specimen  
IAS-25. Ans. (b)

Match List-I (Types of Tests and Materials) with List-II (Types of Fractures) and select the correct answer using the codes given below the lists:

<table>
<thead>
<tr>
<th>List-I (Types of Tests and Materials)</th>
<th>List-II (Types of Fractures)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Tensile test on CI</td>
<td>1. Plain fracture on a transverse plane</td>
</tr>
<tr>
<td>B. Torsion test on MS</td>
<td>2. Granular helecoidal fracture</td>
</tr>
<tr>
<td>C. Tensile test on MS</td>
<td>3. Plain granular at 45° to the axis</td>
</tr>
<tr>
<td>D. Torsion test on CI</td>
<td>4. Cup and Cone</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Codes:</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>A</th>
<th>B</th>
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<th>D</th>
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<tbody>
<tr>
<td>(a)</td>
<td>4</td>
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<td>3</td>
<td>1</td>
<td>(c)</td>
<td>4</td>
<td>1</td>
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<tr>
<td>(b)</td>
<td>5</td>
<td>1</td>
<td>4</td>
<td>2</td>
<td>(d)</td>
<td>5</td>
<td>2</td>
<td>4</td>
</tr>
</tbody>
</table>

IAS-26. Ans. (d)

Assertion (A): For a ductile material stress-strain curve is a straight line up to the yield point. [IAS-2003]
Reason (R): The material follows Hooke's law up to the point of proportionality.
(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is not the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true  
IAS-27. Ans. (d)

Assertion (A): Stress-strain curves for brittle material do not exhibit yield point. [IAS-1996]
Reason (R): Brittle materials fail without yielding.
(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true  
IAS-28. Ans. (a) Up to elastic limit.
Match List I (Materials) with List II (Stress-Strain curves) and select the correct answer using the codes given below the Lists:

List I

A. Mild Steel
B. Pure Copper
C. Cast Iron
D. Pure Aluminium

List II

1. 
2. 
3. 
4. 

Codes:  
A B C D  A B C D 
(a) 3 1 4 1  (b) 3 2 4 2  
(c) 2 4 3 1  (d) 4 1 3 2 

IAS-29. Ans. (b)

The stress-strain curve of an ideal elastic strain hardening material will be as

IAS-30. Ans. (d)

An idealised stress-strain curve for a perfectly plastic material is given by

IAS-31. Ans. (a)

Match List I with List II and select the correct answer using the codes given below the Lists:

List I

A. Ultimate strength

List II

1. Internal structure
Chapter-1  Stress and Strain  S K Mondal’s

2. Change of length per unit instantaneous length
3. Change of length per unit gauge length
4. Load per unit area

<table>
<thead>
<tr>
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<td>(d)</td>
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IAS-32. Ans. (a)

IAS-33. What is the cause of failure of a short MS strut under an axial load? [IAS-2007]
(a) Fracture stress  (b) Shear stress  (c) Buckling  (d) Yielding
IAS-33. Ans. (d)
In compression tests of ductile materials fractures is seldom obtained. Compression is accompanied by lateral expansion and a compressed cylinder ultimately assumes the shape of a flat disc.

IAS-34. Match List I with List II and select the correct answer using the codes given the lists:

List I
A. Rigid-Perfectly plastic
B. Elastic-Perfectly plastic
C. Rigid-Strain hardening
D. Linearly elastic

List II
1. \[ \sigma \rightarrow \varepsilon \]
2. \[ \sigma \rightarrow \varepsilon \]
3. \[ \sigma \rightarrow \varepsilon \]
4. \[ \sigma \rightarrow \varepsilon \]

Codes: 
<table>
<thead>
<tr>
<th></th>
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<tr>
<td>(d)</td>
<td>1</td>
<td>3</td>
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<td>2</td>
</tr>
</tbody>
</table>

IAS-34. Ans. (a)

IAS-35. Which one of the following materials is highly elastic? [IAS-1995]
(a) Rubber  (b) Brass  (c) Steel  (d) Glass
IAS-35. Ans. (c)
Steel is the highly elastic material because it is deformed least on loading, and regains its original from on removal of the load.

IAS-36. Assertion (A): Hooke’s law is the constitutive law for a linear elastic material.
Reason (R) Formulation of the theory of elasticity requires the hypothesis that there exists a unique unstressed state of the body, to which the body returns whenever all the forces are removed. [IAS-2002]
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is not the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IAS-36. Ans. (a)

IAS-37. Consider the following statements [IAS-2002]
1. There are only two independent elastic constants.
2. Elastic constants are different in orthogonal directions.
3. Material properties are same everywhere.
4. Elastic constants are same in all loading directions.
5. The material has ability to withstand shock loading.

Which of the above statements are true for a linearly elastic, homogeneous and isotropic material?
(a) 1, 3, 4 and 5  (b) 2, 3 and 4  (c) 1, 3 and 4  (d) 2 and 5

IAS-37. Ans. (a)

IAS-38. Which one of the following pairs is NOT correctly matched? [IAS-1999]
(a) Uniformly distributed stress .... Force passed through the centroid of the cross-section
(b) Elastic deformation .... Work done by external forces during deformation is dissipated fully as heat
(c) Potential energy of strain .... Body is in a state of elastic deformation
(d) Hooke's law .... Relation between stress and strain

IAS-38. Ans. (b)

IAS-39. A tensile bar is stressed to 250 N/mm² which is beyond its elastic limit. At this stage the strain produced in the bar is observed to be 0.0014. If the modulus of elasticity of the material of the bar is 205000 N/mm² then the elastic component of the strain is very close to [IAS-1997]
(a) 0.0004  (b) 0.0002  (c) 0.0001  (d) 0.00005

IAS-39. Ans. (b)
Conventional Question IES-2010

Q. If a load of 60 kN is applied to a rigid bar suspended by 3 wires as shown in the above figure what force will be resisted by each wire?

The outside wires are of Al, cross-sectional area 300 mm$^2$ and length 4 m. The central wire is steel with area 200 mm$^2$ and length 8 m. Initially there is no slack in the wires $E_{al} = 2 \times 10^5$ N/mm$^2$ for Steel $= 0.667 \times 10^5$ N/mm$^2$ for Aluminum

Ans.

\[ P = 60 \text{ kN} \]
\[ a_{al} = 300 \text{ mm}^2 \quad l_{al} = 4 \text{ m} \]
\[ a_{st} = 200 \text{ mm}^2 \quad l_{st} = 8 \text{ m} \]
\[ E_{al} = 0.667 \times 10^5 \text{ N/mm}^2 \]
\[ E_{st} = 2 \times 10^5 \text{ N/mm}^2 \]

Force balance along vertical direction
\[ 2F_{al} + F_{st} = 60 \text{ kN} \quad (1) \]

Elongation will be same in all wires because rod is rigid remain horizontal after loading

\[ \frac{F_{al} \times l_{al}}{a_{al} \cdot E_{al}} = \frac{F_{st} \cdot l_{st}}{a_{st} \cdot E_{st}} \quad (2) \]
\[ \frac{F_{al} \times 4}{300 \times 0.667 \times 10^5} = \frac{F_{st} \times 8}{200 \times 2 \times 10^5} \]
\[ F_{al} = 1.0005 F_{st} \quad (3) \]
From equation (1) \[ F_{st} = \frac{60 \times 10^3}{3.001} = 19.99 \text{ kN or } 20 \text{ kN} \]

\[ F_{A1} = 20 \text{ kN} \]

\[ F_{st} = 20 \text{ kN} \]

\[ \text{Answer.} \]

**Conventional Question GATE**

**Question:** The diameters of the brass and steel segments of the axially loaded bar shown in figure are 30 mm and 12 mm respectively. The diameter of the hollow section of the brass segment is 20 mm.

**Determine:** (i) The maximum normal stress in the steel and brass (ii) The displacement of the free end; Take \( E_s = 210 \text{ GPa} \) and \( E_b = 105 \text{ GPa} \)

\[ A_s = \frac{\pi}{4} \times (12)^2 = 36\pi \text{ mm}^2 = 36\pi \times 10^{-6} \text{ m}^2 \]

\[ (A_b)_{BC} = \frac{\pi}{4} \times (30)^2 = 225\pi \text{ mm}^2 = 225\pi \times 10^{-6} \text{ m}^2 \]

\[ (A_b)_{CD} = \frac{\pi}{4} \times (30^2 - 20^2) = 125\pi \text{ mm}^2 = 125\pi \times 10^{-6} \text{ m}^2 \]

(i) The maximum normal stress in steel and brass:

\[ \sigma_s = \frac{10 \times 10^3}{36\pi \times 10^{-6}} \times 10^{-6} \text{ MN/m}^2 = 88.42 \text{ MN/m}^2 \]

\[ (\sigma_b)_{BC} = \frac{5 \times 10^3}{225\pi \times 10^{-6}} \times 10^{-6} \text{ MN/m}^2 = 7.07 \text{ MN/m}^2 \]

\[ (\sigma_b)_{CD} = \frac{5 \times 10^3}{125\pi \times 10^{-6}} \times 10^{-6} \text{ MN/m}^2 = 12.73 \text{ MN/m}^2 \]

(ii) The displacement of the free end:

\[ \Delta = (\Delta s)_{AB} + (\Delta b)_{BC} + (\Delta b)_{CD} \]

\[ = \frac{88.42 \times 0.15}{210 \times 10^6 \times 10^{-6}} + \frac{7.07 \times 0.2}{105 \times 10^6 \times 10^{-6}} + \frac{12.73 \times 0.125}{105 \times 10^6 \times 10^{-6}} \]

\[ = 9.178 \times 10^{-5} \text{ m} = 0.09178 \text{ mm} \]

**Conventional Question IES-1999**

**Question:** Distinguish between fatigue strength and fatigue limit.

**Answer:** Fatigue strength as the value of cyclic stress at which failure occurs after \( N \) cycles. And fatigue limit as the limiting value of stress at which failure occurs as \( N \) becomes very large (sometimes called infinite cycle)
Chapter-1 Stress and Strain  

**Question:** List at least two factors that promote transition from ductile to brittle fracture.

**Answer:**
1. With the grooved specimens only a small reduction in area took place, and the appearance of the fracture was like that of brittle materials.
2. By internal cavities, thermal stresses and residual stresses may combine with the effect of the stress concentration at the cavity to produce a crack. The resulting fracture will have the characteristics of a brittle failure without appreciable plastic flow, although the material may prove ductile in the usual tensile tests.

**Conventional Question IES-1999**

**Question:** Distinguish between creep and fatigue.

**Answer:** Fatigue is a phenomenon associated with variable loading or more precisely to cyclic stressing or straining of a material, metallic, components subjected to variable loading get fatigue, which leads to their premature failure under specific conditions. When a member is subjected to a constant load over a long period of time it undergoes a slow permanent deformation and this is termed as "Creep". This is dependent on temperature.

**Conventional Question IES-2008**

**Question:** What different stresses set-up in a bolt due to initial tightening, while used as a fastener? Name all the stresses in detail.

**Answer:**
1. When the nut is initially tightened there will be some elongation in the bolt so tensile stress will develop.
2. While it is tightening a torque across some shear stress. But when tightening will be completed there should be no shear stress.

**Conventional Question IES-2008**

**Question:** A Copper rod 6 cm in diameter is placed within a steel tube, 8 cm external diameter and 6 cm internal diameter, of exactly the same length. The two pieces are rigidly fixed together by two transverse pins 20 mm in diameter, one at each end passing through both rod and the tube.

Calculated the stresses induced in the copper rod, steel tube and the pins if the temperature of the combination is raised by 50°C. 

[Take $E_s=210$ GPa, $\alpha_s=0.0000115 \degree C$ ; $E_c=105$ GPa, $\alpha_c=0.000017 \degree C$ ]

**Answer:**

\[
\sigma_c + \sigma_s = \Delta t (\alpha_c - \alpha_s)
\]

Area of copper rod ($A_c$) = \(\frac{\pi d^2}{4} = \frac{\pi}{4} \left( \frac{6}{100} \right)^2 m^2 = 2.8274 \times 10^{-3} m^2\)

Area of steel tube ($A_s$) = \(\frac{\pi d^2}{4} = \frac{\pi}{4} \left( \frac{8}{100} \right)^2 - \left( \frac{6}{100} \right)^2 m^2 = 2.1991 \times 10^{-3} m^2\)

**Rise** in temperature, $\Delta t = 50 \degree C$

Free expansion of copper bar = $\alpha_c L \Delta t$

Free expansion of steel tube = $\alpha_s L \Delta t$
Chapter 1 Stress and Strain

S K Mondal

Difference in free expansion = \((\alpha_c - \alpha_s) L \Delta t\)

\[= (17 - 11.5) \times 10^{-6} \times L \times 50 = 2.75 \times 10^4 L \text{ m}\]

A compressive force (P) exerted by the steel tube on the copper rod opposed the extra expansion of the copper rod and the copper rod exerts an equal tensile force P to pull the steel tube. In this combined effect reduction in copper rod and increase in length of steel tube equalize the difference in free expansions of the combined system.

Reduction in the length of copper rod due to force P Newton=

\[
(\Delta L)_c = \frac{PL}{A_c E_c} = \frac{PL}{(2.8275 \times 10^{-3})(105 \times 10^6)} \text{ m}
\]

Increase in length of steel tube due to force P

\[
(\Delta L)_s = \frac{PL}{A_s E_s} = \frac{PL}{(2.1991 \times 10^{-3})(210 \times 10^6)} \text{ m}
\]

Difference in length is equated

\[
(\Delta L)_c + (\Delta L)_s = 2.75 \times 10^{-4} L
\]

Or P = 49.695 kN

Stress in copper rod, \(\sigma_c = \frac{P}{A_c} = \frac{49695}{2.8275 \times 10^3} \text{ MPa} = 17.58 \text{ MPa}\)

Stress in steel tube, \(\sigma_s = \frac{P}{A_s} = \frac{49695}{2.1991 \times 10^3} \text{ MPa} = 22.6 \text{ MPa}\)

Since each of the pin is in double shear, shear stress in pins \(\tau_{pin}\)

\[
= \frac{P}{2 \times A_{pin}} = \frac{49695}{2 \times \frac{\pi}{4}(0.02)^2} = 79 \text{ MPa}
\]

Conventional Question IES-2002

Question: Why are the bolts, subjected to impact, made longer?

Answer: If we increase length its volume will increase so shock absorbing capacity will increased.

Conventional Question IES-2007

Question: Explain the following in brief:

(i) Effect of size on the tensile strength
(ii) Effect of surface finish on endurance limit.

Answer:

(i) When size of the specimen increases tensile strength decrease. It is due to the reason that if size increases there should be more change of defects (voids) into the material which reduces the strength appreciably.

(ii) If the surface finish is poor, the endurance strength is reduced because of scratches present in the specimen. From the scratch crack propagation will start.

Conventional Question IES-2004

Question: Mention the relationship between three elastic constants i.e. elastic modulus (E), rigidity modulus (G), and bulk modulus (K) for any Elastic material. How is the Poisson’s ratio (\(\mu\)) related to these moduli?

Answer: \(E = \frac{9KG}{3K + G}\)

\[E = 3K(1 - 2\mu) = 2G(1 + \mu) = \frac{9KG}{3K + G}\]
Chapter-1 Stress and Strain

Conventional Question IES-1996

Question: The elastic and shear moduli of an elastic material are $2 \times 10^{11}$ Pa and $8 \times 10^{10}$ Pa respectively. Determine Poisson’s ratio of the material.

Answer: We know that $E = 2G(1+\mu) = \frac{9KG}{3K+G}$

or, $1+\mu = \frac{E}{2G}$

or $\mu = \frac{E}{2G} - 1 = \frac{2 \times 10^{11}}{2 \times (8 \times 10^{10})} - 1 = 0.25$

Conventional Question IES-2003

Question: A steel bolt of diameter 10 mm passes through a brass tube of internal diameter 15 mm and external diameter 25 mm. The bolt is tightened by a nut so that the length of tube is reduced by 1.5 mm. If the temperature of the assembly is raised by 40°C, estimate the axial stresses the bolt and the tube before and after heating. Material properties for steel and brass are:

$E_s = 2 \times 10^5$ N/mm$^2$ $\alpha_s = 1.2 \times 10^{-5}$ /°C and $E_b = 1 \times 10^5$ N/mm$^2$ $\alpha_b = 1.9 \times 10^{-5}$/°C

Answer:

Area of steel bolt $(A_s) = \frac{\pi}{4} \times (0.010)^2 m^2 = 7.854 \times 10^{-5} m^2$

Area of brass tube $(A_b) = \frac{\pi}{4} \times [(0.025)^2 - (0.015)^2] = 3.1416 \times 10^{-4}$

Stress due to tightening of the nut

Compressive force on brass tube = tensile force on steel bolt

or, $\sigma_b A_b = \sigma_s A_s$

or, $E_b \frac{(\Delta L)}{L} A_b = \sigma_s A_s$

$E = \frac{\sigma}{\varepsilon} \frac{L}{\Delta L}$

Let assume total length $(L) = 1m$

Therefore $(1 \times 10^5 \times 10^6) \times \frac{(1.5 \times 10^{-3})}{1} \times (3.1416 \times 10^{-4}) = \sigma_s \times 7.854 \times 10^5$

or $\sigma_s = 600$ MPa (tensile)

and $\sigma_b = E_b \frac{(\Delta L)}{L} = (1 \times 10^5) \times \frac{(1.5 \times 10^{-3})}{1} MPa = 150$ MPa (Compressive)
So before heating
Stress in brass tube \( \sigma_b = 150 \text{MPa} \) (compressive)
Stress in steel bolt \( \sigma_s = 600 \text{MPa} \) (tensile)

**Stress due to rise of temperature**

Let stress \( \sigma'_b \) & \( \sigma'_s \) are due to brass tube and steel bolt.

If the two members had been free to expand,
Free expansion of steel = \( \alpha_s \times \Delta t \times l \)
Free expansion of brass tube = \( \alpha_b \times \Delta t \times l \)

Since \( \alpha_b > \alpha_s \) free expansion of copper is greater than the free expansion of steel. But they are rigidly fixed so final expansion of each members will be same. Let us assume this final expansion is ‘\( \delta \)’. The free expansion of brass tube is greater than \( \delta \), while the free expansion of steel is less than \( \delta \). Hence the steel rod will be subjected to a tensile stress while the brass tube will be subjected to a compressive stress.

For the equilibrium of the whole system,
Total tension (Pull) in steel = Total compression (Push) in brass tube.
\[ \sigma_s A_b = \sigma'_s A_b \quad \text{or} \quad \sigma'_b = \sigma'_s \times \frac{A_s}{A_b} = \frac{7.854 \times 10^{-5}}{3.14 \times 10^{-4}} \sigma'_s = 0.25 \sigma'_s \]

Final expansion of steel = final expansion of brass tube
\[ \alpha_s (\Delta t) \times 1 + \frac{\sigma'_s}{E_s} = \sigma'_b (\Delta t) \times 1 - \frac{\sigma'_b}{E_b} \]

\[ \text{or, } (1.2 \times 10^{-5}) \times 40 \times 1 + \frac{\sigma'_s}{2 \times 10^5 \times 10^6} = (1.9 \times 10^{-5}) \times 40 \times 1 - \frac{\sigma'_b}{1 \times 10^5 \times 10^6} \quad \text{(ii)} \]

From (i) & (ii) we get
\[ \sigma'_s \left[ \frac{1}{2 \times 10^{11}} + \frac{0.25}{10^{11}} \right] = 2.8 \times 10^{-4} \]

\[ \text{or, } \sigma'_s = 37.33 \text{ MPa (Tensile stress)} \]

\[ \text{or, } \sigma'_b = 9.33 \text{ MPa (compressive)} \]

Therefore, the final stresses due to tightening and temperature rise
Stress in brass tube = \( \sigma_b + \sigma'_b = 150 + 9.33 \text{MPa} = 159.33 \text{MPa} \)
Stress in steel bolt = \( \sigma_s + \sigma'_s = 600 + 37.33 = 637.33 \text{MPa} \).

**Conventional Question IES-1997**

**Question:** A Solid right cone of axial length h is made of a material having density \( \rho \) and elasticity modulus \( E \). It is suspended from its circular base. Determine its elongation due to its self weight.

**Answer:** See in the figure MNH is a solid right cone of length ‘h’.

Let us assume its wider end of diameter ‘d’ fixed rigidly at MN.

Now consider a small strip of thickness dy at a distance y from the lower end.

Let ‘ds’ is the diameter of the strip.

\[ \therefore \text{Weight of portion UVH} = \frac{1}{3} \left( \frac{\pi d^2}{4} \right) y \times \rho g \quad \text{(i)} \]
From the similar triangles MNH and UVH,

\[
\frac{MN}{UV} = \frac{d}{d_s} = \frac{\ell}{y}
\]

or, \(d_s = \frac{d \cdot y}{\ell}\) \(\text{(ii)}\)

:. Stress at section UV = \[
\frac{\text{force at UV}}{\text{cross-section area at UV}} = \frac{\text{Weight of UVH}}{\left(\frac{\pi d_s^2}{4}\right)}
\]

\[
= \frac{1}{3} \frac{\pi d_s^2}{4} \cdot y \cdot \rho g = \frac{1}{3} \cdot \frac{y \cdot \rho g}{\frac{\pi d_s^2}{4}}
\]

So, extension in \(dy\) = \[
\frac{1}{3} \frac{y \cdot \rho g}{E} \cdot dy
\]

:. Total extension of the bar = \[
\int_0^h \frac{1}{3} \frac{y \cdot \rho g \cdot dy}{E} = \frac{\rho gh^2}{6E}
\]

From stress-strain relationship

\[
E = \frac{\delta}{\epsilon} = \frac{\delta}{d\ell} \quad \text{or, } d\ell = \frac{\delta \cdot \ell}{E}
\]

Conventional Question IES-2004

Question: Which one of the three shafts listed here has the highest ultimate tensile strength? Which is the approximate carbon content in each steel?

(i) Mild Steel  (ii) cast iron  (iii) spring steel

Answer: Among three steel given, spring steel has the highest ultimate tensile strength. Approximate carbon content in

(i) Mild steel is (0.3% to 0.8%)
(ii) Cost iron (2% to 4%)
(iii) Spring steel (0.4% to 1.1%)

Conventional Question IES-2003

Question: If a rod of brittle material is subjected to pure torsion, show with help of a sketch, the plane along which it will fail and state the reason for its failure.

Answer: Brittle materials fail in tension. In a torsion test the maximum tensile test occurs at 45° to the axis of the shaft. So failure will occur along a 45° to the axis of the shaft. So failure will occur along a 45° helix

So failures will occur according to 45° plane.
Chapter-1 Stress and Strain S K Mondal's

Conventional Question IAS-1995

Question: The steel bolt shown in Figure has a thread pitch of 1.6 mm. If the nut is initially tightened up by hand so as to cause no stress in the copper spacing tube, calculate the stresses induced in the tube and in the bolt if a spanner is then used to turn the nut through 90°. Take E_c and E_s as 100 GPa and 209 GPa respectively.

Answer: Given: p = 1.6 mm, E_c = 100 GPa; E_s = 209 GPa.

Stresses induced in the tube and the bolt, \( \sigma_c, \sigma_s \):

\[
A_s = \frac{\pi}{4} \left( \frac{10}{1000} \right)^2 = 7.584 \times 10^{-6} \text{m}^2
\]

\[
A_s = \frac{\pi}{4} \left( \frac{18}{1000} \right)^2 - \left( \frac{12}{1000} \right)^2 = 14.14 \times 10^{-5} \text{m}^2
\]

Tensile force on steel bolt, \( P_s \) = compressive force in copper tube, \( P_c = P \)

Also, Increase in length of bolt + decrease in length of tube = axial displacement of nut

\[
\text{i.e} \quad (\delta l)_s + (\delta l)_c = 1.6 \times \frac{90}{360} = 0.4 \text{mm} = 0.4 \times 10^{-3} \text{m}
\]

or \[
\frac{P_e}{A_s E_s} + \frac{P}{A_c E_c} = 0.4 \times 10^{-3} \quad (\because l_s = l_c = l)
\]

or \[
P \times \left( \frac{1000}{1000} \right) \left[ \frac{1}{7.854 \times 10^{-5} \times 209 \times 10^9} + \frac{1}{14.14 \times 10^{-5} \times 100 \times 10^9} \right] = 0.4 \times 10^{-3}
\]

or \[
P = 30386 \text{N}
\]

\[
\therefore \quad \frac{P}{A_s} = 386.88 \text{MPa} \quad \text{and} \quad \frac{P}{A_c} = 214.89 \text{MPa}
\]

Conventional Question AMIE-1997

Question: A steel wire 2 m long and 3 mm in diameter is extended by 0.75 mm when a weight \( W \) is suspended from the wire. If the same weight is suspended from a brass wire, 2.5 m long and 2 mm in diameter, it is elongated by 4.64 mm. Determine the modulus of elasticity of brass if that of steel be \( 2.0 \times 10^5 \text{ N / mm}^2 \)

Answer: Given, \( l_s = 2 \text{ m}, d_s = 3 \text{ mm} \), \( \delta l_s = 0.75 \text{ mm} \); \( E_s = 2 \times 10^5 \text{ N / mm}^2 \); \( l_b = 2.5 \text{ m}, d_b = 2 \text{ mm} \) \( \delta l_b = 4.64 \text{ mm} \) and let modulus of elasticity of brass = \( E_b \)

Hooke's law gives, \( \delta l = \frac{P l}{A E} \) [Symbol has usual meaning]

Case I: For steel wire: 

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\[
\delta_s = \frac{P l_s}{A_s E_s}
\]

or
\[
0.75 = \frac{P \times (2 \times 10^3)}{\left(\frac{\pi}{4} \times 3^2\right) \times 2.0 \times 10^6 \times \frac{1}{2000}}
\]

Case II: For bass wire:
\[
\delta_b = \frac{P l_b}{A_b E_b}
\]

\[
4.64 = \frac{P \times (2.5 \times 10^3)}{\left(\frac{\pi}{4} \times 2^2\right) \times E_b}
\]

or
\[
P = 4.64 \times \left(\frac{\pi}{4} \times 2^2\right) \times E_b \times \frac{1}{2500}
\]

From (i) and (ii), we get
\[
0.75 \times \left(\frac{\pi}{4} \times 3^2\right) \times 2.0 \times 10^6 \times \frac{1}{2000} = 4.64 \times \left(\frac{\pi}{4} \times 2^2\right) \times E_b \times \frac{1}{2500}
\]

or
\[
E_b = 0.909 \times 10^6 \text{ N/m}^2
\]

Conventional Question AMIE-1997

Question: A steel bolt and sleeve assembly is shown in figure below. The nut is tightened up on the tube through the rigid end blocks until the tensile force in the bolt is 40 kN. If an external load 30 kN is then applied to the end blocks, tending to pull them apart, estimate the resulting force in the bolt and sleeve.

Answer: Area of steel bolt, \(A_b = \left(\frac{25}{1000}\right)^2 = 4.908 \times 10^{-4} \text{ m}^2\)

Area of steel sleeve, \(A_s = \frac{\pi}{4} \left(\frac{62.5}{1000}\right)^2 - \left(\frac{50}{1000}\right)^2 = 1.104 \times 10^{-3} \text{ m}^2\)

Forces in the bolt and sleeve:
(i) Stresses due to tightening the nut:
Let \(\sigma_b = \text{stress developed in steel bolt due to tightening the nut; and}\)
\(\sigma_s = \text{stress developed in steel sleeve due to tightening the nut.}\)

Tensile force in the steel bolt = 40 kN = 0.04 MN
\[ \sigma_s \times A_s = 0.04 \]
\[ \text{or } \sigma_s \times 4.908 \times 10^{-4} = 0.04 \]
\[ \therefore \sigma_s = \frac{0.04}{4.908 \times 10^{-4}} = 81.5 \text{MN/m}^2 \text{ (tensile)} \]

Compressive force in steel sleeve = 0.04 MN
\[ \sigma_s \times A_s = 0.04 \]
\[ \text{or } \sigma_s \times 1.104 \times 10^{-3} = 0.04 \]
\[ \therefore \sigma_s = \frac{0.04}{1.104 \times 10^{-3}} = 36.23 \text{MN/m}^2 \text{ (compressive)} \]

(ii) Stresses due to tensile force:
Let the stresses developed due to tensile force of 30 kN = 0.03 MN in steel bolt and sleeve be \( \sigma'_b \) and \( \sigma'_s \) respectively.

Then, \( \sigma'_b \times A_b + \sigma'_s \times A_s = 0.03 \)
\[ \sigma'_b \times 4.908 \times 10^{-4} + \sigma'_s \times 1.104 \times 10^{-3} = 0.03 \] \[ \text{--- (i)} \]

In a compound system with an external tensile load, elongation caused in each will be the same.
\[ \delta_b = \frac{\sigma'_b}{E_b} \times l_b \]
\[ \text{or } \delta_b = \frac{\sigma'_b}{E_b} \times 0.5 \quad \text{(Given,} l_b = 500 \text{mm} = 0.5) \]
and \[ \delta_s = \frac{\sigma'_s}{E_s} \times 0.4 \quad \text{(Given,} l_s = 400 \text{mm} = 0.4) \]
But \[ \delta_b = \delta_s \]
\[ \therefore \frac{\sigma'_b}{E_b} \times 0.5 = \frac{\sigma'_s}{E_s} \times 0.4 \]
\[ \text{or } \sigma'_b = 0.8 \sigma'_s \quad \text{(Given,} E_b = E_s \text{)} \quad \text{--- (2)} \]

Substituting this value in (1), we get
\[ 0.8 \sigma'_s \times 4.908 \times 10^{-4} + \sigma'_s \times 1.104 \times 10^{-3} = 0.03 \]
gives \[ \sigma'_s = 20 \text{MN/m}^2 \text{ (tensile)} \]
and \[ \sigma'_b = 0.8 \times 20 = 16 \text{MN/m}^2 \text{ (tensile)} \]

Resulting stress in steel bolt,
\[ (\sigma_b)_r = \sigma_s + \sigma'_b = 81.5 + 16 = 97.5 \text{MN/m}^2 \]
Resulting stress in steel sleeve,
\[ (\sigma_s)_r = \sigma_s + \sigma'_s = 36.23 - 20 = 16.23 \text{MN/m}^2 \text{ (compressive)} \]
Resulting force in steel bolt, \( (\sigma_b)_r \times A_b \)
\[ = 97.5 \times 4.908 \times 10^{-4} = 0.0478 \text{MN (tensile)} \]
Resulting force in steel sleeve, \( (\sigma_s)_r \times A_s \)
\[ = 16.23 \times 1.104 \times 10^{-3} = 0.0179 \text{MN (compressive)} \]
2. Principal Stress and Strain

Theory at a Glance (for IES, GATE, PSU)

2.1 States of stress

- **Uni-axial stress**: only one non-zero principal stress, i.e. $\sigma_1$
  Right side figure represents Uni-axial state of stress.

- **Bi-axial stress**: one principal stress equals zero, two do not, i.e. $\sigma_1 > \sigma_3$; $\sigma_2 = 0$
  Right side figure represents Bi-axial state of stress.

- **Tri-axial stress**: three non-zero principal stresses, i.e. $\sigma_1 > \sigma_2 > \sigma_3$
  Right side figure represents Tri-axial state of stress.

- **Isotropic stress**: three principal stresses are equal, i.e. $\sigma_1 = \sigma_2 = \sigma_3$
  Right side figure represents isotropic state of stress.

- **Axial stress**: two of three principal stresses are equal, i.e. $\sigma_1 = \sigma_2$ or $\sigma_2 = \sigma_3$
  Right side figure represents axial state of stress.
Chapter-2 Principal Stress and Strain

- **Hydrostatic pressure**: weight of column of fluid in interconnected pore spaces.
  \[ P_{\text{hydrostatic}} = \rho_{\text{fluid}} gh \] (density, gravity, depth)

- **Hydrostatic stress**: Hydrostatic stress is used to describe a state of tensile or compressive stress equal in all directions within or external to a body. Hydrostatic stress causes a change in volume of a material. Shape of the body remains unchanged i.e. no distortion occurs in the body.

Right side figure represents Hydrostatic state of stress.

### 2.2 Uni-axial stress on oblique plane

Let us consider a bar of uniform cross sectional area \( A \) under direct tensile load \( P \) giving rise to axial normal stress \( P/A \) acting on a cross section XX. Now consider another section given by the plane YY inclined at \( \theta \) with the XX. This is depicted in following three ways.

Area of the YY Plane = \( \frac{A}{\cos \theta} \); Let us assume the **normal stress** in the YY plane is \( \sigma_n \) and there is a **shear stress** \( \tau \) acting parallel to the YY plane.

Now resolve the force \( P \) in two perpendicular direction one normal to the plane YY = \( P \cos \theta \) and another parallel to the plane YY = \( P \cos \theta \)
Therefore equilibrium gives,
\[ \sigma_n \frac{A}{\cos \theta} = P \cos \theta \quad \text{or} \quad \sigma_n = \frac{P}{A} \cos^2 \theta \]
and
\[ \tau \frac{A}{\cos \theta} = P \sin \theta \quad \text{or} \quad \tau = \frac{P}{A} \sin \theta \cos \theta \quad \text{or} \quad \tau = \frac{P}{2A} \sin 2\theta \]

- Note the variation of normal stress \( \sigma_n \) and shear stress \( \tau \) with the variation of \( \theta \).

When \( \theta = 0 \), normal stress \( \sigma_n \) is maximum i.e. \( (\sigma_n)_{_{\max}} = \frac{P}{A} \) and shear stress \( \tau = 0 \). As \( \theta \) is increased, the normal stress \( \sigma_n \) diminishes, until when \( \theta = 0, \sigma_n = 0 \). But if angle \( \theta \) increased shear stress \( \tau \) increases to a maximum value \( \tau_{_{\max}} = \frac{P}{2A} \) at \( \theta = \frac{\pi}{4} = 45^\circ \) and then diminishes to \( \tau = 0 \) at \( \theta = 90^\circ \)

- The shear stress will be maximum when \( \sin 2\theta = 1 \) or \( \theta = 45^\circ \)

- And the maximum shear stress, \( \tau_{_{\max}} = \frac{P}{2A} \)

- In ductile material failure in tension is initiated by shear stress i.e. the failure occurs across the shear planes at 45\(^\circ\) (where it is maximum) to the applied load.

**Let us clear a concept about a common mistake:** The angle \( \theta \) is not between the applied load and the plane. It is between the planes XX and YY. But if in any question the angle between the applied load and the plane is given don’t take it as \( \theta \). The angle between the applied load and the plane is 90 - \( \theta \). In this case you have to use the above formula as \( \sigma_n = \frac{P}{A} \cos^2(90 - \theta) \) and \( \tau = \frac{P}{2A} \sin(180 - 2\theta) \) where \( \theta \) is the angle between the applied load and the plane. Carefully observe the following two figures it will be clear.

**Let us take an example:** A metal block of 100 mm\(^2\) cross sectional area carries an axial tensile load of 10 kN. For a plane inclined at 30\(^\circ\) with the direction of applied load, calculate:

(a) Normal stress
(b) Shear stress
(c) Maximum shear stress.

**Answer:** Here \( \theta = 90^\circ - 30^\circ = 60^\circ \)
(a) Normal stress \(\sigma_n = \frac{P}{A} \cos^2 \theta = \frac{10 \times 10^3 N}{100 \text{ mm}^2} \cos^2 60^\circ = 25 \text{ MPa}\)

(b) Shear stress \(\tau = \frac{P}{2A} \sin 2\theta = \frac{10 \times 10^3 N}{2 \times 100 \text{ mm}^2} \times \sin 120^\circ = 43.3 \text{ MPa}\)

(c) Maximum shear stress \(\tau_{max} = \frac{P}{2A} = \frac{10 \times 10^3 N}{2 \times 100 \text{ mm}^2} = 50 \text{ MPa}\)

- Complementary stresses

Now if we consider the stresses on an oblique plane \(Y'Y'\) which is perpendicular to the previous plane \(YY\). The stresses on this plane are known as complementary stresses. Complementary normal stress is \(\sigma_n'\) and complementary shear stress is \(\tau'\). The following figure shows all the four stresses. To obtain the stresses \(\sigma_n'\) and \(\tau'\) we need only to replace \(\theta\) by \(\theta + 90^\circ\) in the previous equation. The angle \(\theta + 90^\circ\) is known as aspect angle.

Therefore

\[
\sigma_n' = \frac{P}{A} \cos^2 (90^\circ + \theta) = \frac{P}{A} \sin^2 \theta
\]

\[
\tau' = \frac{P}{2A} \sin 2 (90^\circ + \theta) = -\frac{P}{2A} \sin 2\theta
\]

It is clear \(\sigma_n' + \sigma_n = \frac{P}{A}\) and \(\tau' = -\tau\)

i.e. Complementary shear stresses are always equal in magnitude but opposite in sign.

- Sign of Shear stress

For sign of shear stress following rule have to be followed:
Chapter-2 Principal Stress and Strain

The shear stress $\tau$ on any face of the element will be considered positive when it has a clockwise moment with respect to a centre inside the element. If the moment is counterclockwise with respect to a centre inside the element, the shear stress is negative.

**Note:** The convention is opposite to that of moment of force. Shear stress tending to turn clockwise is positive and tending to turn counter clockwise is negative.

Let us take an example: A prismatic bar of 500 mm$^2$ cross sectional area is axially loaded with a tensile force of 50 kN. Determine all the stresses acting on an element which makes 30° inclination with the vertical plane.

**Answer:** Take an small element ABCD in 30° plane as shown in figure below,

Given, Area of cross-section, $A = 500$ mm$^2$, Tensile force $P = 50$ kN

Normal stress on 30° inclined plane,
$$\sigma_n = \frac{P}{A} \cos^2 \theta = \frac{50 \times 10^3 \text{ N}}{500 \text{ mm}^2} \times \cos^2 30° = 75 \text{ MPa} \quad (+\text{ive means tensile})$$

Shear stress on 30° planes,
$$\tau = \frac{P}{2A} \sin 2\theta = \frac{50 \times 10^3 \text{ N}}{2 \times 500 \text{ mm}^2} \times \sin(2 \times 30°) = 43.3 \text{ MPa} \quad (+\text{ive means clockwise})$$

Complementary stress on $\theta = 90° + 30° = 120°$

Normal stress on 120° inclined plane,
$$\sigma_i = \frac{P}{A} \cos^2 \theta = \frac{50 \times 10^3 \text{ N}}{500 \text{ mm}^2} \times \cos^2 120° = 25 \text{ MPa} \quad (+\text{ive means tensile})$$

Shear stress on 120° inclined plane,
$$\tau = \frac{P}{2A} \sin 2\theta = \frac{50 \times 10^3 \text{ N}}{2 \times 500 \text{ mm}^2} \times \sin(2 \times 120°) = -43.3 \text{ MPa} \quad (-\text{ive means counter clockwise})$$

State of stress on the element ABCD is given below (magnifying)
2.3 Complex Stresses (2-D Stress system)

*i.e. Material subjected to combined direct and shear stress*

We now consider a complex stress system below. The given figure ABCD shows on small element of material

![Complex Stress Diagram](image)

Stresses in three dimensional element

\( \sigma_x \) and \( \sigma_y \) are normal stresses and may be tensile or compressive. We know that normal stress may come from direct force or bending moment. \( \tau_{xy} \) is shear stress. We know that shear stress may come from direct shear force or torsion and \( \tau_{xy} \) and \( \tau_{yx} \) are complementary and

\[
\tau_{xy} = \tau_{yx}
\]

Let \( \sigma_n \) is the normal stress and \( \tau \) is the shear stress on a plane at angle \( \theta \).

Considering the equilibrium of the element we can easily get

**Normal stress**

\[
\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta
\]

and

**Shear stress**

\[
\tau = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta - \tau_{xy} \cos 2\theta
\]

Above two equations are coming from considering equilibrium. They do not depend on material properties and are valid for elastic and in elastic behavior.
Location of planes of maximum stress

(a) Normal stress, \( (\sigma_n)_{\text{max}} \)

For \( \sigma_n \) maximum or minimum

\[
\frac{\partial \sigma_n}{\partial \theta} = 0, \text{ where } \sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta
\]

\[
or - \frac{\sigma_x - \sigma_y}{2} \times (\sin 2\theta) \times 2 + \tau_{xy} (\cos 2\theta) \times 2 = 0 \quad \text{or} \quad \tan 2\theta = \frac{2\tau_{xy}}{2(\sigma_x - \sigma_y)}
\]

(b) Shear stress, \( \tau_{\text{max}} \)

For \( \tau \) maximum or minimum

\[
\frac{\partial \tau}{\partial \theta} = 0, \text{ where } \tau = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta - \tau_{xy} \cos 2\theta
\]

\[
or \frac{\sigma_x - \sigma_y}{2} (\cos 2\theta) \times 2 - \tau_{xy} (-\sin 2\theta) \times 2 = 0
\]

\[
or \cot 2\theta = -\frac{\tau_{xy}}{\sigma_x - \sigma_y}
\]

Let us take an example: At a point in a crank shaft the stresses on two mutually perpendicular planes are 30 MPa (tensile) and 15 MPa (tensile). The shear stress across these planes is 10 MPa.

Find the normal and shear stress on a plane making an angle 30° with the plane of first stress. Find also magnitude and direction of resultant stress on the plane.

Answer: Given \( \sigma_x = +25 \text{MPa (tensile)}, \sigma_y = +15 \text{MPa (tensile)}, \tau_{xy} = 10 \text{MPa and 40°} \)

Therefore, Normal stress \((\sigma_n)\) = \[
= \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos (2 \times 30°) + \tau_{xy} \sin (2 \times 30°)
\]

\[
= \frac{30 + 15}{2} + \frac{30 - 15}{2} \cos (2 \times 30°) + 10 \sin (2 \times 30°) = 34.91 \text{MPa}
\]

Shear stress \((\tau)\) = \[
= \frac{\sigma_x - \sigma_y}{2} \sin (2 \times 30°) - \tau_{xy} \cos (2 \times 30°)
\]

\[
= \frac{30 - 15}{2} \sin (2 \times 30°) - 10 \cos (2 \times 30°) = 1.5 \text{MPa}
\]

Resultant stress \((\sigma_r)\) = \[
= \sqrt{(34.91)^2 + 1.5^2} = 34.94 \text{MPa}
\]

and Obliquity \((\phi)\), \[
\tan \phi = \frac{\tau}{\sigma_x} = \frac{1.5}{34.91} \quad \Rightarrow \phi = 2.46°
\]
2.4 Bi-axial stress

Let us now consider a stressed element ABCD where $\tau_{xy} = 0$, i.e. only $\sigma_x$ and $\sigma_y$ is there. This type of stress is known as bi-axial stress. In the previous equation if you put $\tau_{xy} = 0$ we get Normal stress, $\sigma_n$ and shear stress, $\tau$ on a plane at angle $\theta$.

- Normal stress, $\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta$
- Shear/Tangential stress, $\tau = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta$
- For complementary stress, aspect angle = $\theta + 90^0$
- Aspect angle ‘$\theta$’ varies from 0 to $\pi/2$
- Normal stress $\sigma_n$ varies between the values $\sigma_x (\theta = 0)$ & $\sigma_y (\theta = \pi / 2)$

Let us take an example: The principal tensile stresses at a point across two perpendicular planes are 100 MPa and 50 MPa. Find the normal and tangential stresses and the resultant stress and its obliquity on a plane at $20^0$ with the major principal plane.

Answer: Given $\sigma_x = 100$ MPa (tensile), $\sigma_y = 50$ MPa (tensile) and $\theta = 20^0$

Normal stress, $(\sigma_n) = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta = \frac{100 + 50}{2} + \frac{100 - 50}{2} \cos (2 \times 20^0) = 94$ MPa

Shear stress, $(\tau) = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta = \frac{100 - 50}{2} \sin (2 \times 20^0) = 16$ MPa

Resultant stress $(\sigma_r) = \sqrt{94^2 + 16^2} = 95.4$ MPa

Therefore angle of obliquity, $\phi = \tan^{-1}\left(\frac{\tau}{\sigma_n}\right) = \tan^{-1}\left(\frac{16}{94}\right) = 9.7^0$
We may derive uni-axial stress on oblique plane from

\[ \sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta \]

and

\[ \tau = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta - \tau_{xy} \cos 2\theta \]

Just put \( \sigma_y = 0 \) and \( \tau_{xy} = 0 \)

Therefore,

\[ \sigma_n = \frac{\sigma_x + 0}{2} + \frac{\sigma_x - 0}{2} \cos 2\theta = \frac{1}{2} \sigma_x (1 + \cos 2\theta) = \sigma_x \cos^2 \theta \]

and

\[ \tau = \frac{\sigma_x - 0}{2} \sin 2\theta = \frac{\sigma_x}{2} \sin 2\theta \]

2.5 Pure Shear

Pure shear is a particular case of bi-axial stress where \( \sigma_x = -\sigma_y \)

Note: \( \sigma_x \) or \( \sigma_y \), which one is compressive that is immaterial but one should be tensile and other should be compressive and equal magnitude. If \( \sigma_x = 100 \text{MPa} \) then \( \sigma_y \) must be \(-100 \text{MPa}\) otherwise if \( \sigma_y = 100 \text{MPa} \) then \( \sigma_x \) must be \(-100 \text{MPa}\).

In case of pure shear on 45° planes

\[ \tau_{\text{max}} = \pm \sigma_x ; \quad \sigma_n = 0 \quad \text{and} \quad \sigma'_n = 0 \]

We may depict the pure shear in an element by following two ways.
Chapter 2 Principal Stress and Strain

(a) In a torsion member, as shown below, an element ABCD is in pure shear (only shear stress is present in this element) in this member at 45° plane an element \( A'B'C'D' \) is also in pure shear where \( \sigma_x = -\sigma_y \) but in this element no shear stress is there.

(b) In a bi-axial state of stress a member, as shown below, an element ABCD in pure shear where \( \sigma_x = -\sigma_y \) but in this element no shear stress is there and an element \( A'B'C'D' \) at 45° plane is also in pure shear (only shear stress is present in this element).

Let us take an example: See the in the Conventional question answer section in this chapter and the question is “Conventional Question IES-2007”

2.6 Stress Tensor

- **State of stress at a point (3-D)**

Stress acts on every surface that passes through the point. We can use three mutually perpendicular planes to describe the stress state at the point, which we approximate as a cube each of the three planes has one normal component & two shear components therefore, 9 components necessary to define stress at a point 3 normal and 6 shear stress.

Therefore, we need nine components, to define the state of stress at a point

\[
\begin{align*}
\sigma_x & \quad \tau_{xy} & \quad \tau_{xz} \\
\sigma_y & \quad \tau_{yx} & \quad \tau_{yz} \\
\sigma_z & \quad \tau_{zx} & \quad \tau_{zy}
\end{align*}
\]

For cube to be in equilibrium (at rest: not moving, not spinning)
The nine components (six of which are independent) can be written in matrix form

\[
\sigma = \begin{pmatrix}
\sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\
\sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\
\sigma_{zx} & \sigma_{zy} & \sigma_{zz}
\end{pmatrix}
\]

or

\[
\tau = \begin{pmatrix}
\tau_{xx} & \tau_{xy} & \tau_{xz} \\
\tau_{yx} & \tau_{yy} & \tau_{yz} \\
\tau_{zx} & \tau_{zy} & \tau_{zz}
\end{pmatrix}
\]

This is the stress tensor.

Components on diagonal are normal stresses; off are shear stresses.

**State of stress at an element (2-D)**

- When examining stress at a point, it is possible to choose **three mutually perpendicular planes** on which **no shear** stresses exist in three dimensions, one combination of orientations for the three mutually perpendicular planes will cause the shear stresses on all three planes to go to zero **this is the state defined by the principal stresses.**
Chapter-2 Principal Stress and Strain

- **Principal stresses** are normal stresses that are orthogonal to each other
- **Principal planes** are the planes across which principal stresses act (faces of the cube) for principal stresses (shear stresses are zero)

**Major Principal Stress**

\[
\sigma_1 = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]

**Minor principal stress**

\[
\sigma_2 = \frac{\sigma_x + \sigma_y}{2} - \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]

**Position of principal planes**

\[
\tan 2\theta_p = \frac{2\tau_{xy}}{(\sigma_x - \sigma_y)}
\]

**Maximum shear stress**

\[
\tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]

Let us take an example: In the wall of a cylinder the state of stress is given by, 
\(\sigma_x = 85\text{MPa} \) (compressive), \(\sigma_y = 25\text{MPa} \) (tensile) and shear stress \(\tau_{xy} = 60\text{MPa}\)

Calculate the principal planes on which they act. Show it in a figure.

**Answer:** Given \(\sigma_x = -85\text{MPa}\), \(\sigma_y = 25\text{MPa}\), \(\tau_{xy} = 60\text{MPa}\)
Major principal stress ($\sigma_1$) = \[ \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \]
\[ = \frac{-85 + 25}{2} + \sqrt{\left(\frac{-85 - 25}{2}\right)^2 + 60^2} = 51.4 \text{ MPa} \]

Minor principal stress ($\sigma_2$) = \[ \frac{\sigma_x + \sigma_y}{2} - \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \]
\[ = \frac{-85 + 25}{2} - \sqrt{\left(\frac{-85 - 25}{2}\right)^2 + 60^2} = -111.4 \text{ MPa} \text{ i.e. 111.4 MPa (Compressive)} \]

For principal planes:
\[ \tan 2\theta_p = \frac{2\tau_{xy}}{\sigma_x - \sigma_y} = \frac{2 \times 60}{-85 - 25} \]
\[ \text{or } \theta_p = -24^\circ \text{ it is for } \sigma_1 \]

Complementary plane $\theta_p' = \theta_p + 90^\circ = 66^\circ$ it is for $\sigma_2$

The Figure showing state of stress and principal stresses is given below:

The direction of one principal plane and the principle stresses acting on this would be $\sigma_1$ when is acting normal to this plane, now the direction of other principal plane would be $90^\circ + \theta_p$ because the principal planes are the two mutually perpendicular plane, hence rotate the another plane $90^\circ + \theta_p$ in the same direction to get the another plane, now complete the material element as $\theta_p$ is negative that means we are measuring the angles in the opposite direction to the reference plane BC. The following figure gives clear idea about negative and positive $\theta_p$. 
2.8 Mohr's circle for plane stress

- The transformation equations of plane stress can be represented in a graphical form which is popularly known as **Mohr's circle**.

- Though the transformation equations are sufficient to get the normal and shear stresses on any plane at a point, with Mohr's circle one can easily visualize their variation with respect to plane orientation $\theta$.

- **Equation of Mohr's circle**

  We know that normal stress, $\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2}\cos 2\theta + \tau_{xy}\sin 2\theta$

  And Tangential stress, $\tau = \frac{\sigma_x - \sigma_y}{2}\sin 2\theta - \tau_{xy}\cos 2\theta$

  Rearranging we get, $\left(\sigma_n - \frac{\sigma_x + \sigma_y}{2}\right) = \frac{\sigma_x - \sigma_y}{2}\cos 2\theta + \tau_{xy}\sin 2\theta$ ..........(i)

  and $\tau = \frac{\sigma_x - \sigma_y}{2}\sin 2\theta - \tau_{xy}\cos 2\theta$ ..........(ii)

  A little consideration will show that the above two equations are the equations of a circle with $\sigma_n$ and $\tau$ as its coordinates and $2\theta$ as its parameter.

  If the parameter $2\theta$ is eliminated from the equations, (i) & (ii) then the significance of them will become clear.

  $\sigma_{\text{avg}} = \frac{\sigma_x + \sigma_y}{2}$ and $R = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}$

  Or $\left(\sigma_n - \sigma_{\text{avg}}\right)^2 + \tau_{xy}^2 = R^2$

  It is the equation of a circle with centre, $\left(\sigma_{\text{avg}}, 0\right)$ i.e. $\left(\frac{\sigma_x + \sigma_y}{2}, 0\right)$
and radius, \[ R = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \]

- **Construction of Mohr’s circle**

  **Convention for drawing**
  - A \( \tau_{xy} \) that is clockwise (positive) on a face resides above the \( \sigma \) axis; a \( \tau_{xy} \) anticlockwise (negative) on a face resides below \( \sigma \) axis.
  - Tensile stress will be positive and plotted right of the origin O. Compressive stress will be negative and will be plotted left to the origin O.
  - An angle \( \theta \) on real plane transfers as an angle \( 2\theta \) on Mohr’s circle plane.

We now construct Mohr’s circle in the following stress conditions

I. Bi-axial stress when \( \sigma_x \) and \( \sigma_y \) known and \( \tau_{xy} = 0 \)

II. Complex state of stress (\( \sigma_x, \sigma_y \) and \( \tau_{xy} \) known)

I. **Constant of Mohr’s circle for Bi-axial stress** (when only \( \sigma_x \) and \( \sigma_y \) known)

If \( \sigma_x \) and \( \sigma_y \) both are tensile or both compressive sign of \( \sigma_x \) and \( \sigma_y \) will be same and this state of stress is known as “like stresses” if one is tensile and other is compressive sign of \( \sigma_x \) and \( \sigma_y \) will be opposite and this state of stress is known as ‘unlike stress’.

- **Construction of Mohr’s circle for like stresses** (when \( \sigma_x \) and \( \sigma_y \) are same type of stress)

  **Step-I:** Label the element ABCD and draw all stresses.

  **Step-II:** Set up axes for the direct stress (as abscissa) i.e., in x-axis and shear stress (as ordinate) i.e. in Y-axis
Step-III: Using sign convention and some suitable scale, plot the stresses on two adjacent faces e.g. AB and BC on the graph. Let OL and OM equal to $\sigma_x$ and $\sigma_y$ respectively on the axis O $\sigma$. 

Step-IV: Bisect ML at C. With C as centre and CL or CM as radius, draw a circle. It is the Mohr’s circle.

Step-V: At the centre C draw a line CP at an angle $2\theta$, in the same direction as the normal to the plane makes with the direction of $\sigma_x$. The point P represents the state of stress at plane ZB.
Step-VI: Calculation, Draw a perpendicular PQ and PR where PQ = \( \tau \) and PR = \( \sigma_n \)

\[
OC = \frac{\sigma_x + \sigma_y}{2} \quad \text{and} \quad MC = CL = CP = \frac{\sigma_x - \sigma_y}{2}
\]

\[
PR = \sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta
\]

\[
PQ = \tau = CP\sin 2\theta = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta
\]

[Note: In the examination you only draw final figure (which is in Step-V) and follow the procedure step by step so that no mistakes occur.]

- Construction of Mohr’s circle for unlike stresses (when \( \sigma_x \) and \( \sigma_y \) are opposite in sign)

Follow the same steps which we followed for construction for ‘like stresses’ and finally will get the figure shown below.

**Note:** For construction of Mohr’s circle for principal stresses when \( (\sigma_1 \text{ and } \sigma_2 \text{ is known}) \) then follow the same steps of Constant of Mohr’s circle for Bi-axial stress (when only \( \sigma_x \) and \( \sigma_y \) known) just change the \( \sigma_x = \sigma_1 \) and \( \sigma_y = \sigma_2 \)
II. Construction of Mohr’s circle for complex state of stress ($\sigma_x, \sigma_y$ and $\tau_{xy}$ known)

**Step-I:** Label the element ABCD and draw all stresses.

**Step-II:** Set up axes for the direct stress (as abscissa) i.e., in x-axis and shear stress (as ordinate) i.e. in Y-axis.

**Step-III:** Using sign convention and some suitable scale, plot the stresses on two adjacent faces e.g. AB and BC on the graph. Let OL and OM equal to $\sigma_x$ and $\sigma_y$ respectively on the axis O$\sigma$. Draw LS perpendicular to O$\sigma$ axis and equal to $\tau_{xy}$ i.e. LS=$\tau_{xy}$. Here LS is downward as $\tau_{xy}$ on AB face is (−ive) and draw MT perpendicular to O$\sigma$ axis and equal to $\tau_{xy}$ i.e. MT=$\tau_{xy}$. Here MT is upward as $\tau_{xy}$ BC face is (+ive).
Step-IV: Join ST and it will cut $O\sigma$ axis at C. With C as centre and CS or CT as radius, draw circle. It is the Mohr’s circle.

Step-V: At the centre draw a line CP at an angle $2\theta$ in the same direction as the normal to the plane makes with the direction of $\sigma_x$.

Step-VI: Calculation, Draw a perpendicular PQ and PR where PQ = $\tau$ and PR = $\sigma_n$.

Centre, $OC = \frac{\sigma_x + \sigma_y}{2}$

Radius CS = $\sqrt{(CL)^2+(LS)^2} = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = CT = CP$

$PR = \sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta$

$PQ = \tau = \frac{\sigma_x - \sigma_y}{2} \sin 2\theta - \tau_{xy} \cos 2\theta$.

[Note: In the examination you only draw final figure (which is in Step-V) and follow the procedure step by step so that no mistakes occur.]
Note: The intersections of $O\sigma$ axis are two principal stresses, as shown below.

Let us take an example: See the in the Conventional question answer section in this chapter and the question is “Conventional Question IES-2000”

2.9 Mohr’s circle for some special cases:

i) Mohr’s circle for axial loading:

$$\sigma_x = \frac{P}{A}; \quad \sigma_y = \tau_{xy} = 0$$

ii) Mohr’s circle for torsional loading:

$$\tau_{xy} = \frac{Tr}{J}; \quad \sigma_x = \sigma_y = 0$$

It is a case of pure shear

iii) In the case of pure shear

$$(\sigma_1 = -\sigma_2 \text{ and } \sigma_3 = 0)$$
iv) A shaft compressed all round by a hub

\[ \sigma_1 = \sigma_2 = \sigma_3 = \text{Compressive (Pressure)} \]

v) Thin spherical shell under internal pressure

\[ \sigma_1 = \sigma_2 = \frac{pr}{2t} = \frac{pD}{4t} \text{ (tensile)} \]

vi) Thin cylinder under pressure

\[ \sigma_1 = \frac{pD}{2t} = \frac{pr}{t} \text{ (tensile)} \] and \[ \sigma_2 = \frac{pd}{4t} = \frac{pr}{2t} \text{ (tensile)} \]

vii) Bending moment applied at the free end of a cantilever

Only bending stress, \( \sigma_1 = \frac{My}{I} \) and \( \sigma_2 = \tau_{xy} = 0 \)
Normal strain

Let us consider an element AB of infinitesimal length δx. After deformation of the actual body if displacement of end A is u, that of end B is \( u + \frac{\partial u}{\partial x} \delta x \). This gives an increase in length of element AB is \( u + \frac{\partial u}{\partial x} \delta x - u = \frac{\partial u}{\partial x} \delta x \) and therefore the strain in x-direction is \( \varepsilon_x = \frac{\partial u}{\partial x} \).

Similarly, strains in y and z directions are \( \varepsilon_y = \frac{\partial v}{\partial y} \) and \( \varepsilon_z = \frac{\partial w}{\partial z} \).

Therefore, we may write the three normal strain components as

\[
\varepsilon_x = \frac{\partial u}{\partial x}, \quad \varepsilon_y = \frac{\partial v}{\partial y}, \quad \text{and} \quad \varepsilon_z = \frac{\partial w}{\partial z}.
\]

Shear strain

Let us consider an element ABCD in x-y plane and let the displaced position of the element be A'B'C'D'. This gives shear strain in x-y plane as \( \gamma_{xy} = \alpha + \beta \) where \( \alpha \) is the angle made by the displaced line B'C' with the vertical and \( \beta \) is the angle made by the displaced line A'D' with the horizontal. This gives \( \alpha = \frac{\partial u}{\partial y} \) and \( \beta = \frac{\partial v}{\partial x} \).

We may therefore write the three shear strain components as

\[
\gamma_{xy} = \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}, \quad \gamma_{yz} = \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \quad \text{and} \quad \gamma_{zx} = \frac{\partial w}{\partial x} + \frac{\partial u}{\partial z}.
\]

Therefore the state of strain at a point can be completely described by the six strain components and the strain components in their turns can be completely defined by the displacement components \( u, v, \) and \( w \).

Therefore, the complete strain matrix can be written as
Shear strain associated with the distortion of an infinitesimal element.

**Strain Tensor**

The three normal strain components are

\[
\begin{align*}
\varepsilon_x &= \varepsilon_{xx} = \frac{\partial u}{\partial x}, & \varepsilon_y &= \varepsilon_{yy} = \frac{\partial v}{\partial y} \quad \text{and} \quad \varepsilon_z &= \varepsilon_{zz} = \frac{\partial w}{\partial z}.
\end{align*}
\]

The three shear strain components are

\[
\begin{align*}
\varepsilon_{xy} &= \frac{\gamma_{xy}}{2} = \frac{1}{2} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right), & \varepsilon_{yz} &= \frac{\gamma_{yz}}{2} = \frac{1}{2} \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right) \quad \text{and} \quad \varepsilon_{xz} &= \frac{\gamma_{xz}}{2} = \frac{1}{2} \left( \frac{\partial w}{\partial x} + \frac{\partial u}{\partial z} \right)
\end{align*}
\]

Therefore the strain tensor is

\[
\varepsilon = \begin{bmatrix}
\varepsilon_{xx} & \varepsilon_{xy} & \varepsilon_{xz} \\
\varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\
\varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz}
\end{bmatrix}
\]

**Constitutive Equation**

The constitutive equations relate stresses and strains and in linear elasticity. We know from the Hook's law \( \sigma = E \varepsilon \)

Where \( E \) is modulus of elasticity
Chapter-2 Principal Stress and Strain  S K Mondal’s

It is known that \( \sigma_x \) produces a strain of \( \frac{\sigma_x}{E} \) in x-direction

and Poisson’s effect gives \(-\mu\frac{\sigma_x}{E}\) in y-direction and \(-\mu\frac{\sigma_x}{E}\) in z-direction.

Therefore we may write the generalized Hook’s law as

\[
\varepsilon_x = \frac{1}{E}\left[\sigma_x - \mu(\sigma_y + \sigma_z)\right], \quad \varepsilon_y = \frac{1}{E}\left[\sigma_y - \mu(\sigma_x + \sigma_z)\right] \quad \text{and} \quad \varepsilon_z = \frac{1}{E}\left[\sigma_z - \mu(\sigma_x + \sigma_y)\right]
\]

It is also known that the shear stress, \( \tau = G\gamma \), where \( G \) is the shear modulus and \( \gamma \) is shear strain.

We may thus write the three strain components as

\[
\gamma_{xy} = \frac{\tau_{xy}}{G}, \quad \gamma_{yz} = \frac{\tau_{yz}}{G} \quad \text{and} \quad \gamma_{zx} = \frac{\tau_{zx}}{G}
\]

In general each strain is dependent on each stress and we may write

\[
\begin{bmatrix}
\varepsilon_x \\
\varepsilon_y \\
\varepsilon_z \\
\gamma_{xy} \\
\gamma_{yz} \\
\gamma_{zx}
\end{bmatrix} = \begin{bmatrix}
K_{11} & K_{12} & K_{13} & K_{14} & K_{15} & K_{16} \\
K_{21} & K_{22} & K_{23} & K_{24} & K_{25} & K_{26} \\
K_{31} & K_{32} & K_{33} & K_{34} & K_{35} & K_{36} \\
K_{41} & K_{42} & K_{43} & K_{44} & K_{45} & K_{46} \\
K_{51} & K_{52} & K_{53} & K_{54} & K_{55} & K_{56} \\
K_{61} & K_{62} & K_{63} & K_{64} & K_{65} & K_{66}
\end{bmatrix} \begin{bmatrix}
\sigma_x \\
\sigma_y \\
\sigma_z \\
\tau_{xy} \\
\tau_{yz} \\
\tau_{zx}
\end{bmatrix}
\]

\[\therefore \text{ The number of elastic constant is 36 (For anisotropic materials)}\]

*For isotropic material*

\[
K_{11} = K_{22} = K_{33} = \frac{1}{E}, \quad K_{44} = K_{55} = K_{66} = \frac{1}{G}
\]

\[
K_{12} = K_{13} = K_{21} = K_{23} = K_{31} = K_{32} = -\frac{\mu}{E}
\]

*Rest of all elements in K matrix are zero.*

*For isotropic material only two independent elastic constant is there say \( E \) and \( G \).*

- **1-D Strain**

*Let us take an example:* A rod of cross sectional area \( A_o \) is loaded by a tensile force \( P \).

It’s stresses \( \sigma_x = \frac{P}{A_o}, \quad \sigma_y = 0, \quad \text{and} \quad \sigma_z = 0 \)

**1-D state of stress or Uni-axial state of stress**

\[
\sigma_y = \begin{bmatrix}
\sigma_{xx} & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{bmatrix} \quad \text{or} \quad \tau_y = \begin{bmatrix}
\tau_{xy} & 0 & 0 \\
0 & 0 & 0 \\
0 & 0 & 0
\end{bmatrix}
\]

Therefore strain components are
\[ \varepsilon_x = \frac{\sigma_x}{E} \; ; \; \varepsilon_y = -\mu \frac{\sigma_y}{E} = -\mu \varepsilon_x \; ; \; \text{and} \; \varepsilon_z = -\mu \frac{\sigma_z}{E} = -\mu \varepsilon_x \]

1-D state of strain or Uni-axial state of strain

\[ \varepsilon_y = \begin{pmatrix} \varepsilon_x & 0 & 0 \\ 0 & -\mu \varepsilon_x & 0 \\ 0 & 0 & -\mu \varepsilon_x \end{pmatrix} = \begin{pmatrix} \frac{\sigma_x}{E} & 0 & 0 \\ 0 & -\mu \frac{\sigma_y}{E} & 0 \\ 0 & 0 & -\mu \frac{\sigma_z}{E} \end{pmatrix} = \begin{pmatrix} \rho_{y} & 0 & 0 \\ 0 & q_{y} & 0 \\ 0 & 0 & q_{y} \end{pmatrix} \]

- 2-D Strain \((\sigma_z = 0)\)

(i) \[ \varepsilon_x = \frac{1}{E} \left[ \sigma_x - \mu \sigma_y \right] \]

(ii) \[ \varepsilon_y = \frac{1}{E} \left[ \sigma_y - \mu \sigma_x \right] \]

\[ \varepsilon_z = \frac{1}{E} \left[ \sigma_z + \sigma_y \right] \]

[Where, \( \varepsilon_x, \varepsilon_y, \varepsilon_z \) are strain component in X, Y, and Z axis respectively]

(iii) \[ \sigma_x = \frac{E}{1 - \mu^2} \left[ \varepsilon_x + \mu \varepsilon_y \right] \]

(ii) \[ \sigma_y = \frac{E}{1 - \mu^2} \left[ \varepsilon_y + \mu \varepsilon_x \right] \]

- 3-D Strain

(i) \[ \varepsilon_x = \frac{1}{E} \left[ \sigma_x - \mu \left( \sigma_y + \sigma_z \right) \right] \]

(ii) \[ \varepsilon_y = \frac{1}{E} \left[ \sigma_y - \mu \left( \sigma_z + \sigma_x \right) \right] \]

\[ \varepsilon_z = \frac{1}{E} \left[ \sigma_z - \mu \left( \sigma_x + \sigma_y \right) \right] \]

(ii) \[ \sigma_x = \frac{E}{(1 + \mu)(1 - 2\mu)} \left[ (1 - \mu) \varepsilon_x + \mu (\varepsilon_y + \varepsilon_z) \right] \]
Let us take an example: At a point in a loaded member, a state of plane stress exists and the strains are \( \varepsilon_x = 270 \times 10^{-6} \); \( \varepsilon_y = -90 \times 10^{-6} \) and \( \varepsilon_{xy} = 360 \times 10^{-6} \). If the elastic constants \( E \), \( \mu \) and \( G \) are 200 GPa, 0.25 and 80 GPa respectively.

Determine the normal stress \( \sigma_x \) and \( \sigma_y \) and the shear stress \( \tau_{xy} \) at the point.

**Answer:** We know that

\[
\varepsilon_x = \frac{1}{E} (\sigma_x - \mu \sigma_y) \\
\varepsilon_y = \frac{1}{E} (\sigma_y - \mu \sigma_x) \\
\varepsilon_{xy} = \frac{\tau_{xy}}{G}
\]

This gives \( \sigma_x = \frac{E}{1-\mu^2} (\varepsilon_x + \mu \varepsilon_y) = \frac{200 \times 10^9}{1-0.25^2} \left[ +270 \times 10^{-6} - 0.25 \times 90 \times 10^{-6} \right] \text{Pa} \\
= 52.8 \text{ MPa (i.e. tensile)} \)

and \( \sigma_y = \frac{E}{1-\mu^2} (\varepsilon_y + \mu \varepsilon_x) = \frac{200 \times 10^9}{1-0.25^2} \left[ -90 \times 10^{-6} + 0.25 \times 270 \times 10^{-6} \right] \text{Pa} = -4.8 \text{ MPa (i.e. compressive)} \)

and \( \tau_{xy} = \varepsilon_{xy} \cdot G = 360 \times 10^{-6} \times 80 \times 10^8 \text{ Pa} = 28.8 \text{ MPa} \)

### 2.12 An element subjected to strain components \( \varepsilon_x, \varepsilon_y \) & \( \frac{\gamma_{xy}}{2} \)

Consider an element as shown in the figure given. The strain component In X-direction is \( \varepsilon_x \), the strain component in Y-direction is \( \varepsilon_y \) and the shear strain component is \( \gamma_{xy} \).

Now consider a plane at an angle \( \theta \) with X-axis in this plane a normal strain \( \varepsilon_\theta \) and a shear strain \( \gamma_\theta \). Then

- \( \varepsilon_\theta = \frac{\varepsilon_x + \varepsilon_y}{2} + \frac{\varepsilon_x - \varepsilon_y}{2} \cos 2\theta + \frac{\gamma_{xy}}{2} \sin 2\theta \)
- \( \frac{\gamma_\theta}{2} = -\frac{\varepsilon_x - \varepsilon_y}{2} \sin 2\theta + \frac{\gamma_{xy}}{2} \cos 2\theta \)
We may find principal strain and principal plane for strains in the same process which we followed for stress analysis.

In the principal plane shear strain is zero.

Therefore principal strains are

\[
\varepsilon_{1,2} = \frac{\varepsilon_x + \varepsilon_y}{2} \pm \sqrt{\left(\frac{\varepsilon_x - \varepsilon_y}{2}\right)^2 + \left(\frac{\gamma_{xy}}{2}\right)^2}
\]

The angle of principal plane

\[
\tan 2\theta_p = \frac{\gamma_{xy}}{(\varepsilon_x - \varepsilon_y)}
\]

- Maximum shearing strain is equal to the difference between the 2 principal strains i.e

\[
(\gamma_{xy})_{\text{max}} = \varepsilon_1 - \varepsilon_2
\]

**Mohr's Circle for circle for Plain Strain**

We may draw Mohr's circle for strain following same procedure which we followed for drawing Mohr's circle in stress. Everything will be same and in the place of \(\sigma_x\) write \(\varepsilon_x\), the place of \(\sigma_y\) write \(\varepsilon_y\) and in place of \(\tau_{xy}\) write \(\gamma_{xy}/2\).
2.15 Volumetric Strain (Dilation)

- **Rectangular block,**
  \[
  \frac{\Delta V}{V_0} = \varepsilon_x + \varepsilon_y + \varepsilon_z
  \]

**Proof:** Volumetric strain
\[
\frac{\Delta V}{V_0} = \frac{V - V_0}{V_0} = \frac{L(1 + \varepsilon_x)(1 + \varepsilon_y)(1 + \varepsilon_z) - L^3}{L^3} = \varepsilon_x + \varepsilon_y + \varepsilon_z
\]
(neglecting second and third order term, as very small)

- **In case of prismatic bar,**

Volumetric strain, \( \frac{dv}{V} = \varepsilon(1 - 2\mu) \)

**Proof:** Before deformation, the volume of the bar, \( V = AL \)
After deformation, the length \( (L') = L(1 + \varepsilon) \)
and the new cross-sectional area \( (A') = A(1 - \mu\varepsilon)^2 \)
Therefore now volume \( (V') = A'L' = AL(1 + \varepsilon)(1 - \mu\varepsilon)^2 \)
\[ \Delta V \over V = \Delta L \over L = {\Delta L \over L} = \frac{\alpha (1+\varepsilon)(1-\mu\varepsilon)^2 - \alpha L}{AL} = \epsilon (1-2\mu) \]

\[ \Delta V \over V = \epsilon (1-2\mu) \]

- **Thin Cylindrical vessel**

\[ \varepsilon_1 = \text{Longitudinal strain} = \frac{\sigma_1}{E} - \mu \frac{\sigma_2}{E} = \frac{pr}{2Et} [1-2\mu] \]

\[ \varepsilon_2 = \text{Circumferential strain} = \frac{\sigma_2}{E} - \mu \frac{\sigma_1}{E} = \frac{pr}{2Et} [\varepsilon - \mu] \]

\[ \frac{\Delta V}{V_0} = \varepsilon_1 + 2 \varepsilon_2 = \frac{pr}{2Et} [5-4\mu] \]

- **Thin Spherical vessels**

\[ \varepsilon = \varepsilon_1 = \varepsilon_2 = \frac{pr}{2Et} [1-\mu] \]

\[ \frac{\Delta V}{V_0} = 3 \varepsilon = \frac{3pr}{2Et} [1-\mu] \]

- **In case of pure shear**

\[ \sigma_x = -\sigma_y = \tau \]

Therefore

\[ \varepsilon_x = \frac{\tau}{E} (1+\mu) \]

\[ \varepsilon_y = -\frac{\tau}{E} (1+\mu) \]

\[ \varepsilon_z = 0 \]

Therefore \( \varepsilon_y = \frac{dv}{v} = \varepsilon_x + \varepsilon_y + \varepsilon_z = 0 \)

### 2.16 Measurement of Strain

Unlike stress, strain can be measured directly. The most common way of measuring strain is by use of the **Strain Gauge**.

**Strain Gauge**
A strain gage is a simple device, comprising of a thin electric wire attached to an insulating thin backing material such as a bakelite foil. The foil is exposed to the surface of the specimen on which the strain is to be measured. The thin epoxy layer bonds the gauge to the surface and forces the gauge to shorten or elongate as if it were part of the specimen being strained.

A change in length of the gauge due to longitudinal strain creates a proportional change in the electric resistance, and since a constant current is maintained in the gauge, a proportional change in voltage. \( V = IR \).

The voltage can be easily measured, and through calibration, transformed into the change in length of the original gauge length, i.e. the longitudinal strain along the gauge length.

**Strain Gauge factor (G.F)**

\[
G_F = \frac{\Delta R}{R} \frac{\Delta l}{l} = \frac{\Delta R}{R} \varepsilon
\]

The strain gauge factor relates a change in resistance with strain.

**Strain Rosette**

The *strain rosette* is a device used to measure the state of strain at a point in a plane. It comprises *three or more* independent strain gauges, each of which is used to read normal strain at the same point but in a different direction.

The relative orientation between the three gauges is known as \( \alpha, \beta \) and \( \delta \).

The three measurements of normal strain provide sufficient information for the determination of the complete state of strain at the measured point in 2-D.

We have to find out \( \varepsilon_x, \varepsilon_y, \) and \( \gamma_{xy} \) form measured values \( \varepsilon_x, \varepsilon_y, \) and \( \varepsilon_z \).
The orientation of strain gauges is given in the figure. To relate strain we have to use the following formula.

\[ \varepsilon_\theta = \frac{\varepsilon_x + \varepsilon_y}{2} + \frac{\varepsilon_x - \varepsilon_y}{2} \cos 2\theta + \frac{\gamma_{xy}}{2} \sin 2\theta \]

We get

\[ \varepsilon_x = \frac{\varepsilon_x + \varepsilon_y}{2} + \frac{\varepsilon_x - \varepsilon_y}{2} \cos 2\alpha + \frac{\gamma_{xy}}{2} \sin 2\alpha \]

\[ \varepsilon_y = \frac{\varepsilon_x + \varepsilon_y}{2} + \frac{\varepsilon_x - \varepsilon_y}{2} \cos 2(\alpha + \beta) + \frac{\gamma_{xy}}{2} \sin 2(\alpha + \beta) \]

\[ \varepsilon_c = \frac{\varepsilon_x + \varepsilon_y}{2} + \frac{\varepsilon_x - \varepsilon_y}{2} \cos 2(\alpha + \beta + \delta) + \frac{\gamma_{xy}}{2} \sin 2(\alpha + \beta + \delta) \]

From this three equations and three unknown we may solve \( \varepsilon_x, \varepsilon_y, \text{and} \gamma_{xy} \)

- **Two standard arrangement of the of the strain rosette are as follows:**
  
  (i) **45° strain rosette or Rectangular strain rosette.**

  In the general arrangement above, put
  \( \alpha = 0^\circ; \beta = 45^\circ \text{ and} \delta = 45^\circ \)

  Putting the value we get
  - \( \varepsilon_x = \varepsilon_y \)
  - \( \varepsilon_b = \frac{\varepsilon_x + \varepsilon_y}{2} + \frac{\gamma_{xy}}{2} \)
  - \( \varepsilon_c = \varepsilon_y \)

  (ii) **60° strain rosette or Delta strain rosette**

  In the general arrangement above, put
  \( \alpha = 0^\circ; \beta = 60^\circ \text{ and} \delta = 60^\circ \)

  Putting the value we get
  - \( \varepsilon_x = \varepsilon_y \)
  - \( \varepsilon_b = \frac{\varepsilon_x + 3\varepsilon_y}{4} + \frac{\sqrt{3}}{4} \gamma_{xy} \)
  - \( \varepsilon_c = \frac{\varepsilon_x + 3\varepsilon_y}{4} - \frac{\sqrt{3}}{4} \gamma_{xy} \)

  Solving above three equation we get
  \( \varepsilon_x = \varepsilon_y \)
  \( \varepsilon_y = \frac{1}{3} (2 \varepsilon_b + 2 \varepsilon_c - \varepsilon_a) \)
  \( \gamma_{xy} = \frac{2}{\sqrt{3}} (\varepsilon_c - \varepsilon_b) \)
Stresses due to Pure Shear

GATE-1. A block of steel is loaded by a tangential force on its top surface while the bottom surface is held rigidly. The deformation of the block is due to [GATE-1992]

(a) Shear only  (b) Bending only  (c) Shear and bending  (d) Torsion

GATE-1. Ans. (a) It is the definition of shear stress. The force is applied tangentially it is not a point load so you cannot compare it with a cantilever with a point load at its free end.

GATE-2. A shaft subjected to torsion experiences a pure shear stress \( \tau \) on the surface. The maximum principal stress on the surface which is at 45\(^\circ\) to the axis will have a value [GATE-2003]

(a) \( \tau \cos 45^\circ \)  (b) \( 2\tau \cos 45^\circ \)  (c) \( \tau \cos^2 45^\circ \)  (d) \( 2\tau \sin 45^\circ \cos 45^\circ \)

GATE-2. Ans. (d) \[
\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2}\cos 2\theta + \tau_{xy}\sin 2\theta
\]

Here \( \sigma_x = \sigma_z = 0, \tau_{xy} = \tau, \theta = 45^\circ \)

GATE-3. The number of components in a stress tensor defining stress at a point in three dimensions is: [GATE-2002]

(a) 3  (b) 4  (c) 6  (d) 9

GATE-3. Ans. (d) It is well known that,

\( \tau_{xy} = \tau_{yx}, \tau_{xz} = \tau_{zx} \) and \( \tau_{yz} = \tau_{zy} \)

so that the state of stress at a point is given by six components \( \sigma_x, \sigma_y, \sigma_z \) and \( \tau_{xy}, \tau_{yz}, \tau_{zx} \)

Principal Stress and Principal Plane

GATE-4. A body is subjected to a pure tensile stress of 100 units. What is the maximum shear produced in the body at some oblique plane due to the above? [IES-2006]

(a) 100 units  (b) 75 units  (c) 50 units  (d) 0 unit

GATE-4. Ans. (c) \[
\tau_{max} = \frac{\sigma_x - \sigma_z}{2} = \frac{100 - 0}{2} = 50 \text{ units.}
\]

GATE-5. In a strained material one of the principal stresses is twice the other. The maximum shear stress in the same case is \( \tau_{max} \). Then, what is the value of the maximum principle stress? [IES 2007]

(a) \( \tau_{max} \)  (b) \( 2\tau_{max} \)  (c) \( 4\tau_{max} \)  (d) \( 8\tau_{max} \)

GATE-5. Ans. (c) \[
\tau_{max} = \frac{\sigma_1 - \sigma_2}{2}, \sigma_1 = 2\sigma_2 \text{ or } \tau_{max} = \frac{\sigma_2}{2} \text{ or } \sigma_1 = 2\sigma_2 = 4\tau_{max}
\]

GATE-6. A material element subjected to a plane state of stress such that the maximum shear stress is equal to the maximum tensile stress, would correspond to [IAS-1998]
GATE-6. Ans. (d) \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{\sigma_1 - (-\sigma_1)}{2} = \sigma_1 \)

GATE-7. A solid circular shaft is subjected to a maximum shearing stress of 140 MPa. The magnitude of the maximum normal stress developed in the shaft is:

(a) 140 MPa  
(b) 80 MPa  
(c) 70 MPa  
(d) 60 MPa  

GATE-7. Ans. (a) \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} \) Maximum normal stress will developed if \( \sigma_1 = -\sigma_2 = \sigma \)

GATE-8. The state of stress at a point in a loaded member is shown in the figure. The magnitude of maximum shear stress is [1MPa = 10 kg/cm²] [IAS 1994]

(a) 10 MPa  
(b) 30 MPa  
(c) 50 MPa  
(d) 100 MPa

GATE-8. Ans. (c) \( \tau_{\text{max}} = \frac{(\sigma_x - \sigma_y)^2}{2} + \tau_{xy} = \sqrt{\frac{(-40 - 40)^2}{2}} + 30^2 = 50 \text{ MPa} \)

GATE-9. A solid circular shaft of diameter 100 mm is subjected to an axial stress of 50 MPa. It is further subjected to a torque of 10 kNm. The maximum principal stress experienced on the shaft is closest to [GATE-2008]

(a) 41 MPa  
(b) 82 MPa  
(c) 164 MPa  
(d) 204 MPa

GATE-9. Ans. (b) Shear Stress \( (\tau) = \frac{16T}{\pi d^3} = \frac{16 \times 10000}{\pi \times (0.1)^3} Pa = 50.93 \text{ MPa} \)

Maximum principal Stress = \( \frac{\sigma_b}{2} + \sqrt{\left(\frac{\sigma_b}{2}\right)^2 + \tau^2} = 82 \text{ MPa} \)

GATE-10. In a bi-axial stress problem, the stresses in x and y directions are \( \sigma_x = 200 \text{ MPa} \) and \( \sigma_y = 100 \text{ MPa} \). The maximum principal stress in MPa, is: [GATE-2000]

(a) 50  
(b) 100  
(c) 150  
(d) 200

GATE-10. Ans. (d) \( \sigma_i = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \text{ if } \tau_{xy} = 0 \)
\[ \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = \sigma \]

GATE-11. The maximum principle stress for the stress state shown in the figure is
(a) \( \sigma \)    (b) 2 \( \sigma \)    (c) 3 \( \sigma \)    (d) 1.5 \( \sigma \)

GATE-11. Ans. (b) \( \sigma_x = \sigma, \quad \sigma_y = \sigma, \quad \tau_{xy} = 0 \)

\[ : \left(\sigma_1\right)_{\text{max}} = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = \frac{\sigma + \sigma - \sqrt{0^2 + \sigma^2}}{2} = 2\sigma \]

GATE-12. The normal stresses at a point are \( \sigma_x = 10 \text{ MPa} \) and, \( \sigma_y = 2 \text{ MPa} \); the shear stress at this point is 4 MPa. The maximum principal stress at this point is:
(a) 16 MPa (b) 14 MPa (c) 11 MPa (d) 10 MPa

GATE-12. Ans. (c) \[ \sigma_1 = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = \frac{10 + 2}{2} + \sqrt{\left(\frac{10 - 2}{2}\right)^2 + 4^2} = 11.66 \text{ MPa} \]

GATE-13. In a Mohr's circle, the radius of the circle is taken as:
(a) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \left(\tau_{xy}\right)^2} \)
(b) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \left(\tau_{xy}\right)^2} \)
(c) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 - \left(\tau_{xy}\right)^2} \)
(d) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \left(\tau_{xy}\right)^2} \)

Where, \( \sigma_x \) and \( \sigma_y \) are normal stresses along x and y directions respectively and \( \tau_{xy} \) is the shear stress.

GATE-13. Ans. (a)

GATE-14. A two dimensional fluid element rotates like a rigid body. At a point within the element, the pressure is 1 unit. Radius of the Mohr's circle, characterizing the state of stress at that point, is:
(a) 0.5 unit (b) 0 unit (c) 1 unit (d) 2 units

GATE-14. Ans. (b)
GATE-15. The Mohr’s circle of plane stress for a point in a body is shown. The design is to be done on the basis of the maximum shear stress theory for yielding. Then, yielding will just begin if the designer chooses a ductile material whose yield strength is:
(a) 45 MPa   (b) 50 MPa
(c) 90 MPa   (d) 100 MPa

GATE-15. Ans. (c)


given \ \sigma_1 = -10 \text{ MPa}, \ \sigma_2 = -100 \text{ MPa}

Maximum shear stress theory gives 
\[ r_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{\sigma_y}{2} \]
or \[ \sigma_1 - \sigma_2 = \sigma_y \Rightarrow \sigma_y = -10 - (-100) = 90 \text{ MPa} \]

GATE-16. The figure shows the state of stress at a certain point in a stressed body. The magnitudes of normal stresses in the x and y direction are 100 MPa and 20 MPa respectively. The radius of Mohr’s stress circle representing this state of stress is:
(a) 120   (b) 80
(c) 60    (d) 40

GATE-16. Ans. (c)

\[ \text{Data for Q17–Q18 are given below. Solve the problems and choose correct answers.} \]

The state of stress at a point “P” in a two dimensional loading is such that the Mohr’s circle is a point located at 175 MPa on the positive normal stress axis.

GATE-17. Determine the maximum and minimum principal stresses respectively from the Mohr’s circle
(a) + 175 MPa, −175 MPa   (b) +175 MPa, +175 MPa
(c) 0, −175 MPa   (d) 0, 0

GATE-17. Ans. (b)

\[ \sigma_1 = \sigma_2 = \sigma_x = \sigma_y = +175 \text{ MPa} \]

GATE-18. Determine the directions of maximum and minimum principal stresses at the point “P” from the Mohr’s circle

GATE-18. Ans. (b)
Principal stress and strain

GATE-18. Ans. (d) From the Mohr’s circle it will give all directions.

Principal strains

GATE-19. If the two principal strains at a point are 1000 × 10^{-6} and -600 × 10^{-6}, then the maximum shear strain is:

(a) 800 × 10^{-6}  
(b) 500 × 10^{-6}  
(c) 1600 × 10^{-6}  
(d) 200 × 10^{-6}

GATE-19. Ans. (c)

Stresses due to Pure Shear

IES-1. If a prismatic bar be subjected to an axial tensile stress $\sigma$, then shear stress induced on a plane inclined at $\theta$ with the axis will be:

(a) $\frac{\sigma}{2} \sin 2\theta$ 
(b) $\frac{\sigma}{2} \cos 2\theta$ 
(c) $\frac{\sigma}{2} \cos^2 \theta$ 
(d) $\frac{\sigma}{2} \sin^2 \theta$

IES-1. Ans. (a)

IES-2. In the case of bi-axial state of normal stresses, the normal stress on 45° plane is equal to

(a) The sum of the normal stresses  
(b) Difference of the normal stresses  
(c) Half the sum of the normal stresses  
(d) Half the difference of the normal stresses

IES-2. Ans. (c) $\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta$

At $\theta = 45^\circ$ and $\tau_{xy} = 0$; $\sigma_n = \frac{\sigma_x + \sigma_y}{2}$

IES-3. In a two-dimensional problem, the state of pure shear at a point is characterized by

(a) $\varepsilon_x = \varepsilon_y$ and $\gamma_{xy} = 0$  
(b) $\varepsilon_x = -\varepsilon_y$ and $\gamma_{xy} \neq 0$  
(c) $\varepsilon_x = 2\varepsilon_y$ and $\gamma_{xy} \neq 0$  
(d) $\varepsilon_x = 0.5\varepsilon_y$ and $\gamma_{xy} = 0$

IES-3. Ans. (b)

IES-4. Which one of the following Mohr’s circles represents the state of pure shear?

IES-4. Ans. (c)
For the state of stress of pure shear $\tau$, the strain energy stored per unit volume in the elastic, homogeneous isotropic material having elastic constants $E$ and $\nu$ will be:

\[
\begin{align*}
(a) & \quad \frac{\tau^2}{E} (1 + \nu) \\
(b) & \quad \frac{\tau^2}{2E} (1 + \nu) \\
(c) & \quad \frac{2\tau^2}{E} (1 + \nu) \\
(d) & \quad \frac{\tau^2}{2E} (2 + \nu)
\end{align*}
\]

IES-5. Ans. (a) $\sigma_1 = \tau$, $\sigma_2 = -\tau$, $\sigma_3 = 0$

\[
U = \frac{1}{2E} \left[ \tau^2 + (\tau)^2 - 2\mu\tau(\tau) \right] V = \frac{1 + \mu}{E} \tau^2 V
\]

IES-6. Assertion (A): If the state at a point is pure shear, then the principal planes through that point making an angle of 45° with plane of shearing stress carries principal stresses whose magnitude is equal to that of shearing stress.

Reason (R): Complementary shear stresses are equal in magnitude, but opposite in direction.

IES-6. Ans. (b)

IES-7. Assertion (A): Circular shafts made of brittle material fail along a helicoidally surface inclined at 45° to the axis (artery point) when subjected to twisting moment.

Reason (R): The state of pure shear caused by torsion of the shaft is equivalent to one of tension at 45° to the shaft axis and equal compression in the perpendicular direction.

IES-7. Ans. (a) Both A and R are true and R is correct explanation for A.

IES-8. A state of pure shear in a biaxial state of stress is given by

\[
\begin{align*}
(a) & \quad \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_2 \end{pmatrix} \\
(b) & \quad \begin{pmatrix} \sigma_1 & 0 \\ 0 & -\sigma_1 \end{pmatrix} \\
(c) & \quad \begin{pmatrix} \sigma_x & \tau_{xy} \\ \tau_{yx} & \sigma_y \end{pmatrix} \\
(d) & \quad \text{None of the above}
\end{align*}
\]

IES-8. Ans. (b) $\sigma_1 = \tau$, $\sigma_2 = -\tau$, $\sigma_3 = 0$

IES-9. The state of plane stress in a plate of 100 mm thickness is given as $\sigma_{xx} = 100$ N/mm², $\sigma_{yy} = 200$ N/mm², Young's modulus = 300 N/mm², Poisson's ratio = 0.3. The stress developed in the direction of thickness is:

(a) Zero   (b) 90 N/mm²   (c) 100 N/mm²   (d) 200 N/mm²

IES-9. Ans. (a)

IES-10. The state of plane stress at a point is described by $\sigma_x = \sigma_y = \sigma$ and $\tau_{xy} = 0$. The normal stress on the plane inclined at 45° to the x-plane will be:

\[
\begin{align*}
(a) & \quad \sigma = \frac{\sigma_x + \sigma_y}{2} \\
(b) & \quad \sqrt{2} \sigma \\
(c) & \quad \sqrt{3} \sigma \\
(d) & \quad 2\sigma
\end{align*}
\]

IES-10. Ans. (a) $\sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta + \tau_{xy} \sin 2\theta$

IES-11. Consider the following statements:

State of stress in two dimensions at a point in a loaded component can be completely specified by indicating the normal and shear stresses on

1. A plane containing the point
2. Any two planes passing through the point
3. Two mutually perpendicular planes passing through the point
Of these statements
(a) 1, and 3 are correct       (b) 2 alone is correct
(c) 1 alone is correct     (d) 3 alone is correct

IES-11. Ans. (d)

Principal Stress and Principal Plane

IES-12. A body is subjected to a pure tensile stress of 100 units. What is the maximum shear produced in the body at some oblique plane due to the above? [IES-2006]
(a) 100 units       (b) 75 units  (c) 50 units  (d) 0 unit

IES-12. Ans. (c) \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{100 - 0}{2} = 50 \text{ units.} \)

IES-13. In a strained material one of the principal stresses is twice the other. The maximum shear stress in the same case is \( \tau_{\text{max}} \). Then, what is the value of the maximum principle stress? [IES 2007]
(a) \( \tau_{\text{max}} \)       (b) \( 2 \tau_{\text{max}} \)  (c) \( 4 \tau_{\text{max}} \)  (d) \( 8 \tau_{\text{max}} \)

IES-13. Ans. (c) \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = 2\sigma_2 \) or \( \tau_{\text{max}} = \frac{\sigma_2}{2} \) or \( \sigma_1 = 2\sigma_2 = 4\tau_{\text{max}} \).

IES-14. In a strained material, normal stresses on two mutually perpendicular planes are \( \sigma_x \) and \( \sigma_y \) (both alike) accompanied by a shear stress \( \tau_{xy} \). One of the principal stresses will be zero, only if [IES-2006]
(a) \( \tau_{xy} = \frac{\sigma_x \times \sigma_y}{2} \)       (b) \( \tau_{xy} = \sigma_x \times \sigma_y \)  (c) \( \tau_{xy} = \sqrt{\sigma_x \times \sigma_y} \)  (d) \( \tau_{xy} = \sqrt{\sigma_x^2 + \sigma_y^2} \)

IES-14. Ans. (c) \( \sigma_{z2} = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \)

if \( \sigma_2 = 0 \) \( \Rightarrow \) \( \frac{\sigma_x + \sigma_y}{2} = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \)

or \( \frac{\sigma_x + \sigma_y}{2} = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \) or \( \tau_{xy} = \sqrt{\sigma_x \times \sigma_y} \)

IES-15. The principal stresses \( \sigma_1, \sigma_2 \) and \( \sigma_3 \) at a point respectively are 80 MPa, 30 MPa and -40 MPa. The maximum shear stress is: [IES-2001]
(a) 25 MPa       (b) 35 MPa  (c) 55 MPa  (d) 60 MPa

IES-15. Ans. (d) \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{80 - (-40)}{2} = 60 \text{ MPa} \)

IES-16. Plane stress at a point in a body is defined by principal stresses \( 3\sigma \) and \( \sigma \). The ratio of the normal stress to the maximum shear stresses on the plane of maximum shear stress is: [IES-2000]
(a) 1       (b) 2  (c) 3  (d) 4

IES-16. Ans. (b) \( \tan 2\theta = \frac{2\tau_{xy}}{\sigma_x - \sigma_y} \Rightarrow \theta = 0 \)

\( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{3\sigma - \sigma}{2} = \sigma \)

Major principal stress on the plane of maximum shear = \( \sigma_1 = \frac{3\sigma + \sigma}{2} = 2\sigma \)

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IES-17. Principal stresses at a point in plane stressed element are \( \sigma_x = \sigma_y = 500 \text{ kg/cm}^2 \).

Normal stress on the plane inclined at 45° to x-axis will be:  \[ \text{IES-1993} \]
(a) 0  \( \quad \) (b) 500 kg/cm\(^2\)  \( \quad \) (c) 707 kg/cm\(^2\)  \( \quad \) (d) 1000 kg/cm\(^2\)

IES-17. Ans. (b) When stresses are alike, then normal stress \( \sigma_n \) on plane inclined at angle 45° is

\[
\sigma_n = \sigma_x \cos^2 \theta + \sigma_y \sin^2 \theta = \sigma_x \left( \frac{1}{\sqrt{2}} \right)^2 + \sigma_x \left( \frac{1}{\sqrt{2}} \right)^2 = 500 \left[ \frac{1}{2} + \frac{1}{2} \right] = 500 \text{ kg/cm}^2
\]

IES-18. If the principal stresses corresponding to a two-dimensional state of stress are \( \sigma_1 \) and \( \sigma_2 \) is greater than \( \sigma_2 \) and both are tensile, then which one of the following would be the correct criterion for failure by yielding, according to the maximum shear stress criterion?  \[ \text{IES-1993} \]
(a) \( \frac{\sigma_1 - \sigma_2}{2} \)  \( \quad \) (b) \( \frac{\sigma_1}{2} \) \( \quad \) (c) \( \frac{\sigma_2}{2} \) \( \quad \) (d) \( \sigma_1 = 2\sigma_{yp} \)

IES-18. Ans. (a)

IES-19. For the state of plane stress. Shown the maximum and minimum principal stresses are:
(a) 60 MPa and 30 MPa
(b) 50 MPa and 10 MPa
(c) 40 MPa and 20 MPa
(d) 70 MPa and 30 MPa

IES-19. Ans. (d) \( \sigma_{12} = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left( \frac{\sigma_x - \sigma_y}{2} \right)^2 + \tau_{xy}^2} \)

\[
\sigma_{12} = \frac{50 + (-10)}{2} \pm \sqrt{\left( \frac{50 - 10}{2} \right)^2 + 40^2}
\]

\[
\sigma_{\text{max}} = 70 \quad \text{and} \quad \sigma_{\text{min}} = -30
\]

IES-20. Normal stresses of equal magnitude \( p \), but of opposite signs, act at a point of a strained material in perpendicular direction. What is the magnitude of the resultant normal stress on a plane inclined at 45° to the applied stresses?  \[ \text{IES-2005} \]
(a) 2 \( p \)  \( \quad \) (b) \( p/2 \)  \( \quad \) (c) \( p/4 \)  \( \quad \) (d) Zero

IES-20. Ans. (d) \( \sigma_n = \frac{p - p}{2} + \frac{p + p}{2} \cos 2\theta \)

\[
\sigma_n = \frac{p - p}{2} + \frac{p + p}{2} \cos 2 \times 45 = 0
\]

IES-21. A plane stressed element is subjected to the state of stress given by \( \sigma_x = \tau_{xy} = 100 \text{ kgf/cm}^2 \) and \( \sigma_y = 0 \). Maximum shear stress in the element is equal to  \[ \text{IES-1997} \]
(a) 50\( \sqrt{3} \) kgf/cm\(^2\)  \( \quad \) (b)100 kgf/cm\(^2\)  \( \quad \) (c) 50\( \sqrt{5} \) kgf/cm\(^2\)  \( \quad \) (d)150 kgf/cm\(^2\)

:\[ \text{IES-1997} \]
IES-21. Ans. (c) 
\[ (\sigma)_{12} = \frac{\sigma_x + 0}{2} \pm \sqrt{\left(\frac{\sigma_x + 0}{2}\right)^2 + \tau_{xy}^2} = 50 \pm 50\sqrt{5} \]

Maximum shear stress 
\[ \left(\frac{\sigma_1 - (\sigma)_{12}}{2}\right) = 50\sqrt{5} \]

IES-22. Match List I with List II and select the correct answer, using the codes given below the lists: [IES-1995]

List I (State of stress) | List II (Kind of loading)
--- | ---
A. | 1. Combined bending and torsion of circular shaft.
B. | 2. Torsion of circular shaft.
C. | 3. Thin cylinder subjected to internal pressure.
D. | 4. Tie bar subjected to tensile force.

Codes: A B C D
(a) 1 2 3 4
(b) 2 3 4 1
(c) 2 4 3 1
(d) 3 4 1 2

IES-22. Ans. (c)

**Mohr’s circle**

IES-23. Consider the Mohr’s circle shown above:
What is the state of stress represented by this circle?
(a) \( \sigma_x = \sigma_y \neq 0; \tau_{xy} = 0 \)
(b) \( \sigma_x + \sigma_y = 0; \tau_{xy} \neq 0 \)
(c) \( \sigma_x = 0; \sigma_y = \tau_{xy} \neq 0 \)
(d) \( \sigma_x \neq 0; \sigma_y = \tau_{xy} = 0 \)

IES-23. Ans. (b) It is a case of pure shear. Just put \( \sigma_1 = -\sigma_2 \)

IES-24. For a general two dimensional stress system, what are the coordinates of the centre of Mohr’s circle?

(a) \( \frac{\sigma_x - \sigma_y}{2}, 0 \)
(b) \( 0, \frac{\sigma_x + \sigma_y}{2} \)
(c) \( \frac{\sigma_x + \sigma_y}{2}, 0 \)
(d) \( 0, \frac{\sigma_x - \sigma_y}{2} \)

IES-24. Ans. (c)

IES-25. In a Mohr’s circle, the radius of the circle is taken as: [IES-2006; GATE-1993]

(a) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \)
(b) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \)
(c) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 - \tau_{xy}^2} \)
(d) \( \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \)
Chapter-2 Principal Stress and Strain S K Mondal’s

Where, \( \sigma_x \) and \( \sigma_y \) are normal stresses along x and y directions respectively and \( \tau_{xy} \) is the shear stress.

IES-25. Ans. (a)

IES-26. Maximum shear stress in a Mohr’s Circle [IES- 2008]
(a) Is equal to radius of Mohr’s circle
(b) Is greater than radius of Mohr’s circle
(c) Is less than radius of Mohr’s circle
(d) Could be any of the above

IES-26. Ans. (a)

IES-27. At a point in two-dimensional stress system \( \sigma_x = 100 \text{ N/mm}^2 \), \( \sigma_y = \tau_{xy} = 40 \text{ N/mm}^2 \).
What is the radius of the Mohr circle for stress drawn with a scale of: 1 cm = 10 N/mm²? [IES-2005]
(a) 3 cm  
(b) 4 cm  
(c) 5 cm  
(d) 6 cm
IES-27. Ans. (c) Radius of the Mohr circle

\[
\frac{\sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}}{10} = \sqrt{\left(\frac{100 - 40}{2}\right)^2 + 40^2} / 10 = 50 / 10 = 5 \text{ cm}
\]

IES-28. Consider a two dimensional state of stress given for an element as shown in the diagram given below: [IES-2004]

![Diagram of stress](image)

What are the coordinates of the centre of Mohr’s circle?

(a) (0, 0)  (b) (100, 200)  (c) (200, 100)  (d) (50, 0)

IES-28. Ans. (d) Centre of Mohr’s circle is 

\[
\left(\frac{\sigma_x + \sigma_y}{2}, \frac{200 - 100}{2}, 0\right) = (50, 0)
\]

IES-29. Two-dimensional state of stress at a point in a plane stressed element is represented by a Mohr circle of zero radius. Then both principal stresses

(a) Are equal to zero  
(b) Are equal to zero and shear stress is also equal to zero  
(c) Are of equal magnitude but of opposite sign  
(d) Are of equal magnitude and of same sign

IES-29. Ans. (d)

IES-30. Assertion (A): Mohr’s circle of stress can be related to Mohr’s circle of strain by some constant of proportionality. [IES-2002]

Reason (R): The relationship is a function of yield stress of the material.

(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true

IES-30. Ans. (c)

IES-31. When two mutually perpendicular principal stresses are unequal but like, the maximum shear stress is represented by 

(a) The diameter of the Mohr’s circle  
(b) Half the diameter of the Mohr’s circle  
(c) One-third the diameter of the Mohr’s circle  
(d) One-fourth the diameter of the Mohr’s circle

IES-31. Ans. (b)

IES-32. State of stress in a plane element is shown in figure I. Which one of the following figures-II is the correct sketch of Mohr’s circle of the state of stress? [IES-1993, 1996]

![Figure I](image)  
![Figure-II](image)

Figure-I  
Figure-II
Strain

IES-33. A point in a two dimensional state of strain is subjected to pure shearing strain of magnitude $\gamma_{xy}$ radians. Which one of the following is the maximum principal strain? [IES-2008]
(a) $\gamma_{xy}$  
(b) $\gamma_{xy}/\sqrt{2}$  
(c) $\gamma_{xy}/2$  
(d) $2\gamma_{xy}$

IES-33. Ans. (c)

IES-34. Assertion (A): A plane state of stress does not necessarily result into a plane state of strain as well. [IES-1996]
Reason (R): Normal stresses acting along X and Y directions will also result into normal strain along the Z-direction.
(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true

IES-34. Ans. (a)

Principal strains

IES-35. Principal strains at a point are $100 \times 10^{-6}$ and $-200 \times 10^{-6}$. What is the maximum shear strain at the point? [IES-2006]
(a) $300 \times 10^{-6}$  
(b) $200 \times 10^{-6}$  
(c) $150 \times 10^{-6}$  
(d) $100 \times 10^{-6}$

IES-35. Ans. (a) $\gamma_{\text{max}} = \varepsilon_1 - \varepsilon_2 = 100 - (-200) \times 10^{-6} = 300 \times 10^{-6}$

in strain $\frac{\gamma_{xy}}{2} = \frac{\varepsilon_x - \varepsilon_y}{2}$ and $r_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2}$ that is the difference.

IES-36. The principal strains at a point in a body, under biaxial state of stress, are $1000 \times 10^{-6}$ and $-600 \times 10^{-6}$. What is the maximum shear strain at that point? [IES-2009]
(a) $200 \times 10^{-6}$  
(b) $800 \times 10^{-6}$  
(c) $1000 \times 10^{-6}$  
(d) $1600 \times 10^{-6}$

IES-36. Ans. (d) $\frac{\varepsilon_x - \varepsilon_y}{2} = \frac{\phi_{xy}}{2} \quad \Rightarrow \quad \phi_{xy} = \varepsilon_x - \varepsilon_y = 1000 \times 10^{-6} - (-600 \times 10^{-6}) = 1600 \times 10^{-6}$

IES-37. The number of strain readings (using strain gauges) needed on a plane surface to determine the principal strains and their directions is: [IES-1994]
(a) 1  
(b) 2  
(c) 3  
(d) 4

IES-37. Ans. (c) Three strain gauges are needed on a plane surface to determine the principal strains and their directions.

Principal strain induced by principal stress

IES-38. The principal stresses at a point in two dimensional stress system are $\sigma_1$ and $\sigma_2$ and corresponding principal strains are $\varepsilon_1$ and $\varepsilon_2$. If $E$ and $\nu$ denote Young’s modulus and Poisson’s ratio, respectively, then which one of the following is correct? [IES-2008]
(a) $\sigma_1 = E\varepsilon_1$  
(b) $\sigma_1 = \frac{E}{1-\nu^2}[\varepsilon_1 + \nu \varepsilon_2]$  
(c) $\sigma_1 = \frac{E}{1-\nu^2}[\varepsilon_1 - \nu \varepsilon_2]$  
(d) $\sigma_1 = -E[a_0 \varepsilon_1 - \varepsilon_2]$
IES-38. Ans. (b) 
\[ \varepsilon_1 = \frac{\sigma_1}{E} - \mu \frac{\sigma_2}{E} \quad \text{and} \quad \varepsilon_2 = \frac{\sigma_2}{E} - \mu \frac{\sigma_1}{E} \]
From these two equations eliminate \( \sigma_2 \).

Reason (R): Mohr's circle represents the transformation of second-order tensor.
(a) Both A and R are individually true and R is the correct explanation of A.
(b) Both A and R are individually true but R is NOT the correct explanation of A.
(c) A is true but R is false.
(d) A is false but R is true.
IES-39. Ans. (a)

Previous 20-Years IAS Questions

Stresses due to Pure Shear
IAS-1. On a plane, resultant stress is inclined at an angle of 45° to the plane. If the normal stress is 100 N/mm², the shear stress on the plane is: 
(a) 71.5 N/mm²  
(b) 100 N/mm²  
(c) 86.6 N/mm²  
(d) 120.8 N/mm²
IAS-1. Ans. (b)

We know \( \sigma = \sigma \cos^2 \theta \) and \( \tau = \sigma \sin \theta \cos \theta \)
\[ 100 = \sigma \cos^2 45 \quad \text{or} \quad \sigma = 200 \]
\[ \tau = 200 \sin 45 \cos 45 = 100 \]

IAS-2. Biaxial stress system is correctly shown in
IAS-2. Ans. (c)

IAS-3. The complementary shear stresses of intensity \( \tau \) are induced at a point in the material, as shown in the figure. Which one of the following is the correct set of orientations of principal planes with respect to AB?
(a) 30° and 120°  
(b) 45° and 135°  
(c) 60° and 150°  
(d) 75° and 165°
IAS-3. Ans. (b)
Chapter-2 Principal Stress and Strain

IAS-3. Ans. (b) It is a case of pure shear so principal planes will be along the diagonal.

IAS-4. A uniform bar lying in the x-direction is subjected to pure bending. Which one of the following tensors represents the strain variations when bending moment is about the z-axis (p, q and r constants)?

\[
\begin{bmatrix}
py & 0 & 0 \\
0 & qy & 0 \\
0 & 0 & ry
\end{bmatrix}
\]

(a) \(\begin{bmatrix}
py & 0 & 0 \\
0 & qy & 0 \\
0 & 0 & ry
\end{bmatrix}\)  

(b) \(\begin{bmatrix}
py & 0 & 0 \\
0 & qy & 0 \\
0 & 0 & ry
\end{bmatrix}\)

(c) \(\begin{bmatrix}
py & 0 & 0 \\
0 & py & 0 \\
0 & 0 & py
\end{bmatrix}\)

(d) \(\begin{bmatrix}
py & 0 & 0 \\
0 & qy & 0 \\
0 & 0 & qy
\end{bmatrix}\)

IAS-4. Ans. (d) Stress in x direction = \(\sigma_x\)

Therefore \(\varepsilon_x = \frac{\sigma_x}{E}\), \(\varepsilon_y = -\mu \frac{\sigma_y}{E}\), \(\varepsilon_z = -\mu \frac{\sigma_z}{E}\)

IAS-5. Assuming \(E = 160\) GPa and \(G = 100\) GPa for a material, a strain tensor is given as:

\[
\begin{bmatrix}
0.002 & 0.004 & 0.006 \\
0.004 & 0.003 & 0 \\
0.006 & 0 & 0
\end{bmatrix}
\]

The shear stress, \(\tau_{xy}\) is:

(a) 400 MPa  
(b) 500 MPa  
(c) 800 MPa  
(d) 1000 MPa

IAS-5. Ans. (c)

\[
\begin{bmatrix}
\varepsilon_{xx} & \varepsilon_{xy} & \varepsilon_{xz} \\
\varepsilon_{yx} & \varepsilon_{yy} & \varepsilon_{yz} \\
\varepsilon_{zx} & \varepsilon_{zy} & \varepsilon_{zz}
\end{bmatrix}
\]

and \(\varepsilon_{xy} = \frac{\gamma_{xy}}{2}\)

\(\tau_{xy} = G \gamma_{xy} = 100 \times 10^3 \times (0.004 \times 2)\) MPa = 800MPa

**Principal Stress and Principal Plane**

IAS-6. A material element subjected to a plane state of stress such that the maximum shear stress is equal to the maximum tensile stress, would correspond to

\[
\begin{align*}
\sigma_1 &= \frac{\sigma_1 - \sigma_2}{2} = \frac{\sigma_1 - (-\sigma_1)}{2} = \sigma_1 \\
\sigma_2 &= \frac{\sigma_1 + \sigma_2}{2} \\
\end{align*}
\]

IAS-6. Ans. (d) \(\tau_{max} = \frac{\sigma_1 - \sigma_2}{2} = \frac{\sigma_1 - (-\sigma_1)}{2} = \sigma_1\)

IAS-7. A solid circular shaft is subjected to a maximum shearing stress of 140 MPa. The magnitude of the maximum normal stress developed in the shaft is:

IAS-7. [IAS-1995]
Chapter-2 Principal Stress and Strain

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(a) 140 MPa  (b) 80 MPa  (c) 70 MPa  (d) 60 MPa

IAS-7. Ans. (a) \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} \) Maximum normal stress will developed if \( \sigma_1 = -\sigma_2 = \sigma \)

IAS-8. The state of stress at a point in a loaded member is shown in the figure. The magnitude of maximum shear stress is [1 MPa = 10 kg/cm²] [IAS 1994]
(a) 10 MPa  (b) 30 MPa  (c) 50 MPa  (d) 100 MPa

\[ \sigma_x = -40 \text{ MPa} \]
\[ \sigma_y = 40 \text{ MPa} \]
\[ \tau_{xy} = 30 \text{ MPa} \]
\[ \sigma_z = 40 \text{ MPa} \]

IAS-8. Ans. (c) \( \tau_{\text{max}} = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = \sqrt{\left(\frac{-40 - 40}{2}\right)^2 + 30^2} = 50 \text{ MPa} \)

IAS-9. A horizontal beam under bending has a maximum bending stress of 100 MPa and a maximum shear stress of 20 MPa. What is the maximum principal stress in the beam? [IAS-2004]
(a) 20 (b) 50 (c) 50 + \( \sqrt{2900} \) (d) 100

IAS-9. Ans. (c) \( \sigma_b = 100 \text{ MPa} \quad \tau = 20 \text{ MPa} \)

\[ \sigma_{b,1,2} = \frac{\sigma_b}{2} + \sqrt{\left(\frac{\sigma_b}{2}\right)^2 + \tau^2} \]

\[ \sigma_{1,2} = \frac{\sigma_b}{2} + \sqrt{\left(\frac{\sigma_b}{2}\right)^2 + \tau^2} = \frac{100}{2} + \sqrt{\left(\frac{100}{2}\right)^2 + 20^2} = \left(50 + \sqrt{2900}\right) \text{ MPa} \]

IAS-10. When the two principal stresses are equal and like: the resultant stress on any plane is: [IAS-2002]
(a) Equal to the principal stress  (b) Zero  (c) One half the principal stress  (d) One third of the principal stress

IAS-10. Ans. (a) \( \sigma_n = \frac{\sigma_x + \sigma_y}{2} + \frac{\sigma_x - \sigma_y}{2} \cos 2\theta \)

[We may consider this as \( \tau_{xy} = 0 \)] \( \sigma_x = \sigma_y = \sigma \) (say) \( \sigma_n = \sigma \) for any plane

IAS-11. Assertion (A): When an isotropic, linearly elastic material is loaded biaxially, the directions of principal stressed are different from those of principal strains. [IAS-2001]
Reason (R): For an isotropic, linearly elastic material the Hooke's law gives only two independent material properties.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-11. Ans. (d) They are same.
IAS-12. Principal stress at a point in a stressed solid are 400 MPa and 300 MPa respectively. The normal stresses on planes inclined at 45° to the principal planes will be: [IAS-2000]
(a) 200 MPa and 500 MPa
(b) 350 MPa on both planes
(c) 100 MPa and 600 MPa
(d) 150 MPa and 550 MPa

IAS-12. Ans. (b)

\[ \sigma_n = \left( \frac{\sigma_x + \sigma_y}{2} \right) + \left( \frac{\sigma_x - \sigma_y}{2} \right) \cos 2\theta = \frac{400 + 300}{2} + \frac{400 - 300}{2} \cos 2 \times 45^\circ = 350 \text{MPa} \]

IAS-13. The principal stresses at a point in an elastic material are 60 N/mm² tensile, 20 N/mm² tensile and 50 N/mm² compressive. If the material properties are: \( \mu = 0.35 \) and \( E = 105 \text{N/mm}^2 \), then the volumetric strain of the material is: [IAS-1997]
(a) \( 9 \times 10^{-5} \)
(b) \( 3 \times 10^{-4} \)
(c) \( 10.5 \times 10^{-5} \)
(d) \( 21 \times 10^{-5} \)

IAS-13. Ans. (a)

\[ \varepsilon_x = \frac{\sigma_x}{E} - \mu \left( \frac{\sigma_y + \sigma_z}{E} \right), \quad \varepsilon_y = \frac{\sigma_y}{E} - \mu \left( \frac{\sigma_x + \sigma_z}{E} \right) \quad \text{and} \quad \varepsilon_z = \frac{\sigma_z}{E} - \mu \left( \frac{\sigma_x + \sigma_y}{E} \right) \]

\[ \varepsilon_v = \varepsilon_x + \varepsilon_y + \varepsilon_z = \frac{\sigma_x + \sigma_y + \sigma_z}{E} - 2\mu \left( \frac{\sigma_x + \sigma_y + \sigma_z}{E} \right) \]

\[ = \left( 1 - 2\mu \right) \left( \frac{\sigma_x + \sigma_y + \sigma_z}{E} \right) = \left( \frac{60 + 20 - 50}{105} \right)(1 - 2 \times 0.35) = 9 \times 10^{-5} \]

Mohr's circle

IAS-14. Match List-I (Mohr’s Circles of stress) with List-II (Types of Loading) and select the correct answer using the codes given below the lists: [IAS-2004]

<table>
<thead>
<tr>
<th>List-I (Mohr's Circles of Stress)</th>
<th>List-II (Types of Loading)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A.</td>
<td>1. A shaft compressed all round by a hub</td>
</tr>
<tr>
<td>B.</td>
<td>2. Bending moment applied at the free end of a cantilever</td>
</tr>
<tr>
<td>C.</td>
<td>3. Shaft under torsion</td>
</tr>
<tr>
<td>D.</td>
<td>4. Thin cylinder under pressure</td>
</tr>
<tr>
<td>5. Thin spherical shell under internal pressure</td>
<td></td>
</tr>
</tbody>
</table>

Codes: A B C D
(a) 5 4 3 2
(b) 2 4 1 3
(c) 4 3 2 5
(d) 2 3 1 5

IAS-14. Ans. (d)
Chapter-2 Principal Stress and Strain

IAS-15. The resultant stress on a certain plane makes an angle of 20° with the normal to the plane. On the plane perpendicular to the above plane, the resultant stress makes an angle of θ with the normal. The value of θ can be: [IAS-2001]
(a) 0° or 20°  
(b) Any value other than 0° or 90°  
(c) Any value between 0° and 20°  
(d) 20° only
IAS-15. Ans. (b)

IAS-16. The correct Mohr's stress-circle drawn for a point in a solid shaft compressed by a shrunken fit hub is as (O-Origin and C-Centre of circle; OA = σ₁ and OB = σ₂) [IAS-2001]

IAS-16. Ans. (d)

IAS-17. A Mohr's stress circle is drawn for a body subjected to tensile stress $f_x$ and $f_y$ in two mutually perpendicular directions such that $f_x > f_y$. Which one of the following statements in this regard is NOT correct? [IAS-2000]
(a) Normal stress on a plane at 45° to $f_x$ is equal to $\frac{f_x + f_y}{2}$
(b) Shear stress on a plane at 45° to $f_x$ is equal to $\frac{f_x - f_y}{2}$
(c) Maximum normal stress is equal to $f_x$.
(d) Maximum shear stress is equal to $\frac{f_x + f_y}{2}$
IAS-17. Ans. (d) Maximum shear stress is $\frac{f_x - f_y}{2}$

IAS-18. For the given stress condition $\sigma_x = 2$ N/mm², $\sigma_y = 0$ and $\tau_{xy} = 0$, the correct Mohr's circle is: [IAS-1999]

IAS-18. Ans. (d) Centre $\left(\frac{\sigma_x + \sigma_x}{2}, 0\right) = \left(2 + 0\right) = (1, 0)$
radio $= \sqrt{\frac{\sigma_x - \sigma_x}{2} + \tau_{xy}^2} = \sqrt{\left(\frac{2 - 0}{2}\right)^2 + 0} = 1$

IAS-19. For which one of the following two-dimensional states of stress will the Mohr's stress circle degenerate into a point? [IAS-1996]
IAS-19. Ans. (c) Mohr’s circle will be a point.

\[
\text{Radius of the Mohr’s circle } = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} = 0 \quad \therefore \tau_{xy} = 0 \text{ and } \sigma_x = \sigma_y = \sigma
\]

**Principal strains**

IAS-20. In an axi-symmetric plane strain problem, let \(u\) be the radial displacement at \(r\). Then the strain components \(\varepsilon_r, \varepsilon_\theta, \gamma_{r\theta}\) are given by [IAS-1995]

(a) \[
\varepsilon_r = \frac{u}{r}, \varepsilon_\theta = \frac{\partial u}{\partial r}, \gamma_{r\theta} = \frac{\partial^2 u}{\partial r \partial \theta}
\]

(b) \[
\varepsilon_r = \frac{\partial u}{\partial r}, \varepsilon_\theta = \frac{u}{r}, \gamma_{r\theta} = 0
\]

(c) \[
\varepsilon_r = \frac{u}{r}, \varepsilon_\theta = \frac{\partial u}{\partial r}, \gamma_{r\theta} = 0
\]

(d) \[
\varepsilon_r = \frac{\partial u}{\partial r}, \varepsilon_\theta = \frac{\partial u}{\partial \theta}, \gamma_{r\theta} = \frac{\partial^2 u}{\partial r \partial \theta}
\]

IAS-20. Ans. (b)

Reason (R): Magnitude of strains in the perpendicular directions of applied stress is smaller than that in the direction of applied stress. [IAS-2004]

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-21. Ans. (b)

IAS-22. Assertion (A): A plane state of stress will, in general, not result in a plane state of strain. [IAS-2002]
Reason (R): A thin plane lamina stretched in its own plane will result in a state of plane strain.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-22. Ans. (c) R is false. Stress in one plane always induce a lateral strain with its orthogonal plane.
Previous Conventional Questions with Answers

Conventional Question IES-1999
Question: What are principal in planes?
Answer: The planes which pass through the point in such a manner that the resultant stress across them is totally a normal stress are known as principal planes. No shear stress exists at the principal planes.

Conventional Question IES-2009
Q. The Mohr’s circle for a plane stress is a circle of radius R with its origin at +2R on \( \sigma \) axis. Sketch the Mohr’s circle and determine \( \sigma_{\max}, \sigma_{\min}, \sigma_{av}, (\tau_{xy})_{\max} \) for this situation. [2 Marks]

Ans. Here \( \sigma_{\max} = 3R \)
\( \sigma_{\min} = R \)
\( \sigma_{av} = \frac{3R + R}{2} = 2R \)
and \( \tau_{xy} = \frac{\sigma_{\max} - \sigma_{\min}}{2} = \frac{3R - R}{2} = R \)

Conventional Question IES-1999
Question: Direct tensile stresses of 120 MPa and 70 MPa act on a body on mutually perpendicular planes. What is the magnitude of shearing stress that can be applied so that the major principal stress at the point does not exceed 135 MPa? Determine the value of minor principal stress and the maximum shear stress.
Answer: Let shearing stress is ‘\( \tau \)’ MPa.
The principal stresses are
\( \sigma_{1,2} = \frac{120 + 70}{2} \pm \sqrt{\left( \frac{120 - 70}{2} \right)^2 + \tau^2} \)
Major principal stress is
\( \sigma_1 = \frac{120 + 70}{2} + \sqrt{\left( \frac{120 - 70}{2} \right)^2 + \tau^2} \)
\( = 135 \) (Given) \( \text{or}, \tau = 31.2 \text{MPa.} \)
Minor principal stress is
\[ \sigma_2 = \frac{120 + 70}{2} - \sqrt{\left(\frac{120 - 70}{2}\right)^2 + 31.2^2} = 55 \text{ MPa} \]
\[ \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{135 - 55}{2} = 40 \text{ MPa} \]

**Conventional Question IES-2009**

Q. The state of stress at a point in a loaded machine member is given by the principle stresses.
\[ \sigma_1 = 600 \text{ MPa}, \sigma_2 = 0 \text{ and } \sigma_3 = -600 \text{ MPa} . \]
(i) What is the magnitude of the maximum shear stress?
(ii) What is the inclination of the plane on which the maximum shear stress acts with respect to the plane on which the maximum principle stress \( \sigma_1 \) acts?

Ans. (i) Maximum shear stress,
\[ \tau = \frac{\sigma_1 - \sigma_3}{2} = \frac{600 - (-600)}{2} = 600 \text{ MPa} \]
(ii) At \( \theta = 45^\circ \) max. shear stress occurs with \( \sigma_1 \) plane. Since \( \sigma_1 \) and \( \sigma_3 \) are principle stress does not contains shear stress. Hence max. shear stress is at \( 45^\circ \) with principle plane.

**Conventional Question IES-2008**

**Question:** A prismatic bar in compression has a cross-sectional area \( A = 900 \text{ mm}^2 \) and carries an axial load \( P = 90 \text{ kN} \). What are the stresses acts on
(i) A plane transverse to the loading axis;
(ii) A plane at \( \theta = 60^\circ \) to the loading axis?

**Answer:**
(i) From figure it is clear A plane transverse to loading axis, \( \theta = 0^\circ \)
\[ \sigma_n = \frac{P}{A} \cos^2 \theta = \frac{90000}{900} = 100 N/\text{mm}^2 \]
and \( \tau = \frac{P}{2A} \sin 2\theta = \frac{90000}{2 \times 900} \times \sin 0^0 = 0 \text{ N/mm}^2 \)

(iii) A plane at \( 60^\circ \) to loading axis,
\[ \theta = 60^\circ - 30^\circ = 30^\circ \]
\[ \sigma_n = \frac{P}{A} \cos^2 \theta = \frac{90000}{900} \times \cos^2 30^\circ = 75 N/\text{mm}^2 \]
\[ \tau = \frac{P}{2A} \sin 2\theta = \frac{90000}{2 \times 900} \times \sin 2 \times 60^\circ = 43.3 N/\text{mm}^2 \]

**Conventional Question IES-2001**

**Question:** A tension member with a cross-sectional area of 30 mm\(^2\) resists a load of 80 kN, Calculate the normal and shear stresses on the plane of maximum shear stress.

**Answer:**
\[ \sigma_n = \frac{P}{A} \cos^2 \theta \]
\[ \tau = \frac{P}{2A} \sin 2\theta \]
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For maximum shear stress sin2θ = 1, or, θ = 45°

\[
\left(\sigma_n\right) = \frac{80 \times 10^3}{30} \times \cos^2 45 = 1333\text{MPa} \quad \text{and} \quad \tau_{\text{max}} = \frac{P}{2A} = \frac{80 \times 10^3}{30 \times 2} = 1333\text{MPa}
\]

Conventional Question IES-2007

Question: At a point in a loaded structure, a pure shear stress state \( \tau = \pm 400 \text{ MPa} \) prevails on two given planes at right angles.

(i) What would be the state of stress across the planes of an element taken at +45° to the given planes?

(ii) What are the magnitudes of these stresses?

Answer:

(i) For pure shear

\[
\sigma_x = -\sigma_y; \quad \tau_{\text{max}} = \pm \sigma_y = \pm 400 \text{MPa}
\]

(ii) Magnitude of these stresses

\[
\sigma_n = \tau_{xy} \sin 2\theta = \tau_{xy} \sin 90^\circ = \tau_{xy} = 400 \text{MPa} \quad \text{and} \quad \tau = (-\tau_{xy} \cos 2\theta) = 0
\]

Conventional Question IAS-1997

Question: Draw Mohr's circle for a 2-dimensional stress field subjected to

(a) Pure shear (b) Pure biaxial tension (c) Pure uniaxial tension and (d) Pure uniaxial compression

Answer:

Mohr’s circles for 2-dimensional stress field subjected to pure shear, pure biaxial tension, pure uniaxial compression and pure uniaxial tension are shown in figure below:

Conventional Question IES-2003

Question: A Solid phosphor bronze shaft 60 mm in diameter is rotating at 800 rpm and transmitting power. It is subjected torsion only. An electrical resistance
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strain gauge mounted on the surface of the shaft with its axis at 45° to the shaft axis, gives the strain reading as $3.98 \times 10^{-4}$. If the modulus of elasticity for bronze is 105 GN/m$^2$ and Poisson’s ratio is 0.3, find the power being transmitted by the shaft. Bending effect may be neglected.

**Answer:**

Let us assume maximum shear stress on the cross-sectional plane MU is $\tau$. Then

Principal stress along, $\text{VM} = -\frac{1}{2}\sqrt{4\tau^2} = -\tau$ (compressive)

Principal stress along, $\text{LU} = \frac{1}{2}\sqrt{4\tau^2} = \tau$ (tensile)

Thus magnitude of the compressive strain along VM is

$$\varepsilon = \frac{\tau}{E} (1 + \mu) = 3.98 \times 10^{-4}$$

or

$$\tau = \frac{3.98 \times 10^{-4} \times (105 \times 10^9)}{(1 + 0.3)} = 32.15 \text{ MPa}$$

$\therefore$ Torque being transmitted ($T$) = $\tau \times \frac{\pi}{16} \times d^3$

$$= \left(32.15 \times 10^6\right) \times \frac{\pi}{16} \times 0.06^3 = 1363.5 \text{ Nm}$$

$\therefore$ Power being transmitted, $P = T \cdot \omega = T \cdot \left(\frac{2\pi N}{60}\right) = 1363.5 \times \left(\frac{2\pi \times 800}{60}\right) W = 114.23 \text{ kW}$

**Conventional Question IES-2002**

**Question:** The magnitude of normal stress on two mutually perpendicular planes, at a point in an elastic body are 60 MPa (compressive) and 80 MPa (tensile) respectively. Find the magnitudes of shearing stresses on these planes if the magnitude of one of the principal stresses is 100 MPa (tensile). Find also the magnitude of the other principal stress at this point.
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Answer: Above figure shows stress condition assuming shear stress is \( \tau_{xy} \).

Principal stresses

\[
\sigma_{1,2} = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]

or,\( \sigma_{1,2} = \frac{-60 + 80}{2} \pm \sqrt{\left(\frac{-60 - 80}{2}\right)^2 + \tau_{xy}^2} \)

or,\( \sigma_{1,2} = \frac{-60 + 80}{2} \pm \sqrt{\left(\frac{-60 - 80}{2}\right)^2 + \tau_{xy}^2} \)

To make principal stress 100 MPa we have to consider '+'.

\( \therefore \sigma_1 = 100 \text{ MPa} = 10 \pm \sqrt{70^2 + \tau_{xy}^2} \); or, \( \tau_{xy} = 56.57 \text{ MPa} \)

Therefore other principal stress will be

\( \sigma_2 = \frac{-60 + 80}{2} - \sqrt{\left(\frac{-60 - 80}{2}\right)^2 + (56.57)^2} \)

i.e. 80 MPa (compressive)

Conventional Question IES-2001

Question: A steel tube of inner diameter 100 mm and wall thickness 5 mm is subjected to a torsional moment of 1000 Nm. Calculate the principal stresses and orientations of the principal planes on the outer surface of the tube.

Answer: Polar moment of Inertia \( (J) = \frac{\pi}{32} [ (0.110)^4 - (0.100)^4 ] = 4.56 \times 10^{-6} m^4 \)

\[
\frac{T}{J} = \frac{\tau}{R} \text{ or } \frac{T.R}{J} = \frac{1000 \times (0.055)}{4.56 \times 10^{-6}} = 12.07 \text{ MPa}
\]

Now, \( \tan 2\theta_p = \frac{2\tau_{xy}}{\sigma_x - \sigma_y} = \infty \)

\( \therefore \theta_p = 45^0 \text{ or } 135^0 \)

\( \therefore \sigma_1 = \tau_{xy} \sin 2\theta = 12.07 \times \sin 90^0 \)

\( = 12.07 \text{ MPa} \)

\( \text{and } \sigma_2 = 12.07 \sin 270^0 \)

\( = -12.07 \text{ MPa} \)

Conventional Question IES-2000

Question: At a point in a two dimensional stress system the normal stresses on two mutually perpendicular planes are \( \sigma_x \) and \( \sigma_y \) and the shear stress is \( \tau_{xy} \). At what value of shear stress, one of the principal stresses will become zero?

Answer: Two principal stresses are

\[
\sigma_{1,2} = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]
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Considering (-)ive sign it may be zero

\[
\sigma_x + \sigma_y = \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \quad \text{or,} \quad \sigma_x + \sigma_y = \left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2
\]

\[\tau_{xy} = \left(\frac{\sigma_x - \sigma_y}{2}\right)^2 \text{ or, } \tau_{xy} = \sigma_x \sigma_y \text{ or, } \tau_{xy} = \pm \sqrt{\sigma_x \sigma_y}
\]

**Conventional Question IES-1996**

**Question:** A solid shaft of diameter 30 mm is fixed at one end. It is subject to a tensile force of 10 kN and a torque of 60 Nm. At a point on the surface of the shaft, determine the principal stresses and the maximum shear stress.

**Answer:** Given: D = 30 mm = 0.03 m; P = 10 kN; T = 60 Nm

Principal stresses \((\sigma_1, \sigma_2)\) and maximum shear stress \((\tau_{\text{max}})\):

Tensile stress \(\sigma_1 = \sigma_x = \frac{10 \times 10^3}{\pi \times 0.03^2} = 14.15 \times 10^6 \text{ N/m}^2 \text{ or } 14.15 \text{ MN/m}^2
\]

As per torsion equation, \(\frac{T}{J} = \frac{\tau}{R}\)

\[\therefore \text{Shear stress, } \tau = \frac{TR}{J} = \frac{TR}{\pi \times \left(\frac{D}{2}\right)^4} = \frac{60 \times 0.015}{\pi \times (0.03)^4} = 11.32 \times 10^6 \text{ N/m}^2
\]

or 11.32 MN/m²

The principal stresses are calculated by using the relations:

\[\sigma_{1,2} = \left(\frac{\sigma_x + \sigma_y}{2}\right) \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]

Here \(\sigma_x = 14.15 \text{ MN/m}^2, \sigma_y = 0; \tau_{xy} = \tau = 11.32 \text{ MN/m}^2
\]

\[\therefore \sigma_{1,2} = \left(\frac{14.15}{2}\right) \pm \sqrt{\left(\frac{14.15}{2}\right)^2 + (11.32)^2}
\]

\[= 7.07 \pm 13.35 = 20.425 \text{ MN/m}^2, -6.275 \text{ MN/m}^2
\]

Hence, major principal stress, \(\sigma_2 = 20.425 \text{ MN/m}^2 \text{ (tensile)}
\]

Minor principal stress, \(\sigma_1 = 6.275 \text{ MN/m}^2 \text{ (compressive)}
\]

Maximum shear stress, \(\tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{24.425 - (-6.275)}{2} = 13.35 \text{ mm/m}^2
\]

**Conventional Question IES-2000**

**Question:** Two planes AB and BC which are at right angles are acted upon by tensile stress of 140 N/mm² and a compressive stress of 70 N/mm² respectively and also by stress 35 N/mm². Determine the principal stresses and principal planes. Find also the maximum shear stress and planes on which they act. Sketch the Mohr circle and mark the relevant data.
**Answer:**

Given

- \( \sigma_x = 140 \text{MPa (tensile)} \)
- \( \sigma_y = -70 \text{MPa (compressive)} \)
- \( \tau_{xy} = 35 \text{MPa} \)

Principal stresses; \( \sigma_1, \sigma_2 \),

\[
\sigma_{1,2} = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}
\]

\[
= \frac{140 - 70}{2} \pm \sqrt{\left(\frac{140 + 70}{2}\right)^2 + 35^2} = 35 \pm 110.7
\]

Therefore \( \sigma_1 = 145.7 \text{MPa} \) and \( \sigma_2 = -75.7 \text{MPa} \)

Position of Principal planes \( \theta_1, \theta_2 \)

\[
\tan 2\theta_p = \frac{2\tau_{xy}}{\sigma_x - \sigma_y} = \frac{2 \times 35}{140 + 70} = 0.3333
\]

Maximum shear stress, \( \tau_{max} = \frac{\sigma_1 - \sigma_2}{2} = \frac{145 + 75.7}{2} = 110.7 \text{MPa} \)

Mohr circle:

- \( OL = \sigma_x = 140 \text{MPa} \)
- \( OM = \sigma_y = -70 \text{MPa} \)
- \( SM = LT = \tau_{xy} = 35 \text{MPa} \)

Joining ST that cuts at 'N'

- \( SN = NT = \text{radius of Mohr circle} = 110.7 \text{MPa} \)
- \( OV = \sigma_1 = 145.7 \text{MPa} \)
- \( OV = \sigma_2 = -75.7 \text{MPa} \)

---

**Conventional Question IES-2010**

**Q6.** The data obtained from a rectangular strain gauge rosette attached to a stressed steel member are \( \varepsilon_0 = -220 \times 10^{-6}, \varepsilon_{45} = 120 \times 10^{-6}, \) and \( \varepsilon_{90} = 220 \times 10^{-6} \). Given that the value of \( E = 2 \times 10^5 \text{N/mm}^2 \) and Poisson's Ratio \( \mu = 0.3 \), calculate the values of principal stresses acting at the point and their directions. [10 Marks]

**Ans.**

A rectangular strain gauge rosette strain

- \( \varepsilon_0 = -220 \times 10^{-6} \)
- \( \varepsilon_{45} = 120 \times 10^{-6} \)
- \( \varepsilon_{90} = 220 \times 10^{-6} \)

\( E = 2 \times 10^{11} \text{N/m}^2 \) poisson ratio \( \mu = 0.3 \)

Find out principal stress and their direction.

Let \( e_a = \varepsilon_0, e_c = \varepsilon_{90} \) and \( e_b = \varepsilon_{45} \)

We know that principal strain are

\[
\varepsilon_{12} = \frac{e_a + e_b}{2} \sqrt{\left(\varepsilon_a - \varepsilon_c\right)^2 + (\varepsilon_b - \varepsilon_c)^2}
\]

\[
\Rightarrow \frac{-220 \times 10^{-6} + 120 \times 10^{-6}}{2} \pm \frac{1}{\sqrt{2}} \sqrt{\left((-220 - 120) + 10^{-6}\right)^2 + \left((120 - 220)10^{-6}\right)^2}
\]

\[
\Rightarrow -50 \times 10^{-6} \pm \frac{1}{\sqrt{2}} \times 354.40 \times 10^{-6}
\]
\[ \varepsilon_{12} = -50 \times 10^{-6} \pm 250.6 \times 10^{-6} \]
\[ \varepsilon_1 = 2.01 \times 10^{-4} \]
\[ \varepsilon_2 = -3.01 \times 10^{-4} \]

Direction can be find out:

\[ \tan 2\theta_{pe} = \frac{2\varepsilon_b - \varepsilon_a - \varepsilon_c}{\varepsilon_c - \varepsilon_a} = \frac{2 \times 120 \times 10^{-6}}{220 \times 10^{-6} + 220 \times 10^{-6}} \]

\[ \Rightarrow \frac{240}{440} = 0.55 \]
\[ 2\theta_{pe} = 28.81^\circ \]

\( \theta_{pe} = 14.45^\circ \) clockwise form principal strain \( t_1 \)

Principal stress:

\[ \sigma_1 = \frac{E(\varepsilon_1 + \mu \varepsilon_2)}{1 - \mu^2} = \frac{2 \times 10^{11} \left(2 + 0.3(-3) \times 10^{-4}\right)}{1 - 0.3^2} \]

\[ = 241.78 \times 10^5 \text{ N/m}^2 \]

\[ = 527.47 \times 10^5 \text{ N/m}^2 \]

**Conventional Question IES-1998**

**Question:** When using strain-gauge system for stress/force/displacement measurements how are in-built magnification and temperature compensation achieved?

**Answer:**

(a) Through use of adjacent arm balancing of Wheat-stone bridge.

(b) By means of self temperature compensation by selected melt-gauge and dual element-gauge.

**Conventional Question AMIE-1998**

**Question:** A cylinder (500 mm internal diameter and 20 mm wall thickness) with closed ends is subjected simultaneously to an internal pressure of 0-60 MPa, bending moment 64000 Nm and torque 16000 Nm. Determine the maximum tensile stress and shearing stress in the wall.

**Answer:**

Given: \( d = 500 \text{ mm} = 0.5 \text{ m} \);
\( t = 20 \text{ mm} = 0.02 \text{ m} \);
\( p = 0.6 \text{ MPa} = 0.6 \text{ MN/m}^2 \);
\( M = 64000 \text{ Nm} = 0.064 \text{ MNm} \);
\( T = 16000 \text{ Nm} = 0.016 \text{ MNm} \).

Maximum tensile stress:

First let us determine the principle stresses \( \sigma_1 \) and \( \sigma_2 \) assuming this as a thin cylinder.

We know,

\[ \sigma_1 = \frac{pd}{2t} = \frac{0.6 \times 0.5}{2 \times 0.02} = 7.5 \text{ MN/m}^2 \]

and

\[ \sigma_2 = \frac{pd}{4t} = \frac{0.6 \times 0.5}{4 \times 0.02} = 3.75 \text{ MN/m}^2 \]

Next consider effect of combined bending moment and torque on the walls of the cylinder. Then the principal stresses \( \sigma'_1 \) and \( \sigma'_2 \) are given by
\[ \sigma_1' = \frac{16}{\pi d^3} \left[ M + \sqrt{M^2 + T^2} \right] \]

and \[ \sigma_2' = \frac{16}{\pi d^3} \left[ M - \sqrt{M^2 + T^2} \right] \]

\[ \therefore \sigma_1' = \frac{16}{\pi \times (0.5)^3} \left[ 0.064 + \sqrt{0.064^2 + 0.016^2} \right] = 5.29 \text{MN} / \text{m}^2 \]

and \[ \sigma_2' = \frac{16}{\pi \times (0.5)^3} \left[ 0.064 - \sqrt{0.064^2 + 0.016^2} \right] = -0.08 \text{MN} / \text{m}^2 \]

Maximum shearing stress, \( \tau_{\text{max}} \): 

We Know, \[ \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} \]

\[ \sigma_2 = \sigma_2 + \sigma_1' = 3.75 - 0.08 = 3.67 \text{MN} / \text{m}^2 \ (\text{tensile}) \]

\[ \therefore \tau_{\text{max}} = \frac{12.79 - 3.67}{2} = 4.56 \text{MN} / \text{m}^2 \]
3. Moment of Inertia and Centroid

Theory at a Glance (for IES, GATE, PSU)

3.1 Centre of gravity
The centre of gravity of a body defined as the point through which the whole weight of a body may be assumed to act.

3.2 Centroid or Centre of area
The centroid or centre of area is defined as the point where the whole area of the figure is assumed to be concentrated.

3.3 Moment of Inertia (MOI)
- About any point the product of the force and the perpendicular distance between them is known as moment of a force or first moment of force.
- This first moment is again multiplied by the perpendicular distance between them to obtain second moment of force.
- In the same way if we consider the area of the figure it is called second moment of area or area moment of inertia and if we consider the mass of a body it is called second moment of mass or mass moment of Inertia.
- Mass moment of inertia is the measure of resistance of the body to rotation and forms the basis of dynamics of rigid bodies.
- Area moment of Inertia is the measure of resistance to bending and forms the basis of strength of materials.

3.4 Mass moment of Inertia (MOI)

\[
I = \sum_i m_i r_i^2
\]

- Notice that the moment of inertia \( I \) depends on the distribution of mass in the system.
- The furthest the mass is from the rotation axis, the bigger the moment of inertia.
- For a given object, the moment of inertia depends on where we choose the rotation axis.
- In rotational dynamics, the moment of inertia \( I \) appears in the same way that mass \( m \) does in linear dynamics.
Chapter-3 Moment of Inertia and Centroid

- **Solid disc or cylinder of mass M and radius R**, about perpendicular axis through its centre, \( I = \frac{1}{2} MR^2 \)

- Solid sphere of mass \( M \) and radius \( R \), about an axis through its centre, \( I = \frac{2}{5} M R^2 \)

- Thin **rod of mass M and length L**, about a perpendicular axis through its centre.
  \[
  I = \frac{1}{12} ML^2
  \]

- Thin rod of mass \( M \) and length \( L \), about a perpendicular axis through its end.
  \[
  I = \frac{1}{3} ML^2
  \]

### 3.5 Area Moment of Inertia (MOI) or Second moment of area

- To find the centroid of an area by the first moment of the area about an axis was determined (\( \int x \, dA \))

- Integral of the **second moment of area** is called moment of inertia (\( \int x^2 dA \))

- Consider the area \( A \)

- By definition, the moment of inertia of the differential area about the x and y axes are \( dI_{xx} \) and \( dI_{yy} \)

  - \( dI_{xx} = y^2 dA \quad I_{xx} = \int y^2 dA \)
  - \( dI_{yy} = x^2 dA \quad I_{yy} = \int x^2 dA \)

### 3.6 Parallel axis theorem for an area

The rotational inertia about any axis is the sum of second moment of inertia about a parallel axis through the C.G and total area of the body times square of the distance between the axes.

\[
I_{NN} = I_{CG} + Ah^2
\]
3.7 Perpendicular axis theorem for an area

If \( x, y, \text{ and } z \) are mutually perpendicular axes as shown, then

\[ I_{zz} = I_{xx} + I_{yy} \]

Z-axis is perpendicular to the plane of \( x – y \) and vertical to this page as shown in figure.

- To find the moment of inertia of the differential area about the pole (point of origin) or z-axis, \( r \) is used. (\( r \)) is the perpendicular distance from the pole to \( dA \) for the entire area

\[ J = \int r^2 \, dA = \int (x^2 + y^2) \, dA = I_{xx} + I_{yy} \]

(since \( r^2 = x^2 + y^2 \))

Where, \( J \) = polar moment of inertia

3.8 Moments of Inertia (area) of some common area

(i) MOI of Rectangular area

Moment of inertia about axis XX which passes through centroid.

Take an element of width ‘dy’ at a distance \( y \) from XX axis.

\[ \therefore \text{Area of the element (dA) = } b \times dy. \]

\[ \text{and Moment of Inertia of the element about XX axis } = dA \times y^2 = b \times y^2 \, dy \]

\[ \therefore \text{Total MOI about XX axis (Note it is area moment of Inertia)} \]

\[ I_{xx} = \int_{-h/2}^{h/2} b y^2 \, dy = 2 \int_{0}^{h/2} b y^2 \, dy = \frac{bh^3}{12} \]

Similarly, we may find, \( I_{yy} = \frac{bh^3}{12} \)

\[ \therefore \text{Polar moment of inertia (J) = } I_{xx} + I_{yy} = \frac{bh^3}{12} + \frac{bh^3}{12} \]
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If we want to know the MOI about an axis NN passing through the bottom edge or top edge.

Axis XX and NN are parallel and at a distance h/2.

Therefore \( I_{NN} = I_{xx} + \text{Area} \times (\text{distance})^2 \)

\[
\frac{bh^3}{12} + b \times h \times \left(\frac{h}{2}\right)^2 = \frac{bh^3}{3}
\]

Case-I: Square area

\[
I_{xx} = \frac{a^4}{12}
\]

Case-II: Square area with diagonal as axis

\[
I_{xx} = \frac{a^4}{12}
\]

Case-III: Rectangular area with a centrally rectangular hole

Moment of inertia of the area = moment of inertia of BIG rectangle – moment of inertia of SMALL rectangle

\[
I_{xx} = \frac{BH^3}{12} - \frac{bh^3}{12}
\]
Chapter-3  
Moment of Inertia and Centroid  

(ii) MOI of a Circular area  
The moment of inertia about axis XX this passes through the centroid. It is very easy to find polar moment of inertia about point ‘O’. Take an element of width ‘dr’ at a distance ‘r’ from centre. Therefore, the moment of inertia of this element about polar axis
\[ d(J) = d(I_{xx} + I_{yy}) = \text{area of ring} \times (\text{radius})^2 \]
or \[ d(J) = 2\pi r dr \times r^2 \]
Integrating both side we get
\[ J = \int 2\pi r^3 dr = \frac{\pi R^4}{2} = \frac{\pi D^4}{32} \]
Due to symmetry \( I_{xx} = I_{yy} \)
Therefore, \[ I_{xx} = I_{yy} = \frac{J}{2} = \frac{\pi D^4}{64} \]

\[ I_{xx} = I_{yy} = \frac{\pi D^4}{64} \quad \text{and} \quad J = \frac{\pi D^4}{32} \]

Case-I: Moment of inertia of a circular area with a concentric hole.  
Moment of inertia of the area = moment of inertia of BIG circle – moment of inertia of SMALL circle.
\[ I_{xx} = I_{yy} = \frac{\pi D^4}{64} - \frac{\pi d^4}{64} = \frac{\pi}{64} (D^4 - d^4) \]
and \[ J = \frac{\pi}{32} (D^4 - d^4) \]

Case-II: Moment of inertia of a semi-circular area.
\[ I_{NN} = \frac{1}{2} \text{ of the moment of total circular lamina} \]
\[ = \frac{1}{2} \times \left( \frac{\pi D^4}{64} \right) = \frac{\pi D^4}{128} \]
We know that distance of CG from base is \[ \frac{4r}{3\pi} = \frac{2D}{3\pi} = h \text{ (say)} \]
i.e. distance of parallel axis XX and NN is (h) \[ \therefore \text{According to parallel axis theory} \]

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Moment of Inertia and Centroid

\[ I_{xx} = I_g + \text{Area} \times (\text{distance})^2 \]

or

\[ \frac{\pi D^4}{128} = I_{xx} + \frac{1}{2} \left( \frac{\pi D^2}{4} \right) \times (h)^2 \]

or

\[ \frac{\pi D^4}{128} = I_{xx} + \frac{1}{2} \left( \frac{\pi D^2}{4} \right) \times \left( \frac{2D}{3\pi} \right) \]

or

\[ I_{xx} = 0.11R^4 \]

Case – III: Quarter circle area

\[ I_{xx} = \frac{1}{2} \times (0.11R^4) = 0.055R^4 \]

\[ I_{NN} = 0.055R^4 \]

I_{NN} = one half of the moment of Inertia of the Semi-circular area about NN.

\[ \therefore I_{NN} = \frac{1}{2} \times \frac{\pi D^4}{64} = \frac{\pi D^4}{128} \]

(iii) Moment of Inertia of a Triangular area

(a) Moment of Inertia of a Triangular area of a axis XX parallel to base and passes through C.G.

\[ I_{XX} = \frac{bh^3}{36} \]

(b) Moment of inertia of a triangle about an axis passes through base

\[ I_{NN} = \frac{bh^3}{12} \]
(iv) Moment of inertia of a thin circular ring:

Polar moment of Inertia

\[ J = R^2 \times \text{area of whole ring} \]

\[ = R^2 \times 2\pi Rt = 2\pi R^4 t \]

\[ I_{XX} = I_{YY} = \frac{J}{2} = \pi R^3 t \]

(v) Moment of inertia of an elliptical area

\[ I_{XX} = \frac{\pi ab^3}{4} \]

Let us take an example: An I-section beam of 100 mm wide, 150 mm depth flange and web of thickness 20 mm is used in a structure of length 5 m. Determine the Moment of Inertia (of area) of cross-section of the beam.

Answer: Carefully observe the figure below. It has sections with symmetry about the neutral axis.

We may use standard value for a rectangle about an axis passes through centroid. i.e. \( I = \frac{bh^3}{12} \).

The section can thus be divided into convenient rectangles for each of which the neutral axis passes through the centroid.

\[ I_{\text{Beam}} = I_{\text{Rectangle}} - I_{\text{Shaded area}} \]

\[ \begin{align*}
&= \left[ \frac{0.100 \times (0.150)^3}{12} + 2 \times \frac{0.40 \times 0.130^3}{12} \right] \text{m}^4 \\
&= 1.183 \times 10^{-4} \text{ m}^4
\end{align*} \]

3.9 Radius of gyration

Consider area \( A \) with moment of inertia \( I_{xx} \). Imagine that the area is concentrated in a thin strip parallel to
the \( x \) axis with equivalent \( I_{xx} \).

\[
I_{xx} = k_{xx}^2 A \quad \text{or} \quad k_{xx} = \sqrt{\frac{I_{xx}}{A}}
\]

\( k_{xx} \) = radius of gyration with respect to the \( x \) axis.

Similarly

\[
I_{yy} = k_{yy}^2 A \quad \text{or} \quad k_{yy} = \sqrt{\frac{I_{yy}}{A}}
\]

\[
J = k_o^2 A \quad \text{or} \quad k_o = \sqrt{\frac{J}{A}}
\]

\( k_o^2 = k_{xx}^2 + k_{yy}^2 \)

Let us take an example: Find radius of gyration for a circular area of diameter 'd' about central axis.

Answer:

We know that, \( I_{xx} = K_{xx}^2 A \)
or $K_{xx} = \sqrt{\frac{I_{xx}}{A}} = \sqrt{\frac{\pi d^4}{64}} = \frac{d}{4}$
OBJECTIVE QUESTIONS (GATE, IES, IAS)

Previous 20-Years GATE Questions

Moment of Inertia (Second moment of an area)

GATE-1. The second moment of a circular area about the diameter is given by (D is the diameter) [GATE-2003]

(a) $\frac{\pi D^4}{4}$  
(b) $\frac{\pi D^4}{16}$  
(c) $\frac{\pi D^4}{32}$  
(d) $\frac{\pi D^4}{64}$

GATE-1. Ans. (d)

GATE-2. The area moment of inertia of a square of size 1 unit about its diagonal is: [GATE-2001]

(a) $\frac{1}{3}$  
(b) $\frac{1}{4}$  
(c) $\frac{1}{12}$  
(d) $\frac{1}{6}$

GATE-2. Ans. (c) $I_{xx} = \frac{a^4}{12} = \frac{(1)^4}{12}$

Radius of Gyration

Data for Q3–Q4 are given below. Solve the problems and choose correct answers.

A reel of mass “m” and radius of gyration “k” is rolling down smoothly from rest with one end of the thread wound on it held in the ceiling as depicted in the figure. Consider the thickness of the thread and its mass negligible in comparison with the radius “r” of the hub and the reel mass “m”. Symbol “g” represents the acceleration due to gravity. [GATE-2003]
Chapter-3 Moment of Inertia and Centroid

GATE-3. The linear acceleration of the reel is:

(a) \( \frac{gr^2}{(r^2 + k^2)} \)  
(b) \( \frac{gk^2}{(r^2 + k^2)} \)  
(c) \( \frac{grk}{(r^2 + k^2)} \)  
(d) \( \frac{mgr^2}{(r^2 + k^2)} \)

GATE-3. Ans. (a) For downward linear motion \( mg - T = mf \), where \( f = \) linear tangential acceleration = \( r \alpha \), \( \alpha = \) rotational acceleration. Considering rotational motion \( Tr = I \alpha \).

or, \( T = mk^2 \times \frac{f}{r^2} \) therefore \( mg - T = mf \) gives \( f = \frac{gr^2}{(r^2 + k^2)} \)

GATE-4. The tension in the thread is:

(a) \( \frac{mgr^2}{(r^2 + k^2)} \)  
(b) \( \frac{mgrk}{(r^2 + k^2)} \)  
(c) \( \frac{mgk^2}{(r^2 + k^2)} \)  
(d) \( \frac{mg}{(r^2 + k^2)} \)

GATE-4. Ans. (c) \( T = mk^2 \times \frac{f}{r^2} = mk^2 \times \frac{gr^2}{r^2(r^2 + k^2)} = \frac{mgk^2}{(r^2 + k^2)} \)

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Previous 20-Years IES Questions

Centroid

IES-1. Assertion (A): Inertia force always acts through the centroid of the body and is directed opposite to the acceleration of the centroid.\,[IES-2001]
Reason (R): It has always a tendency to retard the motion.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-1. Ans. (c) It has always a tendency to oppose the motion not retard. If we want to retard a motion then it will want to accelerate.
**Chapter-3  Moment of Inertia and Centroid**

**Radius of Gyration**

IES-2. Figure shows a rigid body of mass \( m \) having radius of gyration \( k \) about its centre of gravity. It is to be replaced by an equivalent dynamical system of two masses placed at A and B. The mass at A should be:

(a) \( \frac{a \times m}{a + b} \)  
(b) \( \frac{b \times m}{a + b} \)  
(c) \( \frac{m}{3} \times \frac{a}{b} \)  
(d) \( \frac{m}{2} \times \frac{b}{a} \)

IES-2. Ans. (b)

IES-3. Force required to accelerate a cylindrical body which rolls without slipping on a horizontal plane (mass of cylindrical body is \( m \), radius of the cylindrical surface in contact with plane is \( r \), radius of gyration of body is \( k \) and acceleration of the body is \( a \)) is:

(a) \( m(k^2 / r^2 + 1)a \)  
(b) \( mk^2 / r^2 a \)  
(c) \( mk^2 a \)  
(d) \( mk^2 / r + 1 a \)

IES-3. Ans. (a)

IES-4. A body of mass \( m \) and radius of gyration \( k \) is to be replaced by two masses \( m_1 \) and \( m_2 \) located at distances \( h_1 \) and \( h_2 \) from the CG of the original body. An equivalent dynamic system will result, if

(a) \( h_1 + h_2 = k \)  
(b) \( h_1^2 + h_2^2 = k^2 \)  
(c) \( h_1 h_2 = k^2 \)  
(d) \( \sqrt{h_1 h_2} = k \)

IES-4. Ans. (c)

**Previous 20-Years IAS Questions**

**Radius of Gyration**

IAS-1. A wheel of centroidal radius of gyration 'k' is rolling on a horizontal surface with constant velocity. It comes across an obstruction of height 'h'. Because of its rolling speed, it just overcomes the obstruction. To determine \( v \), one should use the principle (s) of conservation of

(a) Energy  
(b) Linear momentum  
(c) Energy and linear momentum  
(d) Energy and angular momentum

IAS-1. Ans. (a)
**Previous Conventional Questions with Answers**

*Conventional Question IES-2004*

**Question:** When are I-sections preferred in engineering applications? Elaborate your answer.

**Answer:** I-section has large section modulus. It will reduce the stresses induced in the material. Since I-section has the considerable area are far away from the natural so its section modulus increased.
At first we try to understand what shear force is and what is bending moment?

We will not introduce any other co-ordinate system. We use general co-ordinate axis as shown in the figure. This system will be followed in shear force and bending moment diagram and in deflection of beam. Here downward direction will be negative i.e. negative Y-axis. Therefore downward deflection of the beam will be treated as negative.

Some books fix a co-ordinate axis as shown in the following figure. Here downward direction will be positive i.e. positive Y-axis. Therefore downward deflection of the beam will be treated as positive. As beam is generally deflected in downward directions and this co-ordinate system treats downward deflection as positive deflection.

Consider a cantilever beam as shown subjected to external load ‘P’. If we imagine this beam to be cut by a section X-X, we see that the applied force tend to displace the left-hand portion of the beam relative to the right hand portion, which is fixed in the wall. This tendency is resisted by internal forces between the two parts of the beam. At the cut section a resistance shear force (Vx) and a bending moment (Mx) is induced. This resistance shear force and the bending moment at the cut section is shown in the left hand and right hand portion of the cut beam.

Using the three equations of equilibrium

\[ \sum F_x = 0 , \sum F_y = 0 \text{ and } \sum M_i = 0 \]

We find that \( V_x = -P \) and \( M_x = -P \cdot x \)

In this chapter we want to show pictorially the...
variation of shear force and bending moment in a beam as a function of ‘x’ measured from one end of the beam.

Shear Force (V) ≡ equal in magnitude but opposite in direction to the algebraic sum (resultant) of the components in the direction perpendicular to the axis of the beam of all external loads and support reactions acting on either side of the section being considered.

Bending Moment (M) equal in magnitude but opposite in direction to the algebraic sum of the moments about (the centroid of the cross section of the beam) the section of all external loads and support reactions acting on either side of the section being considered.

What are the benefits of drawing shear force and bending moment diagram?
The benefits of drawing a variation of shear force and bending moment in a beam as a function of ‘x’ measured from one end of the beam is that it becomes easier to determine the maximum absolute value of shear force and bending moment. The shear force and bending moment diagram gives a clear picture in our mind about the variation of SF and BM throughout the entire section of the beam.

Further, the determination of value of bending moment as a function of ‘x’ becomes very important so as to determine the value of deflection of beam subjected to a given loading where we will use the formula, $EI \frac{dy}{dx^2} = M_x$.

4.2 Notation and sign convention

- **Shear force (V)**
  
  Positive Shear Force
  
  A shearing force having a downward direction to the right hand side of a section or upwards to the left hand of the section will be taken as ‘positive’. It is the usual sign conventions to be followed for the shear force. In some book followed totally opposite sign convention.
The upward direction shearing force which is on the left hand of the section XX is **positive** shear force.

The downward direction shearing force which is on the right hand of the section XX is **positive** shear force.

**Negative Shear Force**

A shearing force having an upward direction to the right hand side of a section or downwards to the left hand of the section will be taken as ‘negative’.

The downward direction shearing force which is on the left hand of the section XX is **negative** shear force.

The upward direction shearing force which is on the right hand of the section XX is **negative** shear force.

**Bending Moment (M)**

**Positive Bending Moment**

A bending moment causing concavity upwards will be taken as ‘positive’ and called as sagging bending moment.
If the bending moment of the left hand of the section XX is clockwise then it is a positive bending moment.

A bending moment causing concavity upwards will be taken as ‘positive’ and called as sagging bending moment.

Negative Bending Moment

If the bending moment of the left hand of the section XX is anti-clockwise then it is a negative bending moment.

A bending moment causing convexity upwards will be taken as ‘negative’ and called as hogging bending moment.

Way to remember sign convention

- Remember in the Cantilever beam both Shear force and BM are negative (−ive).

4.3 Relation between S.F ($V_x$), B.M. ($M_x$) & Load ($w$)

- $\frac{dV_x}{dx} = -w$ (load) The value of the distributed load at any point in the beam is equal to the slope of the shear force curve. (Note that the sign of this rule may change depending on the sign convention used for the external distributed load).

- $\frac{dM_x}{dx} = V_x$ The value of the shear force at any point in the beam is equal to the slope of the bending moment curve.
4.4 Procedure for drawing shear force and bending moment diagram

**Construction of shear force diagram**
- From the loading diagram of the beam constructed shear force diagram.
- First determine the reactions.
- Then the vertical components of forces and reactions are successively summed from the left end of the beam to preserve the mathematical sign conventions adopted. The shear at a section is simply equal to the sum of all the vertical forces to the left of the section.
- The shear force curve is continuous unless there is a point force on the beam. The curve then “jumps” by the magnitude of the point force (+ for upward force).
- When the successive summation process is used, the shear force diagram should end up with the previously calculated shear (reaction at right end of the beam). No shear force acts through the beam just beyond the last vertical force or reaction. If the shear force diagram closes in this fashion, then it gives an important check on mathematical calculations. i.e. The shear force will be zero at each end of the beam unless a point force is applied at the end.

**Construction of bending moment diagram**
- The bending moment diagram is obtained by proceeding continuously along the length of beam from the left hand end and summing up the areas of shear force diagrams using proper sign convention.
- The process of obtaining the moment diagram from the shear force diagram by summation is exactly the same as that for drawing shear force diagram from load diagram.
- The bending moment curve is continuous unless there is a point moment on the beam. The curve then “jumps” by the magnitude of the point moment (+ for CW moment).
- We know that a constant shear force produces a uniform change in the bending moment, resulting in straight line in the moment diagram. If no shear force exists along a certain portion of a beam, then it indicates that there is no change in moment takes place. We also know that \( \frac{dM}{dx} = V \) therefore, from the fundamental theorem of calculus the maximum or minimum moment occurs where the shear is zero.
- The bending moment will be zero at each free or pinned end of the beam. If the end is built in, the moment computed by the summation must be equal to the one calculated initially for the reaction.

4.5 Different types of Loading and their S.F & B.M Diagram

(i) A Cantilever beam with a concentrated load ‘P’ at its free end.
Chapter-4  
Bending Moment and Shear Force Diagram  
S K Mondal's

Shear force: 
At a section a distance x from free end consider the forces to the left, then \( V_x = -P \) (for all values of x) negative in sign i.e. the shear force to the left of the x-section are in downward direction and therefore negative.

Bending Moment: 
Taking moments about the section gives (obviously to the left of the section) \( M_x = -P.x \) (negative sign means that the moment on the left hand side of the portion is in the anticlockwise direction and is therefore taken as negative according to the sign convention) so that the maximum bending moment occurs at the fixed end i.e. \( M_{max} = -PL \) (at x = L)

(ii) A Cantilever beam with uniformly distributed load over the whole length
When a cantilever beam is subjected to a uniformly distributed load whose intensity is given w/ unit length.
Shear force: 
Consider any cross-section XX which is at a distance of x from the free end. If we just take the resultant of all the forces on the left of the X-section, then 
\( V_x = -w.x \) for all values of 'x'.
At x = 0, \( V_x = 0 \)
At x = L, \( V_x = -wL \) (i.e. Maximum at fixed end) 
Plotting the equation \( V_x = -w.x \), we get a straight line because it is a equation of a straight line \( y \) (\( V_x \) = m(- w) .x

Bending Moment: 
Bending Moment at XX is obtained by treating the load to the left of XX as a concentrated load of the same value (w.x) acting through the centre of gravity at x/2. 
Therefore, the bending moment at any cross-section XX is 
\( M_x = (-w.x) \frac{x}{2} = \frac{-w.x^2}{2} \)
Therefore the variation of bending moment is according to parabolic law.
The extreme values of B.M would be at x = 0, \( M_x = 0 \)
and x = L, \( M_x = \frac{-wL^2}{2} \)
Maximum bending moment, \( M_{\text{max}} = \frac{wL^2}{2} \) at fixed end

Another way to describe a cantilever beam with uniformly distributed load (UDL) over its whole length.

(iii) A Cantilever beam loaded as shown below draw its S.F and B.M diagram

In the region \( 0 < x < a \)
Following the same rule as followed previously, we get
\( V_x = -P; \) and \( M_x = -P.x \)

In the region \( a < x < L \)
\( V_x = -P+P=0; \) and \( M_x = -P.x + P(x-a) = Pa \)

(iv) Let us take an example: Consider a cantilever beam of 5 m length. It carries a uniformly distributed load 3 KN/m and a concentrated load of 7 kN at the free end and 10 kN at 3 meters from the fixed end.

Draw SF and BM diagram.
Answer: In the region $0 < x < 2 \text{ m}$
Consider any cross section $XX$ at a distance $x$ from free end.

*Shear force* ($V_x$) = $-7 \cdot -3x$
So, the variation of shear force is linear.

at $x = 0$, $V_x = -7 \text{ kN}$
at $x = 2 \text{ m}$, $V_x = -7 \cdot 3 \times 2 = -13 \text{ kN}$
at *point Z* $V_x = -7 \cdot -3 \cdot 2 \cdot 10 = -23 \text{ kN}$

*Bending moment* ($M_x$) = $-7x - (3x)$
So, the variation of bending force is parabolic.

at $x = 0$, $M_x = 0$
at $x = 2 \text{ m}$, $M_x = -7 \cdot 2 - (3 \cdot 2) \cdot \frac{2}{2} = -20 \text{ kNm}$

In the region $2 \text{ m} < x < 5 \text{ m}$
Consider any cross section $YY$ at a distance $x$ from free end

*Shear force* ($V_x$) = $-7 \cdot -3x - 10 = -17 \cdot 3x$
So, the variation of shear force is linear.

at $x = 2 \text{ m}$, $V_x = -23 \text{ kN}$
at $x = 5 \text{ m}$, $V_x = -32 \text{ kN}$

*Bending moment* ($M_x$) = $-7x - (3x) \cdot \left( \frac{x}{2} \right) \cdot 10 (x - 2)$

$$= -\frac{3}{2}x^2 - 17x + 20$$

So, the variation of bending force is parabolic.

at $x = 2 \text{ m}$, $M_x = -\frac{3}{2} \cdot 2^2 - 17 \times 2 + 20 = -20 \text{ kNm}$
at $x = 5 \text{ m}$, $M_x = -102.5 \text{ kNm}$
(v) A Cantilever beam carrying uniformly varying load from zero at free end and w/unit length at the fixed end

Consider any cross-section XX which is at a distance of x from the free end.

At this point load \( (w_x) = \frac{w}{L} \cdot x \)

Therefore total load \( (W) = \int_0^L w_x \, dx = \int_0^L \frac{w}{L} \cdot x \, dx = \frac{wL}{2} \)

Shear force \( (V_x) = \text{area of ABC (load triangle)} \)

\[
= \frac{1}{2} \left( \frac{w}{L} \right) x = \frac{wx^2}{2L}
\]

\[\therefore \text{ The shear force variation is parabolic.}\]

at \( x = 0, V_x = 0 \)

at \( x = L, V_x = \frac{-WL}{2} \) i.e. Maximum Shear force \( (V_{\text{max}}) = \frac{-WL}{2} \) at fixed end
Bending moment \( M_x \) = load \times distance from centroid of triangle ABC

\[
M_x = \frac{wx^2}{2L} \cdot \frac{2x}{3} = \frac{wx^3}{6L}
\]

\[\therefore\] The bending moment variation is cubic.

at \( x=0 \), \( M_x = 0 \)

at \( x=L \), \( M_x = \frac{-wL^2}{6} \) i.e. Maximum Bending moment \( (M_{\max}) = \frac{wL^2}{6} \) at fixed end.

**Alternative way:** (Integration method)

We know that \[\frac{d(V_x)}{dx} = -\text{load} = -\frac{w}{L} \cdot x\]

or \[d(V_x) = -\frac{w}{L} \cdot x \cdot dx\]

Integrating both side

\[
\int d(V_x) = -\int_0^x \frac{w}{L} \cdot x \cdot dx
\]

or \[V_x = -\frac{w}{L} \cdot \frac{x^2}{2}\]

Again we know that

\[
\frac{d(M_x)}{dx} = V_x = \frac{-wx^2}{2L}
\]

or \[d(M_x) = \frac{-wx^2}{2L} \cdot dx\]
Integrating both side we get (at $x=0, M_x = 0$)

$$\int_0^x d(M_x) = -\frac{wx^2}{2L} \cdot dx$$

or

$$M_x = -\frac{wx^3}{2L} = -\frac{wx^3}{6L}$$

(vi) A Cantilever beam carrying gradually varying load from zero at fixed end and $w$/unit length at the free end

![Cantilever beam diagram]

Considering equilibrium we get, $M_A = \frac{wL^2}{3}$ and Reaction $(R_A) = \frac{wL}{2}$

Considering any cross-section $XX$ which is at a distance of $x$ from the fixed end.

At this point load $(W_x) = \frac{W}{L} \cdot x$

Shear force $(V_x) = R_A - \text{area of triangle ANM}$

$$= \frac{wL}{2} - \frac{1}{2} \left( \frac{w}{L} \cdot x \right) \cdot x = \frac{wL}{2} - \frac{wx^2}{2L}$$

$\therefore$ The shear force variation is parabolic.

at $x = 0$, $V_x = \frac{wL}{2}$ i.e. Maximum shear force, $V_{max} = \frac{wL}{2}$

at $x = L$, $V_x = 0$

Bending moment $(M_x) = R_A \cdot x - \frac{wx^2}{2L} \cdot \frac{2x}{3} - M_A$

$$= \frac{wL}{2} \cdot x - \frac{wx^3}{6L} - \frac{wL^2}{3}$$

$\therefore$ The bending moment variation is cubic

at $x = 0$, $M_x = -\frac{wL^2}{3}$ i.e. Maximum B.M. $(M_{max}) = -\frac{wL^2}{3}$

at $x = L$, $M_x = 0$
(vii) A Cantilever beam carrying a moment $M$ at free end

Consider any cross-section $XX$ which is at a distance of $x$ from the free end.

**Shear force:** $V_x = 0$ at any point.

**Bending moment** $(M_x) = -M$ at any point, i.e. Bending moment is constant throughout the length.

(viii) A Simply supported beam with a concentrated load ‘$P$’ at its mid span.

Considering equilibrium we get, $R_A = R_B = \frac{P}{2}$

Now consider any cross-section $XX$ which is at a distance of $x$ from left end $A$ and section $YY$ at a distance from left end $A$, as shown in figure below.

**Shear force:** In the region $0 < x < L/2$
Chapter 4: Bending Moment and Shear Force Diagram

**Vx = RA = + P/2** (it is constant)

*In the region L/2 < x < L*

**Vx = RA – P = \( \frac{P}{2} \cdot P = - \frac{P}{2} \)** (it is constant)

**Bending moment: In the region 0 < x < L/2**

\[ M_x = \frac{P}{2} \cdot x \] (its variation is linear)

at \( x = 0 \), \( M_x = 0 \) and \( at \ x = L/2 \) \( M_x = \frac{PL}{4} \) i.e. maximum

Maximum bending moment, \( M_{\text{max}} = \frac{PL}{4} \) at \( x = L/2 \) (at mid-point)

*In the region L/2 < x < L*

\[ M_x = \frac{P}{2} \cdot x - P(x - L/2) = \frac{PL}{2} - \frac{P}{2} \cdot x \] (its variation is linear)

at \( x = L/2 \), \( M_x = \frac{PL}{4} \) and \( at \ x = L \), \( M_x = 0 \)

(ix) A Simply supported beam with a concentrated load ‘P’ is *not* at its mid span.

Considering equilibrium we get, \( R_A = \frac{Pb}{L} \) and \( R_B = \frac{Pa}{L} \)

Now consider any cross-section XX which is at a distance \( x \) from left end A and another section YY at a distance \( x \) from end A as shown in the figure below.
Chapter-4 Bending Moment and Shear Force Diagram

Shear force: In the range \(0 < x < a\)

\[ V_x = R_A = +\frac{P_b}{L} \]  
(it is constant)

In the range \(a < x < L\)

\[ V_x = R_A - P = -\frac{P_a}{L} \]  
(it is constant)

Bending moment: In the range \(0 < x < a\)

\[ M_x = +R_Ax = +\frac{P_b}{L}x \]  
(it is variation is linear)

at \(x = 0, M_x = 0\) and \(at \ x = a, M_x = \frac{P_a b}{L}\) (i.e. maximum)

In the range \(a < x < L\)

\[ M_x = R_Ax - P(x - a) = \frac{P_b}{L}x - P_x + P_a \]  
(Put \( b = L - a \))

\[ = P_a \left(1 - \frac{P_a}{L} \left(1 - \frac{x}{L} \right) \right) \]

at \(x = a, M_x = \frac{P_a b}{L}\) and \(at \ x = L, M_x = 0\)

(x) A Simply supported beam with two concentrated load ‘P’ from a distance ‘a’ both end.

The loading is shown below diagram
Chapter 4  Bending Moment and Shear Force Diagram

Take a section at a distance x from the left support. This section is applicable for any value of x just to the left of the applied force P. The shear remains constant and is +P. The bending moment varies linearly from the support, reaching a maximum of +Pa.

A section applicable anywhere between the two applied forces. Shear force is not necessary to maintain equilibrium of a segment in this part of the beam. Only a constant bending moment of +Pa must be resisted by the beam in this zone.

Such a state of bending or flexure is called pure bending.

Shear and bending-moment diagrams for this loading condition are shown below.

(xi) A Simply supported beam with a uniformly distributed load (UDL) throughout its length

We will solve this problem by following two alternative ways.

(a) By Method of Section

Considering equilibrium we get \( R_A = R_B = \frac{wL}{2} \)

Now consider any cross-section XX which is at a distance x from left end A.
Shear force: \( V_x = \frac{wL}{2} - wx \)  
(i.e. S.F. variation is linear)  
\( \text{at } x = 0, \quad V_x = \frac{wL}{2} \)  
\( \text{at } x = L/2, \quad V_x = 0 \)  
\( \text{at } x = L, \quad V_x = -\frac{wL}{2} \)  

Bending moment: \( M_x = \frac{wL}{2}x - \frac{wx^2}{2} \)  
(i.e. B.M. variation is parabolic)  
\( \text{at } x = 0, \quad M_x = 0 \)  
\( \text{at } x = L, \quad M_x = 0 \)  

Now we have to determine maximum bending moment and its position.

For maximum B.M:  
\[ \frac{d(M_x)}{dx} = 0 \quad \text{i.e.} \quad V_x = 0 \]  
\[ \text{or} \quad \frac{wL}{2} - wx = 0 \quad \text{or} \quad x = \frac{L}{2} \]  

Therefore, maximum bending moment, \( M_{\text{max}} = \frac{wL^2}{8} \) at \( x = L/2 \)

(a) By Method of Integration
Shear force:
We know that,  
\[ \frac{d(V_x)}{dx} = -w \]  
\[ \text{or} \quad d(V_x) = -wdx \]  

Integrating both side we get (at \( x = 0, \quad V_x = \frac{wL}{2} \))
Bending moment:

We know that, \( \frac{d(M_x)}{dx} = V_x \)

or \( d(M_x) = V_x dx = \left( \frac{wL}{2} - wx \right) dx \)

Integrating both side we get (at \( x = 0, V_x = 0 \))

\[ M_x = \int_0^x \frac{wL}{2} - wx \, dx \]

or \( M_x = \frac{wL}{2} x - \frac{wx^2}{2} \)

Let us take an example: A loaded beam as shown below. Draw its S.F and B.M diagram.

Considering equilibrium we get

\[ \sum M_A = 0 \text{ gives} \]
\[ -(200 \times 4) \times 2 - 3000 \times 4 + R_B \times 8 = 0 \]

or \( R_B = 1700 \text{N} \)

And \( R_A + R_B = 200 \times 4 + 3000 \)

or \( R_A = 2100 \text{N} \)

Now consider any cross-section \( XX \) which is at a distance 'x' from left end A and as shown in figure
In the region 0 < x < 4m

Shear force (V_x) = R_A – 200x = 2100 – 200x

Bending moment (M_x) = R_A x – 200 x . \frac{x}{2} = 2100 x -100 x^2

at x = 0, \hspace{1cm} V_x = 2100 \text{ N}, \hspace{1cm} M_x = 0

at x = 4m, \hspace{1cm} V_x = 1300 \text{ N}, \hspace{1cm} M_x = 6800 \text{ N.m}

In the region 4 m < x < 8 m

Shear force (V_x) = R_A - 200 x – 3000 = -1700

Bending moment (M_x) = R_A . x - 200 x (x-2) – 3000 (x- 4)

= 2100 x – 800 x + 1600 – 3000x +12000 = 13600 -1700 x

at x = 4 m, \hspace{1cm} V_x = -1700 \text{ N}, \hspace{1cm} M_x = 6800 \text{ Nm}

at x = 8 m, \hspace{1cm} V_x = -1700 \text{ N}, \hspace{1cm} M_x = 0
(xii) A Simply supported beam with a gradually varying load (GVL) zero at one end and w/unit length at other span.

Consider equilibrium of the beam with \( \frac{1}{2} wL \) acting at a point C at a distance \( \frac{2L}{3} \) to the left end A.

\[ \sum M_B = 0 \text{ gives } R_A \cdot L - \frac{wL}{2} \cdot \frac{L}{3} = 0 \]

or \( R_A = \frac{wL}{6} \)

Similarly \( \sum M_A = 0 \) gives \( R_B = \frac{wL}{3} \)

The free body diagram of section A - XX as shown below, Load at section XX, \( (w_x) = \frac{w}{L} \cdot x \)
The resulted of that part of the distributed load which acts on this free body is 
\[ \frac{1}{2}(x) \cdot \frac{wL}{x} = \frac{wx^2}{2L} \]
applied at a point \( Z \), distance \( x/3 \) from \( XX \) section.

**Shear force (\( V_x \))**

\[ V_x = R_A - \frac{wx^2}{2L} = \frac{wL}{6} - \frac{wx^2}{2L} \]

Therefore the variation of shear force is parabolic

- at \( x = 0 \), \( V_x = \frac{wL}{6} \)
- at \( x = L \), \( V_x = -\frac{wL}{3} \)

and **Bending Moment (\( M_x \))**

\[ M_x = \frac{wL}{6}x - \frac{wx^2}{2L} \cdot \frac{x}{3} = \frac{wL}{6}x - \frac{wx^3}{6L} \]

The variation of BM is cubic

- at \( x = 0 \), \( M_x = 0 \)
- at \( x = L \), \( M_x = 0 \)

For maximum BM;

\[ \frac{d(M_x)}{dx} = 0 \quad \text{i.e.} \quad V_x = 0 \]

\[ \frac{wL}{6} \cdot \frac{wx^2}{2L} = 0 \quad \text{or} \quad x = \frac{L}{\sqrt{3}} \]

and \( M_{\text{max}} = \frac{wL}{6} \times \left( \frac{L}{\sqrt{3}} \right) - \frac{w}{6L} \times \left( \frac{L}{\sqrt{3}} \right)^3 = \frac{wL^2}{9\sqrt{3}} \)

i.e.

\[ M_{\text{max}} = \frac{wL^2}{9\sqrt{3}} \quad \text{at} \quad x = \frac{L}{\sqrt{3}} \]
(xiii) A Simply supported beam with a gradually varying load (GVL) zero at each end and \( w/\text{unit length at mid span.} \)

Consider equilibrium of the beam AB total load on the beam:

\[
\begin{align*}
1L & = wL + wL \\
& = 2wL
\end{align*}
\]

Therefore \( R_A = R_B = \frac{wL}{4} \)

The free body diagram of section A -XX as shown below, load at section XX \( (w_x) = \frac{2w}{L}x \)

The resultant of that part of the distributed load which acts on this free body is:

\[
\begin{align*}
&= \frac{1}{2} x \frac{2w}{L} x \frac{wx^2}{L} \\
&= \frac{wx^2}{L}
\end{align*}
\]

applied at a point, distance \( x/3 \) from section XX.

Shear force \((V_x)\):
In the region $0 < x < L/2$

\[
(V_x) = R_A - \frac{wx^2}{L} = \frac{wL}{4} - \frac{wx^2}{L}
\]

Therefore the variation of shear force is parabolic.

- at $x = 0$, $V_x = \frac{wL}{4}$
- at $x = L/4$, $V_x = 0$

In the region of $L/2 < x < L$

The Diagram will be Mirror image of AC.

Bending moment ($M_x$):

In the region $0 < x < L/2$

\[
M_x = \frac{wL}{4} \cdot x - \left( \frac{1}{2} \cdot x \cdot \frac{2wx}{L} \right) \cdot \left( \frac{x}{3} \right) = \frac{wL}{4} \cdot \frac{wx^3}{3L}
\]

The variation of BM is cubic

- at $x = 0$, $M_x = 0$
- at $x = L/2$, $M_x = \frac{wL^2}{12}$

In the region $L/2 < x < L$

BM diagram will be mirror image of AC.

For maximum bending moment

\[
\frac{d(M_x)}{dx} = 0 \quad \text{i.e.} \quad V_x = 0
\]

\[
\therefore \frac{d(M_x)}{dx} = V_x
\]

or \[\frac{wL}{4} \cdot \frac{wx^2}{L} = 0 \quad \text{or} \quad x = \frac{L}{2}\]

and $M_{\text{max}} = \frac{wL^2}{12}$

i.e.

\[
M_{\text{max}} = \frac{wL^2}{12} \quad \text{at} \quad x = \frac{L}{2}
\]
(xiv) A Simply supported beam with a gradually varying load (GVL) zero at mid span and w/unit length at each end.

We now superimpose two beams as

1. Simply supported beam with a UDL through at its length
   \[ (V_s)_1 = \frac{wL}{2} - wx \]
   \[ (M_s)_1 = \frac{wL}{2}x - \frac{wx^2}{2} \]

And (2) a simply supported beam with a gradually varying load (GVL) zero at each end and w/unit length at mid span.

In the range \(0 < x < L/2\)

\[ (V_s)_2 = \frac{wL}{4} - \frac{wx^2}{L} \]
\[ (M_s)_2 = \frac{wL}{4}x - \frac{wx^3}{3L} \]

Now superimposing we get

Shear force \((V_x)\):

In the region of \(0 < x < L/2\)
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\[ V_x = (V_x)_1 - (V_x)_2 = \left( \frac{wL}{2} - wx \right) - \left( \frac{wL}{4} - \frac{wx^2}{L} \right) \]

\[ = \frac{w}{L} (x - L/2)^2 \]

Therefore the variation of shear force is parabolic

at \( x = 0 \), \( V_x = + \frac{wL}{4} \)

at \( x = L/2 \), \( V_x = 0 \)

In the region \( L/2 < x < L \)

The diagram will be mirror image of AC

**Bending moment (M_x) = (M_x)_1 - (M_x)_2 =**

\[ = \left( \frac{wL}{2} \cdot x - \frac{wx^2}{2} \right) - \left( \frac{wL}{4} \cdot x - \frac{wx^3}{3L} \right) = \frac{wx^3}{3L} - \frac{wx^2}{2} + \frac{wL}{4} \cdot x \]

The variation of BM is cubic

at \( x = 0 \), \( M_x = 0 \)

at \( x = L/2 \), \( M_x = \frac{wx^2}{24} \)

(xv) A simply supported beam with a gradually varying load (GVL) \( w_1/\text{unit length} \) at one end and \( w_2/\text{unit length} \) at other end.
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At first we will treat this problem by considering a UDL of identifying \( w_1 \)/unit length over the whole length and a varying load of zero at one end to \( (w_2 - w_1) \)/unit length at the other end. Then superimpose the two loadings.

Consider a section XX at a distance \( x \) from left end A

(i) Simply supported beam with UDL \( w_1 \) over whole length

\[
(V_s)_1 = \frac{w_1 L}{2} - w_1x \\
(M_s)_1 = \frac{w_1 L}{2} x - \frac{1}{2} w_1 x^2
\]

And (ii) simply supported beam with (GVL) zero at one end \( (w_2 - w_1) \) at other end gives

\[
(V_s)_2 = \frac{(w_2 - w_1)}{6} - \frac{(w_2 - w_1) x^2}{2L} \\
(M_s)_2 = (w_2 - w_1) \cdot \frac{L}{6} x - \frac{(w_2 - w_1) x^3}{6L}
\]

Now superimposing we get

Shear force \( (V_s) = (V_s)_1 + (V_s)_2 = \frac{w_1 L}{3} + \frac{w_2 L}{6} - w_1x - \frac{(w_2 - w_1) x^2}{2L} \)

*: The SF variation is parabolic

at \( x = 0, \ V_s = \frac{w_1 L}{3} + \frac{w_2 L}{6} = \frac{L}{6}(2w_1 + w_2) \)

at \( x = L, \ V_s = - \frac{L}{6}(w_1 + 2w_2) \)

Bending moment \( (M_s) = (M_s)_1 + (M_s)_2 = \frac{w_1 L}{3} x + \frac{w_2 L}{6} x - \frac{1}{2} w_1 x^2 - \frac{(w_2 - w_1)}{6L} x^3 \)

*: The BM variation is cubic.

at \( x = 0, \ M_s = 0 \)

at \( x = L, \ M_s = 0 \)
(xvi) A Simply supported beam carrying a continuously distributed load. The intensity of the load at any point is, \( w_x = w \sin \left( \frac{\pi x}{L} \right) \). Where ‘x’ is the distance from each end of the beam.

We will use Integration method as it is easier in this case.

We know that \( \frac{d(V_x)}{dx} = \text{load} \) and \( \frac{d(M_x)}{dx} = V_x \)

Therefore \( \frac{d(V_x)}{dx} = -w \sin \left( \frac{\pi x}{L} \right) \)

\[ d(V_x) = -w \sin \left( \frac{\pi x}{L} \right) dx \]

Integrating both side we get

\[ \int d(V_x) = -w \int \sin \left( \frac{\pi x}{L} \right) dx \quad \text{or} \quad V_x = + \frac{w \cos \left( \frac{\pi x}{L} \right)}{\frac{\pi}{L}} + A = + \frac{wL}{\pi} \cos \left( \frac{\pi x}{L} \right) + A \]

[where, \( A = \text{constant of Integration} \)]
Again we know that
\[ \frac{d(M_x)}{dx} = V_x \quad \text{or} \quad d(M_x) = V_x \, dx = \left\{ \frac{wL}{\pi} \cos \left( \frac{\pi x}{L} \right) + A \right\} \, dx \]

Integrating both side we get
\[ M_x = \frac{wL}{\pi} \sin \left( \frac{\pi x}{L} \right) + Ax + B = \frac{wL^2}{\pi^2} \sin \left( \frac{\pi x}{L} \right) + Ax + B \]

[Where B = constant of Integration]

Now apply boundary conditions

At \( x = 0 \), \( M_x = 0 \) and at \( x = L \), \( M_x = 0 \)

This gives \( A = 0 \) and \( B = 0 \)

\[ \therefore \text{Shear force} \quad (V_x) = \frac{wL}{\pi} \cos \left( \frac{\pi x}{L} \right) \quad \text{and} \quad V_{\text{max}} = \frac{wL}{\pi} \quad \text{at} \quad x = 0 \]

And \( M_x = \frac{wL^2}{\pi^2} \sin \left( \frac{\pi x}{L} \right) \)

\[ \therefore M_{\text{max}} = \frac{wL^2}{\pi^2} \quad \text{at} \quad x = L/2 \]

(xvii) A Simply supported beam with a couple or moment at a distance ‘a’ from left end.

Considering equilibrium we get
\[ \sum M_A = 0 \text{ gives} \]
\[ R_b \times L + M = 0 \quad \text{or} \quad R_b = -\frac{M}{L} \]
and \[ \sum M_B = 0 \text{ gives} \]
\[ -R_A \times L + M = 0 \quad \text{or} \quad R_A = \frac{M}{L} \]

Now consider any cross-section XX which is at a distance ‘x’ from left end A and another section YY at a distance ‘x’ from left end A as shown in figure.

In the region \( 0 < x < a \)
\[ \text{Shear force} \ (V_x) = R_A = \frac{M}{L} \]
\[ \text{Bending moment} \ (M_x) = R_A \times x = \frac{M}{L} \times x \]

In the region \( a < x < L \)
\[ \text{Shear force} \ (V_x) = R_A = \frac{M}{L} \]
\[ \text{Bending moment} \ (M_x) = R_A \times x - M = \frac{M}{L} \times x - M \]
(xviii) A Simply supported beam with an eccentric load

When the beam is subjected to an eccentric load, the eccentric load is to be changed into a couple = Force× (distance travel by force)

= P.a  (in this case) and  a force = P

Therefore equivalent load diagram will be

Considering equilibrium

\[ \sum M_A = 0 \] gives

\[ -P \times (L/2) + P.a + R_B \times L = 0 \]

or \[ R_B = \frac{P}{2} - \frac{P.a}{L} \] and \[ R_A + R_B = P \] gives \[ R_A = \frac{P}{2} + \frac{P.a}{L} \]

Now consider any cross-section XX which is at a distance ‘x’ from left end A and another section YY at a distance ‘x’ from left end A as shown in figure.
In the region $0 < x < L/2$

Shear force ($V_x$) = $\frac{P}{2} + \frac{P_a}{L}$

Bending moment ($M_x$) = $R_A \cdot x = \left( \frac{P}{2} + \frac{P_a}{L} \right) \cdot x$

In the region $L/2 < x < L$

Shear force ($V_x$) = $-\frac{P}{2} + \frac{P_a}{L}$

Bending moment ($V_x$) = $R_A \cdot x - P \cdot (x - L/2) - M$

$= \frac{PL}{2} - \left( \frac{P}{2} - \frac{P_a}{L} \right) \cdot x - P_a$

4.6 Bending Moment diagram of Statically Indeterminate beam

Beams for which reaction forces and internal forces cannot be found out from static equilibrium equations alone are called statically indeterminate beam. This type of beam requires deformation equation in addition to static equilibrium equations to solve for unknown forces.

**Statically determinate** - Equilibrium conditions sufficient to compute reactions.

**Statically indeterminate** - Deflections (Compatibility conditions) along with equilibrium equations should be used to find out reactions.
**Type of Loading & B.M Diagram**

<table>
<thead>
<tr>
<th>Reaction</th>
<th>Bending Moment</th>
</tr>
</thead>
<tbody>
<tr>
<td>$R_A = R_B = \frac{P}{2}$</td>
<td>( M_A = M_B = -\frac{PL}{8} )</td>
</tr>
<tr>
<td>$R_A = R_B = \frac{wL}{2}$</td>
<td>( M_A = M_B = -\frac{wL^2}{12} )</td>
</tr>
<tr>
<td>$R_A = \frac{Pb^2}{L} (3a + b)$</td>
<td>( M_A = -\frac{Pab^2}{L^2} )</td>
</tr>
<tr>
<td>$R_B = \frac{Pa^2}{L} (3b + a)$</td>
<td>( M_B = -\frac{Pa^2b}{L^2} )</td>
</tr>
<tr>
<td>$R_A = R_B = \frac{3wL}{16}$</td>
<td>( R_c = \frac{5wL}{8} )</td>
</tr>
</tbody>
</table>
4.7 Load and Bending Moment diagram from Shear Force diagram

OR

Load and Shear Force diagram from Bending Moment diagram

If S.F. Diagram for a beam is given, then

(i) If S.F. diagram consists of rectangle then the load will be point load

(ii) If S.F. diagram consists of inclined line then the load will be UDL on that portion

(iii) If S.F. diagram consists of parabolic curve then the load will be GVL

(iv) If S.F. diagram consists of cubic curve then the load distribute is parabolic.

After finding load diagram we can draw B.M diagram easily.

If B.M Diagram for a beam is given, then

(i) If B.M diagram consists of inclined line then the load will be free point load

(ii) If B.M diagram consists of parabolic curve then the load will be U.D.L.

(iii) If B.M diagram consists of cubic curve then the load will be G.V.L.

(iv) If B.M diagram consists of fourth degree polynomial then the load distribution is parabolic.

Let us take an example: Following is the S.F diagram of a beam is given. Find its loading diagram.

![Shear Force Diagram](image)

Answer: From A-E inclined straight line so load will be UDL and in AB = 2 m length load = 6 kN if UDL is w N/m then w x 2 = 6 or w = 3 kN/m after that S.F is constant so no force is there. At last a 6 kN for vertical force complete the diagram then the load diagram will be

![Load Diagram](image)

As there is no support at left end it must be a cantilever beam.
4.8 Point of Contraflexure

In a beam if the bending moment changes sign at a point, the point itself having zero bending moment, the beam changes curvature at this point of zero bending moment and this point is called the point of contra flexure.

Consider a loaded beam as shown below along with the B.M diagrams and deflection diagram.

In this diagram we noticed that for the beam loaded as in this case, the bending moment diagram is partly positive and partly negative. In the deflected shape of the beam just below the bending moment diagram shows that left hand side of the beam is ‘sagging’ while the right hand side of the beam is ‘hogging’.

The point C on the beam where the curvature changes from sagging to hogging is a point of contraflexure.

- **There can be more than one point of contraflexure in a beam.**

4.9 General expression

- \( EI \frac{d^4 y}{dx^4} = - \phi \)
- \( EI \frac{d^3 y}{dx^3} = V \)
- \( EI \frac{d^2 y}{dx^2} = M \)
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- \( \frac{dy}{dx} = 0 = \text{slope} \)
- \( y = \delta = \text{Deflection} \)
- Flexural rigidity = EI
Shear Force (S.F.) and Bending Moment (B.M.)

GATE-1. A concentrated force, $F$ is applied (perpendicular to the plane of the figure) on the tip of the bent bar shown in Figure. The equivalent load at a section close to the fixed end is:
(a) Force $F$
(b) Force $F$ and bending moment $FL$
(c) Force $F$ and twisting moment $FL$
(d) Force $F$ bending moment $FL$, and twisting moment $FL$

GATE-1. Ans. (c)

GATE-2. The shear force in a beam subjected to pure positive bending is......
(positive/zero/negative)
GATE-2. Ans. Zero

Cantilever

GATE-3. Two identical cantilever beams are supported as shown, with their free ends in contact through a rigid roller. After the load $P$ is applied, the free ends will have

(a) Equal deflections but not equal slopes
(b) Equal slopes but not equal deflections
(c) Equal slopes as well as equal deflections
(d) Neither equal slopes nor equal deflections

GATE-3. Ans. (a) As it is rigid roller, deflection must be same, because after deflection they also will be in contact. But slope unequal.

GATE-4. A beam is made up of two identical bars AB and BC, by hinging them together at B. The end A is built-in (cantilevered) and the end C is simply-supported. With the load $P$ acting as shown, the bending moment at A is:
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(a) Zero  
(b) \( \frac{PL}{2} \)  
(c) \( \frac{3PL}{2} \)  
(d) Indeterminate

GATE-4. Ans. (b)

Cantilever with Uniformly Distributed Load

GATE-5. The shapes of the bending moment diagram for a uniform cantilever beam carrying a uniformly distributed load over its length is:  
(a) A straight line  
(b) A hyperbola  
(c) An ellipse  
(d) A parabola

GATE-5. Ans. (d)

[Diagram of a cantilever beam with uniformly distributed load]

Cantilever Carrying load Whose Intensity varies

GATE-6. A cantilever beam carries the anti-symmetric load shown, where \( \omega_0 \) is the peak intensity of the distributed load. Qualitatively, the correct bending moment diagram for this beam is:

[Diagram of a cantilever beam with asymmetric load]

(a)  
(b)  
(c)  
(d)

GATE-6. Ans. (d)
Simply Supported Beam Carrying Concentrated Load

GATE-7. A concentrated load of \( P \) acts on a simply supported beam of span \( L \) at a distance \( \frac{L}{3} \) from the left support. The bending moment at the point of application of the load is given by \([GATE-2003]\)

\[
(a) \frac{PL}{3} \quad (b) \frac{2PL}{3} \quad (c) \frac{PL}{9} \quad (d) \frac{2PL}{9}
\]

GATE-7. Ans. (d)

\[
M_e = \frac{Pab}{l} = \frac{PL}{3} \left(\frac{L}{3}\right) \left(\frac{2L}{3}\right) = \frac{2PL}{9}
\]

GATE-8. A simply supported beam carries a load 'P' through a bracket, as shown in Figure. The maximum bending moment in the beam is

(a) \( \frac{PL}{2} \) \quad (b) \( \frac{PL}{2} + \frac{aP}{2} \)
(c) \( \frac{PL}{2} + aP \) \quad (d) \( \frac{PL}{2} - aP \)

GATE-8. Ans. (c)

Taking moment about \( R_a \)

\[-P \times \frac{1}{2} - Pa + R_a l = 0\]

or \( R_a = \frac{P}{2} + \frac{aP}{l} \quad \therefore R_a = \frac{P}{2} - \frac{P a}{l} \]

Maximum bending moment will be at centre ‘C’

\[M_{e} = R_a \times \frac{1}{2} + P \times a + R_a \times \frac{1}{2}\] \( \text{or } M_{max} = \frac{PL}{2} + Pa \)

Simply Supported Beam Carrying a Uniformly Distributed Load

Statement for Linked Answer and Questions Q9-Q10:
A mass less beam has a loading pattern as shown in the figure. The beam is of rectangular cross-section with a width of 30 mm and height of 100 mm. \([GATE-2010]\)
GATE-9. The maximum bending moment occurs at
(a) Location B (b) 2675 mm to the right of A
(c) 2500 mm to the right of A (d) 3225 mm to the right of A
GATE-9. Ans. (C)

\[ R_1 + R_2 = 3000 \times 2 = 6000 \text{N} \]
\[ R_1 \times 4 - 3000 \times 2 \times 1 = 0 \]
\[ R_1 = 1500, \]
S.F. eq. at any section \( x \) from end A.
\[ R_1 - 3000 \times (x - 2) = 0 \quad \text{for} \quad x > 2 \text{m} \]
\[ x = 2.5 \text{ m}. \]

GATE-10. The maximum magnitude of bending stress (in MPa) is given by
(a) 60.0 (b) 67.5 (c) 200.0 (d) 225.0
GATE-10. Ans. (b)

Binding stress will be maximum at the outer surface
So taking \( h = 50 \text{ mm} \)
and \( I = \frac{ld^3}{12} \) & \( \sigma = \frac{m \times 50}{I d^3/12} \)
\[ m_x = 1.5 \times 10^3 [2000 + x] - \frac{x^2}{2} \]
\[ \therefore m_{1500} = 3.375 \times 10^6 \text{ N} \text{– mm} \]
\[ \therefore \sigma = \frac{3.375 \times 10^6 \times 50 \times 12}{30 \times 100^3} = 67.5 \text{ MPa} \]

Data for Q11-Q12 are given below. Solve the problems and choose correct answers
A steel beam of breadth 120 mm and height 750 mm is loaded as shown in the figure. Assume \( E_{\text{steel}} = 200 \text{ GPa} \).

GATE-11. The beam is subjected to a maximum bending moment of
(a) 3375 kNm (b) 4750 kNm (c) 6750 kNm (d) 8750 kNm
GATE-11. Ans. (b)
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GATE-11. Ans. (a) $M_{\text{max}} = \frac{wl^2}{8} = \frac{120 \times 15^2}{8} \text{kNm} = 3375 \text{kNm}$

GATE-12. The value of maximum deflection of the beam is:

(a) 93.75 mm  (b) 83.75 mm  (c) 73.75 mm  (d) 63.75 mm

GATE-12. Ans. (a) Moment of inertia ($I$) = $\frac{bh^3}{12} = \frac{0.12 \times (0.75)^3}{12} = 4.22 \times 10^{-3} \text{m}^4$

$\delta_{\text{max}} = \frac{5 \cdot wL^4}{384EI} = \frac{5 \times 120 \times 10^3 \times 15^4}{384 \times 200 \times 10^8 \times 4.22 \times 10^{-3}} \text{m} = 93.75 \text{mm}$

Statement for Linked Answer and Questions Q13-Q14:

A simply supported beam of span length 6m and 75mm diameter carries a uniformly distributed load of 1.5 kN/m

GATE-13. What is the maximum value of bending moment?

(a) 9 kNm  (b) 13.5 kNm  (c) 81 kNm  (d) 125 kNm

GATE-13. Ans. (a) $M_{\text{max}} = \frac{wl^2}{8} = \frac{1.5 \times 6^2}{8} = 6.75 \text{kNm}$ But not in choice. Nearest choice (a)

GATE-14. What is the maximum value of bending stress?

(a) 162.98 MPa  (b) 325.95 MPa  (c) 625.95 MPa  (d) 651.90 MPa

GATE-14. Ans. (a) $\sigma = \frac{32M}{\pi d^3} = \frac{32 \times 6.75 \times 10^3}{\pi \times (0.075)^2} \text{Pa} = 162.98 \text{MPa}$

Simply Supported Beam Carrying a Load whose Intensity varies Uniformly from Zero at each End to w per Unit Run at the Mid Span

GATE-15. A simply supported beam is subjected to a distributed loading as shown in the diagram given below:

What is the maximum shear force in the beam?

(a) WL/3  (b) WL/2  (c) WL/3  (d) WL/6

GATE-15. Ans. (d)

Total load $= \frac{1}{2} \times L \times W = \frac{WL}{2}$

$S_x = \frac{WL}{4} - \frac{1}{2} x \left( \frac{W}{L} \times X \right) = \frac{WL}{4} - \frac{Wx^2}{L}$

$S_{\text{max}} \text{ at } x=0 = \frac{WL}{4}$

GATE-16. A simply supported beam of length 'l' is subjected to a symmetrical uniformly varying load with zero intensity at the ends and intensity w (load per unit length) at the mid span. What is the maximum bending moment?  [IAS-2004]
Bending Moment and Shear Force Diagram

(a) \( \frac{3wl^2}{8} \)  
(b) \( \frac{wl^2}{12} \)  
(c) \( \frac{wl^2}{24} \)  
(d) \( \frac{5wl^2}{12} \)

GATE-16. Ans. (b)

Previous 20-Years IES Questions

Shear Force (S.F.) and Bending Moment (B.M.)

IES-1. A lever is supported on two hinges at A and C. It carries a force of 3 kN as shown in the above figure. The bending moment at B will be
(a) 3 kN-m  
(b) 2 kN-m  
(c) 1 kN-m  
(d) Zero

IES-1. Ans. (a)

IES-2. A beam subjected to a load P is shown in the given figure. The bending moment at the support AA of the beam will be
(a) PL  
(b) PL/2  
(c) 2PL  
(d) zero

IES-2. Ans. (b) Load P at end produces moment \( \frac{PL}{2} \) in anticlockwise direction. Load P at end produces moment of PL in clockwise direction. Net moment at AA is PL/2.

IES-3. The bending moment (M) is constant over a length segment (I) of a beam. The shearing force will also be constant over this length and is given by
(a) M/I  
(b) M/2I  
(c) M/4I  
(d) None of the above

IES-3. Ans. (d) Dimensional analysis gives choice (d)

IES-4. A rectangular section beam subjected to a bending moment M varying along its length is required to develop same maximum bending stress at any cross-section. If the depth of the section is constant, then its width will vary as
(a) M  
(b) \( \sqrt{M} \)  
(c) M^2  
(d) 1/M

IES-4. Ans. (a) \( \frac{M}{l} = \text{const.} \) and \( l = \frac{bh^3}{12} \)

IES-5. Consider the following statements:
1. \( \frac{dM}{dx} = V \)  
2. \( \frac{dV}{dx} = w \)  
3. \( \frac{dw}{dx} = y \) (the deflection of the beam at the section)

Select the correct answer using the codes given below:
(a) 1 and 3  
(b) 1 and 2  
(c) 2 and 3  
(d) 1, 2 and 3

IES-5. Ans. (b)
IES-6. The given figure shows a beam BC simply supported at C and hinged at B (free end) of a cantilever AB. The beam and the cantilever carry forces of 100 kg and 200 kg respectively. The bending moment at B is:

(a) Zero   (b) 100 kg-m   (c) 150 kg-m   (d) 200 kg-m

IES-6. Ans. (a)

IES-7. Match List-I with List-II and select the correct answer using the codes given below the lists:

<table>
<thead>
<tr>
<th>List-I (Condition of beam)</th>
<th>List-II (Bending moment diagram)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Subjected to bending moment at the end of a cantilever</td>
<td>1. Triangle</td>
</tr>
<tr>
<td>B. Cantilever carrying uniformly distributed load over the whole length</td>
<td>2. Cubic parabola</td>
</tr>
<tr>
<td>C. Cantilever carrying linearly varying load from zero at the fixed end to maximum at the support</td>
<td>3. Parabola</td>
</tr>
<tr>
<td>D. A beam having load at the centre and supported at the ends</td>
<td>4. Rectangle</td>
</tr>
</tbody>
</table>

Codes: A  B  C  D  A  B  C  D
(a)  4  1  2  3 (b)  4  3  2  1
(c)  3  4  2  1 (d)  3  4  1  2

IES-7. Ans. (b)

IES-8. If the shear force acting at every section of a beam is of the same magnitude and of the same direction then it represents a

(a) Simply supported beam with a concentrated load at the centre.
(b) Overhung beam having equal overhang at both supports and carrying equal concentrated loads acting in the same direction at the free ends.
(c) Cantilever subjected to concentrated load at the free end.
(d) Simply supported beam having concentrated loads of equal magnitude and in the same direction acting at equal distances from the supports.

IES-8. Ans. (c)

**Cantilever with Uniformly Distributed Load**

IES-9. A uniformly distributed load $\omega$ (in kN/m) is acting over the entire length of a 3 m long cantilever beam. If the shear force at the midpoint of cantilever is 6 kN, what is the value of $\omega$?

(a) 2   (b) 3   (c) 4   (d) 5

IES-9. Ans. (c)

Shear force at mid point of cantilever

$$\frac{\omega l}{2} = 6$$

$$\Rightarrow \frac{\omega \times 3}{2} = 6$$

$$\Rightarrow \omega = \frac{6 \times 2}{3} = 4 \text{ kN/m}$$
Chapter-4  Bending Moment and Shear Force Diagram  S K Mondal's

IES-10. Match List-I with List-II and select the correct answer using the code given below the Lists:

IES-10. Ans. (b)

IES-11. The shearing force diagram for a beam is shown in the above figure. The bending moment diagram is represented by which one of the following?

IES-11. Ans. (b) Uniformly distributed load on cantilever beam.
IES-12. A cantilever beam having 5 m length is so loaded that it develops a shearing force of 20T and a bending moment of 20 T-m at a section 2m from the free end. Maximum shearing force and maximum bending moment developed in the beam under this load are respectively 50 T and 125 T-m. The load on the beam is:

(a) 25 T concentrated load at free end
(b) 20T concentrated load at free end
(c) 5T concentrated load at free end and 2 T/m load over entire length
(d) 10 T/m udl over entire length

IES-12. Ans. (d)

**Cantilever Carrying Uniformly Distributed Load for a Part of its Length**

IES-13. A vertical hanging bar of length L and weighing w N/ unit length carries a load W at the bottom. The tensile force in the bar at a distance Y from the support will be given by

(a) \( W + wL \) \hspace{1cm} (b) \( W + w(L - y) \) \hspace{1cm} (c) \( (W + w)y / L \) \hspace{1cm} (d) \( W + \frac{W}{w}(L - y) \)

IES-13. Ans. (b)

**Cantilever Carrying load Whose Intensity varies**

IES-14. A cantilever beam of 2m length supports a triangularly distributed load over its entire length, the maximum of which is at the free end. The total load is 37.5 kN. What is the bending moment at the fixed end?

(a) \( 50 \times 10^6 \) N mm \hspace{1cm} (b) \( 12.5 \times 10^6 \) N mm \hspace{1cm} (c) \( 100 \times 10^6 \) N mm \hspace{1cm} (d) \( 25 \times 10^6 \) N mm

IES-14. Ans. (a)
**Simply Supported Beam Carrying Concentrated Load**

IES-15. Assertion (A): If the bending moment along the length of a beam is constant, then the beam cross section will not experience any shear stress. [IES-1998]

Reason (R): The shear force acting on the beam will be zero everywhere along the length.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-15. Ans. (a)

IES-16. Assertion (A): If the bending moment diagram is a rectangle, it indicates that the beam is loaded by a uniformly distributed moment all along the length.

Reason (R): The BMD is a representation of internal forces in the beam and not the moment applied on the beam. [IES-2002]

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-16. Ans. (d)

IES-17. The maximum bending moment in a simply supported beam of length L loaded by a concentrated load W at the midpoint is given by [IES-1996]

(a) WL
(b) \( WL/2 \)
(c) \( WL/4 \)
(d) \( WL/8 \)

IES-17. Ans. (c)

IES-18. A simply supported beam is loaded as shown in the above figure. The maximum shear force in the beam will be [IES-1998]

(a) Zero
(b) W
(c) 2W
(d) 4W

IES-18. Ans. (c)

IES-19. If a beam is subjected to a constant bending moment along its length, then the shear force will [IES-1997]

(a) Also have a constant value everywhere along its length
(b) Be zero at all sections along the beam
(c) Be maximum at the centre and zero at the ends
(d) zero at the centre and maximum at the ends

IES-19. Ans. (b)
IES-20. A loaded beam is shown in the figure. The bending moment diagram of the beam is best represented as:

IES-20. Ans. (a)

IES-21. A simply supported beam has equal over-hanging lengths and carries equal concentrated loads P at ends. Bending moment over the length between the supports
(a) Is zero
(b) Is a non-zero constant
(c) Varies uniformly from one support to the other
(d) Is maximum at mid-span

IES-21. Ans. (b)

IES-22. The bending moment diagram for the case shown below will be q as shown in

IES-22. Ans. (a)
IES-23. Which one of the following portions of the loaded beam shown in the given figure is subjected to pure bending?
(a) AB  (b) DE  (c) AE  (d) BD

IES-23. Ans. (d) Pure bending takes place in the section between two weights W

IES-24. Constant bending moment over span "l" will occur in

IES-24. Ans. (d)

IES-25. For the beam shown in the above figure, the elastic curve between the supports B and C will be:
(a) Circular  (b) Parabolic  (c) Elliptic  (d) A straight line

IES-25. Ans. (b)

IES-26. A beam is simply supported at its ends and is loaded by a couple at its mid-span as shown in figure A. Shear force diagram for the beam is given by the figure.

IES-26. Ans. (d)

IES-27. A beam AB is hinged-supported at its ends and is loaded by couple Pc. as shown in the given figure. The magnitude or shearing force at a section x of the beam is:

IES-27. Ans. (d) Pc./2L
Chapter 4: Bending Moment and Shear Force Diagram

IES-27. Ans. (d) If \( F \) be the shearing force at section \( x \) (at point A), then taking moments about B, \( F \times 2L = P_c \)

or \( F = \frac{P_c}{2L} \)

Thus shearing force in zone \( x \) is \( \frac{P_c}{2L} \).

Simply Supported Beam Carrying a Uniformly Distributed Load

IES-28. A freely supported beam at its ends carries a central concentrated load, and maximum bending moment is \( M \). If the same load be uniformly distributed over the beam length, then what is the maximum bending moment? [IES-2009]

(a) \( M \)  
(b) \( \frac{M}{2} \)  
(c) \( \frac{M}{3} \)  
(d) \( 2M \)

IES-28. Ans. (b)

\[
\text{B.M}_{\text{max}} = \frac{WL}{4} = M
\]

Where the Load is U.D.L.

Maximum Bending Moment

\[
= \left( \frac{W}{L} \right) \left( \frac{L^2}{8} \right)
\]

\[
= \frac{WL}{8} = \frac{1}{2} \left( \frac{WL}{4} \right) = \frac{M}{2}
\]
Simply Supported Beam Carrying a Load whose Intensity varies Uniformly from Zero at each End to \( w \) per Unit Run at the Mid Span

IES-29. A simply supported beam is subjected to a distributed loading as shown in the diagram given below:

What is the maximum shear force in the beam?
(a) \( WL/3 \)  
(b) \( WL/2 \)  
(c) \( WL/3 \)  
(d) \( WL/6 \)

IES-29. Ans. (d)

\[
\begin{align*}
\text{Total load} & = \frac{1}{2} L \times W = \frac{WL}{2} \\
S_x & = \frac{WL}{4} - \frac{1}{2} x \left( \frac{W}{L} \times x \right) = \frac{WL}{4} - \frac{Wx^2}{L} \\
S_{\text{max}} \text{ at } x = 0 & = \frac{WL}{4}
\end{align*}
\]

Simply Supported Beam carrying a Load whose Intensity varies

IES-30. A beam having uniform cross-section carries a uniformly distributed load of intensity \( q \) per unit length over its entire span, and its mid-span deflection is \( \delta \).

The value of mid-span deflection of the same beam when the same load is distributed with intensity varying from \( 2q \) unit length at one end to zero at the other end is:
(a) \( 1/3 \delta \)  
(b) \( 1/2 \delta \)  
(c) \( 2/3 \delta \)  
(d) \( \delta \)

IES-30. Ans. (d)

Simply Supported Beam with Equal Overhangs and carrying a Uniformly Distributed Load

IES-31. A beam, built-in at both ends, carries a uniformly distributed load over its entire span as shown in figure-I. Which one of the diagrams given below, represents bending moment distribution along the length of the beam?

IES-31. [IES-1996]
The Points of Contraflexure

IES-32. The point of contraflexure is a point where:
(a) Shear force changes sign  
(b) Bending moment changes sign  
(c) Shear force is maximum  
(d) Bending moment is maximum

IES-32. Ans. (b)

IES-33. Match List I with List II and select the correct answer using the codes given below the Lists:

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Bending moment is constant</td>
<td>1. Point of contraflexure</td>
</tr>
<tr>
<td>B. Bending moment is maximum or minimum</td>
<td>2. Shear force changes sign</td>
</tr>
<tr>
<td>C. Bending moment is zero</td>
<td>3. Slope of shear force diagram is zero over the portion of the beam</td>
</tr>
<tr>
<td>D. Loading is constant</td>
<td>4. Shear force is zero over the portion of the beam</td>
</tr>
</tbody>
</table>

Code:  
(a) 4 1 2 3  (b) 3 2 1 4  
(c) 4 2 1 3  (d) 3 1 2 4

IES-33. Ans. (b)

Loading and B.M. diagram from S.F. Diagram

IES-34. The bending moment diagram shown in Fig. I correspond to the shear force diagram in

IES-34. Ans. (b) If shear force is zero, B.M. will also be zero. If shear force varies linearly with length, B.M. diagram will be curved line.

IES-35. Bending moment distribution in a built beam is shown in the given
Chapter-4 Bending Moment and Shear Force Diagram

The shear force distribution in the beam is represented by

(a) \[ \text{IES-2001} \]

(b) \[ \text{IES-35. Ans. (a)} \]

IES-36. The given figure shows the shear force diagram for the beam ABCD.

Bending moment in the portion BC of the beam

(a) Is a non-zero constant
(b) Is zero
(c) Varies linearly from B to C
(d) Varies parabolically from B to C

IES-36. Ans. (a)

IES-37. Figure shown above represents the BM diagram for a simply supported beam. The beam is subjected to which one of the following?

(a) A concentrated load at its mid-length
(b) A uniformly distributed load over its length
(c) A couple at its mid-length
(d) Couple at 1/4 of the span from each end

IES-37. Ans. (c)

IES-38. If the bending moment diagram for a simply supported beam is of the form given below.

Then the load acting on the beam is:

(a) A concentrated force at C
(b) A uniformly distributed load over the whole length of the beam
(c) Equal and opposite moments applied at A and B
(d) A moment applied at C

IES-38. Ans. (d) A vertical line in centre of B.M. diagram is possible when a moment is applied there.

IES-39. The figure given below shows a bending moment diagram for the beam CABD:
IES-39. Ans. (a) Load diagram at (a) is correct because B.M. diagram between A and B is parabola which is possible with uniformly distributed load in this region.

IES-40. The shear force diagram shown in the following figure is that of a [IES-1994]
(a) Freely supported beam with symmetrical point load about mid-span.
(b) Freely supported beam with symmetrical uniformly distributed load about mid-span
(c) Simply supported beam with positive and negative point loads symmetrical about the mid-span
(d) Simply supported beam with symmetrical varying load about mid-span

IES-40. Ans. (b) The shear force diagram is possible on simply supported beam with symmetrical varying load about mid span.

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**Previous 20-Years IAS Questions**

**Shear Force (S.F.) and Bending Moment (B.M.)**

IAS-1. Assertion (A): A beam subjected only to end moments will be free from shearing force. [IAS-2004]

Reason (R): The bending moment variation along the beam length is zero.
(a) Both A and R are individually true and R is the correct explanation of A
Chapter-4  Bending Moment and Shear Force Diagram  S K Mondal's

(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-1. Ans. (a)

IAS-2. Assertion (A): The change in bending moment between two cross-sections of a beam is equal to the area of the shearing force diagram between the two sections.  
Reason (R): The change in the shearing force between two cross-sections of beam due to distributed loading is equal to the area of the load intensity diagram between the two sections.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-2. Ans. (b)

IAS-3. The ratio of the area under the bending moment diagram to the flexural rigidity between any two points along a beam gives the change in  
(a) Deflection  (b) Slope  (c) Shear force  (d) Bending moment

IAS-3. Ans. (b)

Cantilever

IAS-4. A beam AB of length 2 L having a concentrated load P at its mid-span is hinge supported at its two ends A and B on two identical cantilevers as shown in the given figure. The correct value of bending moment at A is
(a) Zero  (b) PLl2  (c) PL  (d) 2 PL

IAS-4. Ans. (a)

Because of hinge support between beam AB and cantilevers, the bending moment can't be transmitted to cantilever. Thus bending moment at points A and B is zero.

IAS-5. A load perpendicular to the plane of the handle is applied at the free end as shown in the given figure. The values of Shear Forces (S.F.), Bending Moment (B.M.) and torque at the fixed end of the handle have been determined respectively as 400 N, 340 Nm and 100 by a student. Among these values, those of
(a) S.F., B.M. and torque are correct  (b) S.F. and B.M. are correct  (c) B.M. and torque are correct  (d) S.F. and torque are correct

IAS-5. Ans. (d)

\[ \text{S.F.} = 400 \text{N} \quad \text{and} \quad \text{BM} = 400 \times (0.4 + 0.2) = 240 \text{Nm} \]
\[ \text{Torque} = 400 \times 0.25 = 100 \text{Nm} \]

Cantilever with Uniformly Distributed Load

IAS-6. If the SF diagram for a beam is a triangle with length of the beam as its base, the beam is:
(a) A cantilever with a concentrated load at its free end  
(b) A cantilever with udl over its whole span  
(c) Simply supported with a concentrated load at its mid-point  
(d) Simply supported with a udl over its whole span

IAS-6. Ans. (a)
IA-6. Ans. (b)

IA-7. A cantilever carrying a uniformly distributed load is shown in Fig. I. Select the correct R.M. diagram of the cantilever. 

\[ M_x = -wx \frac{x}{2} = -\frac{wx^2}{2} \]

IA-8. A structural member ABCD is loaded as shown in the given figure. The shearing force at any section on the length BC of the member is:

(a) Zero  
(b) P  
(c) Pa/k  
(d) Pk/a

IA-8. Ans. (a)

**Cantilever Carrying load Whose Intensity varies**

IA-9. The beam is loaded as shown in Fig. I. Select the correct B.M. diagram

\[ \text{B. Diagram} \]
IAS-9. Ans. (d)

**Simply Supported Beam Carrying Concentrated Load**

IAS-10. Assertion (A): In a simply supported beam carrying a concentrated load at mid-span, both the shear force and bending moment diagrams are triangular in nature without any change in sign. [IAS-1999]

Reason (R): When the shear force at any section of a beam is either zero or changes sign, the bending moment at that section is maximum.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-10. Ans. (d) A is false.

IAS-11. For the shear force to be uniform throughout the span of a simply supported beam, it should carry which one of the following loadings? [IAS-2007]

(a) A concentrated load at mid-span
(b) Udl over the entire span
(c) A couple anywhere within its span
(d) Two concentrated loads equal in magnitude and placed at equal distance from each support
IAS-11. Ans. (d) It is a case of pure bending.

IAS-12. Which one of the following figures represents the correct shear force diagram for the loaded beam shown in the given figure I? [IAS-1998; IAS-1995]

IAS-12. Ans. (a)

**Simply Supported Beam Carrying a Uniformly Distributed Load**

IAS-13. For a simply supported beam of length $L$ subjected to downward load of uniform intensity $w$, match List-I with List-II and select the correct answer using the codes given below the Lists: [IAS-1997]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Slope of shear force diagram</td>
<td>$\frac{5wr^4}{384EI}$</td>
</tr>
<tr>
<td>B. Maximum shear force</td>
<td>$w$</td>
</tr>
<tr>
<td>C. Maximum deflection</td>
<td>$wL^4$</td>
</tr>
<tr>
<td>D. Magnitude of maximum bending moment</td>
<td>$\frac{wL^2}{2}$</td>
</tr>
</tbody>
</table>

**Codes:**

- (a) 1 2 3 4
- (b) 3 1 2 4
- (c) 3 2 1
- (d) 2 4 1 3
Simply Supported Beam Carrying a Load whose Intensity varies Uniformly from Zero at each End to \( w \) per Unit Run at the Mid Span

IAS-14. A simply supported beam of length 'l' is subjected to a symmetrical uniformly varying load with zero intensity at the ends and intensity \( w \) (load per unit length) at the mid span. What is the maximum bending moment? [IAS-2004]

(a) \( \frac{3wl^2}{8} \)  
(b) \( \frac{wl^2}{12} \)  
(c) \( \frac{wl^2}{24} \)  
(d) \( \frac{5wl^2}{12} \)

IAS-14. Ans. (b)

**Simply Supported Beam carrying a Load whose Intensity varies**

IAS-15. A simply supported beam of span 1 is subjected to a uniformly varying load having zero intensity at the left support and \( w \) N/m at the right support. The reaction at the right support is: [IAS-2003]

(a) \( \frac{wl}{2} \)  
(b) \( \frac{wl}{5} \)  
(c) \( \frac{wl}{4} \)  
(d) \( \frac{wl}{3} \)

IAS-15. Ans. (d)

**Simply Supported Beam with Equal Overhangs and carrying a Uniformly Distributed Load**

IAS-16. Consider the following statements for a simply supported beam subjected to a couple at its mid-span: [IAS-2004]

1. Bending moment is zero at the ends and maximum at the centre
2. Bending moment is constant over the entire length of the beam
3. Shear force is constant over the entire length of the beam
4. Shear force is zero over the entire length of the beam

Which of the statements given above are correct?

(a) 1, 3 and 4  
(b) 2, 3 and 4  
(c) 1 and 3  
(d) 2 and 4

IAS-16. Ans. (c)
IAS-17. Match List-I (Beams) with List-II (Shear force diagrams) and select the correct answer using the codes given below the Lists: [IAS-2001]

List I

A.  
B.  
C.  
D.  

List II

1.  
2.  
3.  
4.  
5.  

Codes:  

(a)  4  2  5  3  (b)  1  4  5  3  
(c)  1  4  3  5  (d)  4  2  3  5

IAS-17. Ans. (d)

The Points of Contraflexure

IAS-18. A point, along the length of a beam subjected to loads, where bending moment changes its sign, is known as the point of [IAS-1996]

(a) Inflexion  (b) Maximum stress  (c) Zero shear force  (d) Contra flexure

IAS-18. Ans. (d)

IAS-19. Assertion (A): In a loaded beam, if the shear force diagram is a straight line parallel to the beam axis, then the bending moment is a straight line inclined to the beam axis. [IAS 1994]

Reason (R): When shear force at any section of a beam is zero or changes sign, the bending moment at that section is maximum.

(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-19. Ans. (b)

### Loading and B.M. diagram from S.F. Diagram

IAS-20. The shear force diagram of a loaded beam is shown in the following figure:
The maximum Bending Moment of the beam is:
   (a) 16 kN-m  (b) 11 kN-m
   (c) 28 kN-m  (d) 8 kN-m

IAS-20. Ans. (a)

IAS-21. The bending moment for a loaded beam is shown below:

The loading on the beam is represented by which one of the followings diagrams?
   (a)  
   (b)  
   (c)  
   (d)  

IAS-21. Ans. (d)
IAS-22. Which one of the given bending moment diagrams correctly represents that of the loaded beam shown in figure? [IAS-1997]

IAS-22. Ans. (c) Bending moment does not depend on moment of inertia.

IAS-23. The shear force diagram is shown above for a loaded beam. The corresponding bending moment diagram is represented by [IAS-2003]

IAS-23. Ans. (a)

IAS-24. The bending moment diagram for a simply supported beam is a rectangle over a larger portion of the span except near the supports. What type of load does the beam carry? [IAS-2007]
(a) A uniformly distributed symmetrical load over a larger portion of the span except near the supports
(b) A concentrated load at mid-span
(c) Two identical concentrated loads equidistant from the supports and close to mid-point of the beam
Bending Moment and Shear Force Diagram

(d) Two identical concentrated loads equidistant from the mid-span and close to supports

IAS-24. Ans. (d)
**Conventional Question IES-2005**

**Question:** A simply supported beam of length 10 m carries a uniformly varying load whose intensity varies from a maximum value of 5 kN/m at both ends to zero at the centre of the beam. It is desired to replace the beam with another simply supported beam which will be subjected to the same maximum 'bending moment' and 'shear force' as in the case of the previous one. Determine the length and rate of loading for the second beam if it is subjected to a uniformly distributed load over its whole length. Draw the variation of 'SF' and 'BM' in both the cases.

**Answer:**

Total load on beam $= 5 \times \frac{10}{2} = 25 \text{kN}$

$\therefore R_A = R_B = \frac{25}{2} = 12.5 \text{kN}$

Take a section X-X from B at a distance $x$.

For $0 \leq x \leq 5$ we get rate of loading

$\omega = a + bx$ [as linearly varying]

at $x=0$, $\omega = 5 \text{kN/m}$

and at $x = 5$, $\omega = 0$

These two boundary condition gives $a = 5$ and $b = -1$

$\therefore \omega = 5 - x$

We know that shear force ($V$), $\frac{dV}{dx} = -\omega$

$\text{or } V = \int (-\omega)dx = -\int (5 - x)dx = -5x + \frac{x^2}{2} + c_1$

at $x = 0$, $F = 12.5 \text{kN} (R_b)$ so $c_1 = 12.5$

$\therefore V = -5x + \frac{x^2}{2} + 12.5$

It is clear that maximum S.F = 12.5 kN
For a beam \( \frac{dM}{dx} = V \)

or, \( M = \int V \, dx = \int (-5x + \frac{x^2}{2} + 12.5) \, dx = -\frac{5x^2}{2} + \frac{x^3}{6} + 12.5x + C_2 \)

at \( x = 0, M = 0 \) gives \( C_2 = 0 \)

\[ M = 12.5x - 2.5x^2 + \frac{x^3}{6} \]

for Maximum bending moment at \( \frac{dM}{dx} = 0 \)

\[ -5x + \frac{x^2}{2} + 12.5 = 0 \]

or, \( x^2 - 10x + 25 = 0 \)

or, \( x = 5 \) means at centre.

So, \( M_{\text{max}} = 12.5 \times 2.5 - 2.5 \times 5^2 + \frac{5^3}{6} = 20.83 \text{ kNm} \)

Now we consider a simply supported beam carrying uniform distributed load over whole length \( (\omega \text{ KN/m}) \).

Here \( R_A = R_B = \frac{WL}{2} \)

**S.F. at section X-X**

\[ V_x = \frac{W \ell}{2} - \omega x \]

\( V_{\text{max}} = 12.5 \text{ kN} \)

**B.M at section X-X**

\[ M_x = \frac{W \ell}{2} x - \frac{Wx^2}{2} \]

\[ \frac{dM_x}{dx} = \frac{WL}{2} - \omega \frac{L^2}{8} = 20.83 \text{ kNm} \]

Solving \((i)\) & \((ii)\) we get \( L=6.666 \text{ m} \) and \( \omega=3.75 \text{ kN/m} \)
Chapter-4  Bending Moment and Shear Force Diagram  S K Mondal's

Conventional Question IES-1996

Question: A Uniform beam of length L is carrying a uniformly distributed load w per unit length and is simply supported at its ends. What would be the maximum bending moment and where does it occur?

Answer: By symmetry each support reaction is equal i.e. R_A=R_B= \( \frac{W \ell}{2} \)

B.M at the section x-x is

\[ M_x = + \frac{W \ell}{2} x - \frac{W x^2}{2} \]

For the B.M to be maximum we have to

\[ \frac{dM_x}{dx} = 0 \]

that gives.

\[ \frac{W \ell}{2} - \omega x = 0 \]

or \( x = \frac{\ell}{2} \) i.e. at mid point.

And \( M_{max} = \frac{\omega \ell}{2} \times \frac{\ell}{2} - \frac{\omega}{2} \times \left( \frac{\ell}{2} \right)^2 = + \frac{w \ell^2}{8} \)

Conventional Question AMIE-1996

Question: Calculate the reactions at A and D for the beam shown in figure. Draw the bending moment and shear force diagrams showing all important values.
Answer: Equivalent figure below shows an overhanging beam ABCDF supported by a roller support at A and a hinged support at D. In the figure, a load of 4 kN is applied through a bracket 0.5 m away from the point C. Now apply equal and opposite load of 4 kN at C. This will be equivalent to a anticlockwise couple of the value of (4 x 0.5) = 2 kNm acting at C together with a vertical downward load of 4 kN at C. Show U.D.L. (1 kN/m) over the port AB, a point load of 2 kN vertically downward at F, and a horizontal load of $2\sqrt{3}$ kN as shown.

For reaction and A and D.

Let us assume $R_A =$ reaction at roller A.

$R_{DV}$ vertically component of the reaction at the hinged support D, and

$R_{DH}$ horizontal component of the reaction at the hinged support D.
Chapter-4

Bending Moment and Shear Force Diagram

S K Mondal's

Obviously

\[ R_{DH} = 2\sqrt{3} \text{ kN} \ (\rightarrow) \]

In order to determine \( R_A \), taking moments about \( D \), we get

\[ R_A \times 6 + 2 \times 1 = 1 \times 2 \times \left( \frac{2}{2} + 2 + 2 \right) + 2 + 4 \times 2 \]

or

\[ R_A = 3 \text{ kN} \]

Also \( R_A + R_{DV} = (1 \times 2) + 4 + 2 = 8 \)

or

\[ R_{DV} = 5 \text{ kN} \]

Reversely upward.

\[ \therefore \text{Reaction at } D, \ R_D = \sqrt{(R_{DV}^2) + (R_{DH}^2)} = \sqrt{5^2 + (2\sqrt{3})^2} = 6.08 \text{ kN} \]

Inclination with horizontal = \( \theta = \tan^{-1} \left( \frac{5}{2\sqrt{3}} \right) = 55.3^\circ \)

S.F. Calculation:

\[ V_F = -2 \text{ kN} \]
\[ V_D = -2 + 5 = 3 \text{ kN} \]
\[ V_C = 3 - 4 = -1 \text{ kN} \]
\[ V_B = -1 \text{ kN} \]
\[ V_A = -1 - (1 \times 2) = -3 \text{ kN} \]

B.M. Calculation:

\[ M_F = 0 \]
\[ M_D = -2 \times 1 = -2 \text{ kNm} \]
\[ M_C = [-2(1 + 2) + 5 \times 2] + 2 = 6 \text{ kNm} \]

The bending moment increases from 4 kNm in (i.e., \(-2(1 + 2) + 5 \times 2\)) to 6 kNm as shown

\[ M_B = -2(1 + 2 + 2) + 5(2) - 4 \times 2 + 2 = 4 \text{ kNm} \]
\[ M_F = -2 \left( 1 + 2 + 2 + \frac{2}{2} \right) + 5(2 + 2 + 1) - 4(2 + 1) + 2 - 1 \times 1 \times \frac{1}{2} \]
\[ = 2.5 \text{ kNm} \]
\[ M_A = 0 \]

Conventional Question GATE-1997

Question: Construct the bending moment and shearing force diagrams for the beam shown in the figure.

Answer:
Chapter-4 Bending Moment and Shear Force Diagram
S K Mondal's

Calculation: First find out reaction at B and E. Taking moments, about B, we get
\[
E \times 4.5 + 20 \times 0.5 \times \frac{0.5}{2} + 100 = 50 \times 3 + 40 \times 5
\]
or \( R_E = 55 \text{kN} \)
Also, \( R_A + R_E = 20 \times 0.5 + 50 + 40 \)
or \( R_A = 45 \text{kN} \) \([\because R_E = 55 \text{kN}]\)

S.F. Calculation: \( V_F = -40 \text{kN} \)
\( V_E = -40 + 55 = 15 \text{kN} \)
\( V_D = 15 - 50 = -35 \text{kN} \)
\( V_B = -35 + 45 = 10 \text{kN} \)

B.M. Calculation: \( M_G = 0 \)
\( M_F = 0 \)
\( M_E = -40 \times 0.5 = -20 \text{kNm} \)
\( M_D = -40 \times 2 + 55 \times 1.5 = 2.5 \text{kNm} \)
\( M_C = -40 \times 4 + 55 \times 3.5 - 50 \times 2 = -67.5 \text{kNm} \)

The bending moment increases from \(-62.5 \text{kNm}\) to 100.
\( M_B = -20 \times 0.5 \times \frac{0.5}{2} = -2.5 \text{kNm} \)

Conventional Question GATE-1996

Question: Two bars AB and BC are connected by a frictionless hinge at B. The assembly is supported and loaded as shown in figure below. Draw the shear force and bending moment diagrams for the combined beam AC. Clearly labelling the
**Answer:** There shall be a vertical reaction at hinge B and we can split the problem in two parts. Then the FBD of each part is shown below.

**Calculation:** Referring the FBD, we get, $F_y = 0$, and $R_1 + R_2 = 200 \, \text{kN}$

From $\sum M_B = 0, 100 \times 2 + 100 \times 3 - R_2 \times 4 = 0$

or $R_2 = \frac{500}{4} = 125 \, \text{kN}$

$\therefore R_1 = 200 - 125 = 75 \, \text{kN}$

Again, $R_3 = R_1 = 75 \, \text{kN}$

and $M = 75 \times 1.5 = 112.5 \, \text{kNm}$.  

Conventional Question IES-1998
Chapter-4  Bending Moment and Shear Force Diagram  S K Mondal’s

Question: A tube 40 mm outside diameter; 5 mm thick and 1.5 m long simply supported at 125 mm from each end carries a concentrated load of 1 kN at each extreme end.

(i) Neglecting the weight of the tube, sketch the shearing force and bending moment diagrams;

(ii) Calculate the radius of curvature and deflection at mid-span. Take the modulus of elasticity of the material as 208 GN/m²

Answer:

(i) Given, \(d_0 = 40\) mm = 0.04 m; \(d_i = d_0 - 2t = 40 - 2 \times 5 = 30\) mm = 0.03 m;
\(W = 1\) kN; \(E = 208\) GN/m² = 208 × 10⁶ N/m²; \(l = 1.5\); \(a = 125\) mm = 0.125 m

Calculation:

(ii) Radius of coordinate \(R\)
As per bending equation:
\[ EI \frac{dy}{dx} = -M \]

or \[ R = \frac{El}{M} \]  

Here, \(M = W \times a = 1 \times 10^3 \times 0.125 = 125\) Nm

\[ I = \frac{\pi}{64} \left( d_0^4 - d_i^4 \right) \]
\[ = \frac{\pi}{64} \left[ (0.04)^4 - (0.03)^4 \right] = 8.59 \times 10^{-6} \text{ m}^4 \]

Substituting the values in equation(i), we get
\[ R = \frac{208 \times 10^6 \times 8.59 \times 10^{-6}}{125} = 142.9 \text{ m} \]

Deflection at mid-span:
\[ \frac{EI}{dx^2} = M = -Wx + W \left( x - \frac{a}{2} \right) - Wx = Wa - Wx = -Wa \]
Integrating, we get
\[ EI \frac{dy}{dx} = -Wy + C_1 \]

When,
\[ x = \frac{1}{2}, \frac{dy}{dx} = 0 \]

\[ 0 = -\frac{Wy}{2} + C_1, \text{ or } C_1 = \frac{Wal}{2} \]

\[ EI \frac{dy}{dx} = -Wy + \frac{Wal}{2} \]

Integrating again, we get
\[ El = -Wy \frac{x^2}{2} + \frac{Wal}{2} x + C_2 \]

When
\[ x = a, y = 0 \]

\[ 0 = -\frac{Wal^3}{2} + \frac{Wal^2}{2} + C_2 \]

or
\[ C_2 = \frac{Wal^3}{2} - \frac{Wal^2}{2} \]

\[ El = -Wy \frac{x^2}{2} + \frac{Wal}{2} x + \left[ \frac{Wal^3}{2} - \frac{Wal^2}{2} \right] \]

or
\[ y = \frac{Wal}{EI} \left[ \frac{x^2}{2} + \frac{lx}{2} + \frac{a^2}{2} - \frac{al}{2} \right] \]

At mid-span, i.e., \( x = l/2 \)
\[ y = \frac{Wal}{EI} \left[ \frac{l^2}{8} + \frac{l \times (l/2)}{2} + \frac{a^2}{2} - \frac{al}{2} \right] \]
\[ = \frac{Wal}{EI} \left[ \frac{l^2}{8} + \frac{a^2}{2} - \frac{al}{2} \right] \]
\[ = \frac{1 \times 1000 \times 0.125 \times 1.5^2}{208 \times 10^9 \times (8.59 \times 10^{-8})} \left[ \frac{2}{8} + \frac{0.125^2}{2} - \frac{0.125 \times 1.5}{2} \right] \]
\[ = 0.001366 \text{m} = 1.366 \text{mm} \]

It will be in upward direction

**Conventional Question IES-2001**

**Question:** What is meant by point of contraflexure or point of inflexion in a beam? Show the same for the beam given below:

![Beam Diagram](image)

**Answer:** In a beam if the bending moment changes sign at a point, the point itself having zero bending moment, the beam changes curvature at this point of zero bending moment and this point is called the point of contraflexure.
From the bending moment diagram we have seen that it is between A & C. [If marks are more we should calculate exact point.]
5. Deflection of Beam

Theory at a Glance (for IES, GATE, PSU)

5.1 Introduction

- We know that the axis of a beam deflects from its initial position under action of applied forces.
- In this chapter we will learn how to determine the elastic deflections of a beam.

Selection of co-ordinate axes

We will not introduce any other co-ordinate system. We use general co-ordinate axis as shown in the figure. This system will be followed in deflection of beam and in shear force and bending moment diagram. Here downward direction will be negative i.e. negative Y-axis. Therefore downward deflection of the beam will be treated as negative.

To determine the value of deflection of beam subjected to a given loading where we will use the formula, \( \frac{d^2y}{dx^2} = M_x \).

Some books fix a co-ordinate axis as shown in the following figure. Here downward direction will be positive i.e. positive Y-axis. Therefore downward deflection of the beam will be treated as positive. As beam is generally deflected in downward directions and this co-ordinate system treats downward deflection is positive deflection.

To determine the value of deflection of beam subjected to a given loading where we will use the formula, \( \frac{d^2y}{dx^2} = -M_x \).

Why to calculate the deflections?

- To prevent cracking of attached brittle materials
- To make sure the structure not deflect severely and to “appear” safe for its occupants
- To help analyzing statically indeterminate structures
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- Information on deformation characteristics of members is essential in the study of vibrations of machines

**Several methods to compute deflections in beam**

- Double integration method *(without the use of singularity functions)*
- Macaulay's Method *(with the use of singularity functions)*
- Moment area method
- Method of superposition
- Conjugate beam method
- Castigliano’s theorem
- Work/Energy methods

Each of these methods has particular advantages or disadvantages.

**Assumptions in Simple Bending Theory**

- Beams are initially straight
- The material is homogenous and isotropic i.e. it has a uniform composition and its mechanical properties are the same in all directions
- The stress-strain relationship is linear and elastic
- Young’s Modulus is the same in tension as in compression
- Sections are symmetrical about the plane of bending
- Sections which are plane before bending remain plane after bending

**Non-Uniform Bending**

- In the case of non-uniform bending of a beam, where bending moment varies from section to section, there will be shear force at each cross section which will induce shearing stresses
- Also these shearing stresses cause warping (or out-of-plane distortion) of the cross section so that plane cross sections do not remain plane even after bending
5.2 Elastic line or Elastic curve

We have to remember that the differential equation of the elastic line is

\[ EI \frac{d^2 y}{dx^2} = M_x \]

**Proof:** Consider the following simply supported beam with UDL over its length.

From elementary calculus we know that curvature of a line (at point Q in figure)

\[ \frac{1}{R} = \frac{d^2 y}{dx^2} \left\{ 1 + \left( \frac{dy}{dx} \right)^2 \right\}^{1/2} \]

where \( R \) = radius of curvature

For small deflection, \( \frac{dy}{dx} \approx 0 \)

or \( \frac{1}{R} \approx \frac{d^2 y}{dx^2} \)
5.3 General expression

From the equation $EI \frac{d^2 y}{dx^2} = M_x$ we may easily find out the following relations.

- $EI \frac{d^4 y}{dx^4} = - \omega$  \text{Shear force density (Load)}
- $EI \frac{d^3 y}{dx^3} = V_x$  \text{Shear force}
- $EI \frac{d^2 y}{dx^2} = M_x$  \text{Bending moment}
- $\frac{dy}{dx} = \theta = \text{slope}$
- $y = \delta = \text{Deflection, Displacement}$
- Flexural rigidity = $EI$

5.4 Double integration method \textit{(without the use of singularity functions)}

- $V_x = \int -\omega \, dx$
- $M_x = \int V_x \, dx$
- $EI \frac{d^2 y}{dx^2} = M_x$
- $\theta = \text{Slope} = \frac{1}{EI} \int M_x \, dx$
- $\delta = \text{Deflection} = \int \theta \, dx$

\textit{4-step procedure to solve deflection of beam problems by double integration method}
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Step 1: Write down boundary conditions (Slope boundary conditions and displacement boundary conditions), analyze the problem to be solved

Step 2: Write governing equations for, \( EI \frac{d^2y}{dx^2} = M_x \)

Step 3: Solve governing equations by integration, results in expression with unknown integration constants

Step 4: Apply boundary conditions (determine integration constants)

**Following table gives boundary conditions for different types of support.**

<table>
<thead>
<tr>
<th>Types of support and Boundary Conditions</th>
<th>Figure</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Clamped or Built in support or Fixed end:</strong> (Point A)</td>
<td><img src="image" alt="Clamped or Built in support or Fixed end" /></td>
</tr>
<tr>
<td>Deflection, ( (y) = 0 )</td>
<td></td>
</tr>
<tr>
<td>Slope, ( (\theta) = 0 )</td>
<td></td>
</tr>
<tr>
<td>Moment, ( (M) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
<tr>
<td><strong>Free end:</strong> (Point B)</td>
<td><img src="image" alt="Free end" /></td>
</tr>
<tr>
<td>Deflection, ( (y) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
<tr>
<td>Slope, ( (\theta) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
<tr>
<td>Moment, ( (M) = 0 )</td>
<td></td>
</tr>
<tr>
<td><strong>Roller (Point B) or Pinned Support (Point A) or Hinged or Simply supported.</strong></td>
<td><img src="image" alt="Roller (Point B) or Pinned Support" /></td>
</tr>
<tr>
<td>Deflection, ( (y) = 0 )</td>
<td></td>
</tr>
<tr>
<td>Slope, ( (\theta) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
<tr>
<td>Moment, ( (M) = 0 )</td>
<td></td>
</tr>
<tr>
<td><strong>End restrained against rotation but free to deflection</strong></td>
<td><img src="image" alt="End restrained against rotation but free to deflection" /></td>
</tr>
<tr>
<td>Deflection, ( (y) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
<tr>
<td>Slope, ( (\theta) = 0 )</td>
<td></td>
</tr>
<tr>
<td>Shear force, ( (V) = 0 )</td>
<td></td>
</tr>
<tr>
<td><strong>Flexible support</strong></td>
<td><img src="image" alt="Flexible support" /></td>
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<tr>
<td>Deflection, ( (y) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
<tr>
<td>Slope, ( (\theta) \neq 0 ) i.e. A finite value</td>
<td></td>
</tr>
</tbody>
</table>
Using double integration method we will find the deflection and slope of the following loaded beams one by one.

(i) A Cantilever beam with point load at the free end.
(ii) A Cantilever beam with UDL (uniformly distributed load)
(iii) A Cantilever beam with an applied moment at free end.
(iv) A simply supported beam with a point load at its midpoint.
(v) A simply supported beam with a point load NOT at its midpoint.
(vi) A simply supported beam with UDL (Uniformly distributed load)
(vii) A simply supported beam with triangular distributed load (GVL) gradually varied load.
(viii) A simply supported beam with a moment at mid span.
(ix) A simply supported beam with a continuously distributed load the intensity of which at any point ‘x’ along the beam is 

\[ W_x = W \sin \left( \frac{\pi x}{L} \right) \]

(i) **A Cantilever beam with point load at the free end.**

We will solve this problem by double integration method. For that at first we have to calculate \( M_x \).

Consider any section XX at a distance ‘x’ from free end which is left end as shown in figure.

\[ M_x = -P.x \]

We know that differential equation of elastic line

\[ EI \frac{d^2y}{dx^2} = M_y = -P.x \]

Integrating both side we get
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\[ \int EI \frac{d^2y}{dx^2} = - P \int x \, dx \]

or \[ EI \frac{dy}{dx} = - P \cdot \frac{x^2}{2} + A \] ...........(i)

Again integrating both side we get

\[ EI \int dy = \int \left( P \cdot \frac{x^2}{2} + A \right) \, dx \]

or \[ Ey = P \cdot \frac{x^3}{6} + Ax + B \] ...........(ii)

Where A and B is integration constants.

Now apply boundary condition at fixed end which is at a distance \( x = L \) from free end and we also know that at fixed end

- \( x = L, y = 0 \)
- \( x = L, \frac{dy}{dx} = 0 \)

from equation (ii) \[ EIL = - \frac{PL^3}{6} + AL + B \] ...........(iii)

from equation (i) \[ EI(0) = - \frac{PL^2}{2} + A \] .......(iv)

Solving (iii) & (iv) we get \[ A = \frac{PL^2}{2} \] and \[ B = - \frac{PL^3}{3} \]

Therefore, \[ y = - \frac{PL^3}{6EI} + \frac{PL^2x}{2EI} - \frac{PL^3}{3EI} \]

The slope as well as the deflection would be maximum at free end hence putting \( x = 0 \) we get

\[ y_{\text{max}} = - \frac{PL^3}{3EI} \] (Negative sign indicates the deflection is downward)

\[ \text{(Slope)}_{\text{max}} = \theta_{\text{max}} = \frac{PL^2}{2EI} \]

Remember for a cantilever beam with a point load at free end.

Downward deflection at free end,

\[ (\delta) = \frac{PL^3}{3EI} \]

And slope at free end,

\[ (\theta) = \frac{PL^2}{2EI} \]
We will now solve this problem by double integration method, for that at first we have to calculate \( (M_x) \).

Consider any section XX at a distance ‘x’ from free end which is left end as shown in figure.

\[ M_x = -(w.x) \frac{x}{2} = -\frac{wx^2}{2} \]

We know that differential equation of elastic line

\[ EI \frac{d^2 y}{dx^2} = -\frac{wx^2}{2} \]

Integrating both sides we get

\[ EI \frac{dy}{dx} = -\frac{wx^3}{6} + A \quad \text{(i)} \]

Again integrating both side we get

\[ EIy = -\frac{wx^4}{24} + Ax + B \quad \text{......(ii)} \]

[where A and B are integration constants]

Now apply boundary condition at fixed end which is at a distance x = L from free end and we also know that at fixed end.

at \( x = L \), \( y = 0 \)

at \( x = L \), \( \frac{dy}{dx} = 0 \)

from equation (i) we get \( EI \times (0) = -\frac{wL^3}{6} + A \) or \( A = \frac{+wL^3}{6} \)

from equation (ii) we get \( EIy = -\frac{wL^4}{24} + A.L + B \)

or \( B = -\frac{wL^4}{8} \)

The slope as well as the deflection would be maximum at the free end hence putting \( x = 0 \), we get
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\[ y_{\text{max}} = \frac{wL^4}{8EI} \]  

[Negative sign indicates the deflection is downward]

\[ (\text{slope})_{\text{max}} = \theta_{\text{max}} = \frac{wL^3}{6EI} \]

Remember: For a cantilever beam with UDL over its whole length,

\[ (\delta) = \frac{wL^4}{8EI} \]

Maximum deflection at free end

\[ (\theta) = \frac{wL^3}{6EI} \]

Maximum slope,

(iii) A Cantilever beam of length ‘L’ with an applied moment ‘M’ at free end.

Consider a section XX at a distance ‘x’ from free end, the bending moment at section XX is

\[ (M_x) = -M \]

We know that differential equation of elastic line

or \[ EI \frac{d^2y}{dx^2} = -M \]

Integrating both side we get

or \[ EI \int \frac{d^2y}{dx^2} = - \int M \, dx \]

or \[ EI \frac{dy}{dx} = -Mx + A \]...(i)
Again integrating both side we get
\[ EI \int dy = \int (Mx + A) \, dx \]
or \[ EI \, y = -\frac{Mx^2}{2} + Ax + B \] ...(ii)
Where A and B are integration constants.

Applying boundary conditions in equation (i) & (ii)

at \( x = L \), \( \frac{dy}{dx} = 0 \) gives \( A = ML \)

at \( x = L \), \( y = 0 \) gives \( B = \frac{ML^2}{2} - ML^2 = -\frac{ML^2}{2} \)

Therefore deflection equation is \[ y = -\frac{Mx^2}{2Ei} + \frac{MLx}{Ei} - \frac{ML^2}{2Ei} \]
Which is the equation of elastic curve.

\[ \therefore \text{Maximum deflection at free end } \quad \delta = \frac{ML^2}{2EI} \quad \text{(It is downward)} \]

\[ \therefore \text{Maximum slope at free end } \quad \theta = \frac{ML}{EI} \]

**Let us take a funny example:** A cantilever beam AB of length ‘L’ and uniform flexural rigidity EI has a bracket BA (attached to its free end). A vertical downward force P is applied to free end C of the bracket. Find the ratio \( a/L \) required in order that the deflection of point A is zero.

[ISRO – 2008]

We may consider this force ‘P’ and a moment (P.a) act on free end A of the cantilever beam.
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Due to point load ‘P’ at free end ‘A’ downward deflection \((\delta) = \frac{PL^3}{3EI}\)

Due to moment \(M = P.a\) at free end ‘A’ upward deflection \((\delta) = \frac{ML^2}{2EI} = \frac{(P.a)L^2}{2EI}\)

For zero deflection of free end A
\[\frac{PL^3}{3EI} - \frac{(P.a)L^2}{2EI}\]
\[3EI \quad 2EI\]

\[\frac{a}{L} = \frac{2}{3}\]

(iv) A simply supported beam with a point load P at its midpoint.

A simply supported beam AB carries a concentrated load P at its midpoint as shown in the figure.

![Diagram of a simply supported beam with a point load P at its midpoint](image)

We want to locate the point of maximum deflection on the elastic curve and find its value.

**In the region 0 < x < L/2**

Bending moment at any point x (According to the shown co-ordinate system)
\[M_x = \left(\frac{P}{2}\right)x\]

and **In the region L/2 < x < L**
\[M_x = \frac{P}{2}(x - L/2)\]

We know that differential equation of elastic line
\[EI \frac{d^2y}{dx^2} = \frac{P}{2}x\]  
(In the region 0 < x < L/2)

Integrating both side we get
\[or \quad EI \int \frac{d^2y}{dx^2} = \frac{P}{2} \int x \, dx\]
\[or \quad EI \frac{dy}{dx} = \frac{P}{2} \frac{x^2}{2} + A \quad (i)\]

Again integrating both side we get
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\[ EI \int dy = \int \left( \frac{P}{4} x^2 + A \right) dx \]

or \[ EI y = \frac{P x^3}{12} + Ax + B \tag{ii} \]

[Where A and B are integrating constants]

Now applying boundary conditions to equation (i) and (ii) we get

at  \( x = 0, \quad y = 0 \)

at  \( x = L/2, \quad \frac{dy}{dx} = 0 \)

\[ A = - \frac{PL^2}{16} \quad \text{and} \quad B = 0 \]

\[ \therefore \text{Equation of elastic line,} \quad y = - \frac{P x^3}{12} - \frac{PL^2}{16} x \]

Maximum deflection at mid span (\( x = L/2 \))

\[ \left( \delta \right) = \frac{PL^3}{48EI} \]

and maximum slope at each end

\[ \left( \theta \right) = \frac{PL^2}{16EI} \]

(iii) A simply supported beam with a point load ‘P’ NOT at its midpoint.

A simply supported beam AB carries a concentrated load P as shown in the figure.

We have to locate the point of maximum deflection on the elastic curve and find the value of this deflection.

Taking co-ordinate axes x and y as shown below
For the bending moment we have

In the region \(0 \leq x \leq a\), \(M_x = \frac{P \cdot a}{L} \cdot x\)

And, In the region \(a \leq x \leq L\), \(M_x = -\frac{P \cdot a}{L} \cdot (L - x)\)

So we obtain two differential equation for the elastic curve.

\[
El \frac{d^2y}{dx^2} = \frac{P \cdot a}{L} \cdot x \quad \text{for} \quad 0 \leq x \leq a
\]

And

\[
El \frac{d^2y}{dx^2} = -\frac{P \cdot a}{L} \cdot (L - x) \quad \text{for} \quad a \leq x \leq L
\]

Successive integration of these equations gives

\[
El \frac{dy}{dx} = \frac{P \cdot a}{L} \cdot \frac{x^2}{2} + A_1 \quad \text{.....(i)} \quad \text{for} \quad 0 \leq x \leq a
\]

\[
El \frac{dy}{dx} = P \cdot a \cdot x - \frac{P \cdot a}{L} \cdot x^2 + A_2 \quad \text{.....(ii)} \quad \text{for} \quad a \leq x \leq L
\]

\[
El y = \frac{P \cdot a}{L} \cdot \frac{x^3}{6} + A_1 x + B_1 \quad \text{.....(iii)} \quad \text{for} \quad 0 \leq x \leq a
\]

\[
El y = P \cdot a \cdot \frac{x^3}{2} - \frac{P \cdot a}{L} \cdot \frac{x^3}{6} + A_2 x + B_2 \quad \text{.....(iv)} \quad \text{for} \quad a \leq x \leq L
\]

Where \(A_1, A_2, B_1, B_2\) are constants of Integration.

Now we have to use Boundary conditions for finding constants:

**BCs**

(a) at \(x = 0\), \(y = 0\)

(b) at \(x = L\), \(y = 0\)

(c) at \(x = a\), \(\left(\frac{dy}{dx}\right) = \text{Same for equation (i) & (ii)}\)

(d) at \(x = a\), \(y = \text{same from equation (iii) & (iv)}\)

We get

\[
A_1 = \frac{P b}{6L} \left(L^2 - b^2\right); \quad A_2 = \frac{P a}{6L} \left(2L^2 + a^2\right)
\]

and \(B_1 = 0; \quad B_2 = \frac{Pa^3}{6EI}\)

Therefore we get two equations of elastic curve...
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For a > b, the maximum deflection will occur in the left portion of the span, to which equation (v) applies. Setting the derivative of this expression equal to zero gives

\[ x = \sqrt[3]{\frac{a(a+2b)}{3}} = \sqrt[3]{\frac{(L-b)(L+b)}{3}} = \sqrt[3]{\frac{L^2 - b^2}{3}} \]

at that point a horizontal tangent and hence the point of maximum deflection substituting this value of x into equation (v), we find,

\[ y_{\text{max}} = \frac{Pb(L^2 - b^2)^{3/2}}{9\sqrt{3}EI} \]

Case –I: if \( a = b = L/2 \) then

Maximum deflection will be at \( x = \sqrt[3]{\frac{L^2 - (L/2)^2}{3}} = L/2 \)

i.e. at mid point

and \( y_{\text{max}} = \left(\frac{P}{9}\right) \left(\frac{L/2}{EIL}\right)^{3/2} = \frac{PL^3}{48EI} \)

(vi) A simply supported beam with UDL (Uniformly distributed load)

A simply supported beam AB carries a uniformly distributed load (UDL) of intensity \( w \) unit length over its whole span \( L \) as shown in figure. We want to develop the equation of the elastic curve and find the maximum deflection \( \delta \) at the middle of the span.

Taking co-ordinate axes x and y as shown, we have for the bending moment at any point x

\[ M_x = \frac{wL}{2} \cdot x - w \cdot \frac{x^2}{2} \]

Then the differential equation of deflection becomes

\[ EI \frac{d^2y}{dx^2} = M_x = \frac{wL}{2} \cdot x - w \cdot \frac{x^2}{2} \]

Integrating both sides we get

\[ EI \frac{dy}{dx} = \frac{wL}{2} \cdot x^2 - w \cdot \frac{x^3}{2} + A \]
Again Integrating both side we get
\[ EI \, y = \frac{wL}{2} \cdot \frac{x^3}{6} - \frac{w}{2} \cdot \frac{x^4}{12} + Ax + B \quad \ldots \ldots \text{(ii)} \]

Where \( A \) and \( B \) are integration constants. To evaluate these constants we have to use boundary conditions.

At \( x = 0, y = 0 \) gives \( B = 0 \)

At \( x = L/2, \frac{dy}{dx} = 0 \) gives \( A = -\frac{wL^3}{24} \)

Therefore the equation of the elastic curve
\[ y = \frac{wL}{12E} \cdot x^3 - \frac{w}{24E} \cdot x^4 - \frac{wL^3}{12E} \cdot x = \frac{wx}{24E} \left[ L^3 - 2L \cdot x^2 + x^3 \right] \]

The maximum deflection at the mid-span, we have to put \( x = L/2 \) in the equation and obtain

Maximum deflection at mid-span, \( \delta = \frac{5wL^4}{384EI} \) (It is downward)

And Maximum slope \( \theta_A = \theta_B \) at the left end \( A \) and at the right end \( B \) is same putting \( x = 0 \) or \( x = L \)

Therefore we get Maximum slope \( \theta = \frac{wL^3}{24EI} \)

**(vii) A simply supported beam with triangular distributed load (GVL) gradually varied load.**

A simply supported beam carries a triangular distributed load (GVL) as shown in figure below. We have to find equation of elastic curve and find maximum deflection (\( \delta \)).
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\[ \frac{d^4y}{dx^4} = \frac{w}{L} x \]  

.....(i)

Separating variables and integrating we get

\[ \int \frac{d^3y}{dx^3} = \int \left( \frac{w}{2L} x + A \right) dx \]  

.....(ii)

Again integrating thrice we get

\[ \int \frac{d^2y}{dx^2} = \int \left( \frac{w}{6L} x + B + A \right) dx \]  

.....(iii)

\[ \frac{dy}{dx} = \int \left( \frac{w}{24L} x^2 + C + A \right) dx \]  

.....(iv)

\[ y = \int \left( \frac{w}{120L} x^3 + D + A \right) dx \]  

.....(v)

Where A, B, C and D are integration constant.

Boundary conditions at \( x = 0 \), \( M_x = 0 \), \( y = 0 \)  

at \( x = L \), \( M_x = 0 \), \( y = 0 \) gives

\[ A = \frac{wL}{6}, \quad B = 0, \quad C = \frac{7wL^3}{360}, \quad D = 0 \]

Therefore \( y = -\frac{wx}{360EI} \left( 7L^4 - 10L^2x^2 + 3x^4 \right) \) (negative sign indicates downward deflection)

To find maximum deflection \( \delta \), we have \( \frac{dy}{dx} = 0 \)

And it gives \( x = 0.519 \) L and maximum deflection \( \delta = 0.00652 \frac{wL^4}{EI} \)

(viii) A simply supported beam with a moment at mid-span

A simply supported beam AB is acted upon by a couple M applied at an intermediate point distance ‘a’ from the equation of elastic curve and deflection at point where the moment acted.

Considering equilibrium we get \( R_A = \frac{M}{L} \) and \( R_0 = -\frac{M}{L} \)

Taking co-ordinate axes x and y as shown, we have for bending moment

In the region \( 0 \leq x \leq a \), \( M_x = \frac{M}{L} \cdot x \)

In the region \( a \leq x \leq L \), \( M_x = \frac{M}{L} \cdot x - M \)

So we obtain the difference equation for the elastic curve

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\[
\frac{d^2y}{dx^2} = \frac{M}{L} \cdot \frac{x}{2} \quad \text{for } 0 \leq x \leq a
\]

and

\[
\frac{d^2y}{dx^2} = \frac{M}{L} \cdot x - M \quad \text{for } a \leq x \leq L
\]

Successive integration of these equation gives

\[
\frac{dy}{dx} = \frac{M}{L} \cdot \frac{x^2}{2} + A_1 \quad \text{....(i) for } 0 \leq x \leq a
\]

\[
\frac{dy}{dx} = \frac{M}{L} \cdot \frac{x^3}{2} - \frac{Mx}{2} + A_2 \quad \text{....(ii) for } a \leq x \leq L
\]

and

\[
y = \frac{M}{L} \cdot \frac{x^3}{3} + A_3 x + B_1 \quad \text{.....(iii) for } 0 \leq x \leq a
\]

\[
y = \frac{M}{L} \cdot \frac{x^3}{3} - \frac{Mx}{2} + A_4 x + B_2 \quad \text{.....(iv) for } a \leq x \leq L
\]

Where \(A_1, A_2, B_1\) and \(B_2\) are integration constants.

To finding these constants boundary conditions

(a) at \(x = 0, \ y = 0\)

(b) at \(x = L, \ y = 0\)

(c) at \(x = a, \ \left(\frac{dy}{dx}\right) = \text{same form equation (i) & (ii)}\)

(d) at \(x = a, \ y = \text{same form equation (iii) & (iv)}\)

\[
A_1 = \frac{-Ma}{3} + \frac{ML}{2L}, \quad A_2 = \frac{ML}{3} + \frac{Ma^2}{2L}
\]

\[
B_1 = 0, \quad B_2 = \frac{Ma^2}{2}
\]

With this value we get the equation of elastic curve

\[
y = \frac{-Mx}{6L} \left\{6aL - 3a^2 - x^2 - 2L^2\right\} \quad \text{for } 0 \leq x \leq a
\]

∴ deflection of \(x = a\),

\[
y = \frac{Ma}{3EIL} \left\{3aL - 2a^2 - L^2\right\}
\]

(ix) A simply supported beam with a continuously distributed load the intensity of which at any point ‘x’ along the beam is \(w_x = w \sin \left(\frac{\pi x}{L}\right)\)

At first we have to find out the bending moment at any point ‘x’ according to the shown co-ordinate system.

We know that
Integrating both sides we get
\[ \int d(V_x) = -\int w \sin \left( \frac{\pi x}{L} \right) \, dx + A \]
or
\[ V_x = -\frac{wL}{\pi} \cos \left( \frac{\pi x}{L} \right) + A \]
and we also know that
\[ \frac{d(M_x)}{dx} = V_x = -\frac{wL}{\pi} \cos \left( \frac{\pi x}{L} \right) + A \]
Again integrating both sides we get
\[ \int d(M_x) = \int \left( -\frac{wL}{\pi} \cos \left( \frac{\pi x}{L} \right) + A \right) \, dx \]
or
\[ M_x = -\frac{wL^2}{\pi^2} \sin \left( \frac{\pi x}{L} \right) + Ax + B \]

Where A and B are integration constants, to find out the values of A and B. We have to use boundary conditions
at \( x = 0 \), \( M_x = 0 \)
and \( x = L \), \( M_x = 0 \)
From these we get \( A = B = 0 \). Therefore \( M_x = -\frac{wL^2}{\pi^2} \sin \left( \frac{\pi x}{L} \right) \)

So the differential equation of elastic curve
\[ EI \frac{d^2 y}{dx^2} = M_x = -\frac{wL^2}{\pi^2} \sin \left( \frac{\pi x}{L} \right) \]
Successive integration gives
\[ EI \frac{dy}{dx} = -\frac{wL^3}{\pi^3} \cos \left( \frac{\pi x}{L} \right) + C \quad \text{......(i)} \]
\[ EI y = -\frac{wL^4}{\pi^4} \sin \left( \frac{\pi x}{L} \right) + Cx + D \quad \text{......(ii)} \]

Where C and D are integration constants, to find out C and D we have to use boundary conditions
at \( x = 0 \), \( y = 0 \)
at \( x = L \), \( y = 0 \)
and that give \( C = D = 0 \)
Therefore slope equation
\[ EI \frac{dy}{dx} = -\frac{wL^3}{\pi^3} \cos \left( \frac{\pi x}{L} \right) \]
and Equation of elastic curve
\[ y = -\frac{wL^4}{\pi^4 EI} \sin \left( \frac{\pi x}{L} \right) \]
\( \text{(-ive sign indicates deflection is downward)} \)

Deflection will be maximum if \( \sin \left( \frac{\pi x}{L} \right) \) is maximum
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\[ \sin \left( \frac{\pi x}{L} \right) = 1 \quad \text{or} \quad x = L/2 \]

and Maximum downward deflection \( \delta = \frac{W L^4}{\pi^4 E I} \) (downward).

5.5 Macaulay's Method (Use of singularity function)

- When the beam is subjected to point loads (but several loads) this is very convenient method for determining the deflection of the beam.
- In this method we will write single moment equation in such a way that it becomes continuous for entire length of the beam in spite of the discontinuity of loading.
- After integrating this equation we will find the integration constants which are valid for entire length of the beam. This method is known as method of singularity constant.

Procedure to solve the problem by Macaulay’s method

**Step – I:** Calculate all reactions and moments

**Step – II:** Write down the moment equation which is valid for all values of \( x \). This must contain brackets.

**Step – III:** Integrate the moment equation by a typical manner. Integration of \( (x-a)^2 \) will be \( \frac{(x-a)^3}{3} \) so on.

**Step – IV:** After first integration write the first integration constant (A) after first terms and after second time integration write the second integration constant (B) after A.x. Constant A and B are valid for all values of \( x \).

**Step – V:** Using Boundary condition find A and B at a point \( x = p \) if any term in Macaulay’s method, \( (x-a) \) is negative (-ive) the term will be neglected.

(i) Let us take an example: A simply supported beam AB length 6m with a point load of 30 kN is applied at a distance 4m from left end A. Determine the equations of the elastic curve between each change of load point and the maximum deflection of the beam.

**Answer:** We solve this problem using Macaulay’s method, for that first writes the general momentum equation for the last portion of beam BC of the loaded beam.

\[ EI \frac{d^2 y}{dx^2} = M_x = 10x \quad |-30(x - 4)| \quad N.m \quad \ldots(i) \]

By successive integration of this equation (using Macaulay’s integration rule
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e.g \int (x - a) \, dx = \frac{(x - a)^2}{2}

We get
\[
E I \frac{dy}{dx} = 5x^2 + A \begin{vmatrix} -15(x-4)^2 \end{vmatrix} \text{ N.m}^2 \quad \ldots (ii)
\]
and \(E I \ y = \frac{5}{3}x^3 + Ax + B \begin{vmatrix} -5(x-4)^3 \end{vmatrix} \text{ N.m}^3\quad \ldots (iii)

Where A and B are two integration constants. To evaluate its value we have to use following boundary conditions.

at \(x = 0\), \(y = 0\) and at \(x = 6\), \(y = 0\)

Note: When we put \(x = 0\), \(x - 4\) is negative (–ive) and this term will not be considered for \(x = 0\), so our equation will be \(E I \ y = \frac{5}{3}x^3 + Ax + B\), and at \(x = 0\), \(y = 0\) gives \(B = 0\)

But when we put \(x = 6\), \(x-4\) is positive (+ive) and this term will be considered for \(x = 6\), \(y = 0\) so our equation will be \(E I \ y = \frac{5}{3}x^3 + Ax + 0 - 5(x - 4)^3\)

This gives
\[
E I \ y(0) = \frac{5}{3}6^3 + A.6 + 0 - 5(6 - 4)^3
\]
or \(A = -53\)

So our slope and deflection equation will be
\[
E I \frac{dy}{dx} = 5x^2 - 53 \begin{vmatrix} 15(x - 4)^2 \end{vmatrix}
\]
and \(E I \ y = \frac{5}{3}x^3 - 53x + 0 \begin{vmatrix} -5(x - 4)^3 \end{vmatrix}\)

Now we have two equations for entire section of the beam and we have to understand how we use these equations. Here if \(x < 4\) then \(x - 4\) is negative so this term will be deleted. That so why in the region \(0 \leq x \leq 4\) we will neglect \((x - 4)\) term and our slope and deflection equation will be
\[
E I \frac{dy}{dx} = 5x^2 - 53
\]
and \(E I \ y = \frac{5}{3}x^3 - 53x\)

But in the region \(4 < x \leq 6\), \((x - 4)\) is positive so we include this term and our slope and deflection equation will be
\[
E I \frac{dy}{dx} = 5x^2 - 53 - 15(x - 4)^2
\]
\(E I \ y = \frac{5}{3}x^3 - 53x - 5(x - 4)^3\)

Now we have to find out maximum deflection, but we don’t know at what value of ‘x’ it will be maximum. For this assuming the value of ‘x’ will be in the region \(0 \leq x \leq 4\).
Deflection (y) will be maximum for that \( \frac{dy}{dx} = 0 \) or \( 5x^2 - 53 = 0 \) or \( x = 3.25 \) m as our calculated \( x \) is in the region \( 0 \leq x \leq 4 \) m; at \( x = 3.25 \) m deflection will be maximum

or \( EI \ y_{\text{max}} = \frac{5}{3} \times 3.25^3 - 53 \times 3.25 \)

or \( y_{\text{max}} = -\frac{115}{EI} \) (−ive sign indicates downward deflection)

But if you have any doubt that Maximum deflection may be in the range of \( 4 < x \leq 6 \) m, use \( EIy = 5x^2 - 53x - 5( x - 4)^2 \) and find out \( x \). The value of \( x \) will be absurd that indicates the maximum deflection will not occur in the region \( 4 < x \leq 6 \) m.

Deflection (y) will be maximum for that \( \frac{dy}{dx} = 0 \)

or \( 5x^2 - 53 - 15(x - 4)^2 = 0 \)

or \( 10x^2 - 120x + 293 = 0 \)

or \( x = 3.41 \) m or \( 8.6 \) m

Both the value fall outside the region \( 4 < x \leq 6 \) m and in this region \( 4 < x \leq 6 \) m and in this region maximum deflection will not occur.

(ii) Now take an example where Point load, UDL and Moment applied simultaneously in a beam:

Let us consider a simply supported beam AB (see Figure) of length 3m is subjected to a point load 10 kN, UDL = 5 kN/m and a bending moment \( M = 25 \) kNm. Find the deflection of the beam at point D if flexural rigidity (EI) = 50 KNm².

![Beam diagram](image)

**Answer:** Considering equilibrium

\[
\sum M_A = 0 \text{ gives } -10 \times 1 - 25 - (5 \times 1) \times (1 + 1 + 1/2) + R_B \times 3 = 0
\]

or \( R_B = 15.83 \) kN

\( R_A + R_B = 10 + 5 \times 1 \) gives \( R_A = -0.83 \) kN

We solve this problem using Macaulay’s method, for that first writing the general momentum equation for the last portion of beam, DB of the loaded beam.

\[
EI \ \frac{d^2y}{dx^2} = M_x = -0.83x \left| -10(x-1) \right| + 25(x-2)^0 \left| -\frac{5(x-2)^2}{2!} \right|
\]

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By successive integration of this equation (using Macaulay’s integration rule)

e.g \[ \int (x-a) \, dx = \frac{(x-a)^2}{2} \]

We get

\[ EI \frac{dy}{dx} = -\frac{0.83}{2} x^2 + A \left| -5(x-1)^2 \right| + 25(x-2)^3 \left| -\frac{5}{6}(x-2)^3 \right| \]

and \[ Ely = -\frac{0.83}{6} x^3 + Ax + B \left| -\frac{5}{3}(x-1)^3 \right| + \frac{25}{2}(x-2)^2 \left| -\frac{5}{24}(x-2)^4 \right| \]

Where A and B are integration constant we have to use following boundary conditions to find out A & B.

at \( x = 0, \ y = 0 \)

at \( x = 3m, \ y = 0 \)

Therefore \( B = 0 \)

\[ 0 = -\frac{0.83}{6} x^3 + A x + 0 \left| -\frac{5}{3} x^2 \right| + 12.5 x^2 \left| -\frac{5}{24} x^3 \right| \]

or \( A = 1.93 \)

\[ Ely = -0.138 x^3 + 1.93 x \left| -1.67(x-1)^3 \right| + 12.5(x-2)^2 \left| -0.21(x-2)^3 \right| \]

Deflection at point D at \( x = 2m \)

\[ Ely_D = -0.138 \times 2^3 + 1.93 \times 2 - 1.67 \times 1^3 = -8.85 \]

or \( y_D = -\frac{8.85}{EI} = -\frac{8.85}{50 \times 10^6} m \) (−ive sign indicates deflection downward)

\[ = 0.177mm \text{ (downward)}. \]

(iii) A simply supported beam with a couple \( M \) at a distance ‘\( a \)’ from left end

If a couple acts we have to take the distance in the bracket and this should be raised to the power zero. i.e. \( M(x-a)^0 \). Power is zero because \( (x-a)^0 = 1 \) and unit of \( M(x-a)^0 = M \) but we introduced the distance which is needed for Macaulay’s method.

\[ EI \frac{d^2y}{dx^2} = M = R_A x - M(x-a)^6 \]

Successive integration gives

\[ EI \frac{dy}{dx} = \frac{M}{L} x^2 + A - M(x-a)^1 \]

\[ EI y = \frac{M}{6L} x^3 + Ax + B - \frac{M(x-a)^2}{2} \]

Where A and B are integration constants, we have to use boundary conditions to find out A & B.

at \( x = 0, \ y = 0 \) gives \( B = 0 \)

at \( x = L, \ y = 0 \) gives \( A = \frac{M(L-a)^2}{2L} - \frac{ML}{6} \)
8. Moment area method

- This method is used generally to obtain displacement and rotation at a single point on a beam.
- The moment area method is convenient in case of beams acted upon with point loads in which case bending moment area consist of triangle and rectangles.

\[ \theta_{AB} = \frac{1}{EI} \times \text{Area of the bending moment diagram between A&B} \]

i.e. slope \( \theta_{AB} = \frac{A_{B.M.}}{EI} \)

- **Deflection of B related to ‘A’**

\[ y_{BA} = \text{Moment of} \frac{M}{EI} \text{ diagram between B&A taking about B} \]

i.e. deflection \( y_{BA} = \frac{A_{B.M.} \times x}{EI} \)

**Important Note**

If \( A_1 = \text{Area of shear force (SF) diagram} \)

\( A_2 = \text{Area of bending moment (BM) diagram} \),

Then, Change of slope over any portion of the loaded beam = \( \frac{A_1 \times A_2}{EI} \)
Some typical bending moment diagram and their area (A) and distance of C.G from one edge \( \bar{x} \) is shown in the following table. [Note the distance will be different from other end]

<table>
<thead>
<tr>
<th>Shape</th>
<th>BM Diagram</th>
<th>Area</th>
<th>Distance from C.G</th>
</tr>
</thead>
<tbody>
<tr>
<td>1. Rectangle</td>
<td><img src="image" alt="Rectangle BM Diagram" /></td>
<td>( A = bh )</td>
<td>( \bar{x} = \frac{b}{2} )</td>
</tr>
<tr>
<td>2. Triangle</td>
<td><img src="image" alt="Triangle BM Diagram" /></td>
<td></td>
<td>( \bar{x} = \frac{b}{3} )</td>
</tr>
<tr>
<td>3. Parabola</td>
<td><img src="image" alt="Parabola BM Diagram" /></td>
<td></td>
<td>( \bar{x} = \frac{b}{4} )</td>
</tr>
<tr>
<td>4. Parabola</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5. Cubic Parabola</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>6. ( y = kx^n )</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>7. Sine curve</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**Determination of Maximum slope and deflection by Moment Area- Method**

(i) A Cantilever beam with a point load at free end
Chapter-5 Deflection of Beam
S K Mondal's

Area of BM (Bending moment diagram)

(A) = \frac{1}{2} \times L \times PL = \frac{PL^2}{2}

Therefore

Maximum slope (\( \theta \)) = \frac{A}{EI} = \frac{PL^2}{2EI} (at free end)

Maximum deflection (\( \delta \)) = \frac{Ax}{EI} = \left( \frac{PL^2}{2} \right) \times \left( \frac{2}{3} L \right) = \frac{PL^3}{3EI} (at free end)

(ii) A cantilever beam with a point load not at free end

Area of BM diagram (A) = \frac{1}{2} \times a \times Pa = \frac{Pa^2}{2}

Therefore

Maximum slope (\( \theta \)) = \frac{A}{EI} = \frac{Pa^2}{2EI} (at free end)

Maximum deflection (\( \delta \)) = \frac{Ax}{EI} = \left( \frac{Pa^2}{2} \right) \times \left( \frac{L-a}{3} \right) = \frac{Pa^2}{2EI} \left( \frac{L-a}{3} \right) (at free end)

(iii) A cantilever beam with UDL over its whole length

Area of BM diagram (A) = \frac{1}{3} \times L \times \left( \frac{wl^2}{2} \right) = \frac{wl^3}{6}

Therefore

Maximum slope (\( \theta \)) = \frac{A}{EI} = \frac{wl^3}{6EI} (at free end)

Maximum deflection (\( \delta \)) = \frac{Ax}{EI} = \left( \frac{wl^3}{6} \right) \times \left( \frac{3}{4} L \right) = \frac{wl^4}{8EI} (at free end)

(iv) A simply supported beam with point load at mid-spam
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Area of shaded BM diagram

\[ (A) = \frac{1}{2} \times \frac{L}{2} \times \frac{PL}{4} = \frac{PL^2}{16} \]

Therefore

Maximum slope \( \theta \) = \( \frac{A}{EI} \times \frac{PL^2}{16EI} \) (at each ends)

Maximum deflection \( \delta \) = \( \frac{AX}{EI} \)

\[ = \frac{PL^2 \times L}{16 \times 3} \]

\[ = \frac{PL^3}{48EI} \] (at mid point)

(v) A simply supported beam with UDL over its whole length

Area of BM diagram (shaded)

\[ (A) = \frac{2}{3} \times \frac{L}{2} \times \left( \frac{wL^2}{8} \right) = \frac{wL^3}{24} \]

Therefore

Maximum slope \( \theta \) = \( \frac{A}{EI} = \frac{wL^3}{24EI} \) (at each ends)

Maximum deflection \( \delta \) = \( \frac{AX}{EI} \)

\[ = \left( \frac{wL^3}{24} \right) \times \left( \frac{5}{8} \times \frac{L}{2} \right) \]

\[ = \frac{5 \ wL^4}{384 \ EI} \] (at mid point)

9. Method of superposition

Assumptions:

- Structure should be linear
- Slope of elastic line should be very small.
- The deflection of the beam should be small such that the effect due to the shaft or rotation of the line of action of the load is neglected.

Principle of Superposition:

- Deformations of beams subjected to combinations of loadings may be obtained as the linear combination of the deformations from the individual loadings
- Procedure is facilitated by tables of solutions for common types of loadings and supports.

Example:

For the beam and loading shown, determine the slope and deflection at point B.
Superpose the deformations due to Loading I and Loading II as shown.

In the **conjugate beam method**, the length of the conjugate beam is the same as the length of the actual beam, the **loading diagram** (showing the loads acting) on the conjugate beam is simply the bending-moment diagram of the actual beam divided by the flexural rigidity $EI$ of the actual beam, and the **corresponding support condition** for the conjugate beam is given by the rules as shown below.

**Corresponding support condition for the conjugate beam**
Conjugates of Common Types of Real Beams

Conjugate beams for stastically determinate real beams

Conjugate beams for stastically indeterminate real beams

By the conjugate beam method, the slope and deflection of the actual beam can be found by using the following two rules:

- The slope of the actual beam at any cross section is equal to the shearing force at the corresponding cross section of the conjugate beam.
- The deflection of the actual beam at any point is equal to the bending moment of the conjugate beam at the corresponding point.

Procedure for Analysis

- Construct the $M / EI$ diagram for the given (real) beam subjected to the specified (real) loading. If a combination of loading exists, you may use M-diagram by parts.
- Determine the conjugate beam corresponding to the given real beam.
- Apply the $M / EI$ diagram as the load on the conjugate beam as per sign convention.
- Calculate the reactions at the supports of the conjugate beam by applying equations of equilibrium and conditions.
- Determine the shears in the conjugate beam at locations where slopes is desired in the real beam, $V_{conj} = \theta_{real}$.
- Determine the bending moments in the conjugate beam at locations where deflections is desired in the real beam, $M_{conj} = y_{real}$.
The method of double integration, method of superposition, moment-area theorems, and Castigliano’s theorem are all well established methods for finding deflections of beams, but they require that the **boundary conditions** of the beams be known or specified. If not, all of them become **helpless**. However, the conjugate beam method is able to proceed and yield a solution for the possible deflections of the beam based on the **support conditions**, rather than the boundary conditions, of the beams.

(i) A Cantilever beam with a point load ‘P’ at its free end.

**For Real Beam:** At a section a distance ‘x’ from free end consider the forces to the left. Taking moments about the section gives (obviously to the left of the section) $M_x = -P \cdot x$

(negative sign means that the moment on the left hand side of the portion is in the anticlockwise direction and is therefore taken as negative according to the sign convention)

so that the **maximum bending moment** occurs at the fixed end i.e. $M_{max} = -PL$ (at $x = L$)

Considering equilibrium we get, $M_A = \frac{wL^2}{3}$ and Reaction $(R_A) = \frac{wL}{2}$

Considering any cross-section XX which is at a distance of x from the fixed end.

At this point load $(W_x) = \frac{W}{L} \cdot x$

**Shear force** $(V_x) = R_A - \text{area of triangle ANM}$

$$\quad = \frac{wL}{2} - \frac{1}{2} \left( \frac{w}{L} \cdot x \right)x = + \frac{wL}{2} - \frac{wx^2}{2L}$$

∴ The shear force variation is parabolic.

at $x = 0$, $V_x = + \frac{wL}{2}$ i.e. Maximum shear force, $V_{max} = + \frac{wL}{2}$

at $x = L$, $V_x = 0$

**Bending moment** $(M_x) = R_A \cdot x - \frac{wx^2}{2L} \cdot \frac{2x}{3} - M_A$
\[ M = \frac{wL}{2} x - \frac{wx^3}{6L} - \frac{wL^2}{3} \]

∴ The bending moment variation is cubic

at \( x = 0 \), \( M_x = -\frac{wL^2}{3} \) i.e. Maximum B.M. \( (M_{\text{max}}) = -\frac{wL^2}{3} \).

at \( x = L \), \( M_x = 0 \)
**Objective Questions (GATE, IES, IAS)**

**Previous 20-Years GATE Questions**

**Beam Deflection**

GATE-1. A lean elastic beam of given flexural rigidity, $EI$, is loaded by a single force $F$ as shown in figure. How many boundary conditions are necessary to determine the deflected centre line of the beam?

(a) 5     (b) 4  
(c) 3    (d) 2

[GATE-1999]

GATE-1. Ans. (d) \[ EI \frac{d^2y}{dx^2} = M. \] Since it is second order differential equation so we need two boundary conditions to solve it.

**Double Integration Method**

GATE-2. A simply supported beam carrying a concentrated load $W$ at mid-span deflects by $\delta_1$ under the load. If the same beam carries the load $W$ such that it is distributed uniformly over entire length and undergoes a deflection $\delta_2$ at the mid span. The ratio $\delta_1: \delta_2$ is:  

(a) 2: 1    (b) $\sqrt{2} : 1$  
(c) 1: 1    (d) 1: 2

[IES-1995; GATE-1994]

GATE-2. Ans. (d)  

\[ \delta_1 = \frac{WL^3}{48EI}, \quad \delta_2 = \frac{5(W^4)}{384EI} = \frac{5Wl^4}{384EI} \]

Therefore $\delta_1: \delta_2 = 5: 8$

GATE-3. A simply supported laterally loaded beam was found to deflect more than a specified value. Which of the following measures will reduce the deflection?  

(a) Increase the area moment of inertia  
(b) Increase the span of the beam  
(c) Select a different material having lesser modulus of elasticity  
(d) Magnitude of the load to be increased

GATE-3. Ans. (a) Maximum deflection $\delta = \frac{Wl^3}{48EI}$

To reduce, $\delta$, increase the area moment of Inertia.
Double Integration Method

IES-1. Consider the following statements: [IES-2003]
In a cantilever subjected to a concentrated load at the free end
1. The bending stress is maximum at the free end
2. The maximum shear stress is constant along the length of the beam
3. The slope of the elastic curve is zero at the fixed end
Which of these statements are correct?
(a) 1, 2 and 3  (b) 2 and 3  (c) 1 and 3  (d) 1 and 2
IES-1. Ans. (b)

IES-2. A cantilever of length L, moment of inertia I. Young's modulus E carries a concentrated load W at the middle of its length. The slope of cantilever at the free end is: [IES-2001]
\[ \theta = \frac{W L^2}{2 EI} \]
(a) \( \frac{W L^2}{2 EI} \)  (b) \( \frac{W L^2}{4 EI} \)  (c) \( \frac{W L^2}{8 EI} \)  (d) \( \frac{W L^2}{16 EI} \)
IES-2. Ans. (c) \( \theta = \frac{W L^2}{8 EI} \)

IES-3. The two cantilevers A and B shown in the figure have the same uniform cross-section and the same material. Free end deflection of cantilever 'A' is \( \delta \).
The value of mid-span deflection of the cantilever 'B' is:
(a) \( \frac{1}{2} \delta \)  (b) \( \frac{2}{3} \delta \)  (c) \( \delta \)  (d) \( 2\delta \)
IES-3. Ans. (c) \( \delta = \frac{WL^3}{3EI} + \left( \frac{WL^2}{2EI} \right) L = \frac{5WL^3}{6EI} \)
\[ y_{mid} = \frac{W}{EI} \left( \frac{2Lx^2}{2} - \frac{x^3}{6} \right)_{x=L} = \frac{5WL^3}{6EI} = \delta \]

IES-4. A cantilever beam of rectangular cross-section is subjected to a load W at its free end. If the depth of the beam is doubled and the load is halved, the deflection of the free end as compared to original deflection will be: [IES-1999]
(a) Half   (b) One-eighth   (c) One-sixteenth   (d) Double
IES-4. Ans. (c) Deflection in cantilever \( \frac{W L^3}{3EI} \times 12 = \frac{4WL^3}{Eah^3} \) If h is doubled, and W is halved, New deflection \( \frac{4WL^3}{2Ea(2h)^3} = \frac{1}{16} \times \frac{4WL^3}{Eah^3} \)

IES-5. A simply supported beam of constant flexural rigidity and length 2L carries a concentrated load 'P' at its mid-span and the deflection under the load is \( \delta \). If a cantilever beam of the same flexural rigidity and length 'L' is subjected to load 'P' at its free end, then the deflection at the free end will be: [IES-1998]
(a) \( \frac{1}{2} \delta \)  (b) \( \delta \)  (c) \( 2\delta \)  (d) \( 4\delta \)
IES-5. Ans. (c) \( \delta \) for simply supported beam = \( \frac{W (2L)^3}{48EI} = \frac{WL^3}{6EI} \)

and deflection for Cantilever = \( \frac{WL^3}{3EI} = 2\delta \)

IES-6. Two identical cantilevers are loaded as shown in the respective figures. If slope at the free end of the cantilever in figure E is \( \theta \), the slope at free end of the cantilever in figure F will be:

(a) \( \frac{1}{3} \) \( \theta \)  
(b) \( \frac{1}{2} \) \( \theta \)  
(c) \( \frac{2}{3} \) \( \theta \)  
(d) \( \theta \)

IES-6. Ans. (d) When a B. M is applied at the free end of cantilever, \( \theta = \frac{ML}{EI} \) = \( \frac{(PL/2) L}{EI} \) = \( \frac{PL^2}{2EI} \)

When a cantilever is subjected to a single concentrated load at free end, then \( \theta = \frac{PL^2}{2EI} \)

IES-7. A cantilever beam carries a load \( W \) uniformly distributed over its entire length. If the same load is placed at the free end of the same cantilever, then the ratio of maximum deflection in the first case to that in the second case will be:

(a) 3/8  
(b) 8/3  
(c) 5/8  
(d) 8/5

IES-7. Ans. (a) \( \frac{WL^3}{8EI} + \frac{WL^3}{3EI} = \frac{3}{8} \)

IES-8. The given figure shows a cantilever of span 'L' subjected to a concentrated load 'P' and a moment 'M' at the free end. Deflection at the free end is given by

(a) \( \frac{PL^2}{2EI} + \frac{ML^2}{3EI} \)  
(b) \( \frac{ML^2}{2EI} + \frac{PL^3}{3EI} \)  
(c) \( \frac{ML^2}{3EI} + \frac{PL^3}{2EI} \)  
(d) \( \frac{ML^2}{2EI} + \frac{PL^3}{48EI} \)

IES-8. Ans. (b)

IES-9. For a cantilever beam of length 'L', flexural rigidity EI and loaded at its free end by a concentrated load \( W \), match List I with List II and select the correct answer.

List I  List II
A. Maximum bending moment 1. \( W L \)  
B. Strain energy 2. \( W L^2/2EI \)  
C. Maximum slope 3. \( W L^3/3EI \)  
D. Maximum deflection 4. \( W L^3/6EI \)

Codes: A B C D A B C D
(a) 1 4 3 2  
(b) 1 4 2 3  
(c) 4 2 1 3  
(d) 4 3 1 2

IES-9. Ans. (b)

IES-10. Maximum deflection of a cantilever beam of length 'L' carrying uniformly distributed load \( w \) per unit length will be:

[IES- 2008]
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(a) $wl^4/ (EI)$  (b) $wl^4/ (4EI)$  (c) $wl^4/ (8EI)$  (d) $wl^4/ (384EI)$

[Where $E$ = modulus of elasticity of beam material and $I$ = moment of inertia of beam cross-section]

IES-10. Ans. (c)

IES-11. A cantilever beam of length ‘l’ is subjected to a concentrated load $P$ at a distance of $l/3$ from the free end. What is the deflection of the free end of the beam? (EI is the flexural rigidity) [IES-2004]

(a) $\frac{2Pl^3}{81EI}$  (b) $\frac{3Pl^3}{81EI}$  (c) $\frac{14Pl^3}{81EI}$  (d) $\frac{15Pl^3}{81EI}$

IES-11. Ans. (d)

Moment Area method gives us

$$\delta_x = \frac{\text{Area}}{EI} = \frac{1}{l^3} \left( \frac{2P}{3} \right) \left( \frac{2l}{3} \right) \left( \frac{4}{9} \right)$$

Alternatively

$$W_{l/3} = \frac{Wl^2}{6} = \frac{Wl^2}{2} - \frac{Wl^2}{2}$$

$$W_{2l/3} = \frac{Wl^2}{6} = \frac{Wl^2}{2} - \frac{Wl^2}{2}$$

IES-12. A 2 m long beam BC carries a single concentrated load at its mid-span and is simply supported at its ends by two cantilevers $AB = 1$ m long and $CD = 2$ m long as shown in the figure. The shear force at end A of the cantilever AB will be

(a) Zero  (b) 40 kg  (c) 50 kg  (d) 60 kg  [IES-1997]

IES-12. Ans. (c) Reaction force on B and C is same $100/2 = 50$ kg. And we know that shear force is same throughout its length and equal to load at free end.

IES-13. Assertion (A): In a simply supported beam subjected to a concentrated load $P$ at mid-span, the elastic curve slope becomes zero under the load. [IES-2003]

Reason (R): The deflection of the beam is maximum at mid-span.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-13. Ans. (a)

IES-14. At a certain section at a distance 'x' from one of the supports of a simply supported beam, the intensity of loading, bending moment and shear force arc $W_x$, $M_x$ and $V_x$ respectively. If the intensity of loading is varying continuously along the length of the beam, then the invalid relation is: [IES-2000]

(a) Slope $Q_x = \frac{M_x}{V_x}$  (b) $V_x = \frac{dM_x}{dx}$  (c) $W_x = \frac{d^2M_x}{dx^2}$  (d) $W_x = \frac{dV_x}{dx}$

IES-14. Ans. (a)
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IES-15. The bending moment equation, as a function of distance x measured from the left end, for a simply supported beam of span L m carrying a uniformly distributed load of intensity w N/m will be given by [IES-1999]

(a) \( M = \frac{wL}{2} (L-x) \left( \frac{w}{2} (L-x)^3 \right) Nm \)  
(b) \( M = \frac{wL}{2} \left( x - \frac{w}{2} x^2 \right) \) Nm 
(c) \( M = \frac{wL}{2} (x - \frac{w}{2} x^3) \) Nm  
(d) \( M = \frac{wL}{2} \left( x - \frac{wLx}{2} \right) \) Nm

IES-15. Ans. (b)

IES-16. A simply supported beam with width ‘b’ and depth ‘d’ carries a central load W and undergoes deflection δ at the centre. If the width and depth are interchanged, the deflection at the centre of the beam would attain the value [IES-1997]

(a) \( \frac{d}{b} \delta \)  
(b) \( \left( \frac{d}{b} \right)^2 \delta \)  
(c) \( \left( \frac{d}{b} \right)^3 \delta \)  
(d) \( \left( \frac{d}{b} \right)^{3/2} \delta \)

IES-16. Ans. (b) Deflection at center \( \delta = \frac{Wl^3}{48EI} = \frac{Wl^3}{48E \left( \frac{bd^3}{12} \right)} \)

In second case, deflection \( \delta’ = \frac{Wl^3}{48EI'} = \frac{Wl^3}{48E \left( \frac{db^3}{12} \right)} = \frac{Wl^3}{48E \left( \frac{bd^3}{12} \right)} \left( \frac{d^2}{b^2} \right) = \frac{d^2}{b^2} \delta’

IES-17. A simply supported beam of rectangular section 4 cm by 6 cm carries a mid-span concentrated load such that the 6 cm side lies parallel to line of action of loading; deflection under the load is δ. If the beam is now supported with the 4 cm side parallel to line of action of loading, the deflection under the load will be: [IES-1993]

(a) 0.44 δ  
(b) 0.67 δ  
(c) 1.5 δ  
(d) 2.25 δ

IES-17. Ans. (d) Use above explanation

IES-18. A simply supported beam carrying a concentrated load W at mid-span deflects by δ₁ under the load. If the same beam carries the load W such that it is distributed uniformly over entire length and undergoes a deflection δ₂ at the mid span. The ratio δ₁: δ₂ is: [IES-1995; GATE-1994]

(a) 2: 1  
(b) \( \sqrt{2} : 1 \)  
(c) 1: 1  
(d) 1: 2

IES-18. Ans. (d) \( \delta_1 = \frac{Wl^3}{48EI} \) and \( \delta_2 = \frac{5 \left( \frac{W}{I} \right)}{384EI} = \frac{5Wl^3}{384EI} \) Therefore δ₁: δ₂ = 5: 8

Moment Area Method

IES-19. Match List-I with List-II and select the correct answer using the codes given below the Lists: [IES-1997]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Toughness</td>
<td>1. Moment area method</td>
</tr>
<tr>
<td>B. Endurance strength</td>
<td>2. Hardness</td>
</tr>
<tr>
<td>C. Resistance to abrasion</td>
<td>3. Energy absorbed before fracture in a tension test</td>
</tr>
<tr>
<td>D. Deflection in a beam</td>
<td>4. Fatigue loading</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Code:</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
<th>A</th>
<th>B</th>
<th>C</th>
<th>D</th>
</tr>
</thead>
<tbody>
<tr>
<td>(a)</td>
<td>4</td>
<td>3</td>
<td>1</td>
<td>2</td>
<td>(b)</td>
<td>4</td>
<td>3</td>
<td>2</td>
</tr>
<tr>
<td>(c)</td>
<td>3</td>
<td>4</td>
<td>2</td>
<td>1</td>
<td>(d)</td>
<td>3</td>
<td>4</td>
<td>1</td>
</tr>
</tbody>
</table>

IES-19. Ans. (c)
Slope and Deflection at a Section

IAS-1. Which one of the following is represented by the area of the S.F diagram from one end upto a given location on the beam? [IAS-2004]
(a) B.M. at the location  (b) Load at the location  (c) Slope at the location  (d) Deflection at the location
IAS-1. Ans. (a)

Double Integration Method

IAS-2. Which one of the following is the correct statement? [IAS-2007]
If for a beam \( \frac{dM}{dx} = 0 \) for its whole length, the beam is a cantilever:
(a) Free from any load  (b) Subjected to a concentrated load at its free end  (c) Subjected to an end moment  (d) Subjected to a udl over its whole span
IAS-2. Ans. (c)

IAS-3. In a cantilever beam, if the length is doubled while keeping the cross-section and the concentrated load acting at the free end the same, the deflection at the free end will increase by [IAS-1996]
(a) 2.66 times  (b) 3 times  (c) 6 times  (d) 8 times
IAS-3. Ans. (d)

Conjugate Beam Method

IAS-4. By conjugate beam method, the slope at any section of an actual beam is equal to: [IAS-2002]
(a) EI times the S.F. of the conjugate beam  (b) EI times the B.M. of the conjugate beam  (c) S.F. of conjugate beam  (d) B.M. of the conjugate beam
IAS-4. Ans. (c)

IAS-5. I = 375 × 10^{-6} \text{ m}^4; l = 0.5 \text{ m}
E = 200 \text{ GPa}
Determine the stiffness of the beam shown in the above figure [IES-2002]
(a) 12 \times 10^{10} \text{ N/m}  (b) 10 \times 10^{10} \text{ N/m}  (c) 4 \times 10^{10} \text{ N/m}  (d) 8 \times 10^{10} \text{ N/m}
IAS-5. Ans. (c) Stiffness means required load for unit deformation. BMD of the given beam
The deflection at the free end of the actual beam = BM of the at fixed point of conjugate beam

\[ y = \left( \frac{1}{2} \times \frac{ML}{EI} \right) \times \frac{2L}{3} + \left( \frac{WL}{2EI} \times L \right) \times \left( L + \frac{L}{2} \right) + \left( \frac{1}{2} \times \frac{L}{2 \times \frac{WL}{2EI}} \right) \times \left( L + \frac{2L}{3} \right) = \frac{3WL^3}{2EI} \]

Or stiffness

\[ \frac{W}{y} = \frac{2EI}{3L^3} = \frac{2 \times (200 \times 10^3) \times (375 \times 10^{-6})}{3 \times (0.5)^3} = 4 \times 10^{10} \text{ N/m} \]
Previous Conventional Questions with Answers

Conventional Question GATE-1999

Question: Consider the signboard mounting shown in figure below. The wind load acting perpendicular to the plane of the figure is \( F = 100 \) N. We wish to limit the deflection, due to bending, at point A of the hollow cylindrical pole of outer diameter 150 mm to 5 mm. Find the wall thickness for the pole. [Assume \( E = 2.0 \times 10^{11} \) N/m\(^2\)]

Answer: Given: \( F = 100 \) N; \( d_0 = 150 \) mm, 0.15 my = 5 mm; \( E = 2.0 \times 10^{11} \) N/m\(^2\)

Thickness of pole, \( t \)

The system of signboard mounting can be considered as a cantilever loaded at A i.e. \( W = 100 \) N and also having anticlockwise moment of \( M = 100 \times 1 = 100 \) Nm at the free end. Deflection of cantilever having concentrated load at the free end,

\[
y = \frac{WL^3}{3EI} + \frac{ML^2}{2EI}
\]

\[
5 \times 10^{-3} = \frac{100 \times 5^3}{3 \times 2.0 \times 10^{11} \times l} + \frac{100 \times 5^3}{2 \times 2.0 \times 10^{11} \times l}
\]

or

\[
l = \frac{1}{5 \times 10^{-3}} \left[ \frac{100 \times 5^3}{3 \times 2.0 \times 10^{11}} + \frac{100 \times 5^3}{2 \times 2.0 \times 10^{11}} \right] = 5.417 \times 10^{-6} \text{ m}^4
\]

But

\[
l = \frac{\pi}{64} (d_0^4 - d_i^4)
\]

\[
\therefore 5.417 \times 10^{-6} = \frac{\pi}{64} (0.154 - d_i^4)
\]

or

\[
d_i = 0.141 \text{ m or 141 mm}
\]

\[
\therefore t = \frac{d_0 - d_i}{2} = \frac{150 - 141}{2} = 4.5 \text{ mm}
\]

Conventional Question IES-2003

Question: Find the slope and deflection at the free end of a cantilever beam of length 6 m as loaded shown in figure below, using method of superposition. Evaluate their numerical value using \( E = 200 \) GPa, \( I = 1 \times 10^{-4} \) m\(^4\) and \( W = 1 \) kN.
Chapter-5

Deflection of Beam

S K Mondal's

**Answer:**

We have to use superposition theory.

1st consider

\[ \delta_c = \frac{PL^3}{3EI} = \frac{(3W)^3}{3EI} = \frac{8W}{EI} \]

\[ \theta_c = \frac{PL^2}{2EI} = \frac{(3W)^2}{2EI} = \frac{6W}{EI} \]

Deflection at A due to this load\(\delta_c\) = \(\delta_c + \theta_c(6 - 2) = \frac{8W}{EI} + \frac{6W}{EI} \times 4 = \frac{32W}{EI} \)

2nd consider:

\[ \delta_B = \frac{(2W)^3}{3EI} = \frac{128W}{3EI} \]

\[ \theta_B = \frac{(2W)^2}{2EI} = \frac{16W}{EI} \]

Deflection at A due to this load\(\delta_B\)

\[ = \delta_B + \theta_B \times (6 - 4) = \frac{224W}{3EI} \]

3rd consider:

\[ (\delta_3) = \delta_A = \frac{W \times 6^3}{3EI} = \frac{72W}{EI} \]

\[ \theta_A = \frac{W \times 6^2}{2EI} = \frac{18W}{EI} \]

Apply superpositioning formula

\[ \delta = \delta_1 + \delta_2 + \delta_3 = \frac{32W}{EI} + \frac{224W}{3EI} + \frac{72W}{EI} = \frac{40W}{EI} = \frac{563 \times W}{3EI} \]

\[ = \frac{563 \times (10^3)}{3 \times (200 \times 10^6) \times 10^{-4}} = 8.93 \text{ mm} \]

**Conventional Question IES-2002**

**Question:** If two cantilever beams of identical dimensions but made of mild steel and grey cast iron are subjected to same point load at the free end, within elastic limit, which one will deflect more and why?

**Answer:** Grey cost iron will deflect more.

We know that a cantilever beam of length 'L' end load 'P' will deflect at free end

\[ (\delta) = \frac{PL^3}{3EI} \]
Conventional Question IES-1997

Question: A uniform cantilever beam (EI = constant) of length L is carrying a concentrated load P at its free end. What would be its slope at the (i) Free end and (ii) Built in end

Answer: (i) Free end, \( \theta = \frac{PL^2}{2EI} \)
(ii) Built-in end, \( \theta = 0 \)
6.1 Euler Bernoulli’s Equation or (Bending stress formula) or Bending Equation

\[
\frac{\sigma}{y} = \frac{M}{I} = \frac{E}{R}
\]

Where
- \( \sigma \) = Bending Stress
- \( M \) = Bending Moment
- \( I \) = Moment of Inertia
- \( E \) = Modulus of elasticity
- \( R \) = Radius of curvature
- \( y \) = Distance of the fibre from NA (Neutral axis)

6.2 Assumptions in Simple Bending Theory

All of the foregoing theory has been developed for the case of pure bending i.e. constant B.M along the length of the beam. In such case

- The shear force at each c/s is zero.
- Normal stress due to bending is only produced.
- Beams are initially straight
- The material is homogenous and isotropic i.e. it has a uniform composition and its mechanical properties are the same in all directions
- The stress-strain relationship is linear and elastic
- Young’s Modulus is the same in tension as in compression
- Sections are symmetrical about the plane of bending
- Sections which are plane before bending remain plane after bending
\[ \sigma_{\max} = \sigma_r = \frac{Mc_1}{I} \]

\[ \sigma_{\min} = \sigma_c = \frac{Mc_2}{I} \] (Minimum in sense of sign)

### 6.4 Section Modulus (Z)

\[ Z = \frac{I}{y} \]

- \( Z \) is a function of beam c/s only
- \( Z \) is other name of the strength of the beam
- The strength of the beam sections depends mainly on the section modulus

- The flexural formula may be written as, \( \sigma = \frac{M}{Z} \)

- Rectangular c/s of width "b" & depth "h" with sides horizontal, \( Z = \frac{bh^2}{6} \)

- Square beam with sides horizontal, \( Z = \frac{a^3}{6} \)

- Square c/s with diagonal horizontal, \( Z = \frac{a^3}{6\sqrt{2}} \)

- Circular c/s of diameter "d", \( Z = \frac{\pi d^3}{32} \)
Chapter-6  Bending Stress in Beam

A log diameter "d" is available. It is proposed to cut out a strongest beam from it. Then

\[ Z = \frac{b(d^2 - b^2)}{6} \]

Therefore, \( Z_{\text{max}} = \frac{bd^3}{9} \) for \( b = \frac{d}{\sqrt{3}} \)

### 6.5 Flexural Rigidity (EI)

Reflects both
- Stiffness of the material (measured by E)
- Proportions of the c/s area (measured by I)

### 6.6 Axial Rigidity = EA

### 6.7 Beam of uniform strength

It is one is which the maximum bending stress is same in every section along the longitudinal axis.

For it \( M \propto bh^2 \)

Where \( b = \) Width of beam
\( h = \) Height of beam

*To make Beam of uniform strength the section of the beam may be varied by*
- Keeping the width constant throughout the length and varying the depth, *(Most widely used)*
- Keeping the depth constant throughout the length and varying the width
- By varying both width and depth suitably.

### 6.8 Bending stress due to additional Axial thrust (P).

A shaft may be subjected to a combined bending and axial thrust. This type of situation arises in various machine elements.

If \( P = \) Axial thrust

Then direct stress \( (\sigma_d) = P / A \) (stress due to axial thrust)

This direct stress \( (\sigma_d) \) may be tensile or compressive depending upon the load P is tensile or compressive.
And the bending stress \( \sigma_y = \frac{M_y}{I} \) is varying linearly from zero at centre and extremum (minimum or maximum) at top and bottom fibres.

If \( P \) is compressive then

- At top fibre \( \sigma = \frac{P}{A} + \frac{M_y}{I} \) (compressive)
- At mid fibre \( \sigma = \frac{P}{A} \) (compressive)
- At bottom fibre \( \sigma = \frac{P}{A} - \frac{M_y}{I} \) (compressive)

### 6.9 Load acting eccentrically to one axis

\[
\sigma_{\text{max}} = \frac{P}{A} + \frac{(P \times e) y}{I} \quad \text{where 'e' is the eccentricity at which 'P' is act.}
\]

\[
\sigma_{\text{min}} = \frac{P}{A} - \frac{(P \times e) y}{I}
\]

**Condition for No tension in any section**

- For no tension in any section, the eccentricity must not exceed \( \frac{2k^2}{d} \)

[Where \( d = \) depth of the section; \( k = \) radius of gyration of c/s]

- For rectangular section \((b \times h)\), \( e \leq \frac{h}{6} \) i.e load will be \( 2e = \frac{h}{3} \) of the middle section.

- For circular section of diameter ‘d’, \( e \leq \frac{d}{8} \) i.e diameter of the kernel, \( 2e = \frac{d}{4} \)

For hollow circular section of diameter ‘d’, \( e \leq \frac{D^2 + d^2}{8D} \) i.e diameter of the kernel, \( 2e \leq \frac{D^2 + d^2}{4D} \).
**OBJECTIVE QUESTIONS (GATE, IES, IAS)**

### Previous 20-Years GATE Questions

#### Bending equation

**GATE-1.** A cantilever beam has the square cross section 10mm × 10 mm. It carries a transverse load of 10 N. Considering only the bottom fibres of the beam, the correct representation of the longitudinal variation of the bending stress is:

- **(a)**
- **(b)**
- **(c)**
- **(d)**

![Figure](image.png)

**GATE-1.** Ans. (a) \( M_y = P \cdot x \) \( \frac{M}{I} = \frac{\sigma}{y} \) or \( \sigma = \frac{M_y}{I} = \frac{10 \times (x) \times 0.005}{(0.01)^2} = 60 \cdot (x) \) MPa

At \( x = 0 \); \( \sigma = 0 \)

At \( x = 1 \text{m} \); \( \sigma = 60 \text{MPa} \)

And it is linear as \( \sigma \propto x \)

**GATE-2.** Two beams, one having square cross section and another circular cross-section, are subjected to the same amount of bending moment. If the cross sectional area as well as the material of both the beams are the same then [GATE-2003]

(a) Maximum bending stress developed in both the beams is the same

(b) The circular beam experiences more bending stress than the square one

(c) The square beam experiences more bending stress than the circular one

(d) As the material is same both the beams will experience same deformation

**GATE-2.** Ans. (b) \( \frac{M}{I} = \frac{E}{\rho} \cdot \sigma \); or \( \sigma = \frac{M_y}{I} \),

\[
\sigma_{sq} = \frac{M}{I} \frac{\left(\frac{a}{2}\right)}{1} = 6M \frac{a}{a^2}; \quad \sigma_{cr} = \frac{M}{I} \frac{\left(\frac{d}{2}\right)}{\pi d^4} = \frac{2\pi \cdot \pi d^4}{a^2} = \frac{4\pi \cdot \pi d^4}{a^2} = \frac{22.27M}{a^2} \rightarrow \frac{\pi d^4}{4} = a^2
\]

\[ \therefore \sigma_{sq} \ < \ \sigma_{cr} \]

#### Section Modulus

**GATE-3.** Match the items in Columns I and II. [GATE-2006]

<table>
<thead>
<tr>
<th>Column-I</th>
<th>Column-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>P. Addendum</td>
<td>1. Cam</td>
</tr>
<tr>
<td>Q. Instantaneous centre of velocity</td>
<td>2. Beam</td>
</tr>
</tbody>
</table>
Combined direct and bending stress

GATE-4. For the component loaded with a force $F$ as shown in the figure, the axial stress at the corner point P is:

$$
\sigma = \frac{P}{A} \left[ \frac{M y}{I} + \frac{F}{4b^2} + \frac{F(L-b) \times b}{2b \times (b^3)} \right].
$$

GATE-4. Ans. (d) Total Stress = Direct stress + Stress due to Moment

Bending equation

IES-1. Beam A is simply supported at its ends and carries udl of intensity $w$ over its entire length. It is made of steel having Young's modulus $E$. Beam B is cantilever and carries a udl of intensity $w/4$ over its entire length. It is made of brass having Young's modulus $E/2$. The two beams are of same length and have same cross-sectional area. If $\sigma_A$ and $\sigma_B$ denote the maximum bending stresses developed in beams A and B, respectively, then which one of the following is correct?

(a) $\sigma_A/\sigma_B$  
(b) $\sigma_A/\sigma_B < 1.0$  
(c) $\sigma_A/\sigma_B > 1.0$  
(d) $\sigma_A/\sigma_B$ depends on the shape of cross-section

IES-1. Ans. (d) Bending stress $(\sigma) = \frac{M y}{I}$, $y$ and $I$ both depends on the

Shape of cross–section so $\frac{\sigma_A}{\sigma_B}$ depends on the shape of cross–section

IES-2. If the area of cross-section of a circular section beam is made four times, keeping the loads, length, support conditions and material of the beam unchanged, then the qualities (List-I) will change through different factors (List-II). Match the List-I with the List-II and select the correct answer using the code given below the Lists:

List-I
A. Maximum BM

List-II
1. 8
B. Deflection
C. Bending Stress
D. Section Modulus

Codes: A B C D A B C D
(a)  3 1 2 4  (b) 2 4 3 1
(c)  3 4 2 1  (d) 2 1 3 4

IES-2. Ans. (b) Diameter will be double, D = 2d.
A. Maximum BM will be unaffected
B. deflection ratio $\frac{E_l}{E_l} = \left(\frac{d}{4}\right)^4 = \frac{1}{16}$
C. Bending stress $\sigma = \frac{My}{I} = \frac{M(d/2)}{\pi d^4}$ or Bending stress ratio $\frac{\sigma_2}{\sigma_1} = \left(\frac{d}{D}\right)^3 = \frac{1}{8}$
D. Selection Modulus ratio $\frac{Z_2}{Z_1} = \frac{b}{y_1} \times \frac{y_1}{l_1} = \left(\frac{D}{d}\right)^3 = 8$

IES-3. Consider the following statements in case of beams: [IES-2002]
1. Rate of change of shear force is equal to the rate of loading at a particular section
2. Rate of change of bending moment is equal to the shear force at a particular suction.
3. Maximum shear force in a beam occurs at a point where bending moment is either zero or bending moment changes sign
Which of the above statements are correct?
(a) 1 alone  (b) 2 alone  (c) 1 and 2  (d) 1, 2 and 3
IES-3. Ans. (c)

IES-4. Match List-I with List-II and select the correct answer using the code given below the Lists: [IES-2006]
List-I (State of Stress) List-II (Kind of Loading)
1. Combined bending and torsion of circular shaft
2. Torsion of circular shaft
3. Thin cylinder subjected to internal pressure
4. Tie bar subjected to tensile force

Codes: A B C D A B C D
(a)  2 1 3 4  (b) 3 4 2 1
(c)  2 4 3 1  (d) 3 1 2 4
IES-4. Ans. (c)
Section Modulus

IES-5. Two beams of equal cross-sectional area are subjected to equal bending moment. If one beam has square cross-section and the other has circular section, then

(a) Both beams will be equally strong
(b) Circular section beam will be stronger
(c) Square section beam will be stronger
(d) The strength of the beam will depend on the nature of loading

IES-5. Ans. (b)

If \( D \) is diameter of circle and 'a' the side of square section, \( \frac{\pi d^2}{4} = a^2 \) or \( d = \sqrt{\frac{4}{\pi}}a \)

\[
Z \text{ for circular section} = \frac{\pi d^2}{32} = \frac{a^3}{4\sqrt{\pi}}; \quad \text{and} \quad Z \text{ for square section} = \frac{a^3}{6}
\]

IES-6. A beam cross-section is used in two different orientations as shown in the given figure:

Bending moments applied to the beam in both cases are same. The maximum bending stresses induced in cases (A) and (B) are related as:

(a) \( \sigma_A = 4\sigma_B \)
(b) \( \sigma_A = 2\sigma_B \)
(c) \( \sigma_A = \frac{\sigma_B}{2} \)
(d) \( \sigma_A = \frac{\sigma_B}{4} \)

IES-6. Ans. (b)

\[
Z \text{ for rectangular section is } \frac{bd^2}{6}, \quad Z_A = \frac{b \left( \frac{b}{2} \right)^2}{6} = \frac{b^3}{24}, \quad Z_B = \frac{b \times b^2}{6} = \frac{b^3}{12}
\]

\[
M = Z_A \sigma_A = Z_B \sigma_B \quad \text{or} \quad \frac{b^3}{24} \sigma_A = \frac{b^3}{12} \sigma_B, \quad \text{or} \quad \sigma_A = 2\sigma_B
\]

IES-7. A horizontal beam with square cross-section is simply supported with sides of the square horizontal and vertical and carries a distributed loading that produces maximum bending stress \( a \) in the beam. When the beam is placed with one of the diagonals horizontal the maximum bending stress will be:

(a) \( \frac{1}{\sqrt{2}} \sigma \)
(b) \( \sigma \)
(c) \( \sqrt{2} \sigma \)
(d) \( 2\sigma \)

IES-7. Ans. (c)

Bending stress = \( \frac{M}{Z} \)

For rectangular beam with sides horizontal and vertical, \( Z = \frac{a^3}{6} \)

For same section with diagonal horizontal, \( Z = \frac{a^3}{6\sqrt{2}} \)

\( \therefore \) Ratio of two stresses = \( \sqrt{2} \)

IES-8. Which one of the following combinations of angles will carry the maximum load as a column?
IES-9. **Assertion (A):** For structures steel I-beams preferred to other shapes. [IES-1992]

**Reason (R):** In I-beams a large portion of their cross-section is located far from the neutral axis.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-9. Ans. (a)

---

**Combined direct and bending stress**

IES-10. **Assertion (A):** A column subjected to eccentric load will have its stress at centroid independent of the eccentricity. [IES-1994]

**Reason (R):** Eccentric loads in columns produce torsion.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-10. Ans. (c) A is true and R is false.

IES-11. For the configuration of loading shown in the given figure, the stress in fibre AB is given by:

(a) $P/A$ (tensile)
(b) $\left( \frac{P}{A} - \frac{P_e\epsilon_5}{I_{xx}} \right)$ (Compressive)
(c) $\left( \frac{P}{A} + \frac{P_e\epsilon_5}{I_{xx}} \right)$ (Compressive)
(d) $P/A$ (Compressive)

IES-11. Ans. (b) $\sigma_y = \frac{P}{A}$ (compressive), $\sigma_x = \frac{M_y}{I_x} = \frac{P\epsilon_y}{I_x}$ (tensile)
IES-12. A column of square section 40 mm × 40 mm, fixed to the ground carries an eccentric load P of 1600 N as shown in the figure.

If the stress developed along the edge CD is –1.2 N/mm², the stress along the edge AB will be:

(a) –1.2 N/mm²
(b) +1 N/mm²
(c) +0.8 N/mm²
(d) –0.8 N/mm²

IES-12. Ans. (d) Compressive stress at CD = 1.2 N/mm² = \( \frac{P}{A} \left( 1 + \frac{6e}{b} \right) = \frac{1600}{1600} \left( 1 + \frac{6e}{20} \right) \)

or \( \frac{6e}{20} = 0.2 \). So stress at AB = \( -\frac{1600}{1600} (1-0.2) = -0.8 \) N/mm² (com)

IES-13. A short column of symmetric cross-section made of a brittle material is subjected to an eccentric vertical load P at an eccentricity e. To avoid tensile stress in the short column, the eccentricity e should be less than or equal to:

(a) h/12 \hspace{1cm} (b) h/6 \hspace{1cm} (c) h/3 \hspace{1cm} (d) h/2

IES-13. Ans. (b)

IES-14. A short column of external diameter D and internal diameter d carries an eccentric load W. The greatest eccentricity which the load can have without producing tension on the cross-section of the column would be:

(a) \( \frac{D + d}{8} \) \hspace{1cm} (b) \( \frac{D^2 + d^2}{8d} \) \hspace{1cm} (c) \( \frac{D^2 + d^2}{8D} \) \hspace{1cm} (d) \( \frac{\sqrt{D^2 + d^2}}{8} \)

IES-14. Ans. (e)
Bending equation

IAS-1. Consider the cantilever loaded as shown below: [IAS-2004]

What is the ratio of the maximum compressive to the maximum tensile stress?
(a) 1.0    (b) 2.0    (c) 2.5    (d) 3.0

IAS-1. Ans. (b) \[\sigma_{\text{compressive, Max}} = \frac{M}{I} \times \frac{2h}{3}\] at lower end of A.

\[\sigma_{\text{tensile, max}} = \frac{M}{I} \times \left(\frac{h}{3}\right)\] at upper end of B

IAS-2. A 0.2 mm thick tape goes over a frictionless pulley of 25 mm diameter. If E of the material is 100 GPa, then the maximum stress induced in the tape is:
(a) 100 MPa  (b) 200 MPa  (c) 400 MPa  (d) 800 MPa

IAS-2. Ans. (d) \[\sigma = \frac{E}{y} \frac{y}{R}\] Here \(y = \frac{0.2}{2} = 0.1\) mm = 0.1 x 10^{-3} m, \(R = \frac{25}{2}\) mm = 12.5 x 10^{-3} m

\[\sigma = \frac{100 \times 10^3 \times 0.1 \times 10^{-3}}{12.5 \times 10^{-3}} \text{ MPa} = 800 \text{MPa}\]

Section Modulus

IAS-3. A pipe of external diameter 3 cm and internal diameter 2 cm and of length 4 m is supported at its ends. It carries a point load of 65 N at its centre. The sectional modulus of the pipe is:

IAS-3. [IAS-2002]
IAS-3. Ans. (c) Section modulus \( (z) = \frac{I}{y} = \frac{\pi}{64} \left( \frac{3^4 - 2^4}{3} \right) cm^3 = \frac{65\pi}{96} cm^3 \)

IAS-4. A Cantilever beam of rectangular cross-section is 1m deep and 0.6 m thick. If the beam were to be 0.6 m deep and 1m thick, then the beam would. \([\text{IAS-1999}]\)
(a) Be weakened 0.5 times
(b) Be weakened 0.6 times
(c) Be strengthened 0.6 times
(d) Have the same strength as the original beam because the cross-sectional area remains the same

IAS-4. Ans. (b) 

\[
\begin{align*}
I & = \frac{1}{y} = \frac{0.6 \times 1^2}{0.5} = 1.2 m^3 \\
\text{and} \quad z_2 & = \frac{I}{y} = \frac{1 \times 0.6^2}{0.3} = 0.72 m^3 \\
\frac{z_2}{z_1} & = \frac{0.72}{1.2} = 0.6 \text{ times}
\end{align*}
\]

IAS-5. A T-beam shown in the given figure is subjected to a bending moment such that plastic hinge forms. The distance of the neutral axis from D is (all dimensions are in mm)
(a) Zero
(b) 109 mm
(c) 125 mm
(d) 170 mm

IAS-5. Ans. (b)

IAS-6. Assertion (A): I, T and channel sections are preferred for beams. \([\text{IAS-2000}]\)
Reason(R): A beam cross-section should be such that the greatest possible amount of area is as far away from the neutral axis as possible.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IAS-6. Ans. (a) Because it will increase area moment of inertia, i.e. strength of the beam.
IAS-7. If the T-beam cross-section shown in the given figure has bending stress of 30 MPa in the top fiber, then the stress in the bottom fiber would be (G is centroid)
(a) Zero  
(b) 30 MPa  
(c) −80 MPa  
(d) 50 MPa

IAS-7. Ans. (c)  
\[
\frac{M}{I} = \frac{\sigma_1}{y_1} = \frac{\sigma_2}{y_2} \text{ or } \sigma_2 = y_2 \frac{\sigma_1}{y_1} = \frac{110 - 30}{30} \times 30 = 80 \text{ MPa}
\]

As top fibre in tension so bottom fibre will be in compression.

IAS-8. Assertion (A): A square section is more economical in bending than the circular section of same area of cross-section.  
Reason (R): The modulus of the square section is less than of circular section of same area of cross-section.
(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true

IAS-8. ans. (c)

Bimetallic Strip
IAS-9. A straight bimetallic strip of copper and steel is heated. It is free at ends. The strip, will:
(a) Expand and remain straight  
(b) Will not expand but will bend  
(c) Will expand and bend also  
(d) Twist only
IAS-9. Ans. (c) As expansion of copper will be more than steel.

Combined direct and bending stress
IAS-10. A short vertical column having a square cross-section is subjected to an axial compressive force, centre of pressure of which passes through point R as shown in the above figure. Maximum compressive stress occurs at point
(a) S  
(b) Q  
(c) R  
(d) P
IAS-10. Ans. (a) As direct and bending both the stress is compressive here.

IAS-11. A strut's cross-sectional area A is subjected to load P a point S (h, k) as shown in the given figure. The stress at the point Q (x, y) is:  
IAS-11.
Chapter-6 Bending Stress in Beam

(a) \( \frac{P}{A} + \frac{Phy}{I_y} + \frac{Pky}{I_x} \)

(b) \( -\frac{P}{A} - \frac{Phx}{I_y} - \frac{Phy}{I_x} \)

(c) \( \frac{P}{A} + \frac{Phy}{I_y} + \frac{Pky}{I_x} \)

(d) \( \frac{P}{A} + \frac{Phx}{I_y} + \frac{Pky}{I_x} \)

IAS-11. Ans. (b) All stress are compressive, direct stress,

\[ \sigma_d = \frac{P}{A} \text{ (compressive)}, \quad \sigma_x = \frac{My}{I_x} = \frac{Pky}{I_x} \text{ (compressive)} \]

and \( \sigma_y = \frac{Mx}{I_y} = \frac{Phx}{I_y} \text{ (compressive)} \)
Conventional Question IES-2008

Question: A simply supported beam AB of span length 4 m supports a uniformly distributed load of intensity \( q = 4 \text{ kN/m} \) spread over the entire span and a concentrated load \( P = 2 \text{ kN} \) placed at a distance of 1.5 m from left end A. The beam is constructed of a rectangular cross-section with width \( b = 10 \text{ cm} \) and depth \( d = 20 \text{ cm} \). Determine the maximum tensile and compressive stresses developed in the beam to bending.

Answer:

\[
R_A + R_B = 2 + 4 	imes 4 \quad \text{...(i)}
\]

\[
-R_A 	imes 4 + 2(4-1.5) + (4 \times 4) 	imes 2 = 0 \quad \text{...(ii)}
\]

Or \( R_A = 9.25 \text{ kN} \), \( R_B = 18 - R_A = 8.75 \text{ kN} \)

If \( 0 \leq x \leq 2.5 \text{ m} \)

\[
M_x = R_B x - 4x \left( \frac{x}{2} \right) - 2(x-2.5)
\]

\[= 8.75x - 2x^2 - 2x + 5 = 6.75x - 2x^2 + 5 \quad \text{...(ii)}
\]

From (i) & (ii) we find out that bending movement at \( x = 2.1875 \text{ m} \) in (i) gives maximum bending movement.

[Just find \( \frac{dM}{dx} \) for both the cases]

\[
M_{max} = 8.25 \times 2.1875 - 2 \times 1875^2 = 9.57K7kNm
\]

Area moment of Inertia (I) = \[
\frac{bh^3}{12} = \frac{0.1 \times 0.2^3}{12} = 6.6667 \times 10^{-5} \text{ m}^4
\]

Maximum distance from NA is \( y = 10 \text{ cm} = 0.1 \text{ m} \)

\[
\sigma_{max} = \frac{M_y}{I} = \frac{(9.57 \times 10^3) \times 0.1}{6.6667 \times 10^{-5} \frac{N}{m^2}} = 14.355 \text{ MPa}
\]

Therefore maximum tensile stress in the lowest point in the beam is 14.355 MPa and maximum compressive stress in the topmost fiber of the beam is -14.355 MPa.

Conventional Question IES-2007

Question: A simply supported beam made of rolled steel joist (I-section: 450mm × 200mm) has a span of 5 m and it carries a central concentrated load W. The flanges are strengthened by two 300mm × 20mm plates, one riveted to each flange over the entire length of the flanges. The second moment of area of the joist about the principal bending axis is 35060 cm⁴. Calculate...
(i) The greatest central load the beam will carry if the bending stress in the 300mm/20mm plates is not to exceed 125 MPa.

(ii) The minimum length of the 300 mm plates required to restrict the maximum bending stress is the flanges of the joist to 125 MPa.

**Answer:**

Moment of Inertia of the total section about X-X

\[(I) = \text{moment of inertia of I-section} + \text{moment of inertia of the plates about X-X axis.}\]

\[= 35060 + 2\left[\frac{30 \times 2^3}{12} + 30 \times 2 \times \left(\frac{45}{2} + \frac{2}{2}\right)^2\right] = 101370 \text{ cm}^4\]

(i) Greatest central point load (W):

For a simply supported beam a concentrated load at centre.

\[M = \frac{WL}{4} = \frac{W \times 5}{4} = 1.25W\]

\[M = \frac{\sigma I}{y} = \frac{(125 \times 10^6) \times (101370 \times 10^{-8})}{0.245} = 517194 \text{ Nm}\]

\[\therefore 1.25W = 517194 \quad \text{or} \quad W = 413.76 \text{ kN}\]

(ii) Suppose the cover plates are absent for a distance of x-meters from each support. Then at these points the bending moment must not exceed moment of resistance of I section alone i.e

\[\frac{\sigma I}{y} = \frac{(125 \times 10^6) \times (35060 \times 10^{-8})}{0.245} = 178878 \text{ Nm}\]

\[\therefore \text{Bending moment at x metres from each support}\]
Chapter-6  Bending Stress in Beam  S K Mondal's

\[ W = \frac{1}{2} \times x = 178878 \]

\[ or, \frac{41760}{2} \times x = 178878 \]

\[ or \ x = 0.86464 \text{ m} \]

*Hence* leaving 0.86464 m from each support, for the middle 5 - 2×0.86464 = 3.27 m the cover plate should be provided.

**Conventional Question IES-2002**

**Question:** A beam of rectangular cross-section 50 mm wide and 100 mm deep is simply supported over a span of 1500 mm. It carries a concentrated load of 50 kN, 500 mm from the left support.

**Calculate:**

(i) The maximum tensile stress in the beam and indicate where it occurs:

(ii) The vertical deflection of the beam at a point 500 mm from the right support. E for the material of the beam = 2 × 10^5 MPa.

**Answer:**

Taking moment about L

\[ R_L \times 1500 = 50 \times 500 \]

\[ or, R_L = 16.667 \text{ kN} \]

\[ or, R_L + R_R = 50 \]

\[ \therefore R_R = 50 - 16.667 = 33.333 \text{ kN} \]

Take a section from right R, x-x at a distance x.

Bending moment (\( M_x \)) = +\( R_R \times x \)

Therefore maximum bending moment will occur at 'c' \( M_{max} = 16.667 \times 1 \text{ KNm} \)

(i) Moment of Inertia of beam cross-section

\[ (I) = \frac{bh^3}{12} = \frac{0.050 \times (0.100)^3}{12} = 4.167 \times 10^{-6} \text{ m}^4 \]

Applying bending equation

\[ \frac{M}{I} = \frac{\sigma}{\rho} \quad \text{or, } \sigma_{max} = \frac{M_y}{I} = \frac{(16.67 \times 10^3) \times (0.001)}{4.167 \times 10^{-6}} \text{ N/m}^2 = 200 \text{ MPa} \]

It will occur where M is maximum at point 'C'

(ii) Macaulay's method for determining the deflection of the beam will be convenient as there is point load.

\[ M_x = EI \frac{d^2y}{dx^2} = 33.333 \times x - 50 \times (x - 0.5) \]
Integrate both side we get

\[
EI \frac{d^2 y}{dx^2} = 33.333 \times \frac{x^2}{2} - \frac{50}{2} (x - 0.5)^2 + c_1 x + c_2
\]

at \( x=0, y=0 \) gives \( c_2 = 0 \)

at \( x=1.5, y=0 \) gives

\[
0 = 5.556 \times (1.5)^3 - 8.333 \times 1^3 + c_1 \times 1.5
\]

or, \( c_1 = -6.945 \)

\[
:\ El y = 5.556 \times x^3 - 8.333(x - 0.5)^3 - 6.945 \times 1 = -2.43
\]

or, \( y = \frac{-2.43}{(2 \times 10^5 \times 10^6)} = -2.9167 \text{ mm [downward so -ive]} \)

**Conventional Question AMIE-1997**

**Question:** If the beam cross-section is rectangular having a width of 75 mm, determine the required depth such that maximum bending stress induced in the beam does not exceed 40 MN/m²

**Answer:** Given: \( b = 75 \text{ mm} = 0.075 \text{ m}, \) \( \sigma_{\text{max}} = 40 \text{ MN/m}^2 \)

Depth of the beam, \( d \): Figure below shows a rectangular section of width \( b = 0.075 \text{ m} \) and depth \( d \) metres. The bending is considered to take place about the horizontal neutral axis N.A. shown in the figure. The maximum bending stress occurs at the outer fibres of the rectangular section at a distance \( \frac{d}{2} \) above or below the neutral axis. Any fibre at a distance \( y \) from N.A. is subjected to a bending stress, \( \sigma = \frac{My}{I} \), where \( I \) denotes the second moment of area of the rectangular section about the N.A. i.e. \( \frac{bd^3}{12} \).

At the outer fibres, \( y = \frac{d}{2} \), the maximum bending stress there becomes

\[
\sigma_{\text{max}} = \frac{M \times \left(\frac{d}{2}\right)}{bd^3} = \frac{M}{bd^2} \quad \text{--- (i)}
\]

or

\[
M = \sigma_{\text{max}} \times \frac{bd^2}{6} \quad \text{--- (ii)}
\]

For the condition of maximum strength i.e. maximum moment \( M \), the product \( bd^2 \) must be a maximum, since \( \sigma_{\text{max}} \) is constant for a given material. To maximize the quantity \( bd^2 \) we realise that it must be expressed in terms of one independent variable, say, \( b \), and we may do this from the right angle triangle relationship.
Multiplying both sides by \( b \), we get \( bd^2 = bD^2 - b^3 \).

To maximize \( bd^2 \) we take the first derivative of expression with respect to \( b \) and set it equal to zero, as follows:

\[
\frac{d}{db} (bd^2) = \frac{d}{db} (bD^2 - b^3) = D^2 - 3b^2 = b^2 + d^2 - 3b^2 = d^2 - 2b^2 = 0
\]

Solving, we have, depth \( d = \sqrt{2} \ b \) \ ...(iii)

This is the desired ratio in order that the beam will carry a maximum moment \( M \).

It is to be noted that the expression appearing in the denominator of the right side of eqn. (i) i. e. \( \frac{bd^2}{6} \) is the section modulus \((Z)\) of a rectangular bar. Thus, it follows; the section modulus is actually the quantity to be maximized for greatest strength of the beam.

Using the relation (iii), we have

\[ d = \sqrt{2} \times 0.075 = 0.106 \text{ m} \]

Now, \( M = \sigma_{\text{max}} \times Z = \sigma_{\text{max}} \times \frac{bd^2}{6} \)

Substituting the values, we get

\[ M = 40 \times \frac{0.075 \times (0.106)^2}{6} = 0.005618 \text{ MNm} \]

\[ \sigma_{\text{max}} = \frac{M}{Z} = \frac{0.005618}{(0.075 \times (0.106)^2 / 6)} = 40 \text{ MN/m}^2 \]

Hence, the required depth \( d = 0.106 \text{ m} = 106 \text{ mm} \)
7. Shear Stress in Beam

Theory at a Glance (for IES, GATE, PSU)

1. Shear stress in bending ($\tau$)

$$\tau = \frac{VQ}{Ib}$$

Where, $V$ = Shear force = $\frac{dM}{dx}$

$Q$ = Statical moment = $\int_{y_1}^{y_f} ydA$

$I$ = Moment of inertia

$b$ = Width of beam c/s.

2. Statical Moment (Q)

$$Q = \int_{y_1}^{y_f} ydA = \text{Shaded Area} \times \text{distance of the centroid of the shaded area from the neutral axis of the c/s.}$$

3. Variation of shear stress

<table>
<thead>
<tr>
<th>Section</th>
<th>Diagram</th>
<th>Position of $\tau_{\text{max}}$</th>
<th>$\tau_{\text{max}}$</th>
</tr>
</thead>
</table>
| Rectangular | ![Diagram](image1) | N.A | $\tau_{\text{max}} = \frac{3V}{2A}$  
$\tau_{\text{max}} = 1.5\tau_{\text{mean}}$  
$= \tau_{N_A}$ |
| Circular | ![Diagram](image2) | N.A | $\tau_{\text{max}} = \frac{4}{3}\tau_{\text{mean}}$ |
### Chapter 7: Shear Stress in Beam

<table>
<thead>
<tr>
<th>Section</th>
<th>Diagram</th>
<th>( \tau_{\text{max}} )</th>
<th>( \tau_{\text{max}} = 1.5 \tau_{\text{mean}} )</th>
<th>( \tau_{\text{N.d}} = 1.33 \tau_{\text{mean}} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>Triangular</td>
<td><img src="image1" alt="Diagram" /></td>
<td>( \frac{h}{6} ) from N.A</td>
<td><img src="image2" alt="Diagram" /></td>
<td><img src="image3" alt="Diagram" /></td>
</tr>
<tr>
<td>Trapezoidal</td>
<td><img src="image4" alt="Diagram" /></td>
<td>( \frac{h}{6} ) from N.A</td>
<td><img src="image5" alt="Diagram" /></td>
<td><img src="image6" alt="Diagram" /></td>
</tr>
<tr>
<td>Section Diagram</td>
<td><img src="image7" alt="Diagram" /></td>
<td><img src="image8" alt="Diagram" /></td>
<td><img src="image9" alt="Diagram" /></td>
<td><img src="image10" alt="Diagram" /></td>
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<td>Uni form</td>
<td><img src="image11" alt="Diagram" /></td>
<td><img src="image12" alt="Diagram" /></td>
<td><img src="image13" alt="Diagram" /></td>
<td><img src="image14" alt="Diagram" /></td>
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<tr>
<td>I-Section</td>
<td><img src="image15" alt="Diagram" /></td>
<td><img src="image16" alt="Diagram" /></td>
<td><img src="image17" alt="Diagram" /></td>
<td><img src="image18" alt="Diagram" /></td>
</tr>
</tbody>
</table>

\[ (\tau_{\text{max}})_{y=y} = \frac{V}{8I} \left[ h^2 - h_i^2 \right] \]

\[ (\tau_{\text{max}})_{y=\frac{h}{2}} = 0 \]

\[ (\tau_{\text{max}})_{y=0} = \frac{V}{8I} \left[ b(h_i^2 - h_i^2) + th_i^2 \right] \]

\[ (\tau_{\text{max}})_{y=\frac{h_i}{2}} = \frac{Vb}{8I} \left[ h^2 - h_i^2 \right] \]

### 4. Variation of shear stress for some more section [As asked in different examinations]

**Non uniform I-Section**

**Diagonally placed square section**

**L-section**

**Hollow circle**

**T-section**

**Cross**
5. Rectangular section

- Maximum shear stress for rectangular beam: \( \tau_{\text{max}} = \frac{3V}{2A} \)
- For this, \( A \) is the area of the entire cross section
- Maximum shear occurs at the neutral axis
- Shear is zero at the top and bottom of beam

6. Shear stress in beams of thin walled profile section.

- Shear stress at any point in the wall distance "s" from the free edge

\[
\tau = \frac{V_x}{It} \int_0^s y \, dA
\]

where \( V_x = \text{Shear force} \)
\( \tau = \text{Thickness of the section} \)
\( I = \text{Moment of inertia about NA} \)

- Shear Flow (q)

\[
q = \tau t = \frac{V_x}{I_{NA}} \int_0^s y \, dA
\]

- Shear Force (F)
F = \int qds

- **Shear Centre (e)**
  Point of application of shear stress resultant
OBJECTIVE QUESTIONS (GATE, IES, IAS)

Previous 20-Years GATE Questions

Shear Stress Variation

GATE-1. The transverse shear stress acting in a beam of rectangular cross-section, subjected to a transverse shear load, is:
(a) Variable with maximum at the bottom of the beam
(b) Variable with maximum at the top of the beam
(c) Uniform
(d) Variable with maximum on the neutral axis

GATE-1. Ans (d) \( \tau_{\text{max}} = \frac{3}{2} \tau_{\text{mean}} \)

GATE-2. The ratio of average shear stress to the maximum shear stress in a beam with a square cross-section is:

(a) 1 (b) \( \frac{2}{3} \) (c) \( \frac{3}{2} \) (d) 2

GATE-2. Ans. (b)

\[ \frac{\tau_{\text{max}}}{\tau_{\text{mean}}} = \frac{3}{2} \]

Previous 20-Years IES Questions

Shear Stress Variation

IES-1. At a section of a beam, shear force is \( F \) with zero BM. The cross-section is square with side \( a \). Point A lies on neutral axis and point B is mid way between neutral axis and top edge, i.e. at distance \( a/4 \) above the neutral axis. If \( \tau_A \) and \( \tau_B \) denote shear stresses at points A and B, then what is the value of \( \tau_A / \tau_B \)?

(a) 0 (b) \( \frac{1}{3} \) (c) \( \frac{4}{3} \) (d) None of above

IES-1. Ans. (c)

\[ \tau = \frac{V A y}{12 b} = \frac{V a^2 a}{12 a (a^2 - 4 y^2)} = \frac{3 V a}{2 a^3} \left( a^2 - 4 y^2 \right) \]

\[ \tau_A = \frac{3 V a}{2 a^3} \left( a^2 - 4 \left( \frac{a}{4} \right)^2 \right) = \frac{4}{3} \]
IES-2. A wooden beam of rectangular cross-section 10 cm deep by 5 cm wide carries maximum shear force of 2000 kg. Shear stress at neutral axis of the beam section is:

(a) Zero  (b) 40 kgf/cm$^2$  (c) 60 kgf/cm$^2$  (d) 80 kgf/cm$^2$

IES-2. Ans. (c) Shear stress at neutral axis $\tau = \frac{3F}{2bd} = \frac{3 \times 2000}{2 \times 10 \times 5} = 60$ kgf/cm$^2$

IES-3. In case of a beam of circular cross-section subjected to transverse loading, the maximum shear stress developed in the beam is greater than the average shear stress by:

(a) 50%  (b) 33%  (c) 25%  (d) 10%

IES-3. Ans. (b) In the case of beams with circular cross-section, the ratio of the maximum shear stress to average shear stress is 4:3

IES-4. What is the nature of distribution of shear stress in a rectangular beam?

(a) Linear  (b) Parabolic  (c) Hyperbolic  (d) Elliptic

IES-4. Ans. (b)

\[ \tau = \sqrt{\frac{h^2}{4l} - y_1^2} \] indicating a parabolic distribution of shear stress across the cross-section.

IES-5. Which one of the following statements is correct?

When a rectangular section beam is loaded transversely along the length, shear stress develops on

(a) Top fibre of rectangular beam  (b) Middle fibre of rectangular beam  (c) Bottom fibre of rectangular beam  (d) Every horizontal plane

IES-5. Ans. (b)

IES-6. A beam having rectangular cross-section is subjected to an external loading. The average shear stress developed due to the external loading at a particular
cross-section is $t_{avg}$. What is the maximum shear stress developed at the same cross-section due to the same loading?

IES-6. Ans. (c)

Shear stress in a rectangular beam, maximum shear stress,
$$\tau_{max} = \frac{3F}{2b \cdot h} = 1.5 \tau_{(average)}$$

Shear stress in a circular beam, the maximum shear stress,
$$\tau_{max} = \frac{4F}{3 \cdot \frac{\pi}{4} d^2} = \frac{4}{3} \tau_{(average)}$$

IES-7. The transverse shear stress acting in a beam of rectangular cross-section, subjected to a transverse shear load, is:
(a) Variable with maximum at the bottom of the beam
(b) Variable with maximum at the top of the beam
(c) Uniform
(d) Variable with maximum on the neutral axis

IES-7. Ans (d) $\tau_{max} = \frac{3}{2} \tau_{mean}$

IES-8.

A cantilever is loaded by a concentrated load P at the free end as shown. The shear stress in the element LMNOPQRS is under consideration. Which of the following figures represents the shear stress directions in the cantilever?

IES-2002
IES-8. Ans. (d)

IES-9. In I-Section of a beam subjected to transverse shear force, the maximum shear stress is developed.  
(a) At the centre of the web  
(b) At the top edge of the top flange  
(c) At the bottom edge of the top flange  
(d) None of the above  
IES-9. Ans. (a)

IES-10. The given figure (all dimensions are in mm) shows an I-Section of the beam. The shear stress at point P (very close to the bottom of the flange) is 12 MPa. The stress at point Q in the web (very close to the flange) is:  
(a) Indeterminable due to incomplete data  
(b) 60MPa  
(c) 18 MPa  
(d) 12 MPa  
IES-10. Ans. (b)

IES-11. Assertion (A): In an I-Section beam subjected to concentrated loads, the shearing force at any section of the beam is resisted mainly by the web portion.  
Reason (R): Average value of the shearing stress in the web is equal to the value of shearing stress in the flange.  
(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true  
IES-11. Ans. (c)

Shear stress distribution for different section

IES-12. The shear stress distribution over a beam cross-section is shown in the figure above. The beam is of  
(a) Equal flange I-Section  
(b) Unequal flange I-Section  
(c) Circular cross-section  
(d) T-section  
IES-12. Ans. (b)
Shear Stress in Beam

Shear Stress Variation

IAS-1. Consider the following statements: [IAS-2007]

Two beams of identical cross-section but of different materials carry same bending moment at a particular section, then

1. The maximum bending stress at that section in the two beams will be same.
2. The maximum shearing stress at that section in the two beams will be same.
3. Maximum bending stress at that section will depend upon the elastic modulus of the beam material.
4. Curvature of the beam having greater value of E will be larger.

Which of the statements given above are correct?
(a) 1 and 2 only  (b) 1, 3 and 4  (c) 1, 2 and 3  (d) 2, 3 and 4
IAS-1. Ans. (a)

Bending stress $\sigma = \frac{My}{I}$ and shear stress ($\tau$) = $\frac{VAy}{Ib}$ both of them does not depends on material of beam.

IAS-2. In a loaded beam under bending [IAS-2003]

(a) Both the maximum normal and the maximum shear stresses occur at the skin fibres
(b) Both the maximum normal and the maximum shear stresses occur the neutral axis
(c) The maximum normal stress occurs at the skin fibres while the maximum shear stress occurs at the neutral axis
(d) The maximum normal stress occurs at the neutral axis while the maximum shear stress occurs at the skin fibres
IAS-2. Ans. (c)

$\tau = \frac{V}{4I} \left( \frac{h^2}{4} - y_1^2 \right)$ indicating a parabolic distribution of shear stress across the cross-section.

Shear stress distribution for different section

IAS-3. Select the correct shear stress distribution diagram for a square beam with a diagonal in a vertical position: [IAS-2002]
IAS-3. Ans. (d)

IAS-4. The distribution of shear stress of a beam is shown in the given figure. The cross-section of the beam is:

(a)  
(b)  
(c)  
(d)  

IAS-4. Ans. (b)

IAS-5. A channel-section of the beam shown in the given figure carries a uniformly distributed load.

Assertion (A): The line of action of the load passes through the centroid of the cross-section. The beam twists besides bending.
Reason (R): Twisting occurs since the line of action of the load does not pass through the web of the beam.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-5. Ans. (c) Twisting occurs since the line of action of the load does not pass through the shear.
Conventional Question IES-2009

Q. (i) A cantilever of circular solid cross-section is fixed at one end and carries a concentrated load \( P \) at the free end. The diameter at the free end is 200 mm and increases uniformly to 400 mm at the fixed end over a length of 2 m. At what distance from the free end will the bending stresses in the cantilever be maximum? Also calculate the value of the maximum bending stress if the concentrated load \( P = 30 \text{ kN} \). [15-Marks]

Ans.

We have \( \frac{\sigma}{y} = \frac{M}{I} \) \hspace{1cm} \ldots \ldots \hspace{1cm} (i)

Taking distance \( x \) from the free end we have

\[
M = 30x \text{ kN.m} = 30x \times 10^3 \text{ N.m}
\]

\[
y = 100 + \frac{x}{2} (200 - 100)
\]

\[
= 100 + 50x \text{ mm}
\]

and \( I = \frac{\pi d^4}{64} \)

Let \( d \) be the diameter at \( x \) from free end.

\[
\pi \left[ \frac{200 + \frac{(400 - 200) x}{2}}{2} \right]^4
\]

\[
= \frac{\pi (200 + 100x)^4}{64} \text{ mm}^4
\]

From equation (i), we have

\[
\sigma = \frac{30x \times 10^3}{(100 + 50x) \times 10^{-3}}
\]

\[
= \frac{30x \times 10^3}{\pi \left(200 + 100x\right)^4 \times 10^{-12}}
\]

\[
\therefore \sigma = \frac{960x}{\pi} \left(200 + 100x\right)^{-3} \times 10^{12} \hspace{1cm} \ldots \ldots \hspace{1cm} (ii)
\]

For max \( \sigma \), \( \frac{d\sigma}{dx} = 0 \)

\[
\Rightarrow \frac{10^{12} \times 960}{\pi}
\]

\[
\left[ x(-3)(100)(200 + 100x)^{-4} + 1, (200 + 100x)^{-3} \right] = 0
\]

\[
\Rightarrow -300x + 200 + 100x = 0
\]

\[
\Rightarrow x = 1 \text{ m}
\]
Hence maximum bending stress occurs at the midway and from equation (ii), maximum bending stress
\[ \sigma = \frac{960}{\pi} \left(1\right)(200 + 100)^3 \times 10^{12} \]
\[ = \frac{960 \times 10^{12}}{\pi \times (300)^3} = 11.32 \text{ MPa} \]

Conventional Question IES-2006

Question: A timber beam 15 cm wide and 20 cm deep carries uniformly distributed load over a span of 4 m and is simply supported. If the permissible stresses are 30 N/mm² longitudinally and 3 N/mm² transverse shear, calculate the maximum load which can be carried by the timber beam.

Answer: Moment of inertia \((I) = \frac{bh^3}{12} = \frac{(0.15) \times (0.20)^3}{12} = 10^{-4} \text{ m}^4 \)

Distance of neutral axis from the top surface \(y = \frac{20}{2} = 10 \text{ cm} = 0.1 \text{ m} \)

We know that \(\frac{M}{I} = \frac{\sigma}{y} \) or \(\sigma = \frac{My}{I} \)

Where maximum bending moment due to uniformly distributed load in simply supported beam \((M) = \frac{\omega \ell^2}{8} = \frac{\omega \times 4^2}{8} = 2\omega \)

Considering longitudinal stress
\[ 30 \times 10^6 = \frac{(2\omega) \times 0.1}{10^{-4}} \]

or, \(\omega = 15 \text{ kN/m} \)
Now considering shear

Maximum shear force \[\frac{\omega L}{2} = \frac{\omega \cdot 4}{2} = 2\omega\]

Therefore average shear stress \(\tau_{\text{mean}}\) = \[\frac{2\omega}{0.15 \times 0.2} = 66.67\omega\]

For rectangular cross-section

Maximum shear stress \(\tau_{\text{max}}\) = \[\frac{3}{2} \cdot \omega = \frac{3}{2} \times 66.67\omega = 100\omega\]

Now \(3 \times 10^6 = 100\omega\); \(\omega = 30\) kN/m

So maximum load carrying capacity of the beam = 15 kN/m (without fail).
8. Fixed and Continuous Beam

Theory at a Glance (for IES, GATE, PSU)

What is a beam?
A (usually) horizontal structural member that is subjected to a load that tends to bend it.

Types of Beams

- Simply supported beam
- Cantilever beam
- Simply Supported Beams
- Cantilever Beam
- Continuous Beam
- Single Overhang Beam
- Double Overhang Beam
- Single Overhang Beam with internal hinge
- Fixed Beam
- Continuous beam

Continuous beams
Beams placed on more than 2 supports are called continuous beams. Continuous beams are used when the span of the beam is very large, deflection under each rigid support will be equal zero.

Analysis of Continuous Beams
(Using 3-moment equation)

Stability of structure
If the equilibrium and geometry of structure is maintained under the action of forces than the structure is said to be stable.
External stability of the structure is provided by the reaction at the supports. Internal stability is provided by proper design and geometry of the member of the structure.

**Statically determinate and indeterminate structures**

Beams for which reaction forces and internal forces can be found out from static equilibrium equations alone are called statically determinate beam.

**Example:**

\[ \sum X_i = 0, \sum Y_i = 0 \text{ and } \sum M_i = 0 \text{ is sufficient to calculate } R_A \& R_B. \]

Beams for which reaction forces and internal forces cannot be found out from static equilibrium equations alone are called statically indeterminate beam. This type of beam requires deformation equation in addition to static equilibrium equations to solve for unknown forces.

**Example:**
Advantages of fixed ends or fixed supports

- Slope at the ends is zero.
- Fixed beams are stiffer, stronger and more stable than SSB.
- In case of fixed beams, fixed end moments will reduce the BM in each section.
- The maximum deflection is reduced.

Bending moment diagram for fixed beam

Example:

BMD for Continuous beams

BMD for continuous beams can be obtained by superimposing the fixed end moments diagram over the free bending moment diagram.
Three - moment Equation for continuous beams OR

Clapeyron’s Three Moment Equation

\[
M_A \left( \frac{L_1}{E_1 I_1} \right) + 2M_B \left( \frac{L_1}{E_1 I_1} + \frac{L_2}{E_2 I_2} \right) + M_C \left( \frac{L_2}{E_2 I_2} \right) = -6a_1 \overline{x_1} - \frac{6a_1 L_2}{E_2 I_2} - 6 \left[ \frac{\delta_a - \delta_b}{L_1} + \frac{\delta_c - \delta_b}{L_2} \right]
\]

The above equation is called generalized 3-moments Equation.

\( M_A, M_B \) and \( M_C \) are support moments \( E_1, E_2 \) → Young’s modulus
of Elasticity of 2 spans.
\( I_1, I_2 \) → M O I of 2 spans,
\( a_1, a_2 \) → Areas of free B.M.D.
\( \overline{x_1} \) and \( \overline{x_2} \) → Distance of free B.M.D. from the end supports, or outer supports.

(A and C)
\( \delta_a, \delta_b \) and \( \delta_c \) → are sinking or settlements of support from their initial position.
OBJECTIVE QUESTIONS (GATE, IES, IAS)

Previous 20-Years IES Questions

Overhanging Beam

IES-1. An overhanging beam ABC is supported at points A and B, as shown in the above figure. Find the maximum bending moment and the point where it occurs. 

(a) 6 kN-m at the right support  
(b) 6 kN-m at the left support  
(c) 4.5 kN-m at the right support  
(d) 4.5 kN-m at the midpoint between the supports

IES-1. Ans. (a) Taking moment about A

\[ V_b \times 2 = (2 \times 1) + (6 \times 3) \]
\[ \Rightarrow 2V_b = 2 + 18 \]
\[ \Rightarrow V_b = 10 \text{ kN} \]
\[ V_a + V_b = 2 + 6 = 8 \text{ kN} \]
\[ \therefore V_a = 8 - 10 = -2 \text{ kN} \]
\[ \therefore \text{Maximum Bending Moment} = 6 \text{ kN-m at the right support} \]

IES-2. A beam of length 4 L is simply supported on two supports with equal overhangs of L on either sides and carries three equal loads, one each at free ends and the third at the mid-span. Which one of the following diagrams represents correct distribution of shearing force on the beam? 

IES-2. Ans. (d)
They use opposite sign conversions but for correct sign remember S.F & B.M of cantilever is (-) ive.

IES-3. A horizontal beam carrying uniformly distributed load is supported with equal overhangs as shown in the given figure. The resultant bending moment at the mid-span shall be zero if a/b is: [IES-2001]
(a) 3/4    (b) 2/3    (c) 1/2    (d) 1/3

IES-3. Ans. (c)

Previous 20-Years IAS Questions

Overhanging Beam

IAS-1.

If the beam shown in the given figure is to have zero bending moment at its middle point, the overhang x should be: [IAS-2000]
(a) \( \frac{wl^2}{4P} \)    (b) \( \frac{wl^2}{6P} \)    (c) \( \frac{wl^2}{8P} \)    (d) \( \frac{wl^2}{12P} \)

IAS-1. Ans. (c) \( R_c = R_D = P + \frac{wl}{2} \)

Bending moment at mid point (M) = \( -\frac{wl}{2} \cdot \frac{l}{4} + R_D \cdot \frac{l}{2} - P \left( x + \frac{l}{2} \right) = 0 \) gives \( x = \frac{wl^2}{8P} \)

IAS-2. A beam carrying a uniformly distributed load rests on two supports 'b' apart with equal overhangs 'a' at each end. The ratio b/a for zero bending moment at mid-span is: [IAS-1997]
(a) \( \frac{1}{2} \)    (b) \( \frac{1}{3} \)    (c) \( \frac{3}{2} \)    (d) 2

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(i) By similarity in the B.M diagram, a must be b/2

(ii) By formula \( M = \frac{w}{2} \left[ \frac{b^2}{4} - a^2 \right] = 0 \) gives \( a = b/2 \)

**IAS-3.** A beam carries a uniformly distributed load and is supported with two equal overhangs as shown in figure 'A'. Which one of the following correctly shows the bending moment diagram of the beam? [IAS 1994]

**IAS-3. Ans. (a)**
**Conventional Question IES-2006**

*Question:* What are statically determinate and indeterminate beams? Illustrate each case through examples.

*Answer:* Beams for which reaction forces and internal forces can be found out from static equilibrium equations alone are called statically determinate beam.

**Example:**

\[
\sum X_i = 0, \sum Y_i = 0 \text{ and } \sum M_i = 0 \text{ is sufficient to calculate } R_A \text{ & } R_B.
\]

Beams for which reaction forces and internal forces cannot be found out from static equilibrium equations alone are called statically indeterminate beam. This type of beam requires deformation equation in addition to static equilibrium equations to solve for unknown forces.

**Example:**
9. **Torsion**

**Theory at a Glance (for IES, GATE, PSU)**

- In machinery, the general term "shaft" refers to a member, usually of circular cross-section, which supports gears, sprockets, wheels, rotors, etc., and which is subjected to torsion and to transverse or axial loads acting singly or in combination.
- An "axle" is a rotating/non-rotating member that supports wheels, pulleys,... and carries no torque.
- A "spindle" is a short shaft. Terms such as lineshaft, headshaft, stub shaft, transmission shaft, countershaft, and flexible shaft are names associated with special usage.

**Torsion of circular shafts**

1. Equation for shafts subjected to torsion "T"

\[
\frac{\tau}{R} = \frac{T}{J} = \frac{G\theta}{L}
\]

Torsion Equation

Where

- \( J \) = Polar moment of inertia
- \( \tau \) = Shear stress induced due to torsion \( T \).
- \( G \) = Modulus of rigidity
- \( \theta \) = Angular deflection of shaft
- \( R, L \) = Shaft radius & length respectively

**Assumptions**

- The bar is acted upon by a pure torque.
- The section under consideration is remote from the point of application of the load and from a change in diameter.
- Adjacent cross sections originally plane and parallel remain plane and parallel after twisting, and any radial line remains straight.
- The material obeys Hooke’s law
- Cross-sections rotate as if rigid, i.e. every diameter rotates through the same angle
2. Polar moment of inertia

As stated above, the polar second moment of area, J is defined as

\[ J = \int_0^R 2\pi r^3 \, dr \]

For a solid shaft
\[ J = 2\pi \left[ \frac{r^4}{4} \right]_0^R = \frac{2\pi R^4}{4} = \frac{\pi D^4}{32} \]  \hspace{1cm} (6)

For a hollow shaft of internal radius \( r \):
\[ J = \int_0^R 2\pi r^3 \, dr = 2\pi \left[ \frac{r^4}{4} \right]_0^R = \frac{\pi}{2} (R^4 - r^4) = \frac{\pi}{32} (D^4 - d^4) \] \hspace{1cm} (7)

Where D is the external and d is the internal diameter.

- Solid shaft “J” = \( \frac{\pi d^4}{32} \)
- Hollow shaft, "J" = \( \frac{\pi}{32} (d_i^4 - d_o^4) \)

3. The polar section modulus

\[ Z_p = J / c, \text{ where } c = r = D/2 \]

- For a solid circular cross-section, \( Z_p = \pi D^3 / 16 \)
- For a hollow circular cross-section, \( Z_p = \pi (D_o^4 - d_i^4) / 16D_o \)
- Then, \( \tau_{\text{max}} = T / Z_p \)
- If design shears stress, \( \tau_d \) is known, required polar section modulus can be calculated from:

\[ Z_p = T / \tau_d \]

4. Power Transmission (P)

- \( P \) (in Watt) = \( \frac{2\pi NT}{60} \)
5. Safe diameter of Shaft (d)

- Stiffness consideration
  \[ \frac{T}{J} = \frac{G\theta}{L} \]

- Shear Stress consideration
  \[ \frac{T}{J} = \frac{\tau}{R} \]

We take higher value of diameter of both cases above for overall safety if other parameters are given.

6. In twisting

- Solid shaft, \( \tau_{\text{max}} = \frac{16T}{\pi d^3} \)

- Hollow shaft, \( \tau_{\text{max}} = \frac{16T d_o}{\pi (d_o^4 - d_i^4)} \)

- Diameter of a shaft to have a maximum deflection "\( \alpha \)"
  \[ d = 4.9 \times \sqrt{\frac{TL}{Ga}} \]
  [Where \( T \) in N-mm, \( L \) in mm, \( G \) in N/mm²]

7. Comparison of solid and hollow shaft

- A Hollow shaft will transmit a greater torque than a solid shaft of the same weight & same material because the average shear stress in the hollow shaft is smaller than the average shear stress in the solid shaft

  \( \frac{(\tau_{\text{max}})\text{hollow shaft}}{(\tau_{\text{max}})\text{solid shaft}} = \frac{16}{15} \left[ \begin{array}{l} \text{If solid shaft dia = D} \\
  \text{Hollow shaft, } d_o = D, \frac{d_i}{2} \end{array} \right] \)

- Strength comparison (same weight, material, length and \( \tau_{\text{max}} \))
  \[ \frac{T_h}{T_s} = \frac{n^2 + 1}{n^3/n^2 - 1} \]
  Where, \( n = \frac{\text{External diameter of hollow shaft}}{\text{Internal diameter of hollow shaft}} \)
  [ONGC-2005]

- Weight comparison (same Torque, material, length and \( \tau_{\text{max}} \))
  \[ \frac{W_h}{W_s} = \frac{(n^2 - 1)n^{2/3}}{(n^4 - 1)^{2/3}} \]
  Where, \( n = \frac{\text{External diameter of hollow shaft}}{\text{Internal diameter of hollow shaft}} \)
  [WBPSC-2003]

- Strain energy comparison (same weight, material, length and \( \tau_{\text{max}} \))
  \[ \frac{U_h}{U_s} = 1 + \frac{1}{n^2} \]
  \[ = 1 + \frac{1}{n^2} \]

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8. Shaft in series
\[ \theta = \theta_1 + \theta_2 \]
Torque \( T \) is same in all section
Electrical analogy gives torque\( (T) = \text{Current (I)} \)

9. Shaft in parallel
\[ \theta_1 = \theta_2 \text{ and } T = T_1 + T_2 \]
Electrical analogy gives torque\( (T) = \text{Current (I)} \)

10. Combined Bending and Torsion
- In most practical transmission situations shafts which carry torque are also subjected to bending, if only by virtue of the self-weight of the gears they carry. Many other practical applications occur where bending and torsion arise simultaneously so that this type of loading represents one of the major sources of complex stress situations.
- In the case of shafts, bending gives rise to tensile stress on one surface and compressive stress on the opposite surface while torsion gives rise to pure shear throughout the shaft.
- For shafts subjected to the simultaneous application of a bending moment \( M \) and torque \( T \) the principal stresses set up in the shaft can be shown to be equal to those produced by an equivalent bending moment, of a certain value \( M_e \) acting alone.

- Figure

- Maximum direct stress \( (\sigma_x) \) & Shear stress \( (\tau_{xy}) \) in element A
  \[
  \sigma_x = \frac{32M}{\pi d^3} + \frac{P}{A}, \quad \tau_{xy} = \frac{16T}{\pi d^3}
  \]
- Principal normal stresses \( (\sigma_{1,2}) \) & Maximum shearing stress \( (\tau_{\text{max}}) \)
Chapter-9  
Torsion  

\[ \sigma_{1,2} = \frac{\sigma_x}{2} \pm \sqrt{\left(\frac{\sigma_x}{2}\right)^2 + \tau_{xy}^2} \]

\[ \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \pm \sqrt{\left(\frac{\sigma_x}{2}\right)^2 + (\tau_{xy})^2} \]

- Maximum Principal Stress (\(\sigma_{\text{max}}\)) & Maximum shear stress (\(\tau_{\text{max}}\))

\[ \sigma_{\text{max}} = \frac{16}{\pi d^3} \left[ M + \sqrt{M^2 + T^2} \right] \]

\[ \tau_{\text{max}} = \frac{16}{\pi d^3} \sqrt{M^2 + T^2} \]

- Location of Principal plane (\(\theta\))

\[ \theta = \frac{1}{2} \tan^{-1} \left( \frac{T}{M} \right) \]

- Equivalent bending moment (\(M_e\)) & Equivalent torsion (\(T_e\)).

\[ M_e = \left[ \frac{M + \sqrt{M^2 + T^2}}{2} \right] \]

\[ T_e = \sqrt{M^2 + T^2} \]

- Important Note
  - Uses of the formulas are limited to cases in which both M & T are known. Under any other condition Mohr’s circle is used.

- Safe diameter of shaft (\(d\)) on the basis of an allowable working stress.
  - \(\sigma_w\) in tension, \(d = \sqrt[3]{\frac{32M_e}{\pi \sigma_w}}\)
  - \(\tau_w\) in shear, \(d = \sqrt[3]{\frac{16T_e}{\pi \tau_w}}\)

11. Shaft subjected to twisting moment only

- Figure
Normal force \( (F_n) \) & Tangential force \( (F_t) \) on inclined plane AB

\[
F_n = -\tau \times [BC \sin \theta + AC \cos \theta] \\
F_t = \tau \times [BC \cos \theta - AC \sin \theta]
\]

Normal stress \( (\sigma_n) \) & Tangential stress (shear stress) \( (\sigma_t) \) on inclined plane AB.

\[
\sigma_n = -\tau \sin 2\theta \\
\sigma_t = \tau \cos 2\theta
\]

Maximum normal & shear stress on AB

<table>
<thead>
<tr>
<th>( \theta )</th>
<th>( (\sigma_n)_{\text{max}} )</th>
<th>( \tau_{\text{max}} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>+( \tau )</td>
</tr>
<tr>
<td>45°</td>
<td>-( \tau )</td>
<td>0</td>
</tr>
<tr>
<td>90</td>
<td>0</td>
<td>-( \tau )</td>
</tr>
<tr>
<td>135</td>
<td>+( \tau )</td>
<td>0</td>
</tr>
</tbody>
</table>

Important Note

- Principal stresses at a point on the surface of the shaft = +\( \tau \), -\( \tau \), 0
  
i.e \( \sigma_{1,2} = \pm \tau \sin 2\theta \)

- Principal strains
  \[
  \varepsilon_1 = \frac{\tau}{E} (1 + \mu); \quad \varepsilon_2 = -\frac{\tau}{E} (1 + \mu); \quad \varepsilon_3 = 0
  \]

- Volumetric strain,
  \[
  \varepsilon_v = \varepsilon_1 + \varepsilon_2 + \varepsilon_3 = 0
  \]

- No change in volume for a shaft subjected to pure torque.

12. Torsional Stresses in Non-Circular Cross-section Members

- There are some applications in machinery for non-circular cross-section members and shafts where a regular polygonal cross-section is useful in transmitting torque to a gear or pulley that can have an axial change in position. Because no key or keyway is needed, the possibility of a lost key is avoided.

- Saint Venant (1855) showed that \( \tau_{\text{max}} \) in a rectangular \( b \times c \) section bar occurs in the middle of the longest side \( b \) and is of magnitude formula

\[
\tau_{\text{max}} = \frac{T}{abc^2} = \frac{T}{bc^2} \left( 3 + \frac{1.8}{b/c} \right)
\]

Where \( b \) is the longer side and \( \alpha \) factor that is function of the ratio \( b/c \).

The angle of twist is given by
\[ \theta = \frac{Tl}{\beta bc^3 G} \]

Where \( \beta \) is a function of the ratio \( b/c \)

Shear stress distribution in different cross-section

13. Torsion of thin walled tube

- For a thin walled tube

  \[ \tau = \frac{T}{2A_o t} \]

  \[ \phi = \frac{\tau sL}{2A_o G} \]

  [Where \( S = \) length of mean centre line, \( A_o = \) Area enclosed by mean centre line]

- Special Cases
  - For circular c/s
    \[ J = 2\pi r^3 t; \quad A_o = \pi r^2; \quad S = 2\pi r \]
    \[ r = \text{radius of mean Centre line and} \quad t = \text{wall thickness} \]
    \[ \therefore \tau = \frac{T}{2\pi r^2 t} = \frac{T r}{J} = \frac{T}{2A_o t} \]
    \[ \phi = \frac{TL}{GJ} = \frac{\tau L}{A_o J G} = \frac{TL}{2\pi r^3 t G} \]
  - For square c/s of length of each side ‘b’ and thickness ‘t’
    \[ A_o = b^2 \]
    \[ S = 4b \]
  - For elliptical c/s ‘a’ and ‘b’ are the half axis lengths.
    \[ A_o = \pi ab \]
    \[ S \approx \pi \left[ \frac{3}{2} (a + b) - \sqrt{ab} \right] \]


Torsion Equation

GATE-1. A solid circular shaft of 60 mm diameter transmits a torque of 1600 Nm. The value of maximum shear stress developed is: 

(a) 37.72 MPa  (b) 47.72 MPa  (c) 57.72 MPa  (d) 67.72 MPa 

GATE-1. Ans. (a) \( \tau = \frac{16T}{\pi d^3} \)

GATE-2. Maximum shear stress developed on the surface of a solid circular shaft under pure torsion is 240 MPa. If the shaft diameter is doubled then the maximum shear stress developed corresponding to the same torque will be: 

(a) 120 MPa  (b) 60 MPa  (c) 30 MPa  (d) 15 MPa 

GATE-2. Ans. (c) \( \tau = \frac{16T}{\pi d^3} \), \( 240 = \frac{16T}{\pi d^3} \) if diameter doubled \( d' = 2d \), then \( \tau' = \frac{16T}{\pi (2d)^3} = \frac{1600}{8} = 30 \text{ MPa} \)

GATE-3. A steel shaft 'A' of diameter 'd' and length 'l' is subjected to a torque 'T'. Another shaft 'B' made of aluminium of the same diameter 'd' and length 0.5l is also subjected to the same torque 'T'. The shear modulus of steel is 2.5 times the shear modulus of aluminium. The shear stress in the steel shaft is 100 MPa. The shear stress in the aluminium shaft, in MPa, is: 

(a) 40  (b) 50  (c) 100  (d) 250 

GATE-3. Ans. (c) \( \tau = \frac{16T}{\pi d^3} \) as \( T \) & \( d \) both are same \( \tau \) is same

GATE-4. For a circular shaft of diameter \( d \) subjected to torque \( T \), the maximum value of the shear stress is: 

(a) \( \frac{64T}{\pi d^3} \)  (b) \( \frac{32T}{\pi d^3} \)  (c) \( \frac{16T}{\pi d^3} \)  (d) \( \frac{8T}{\pi d^3} \) 

GATE-4. Ans. (c)

Power Transmitted by Shaft

GATE-5. The diameter of shaft A is twice the diameter or shaft B and both are made of the same material. Assuming both the shafts to rotate at the same speed, the maximum power transmitted by B is: 

(a) The same as that of A  (b) Half of A  (c) 1/8th of A  (d) 1/4th of A 

GATE-5. Ans. (c) Power, \( P = T \times \frac{2\pi N}{60} \) and \( \tau = \frac{16T}{\pi d^3} \) or \( T = \frac{\tau \pi d^3}{16} \) 

or \( P = \frac{\tau \pi d^3}{16} \times \frac{2\pi N}{60} \) or \( P \propto d^3 \)

Combined Bending and Torsion

GATE-6. A solid shaft can resist a bending moment of 3.0 kNm and a twisting moment of 4.0 kNm together, then the maximum torque that can be applied is: 

(a) 7.0 kNm  (b) 3.5 kNm  (c) 4.5 kNm  (d) 5.0 kNm 

GATE-6. Ans. (d) Equivalent torque \( (T_e) = \sqrt{M^2 + T^2} = \sqrt{3^2 + 4^2} = 5\text{kNm} \)
Comparison of Solid and Hollow Shafts

GATE-7. The outside diameter of a hollow shaft is twice its inside diameter. The ratio of its torque carrying capacity to that of a solid shaft of the same material and the same outside diameter is:  
\[ \frac{T_h}{T_s} = \frac{\frac{G\theta}{L}}{\frac{G\theta}{R}} = \frac{r}{R} \quad \text{or} \quad T = \frac{rJ}{R} \quad \text{if} \quad r \text{ is const.} \quad T \propto J \]

\[ \frac{T_h}{T_s} = \frac{\frac{\pi}{32} \left( D^4 - \left( \frac{D}{2} \right)^4 \right)}{16} = \frac{15}{16} \]

GATE-7. Ans. (a)

Shafts in Series

GATE-8. A torque of 10 Nm is transmitted through a stepped shaft as shown in figure. The torsional stiffness of individual sections of lengths MN, NO and OP are 20 Nm/rad, 30 Nm/rad and 60 Nm/rad respectively. The angular deflection between the ends M and P of the shaft is:

\[ \theta = \frac{T}{GJ} = \frac{10}{20 + 30 + 60} = 0.5 \text{ rad} \]

GATE-8. Ans. (b)

Shafts in Parallel

GATE-9. The two shafts AB and BC, of equal length and diameters d and 2d, are made of the same material. They are joined at B through a shaft coupling, while the ends A and C are built-in (cantilevered). A twisting moment T is applied to the coupling. If \( T_A \) and \( T_C \) represent the twisting moments at the ends A and C, respectively, then

\[ \frac{T_C}{T_A} = \frac{16}{1} \]

GATE-9. Ans. (c)

Previous 20-Years IES Questions

Torsion Equation

IES-1. Consider the following statements:  
1. Directly proportional to torque being transmitted.  
2. Inversely proportional to the cube of its diameter.
3. Directly proportional to its polar moment of inertia.

Which of the statements given above are correct?

(a) 1, 2 and 3  
(b) 1 and 3 only  
(c) 2 and 3 only  
(d) 1 and 2 only

IES-1. Ans. (d) \( \tau = \frac{T \times r}{J} = \frac{16T}{\pi d^2} \)

IES-2. A solid shaft transmits a torque \( T \). The allowable shearing stress is \( \tau \). What is the diameter of the shaft? \[[IES-2008]\]

(a) \( \sqrt[3]{\frac{16T}{\pi \tau}} \)  
(b) \( \sqrt[3]{\frac{32T}{\pi \tau}} \)  
(c) \( \sqrt[3]{\frac{16T}{\tau}} \)  
(d) \( \sqrt[3]{\frac{T}{\tau}} \)

IES-2. Ans. (a)

IES-3. Maximum shear stress developed on the surface of a solid circular shaft under pure torsion is 240 MPa. If the shaft diameter is doubled, then what is the maximum shear stress developed corresponding to the same torque? \[[IES-2009]\]

(a) 120 MPa  
(b) 60 MPa  
(c) 30 MPa  
(d) 15 MPa

IES-3. Ans. (c) \[ \text{Maximum shear stress} = \frac{16T}{\pi d^3} = 240 \text{ MPa} \]

Maximum shear stress developed when diameter is doubled

\[ \frac{16\tau}{\pi (2d)^3} = \frac{1}{8} \left( \frac{16T}{\pi d^3} \right) = \frac{\tau}{8} = \frac{240}{8} = 30 \text{ MPa} \]

IES-4. The diameter of a shaft is increased from 30 mm to 60 mm, all other conditions remaining unchanged. How many times is its torque carrying capacity increased? \[[IES-1995; 2004]\]

(a) 2 times  
(b) 4 times  
(c) 8 times  
(d) 16 times

IES-4. Ans. (c) \[ \tau = \frac{16T}{\pi d^3} \text{ or } T = \frac{\pi d^3}{16} \text{ for same material } \tau = \text{const.} \]

\[ \therefore \frac{T_2}{T_1} = \left( \frac{d_2}{d_1} \right)^3 = \left( \frac{60}{30} \right)^3 = 8 \]

IES-5. A circular shaft subjected to twisting moment results in maximum shear stress of 60 MPa. Then the maximum compressive stress in the material is: \[[IES-2003]\]

(a) 30 MPa  
(b) 60 MPa  
(c) 90 MPa  
(d) 120 MPa

IES-5. Ans. (b)

IES-6. Angle of twist of a shaft of diameter ‘d’ is inversely proportional to \[[IES-2000]\]

(a) d  
(b) d^2  
(c) d^3  
(d) d^4

IES-6. Ans. (d)

IES-7. A solid circular shaft is subjected to pure torsion. The ratio of maximum shear to maximum normal stress at any point would be: \[[IES-1999]\]

(a) 1 : 1  
(b) 1 : 2  
(c) 2 : 1  
(d) 2 : 3

IES-7. Ans. (a) \[ \text{Shear stress } = \frac{16T}{\pi d^3} \text{ and normal stress } = \frac{32T}{\pi d^3} \]

\[ \therefore \text{Ratio of shear stress and normal stress } = 1 : 2 \]

IES-8. Assertion (A): In a composite shaft having two concentric shafts of different materials, the torque shared by each shaft is directly proportional to its polar moment of inertia. \[[IES-1999]\]

Reason (R): In a composite shaft having concentric shafts of different materials, the angle of twist for each shaft depends upon its polar moment of inertia.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IES-9. A shaft is subjected to torsion as shown. [IES-2002]

Which of the following figures represents the shear stress on the element LMNOPQRS?

IES-9. Ans. (c)

IES-10. A round shaft of diameter 'd' and length 'l' fixed at both ends 'A' and 'B' is subjected to a twisting moment 'T' at 'C', at a distance of 1/4 from A (see figure). The torsional stresses in the parts AC and CB will be:
(a) Equal
(b) In the ratio 1:3
(c) In the ratio 3:1
(d) Indeterminate

IES-10. Ans. (c)

IES-11. One-half length of 50 mm diameter steel rod is solid while the remaining half is hollow having a bore of 25 mm. The rod is subjected to equal and opposite torque at its ends. If the maximum shear stress in solid portion is \( \tau \) or, the maximum shear stress in the hollow portion is:

(a) \( \frac{15}{16} \) \( \tau \)  
(b) \( \tau \)  
(c) \( \frac{4}{3} \) \( \tau \)  
(d) \( \frac{16}{15} \) \( \tau \)

IES-11. Ans. (d)
or \[ \tau_h = \tau \frac{J_s}{J_h} = \tau \frac{\pi}{32} \frac{D^4}{d^4} = \tau \frac{1}{1 - \left( \frac{d}{D} \right)^4} \]

\[ \tau = \tau \left( \frac{16}{15} \right) \]

**Power Transmitted by Shaft**

IES-12. In power transmission shafts, if the polar moment of inertia of a shaft is doubled, then what is the torque required to produce the same angle of twist?

(a) 1/4 of the original value (b) 1/2 of the original value
(c) Same as the original value (d) Double the original value

IES-12. Ans. (d)

\[ \frac{T}{J} = \frac{G \theta}{L} = \frac{\tau}{R} \quad \text{or} \quad Q = \frac{TL}{GJ} \quad \text{if } \theta \text{ is const.} \quad \alpha = \frac{T}{J} \quad \text{if } J \text{ is doubled then } T \text{ is also doubled.} \]

IES-13. While transmitting the same power by a shaft, if its speed is doubled, what should be its new diameter if the maximum shear stress induced in the shaft remains same?

(a) \( \frac{1}{2} \) of the original diameter (b) \( \frac{1}{\sqrt{2}} \) of the original diameter
(c) \( \sqrt{2} \) of the original diameter (d) \( \frac{1}{(2)^{\frac{1}{3}}} \) of the original diameter

IES-13. Ans. (d)

Power \( (P) \) = torque \( (T) \) \times \text{angular speed} \( (\omega) \)

if \( P \) is const. \( T \alpha \frac{1}{\omega} \) \( \frac{T'}{T} = \frac{\omega}{\omega'} = \frac{1}{2} \) or \( T' = \frac{T}{2} \)

\[ \sigma = \frac{16T}{\pi d^3} = \frac{16(T/2)}{\pi (d')^3} \quad \text{or} \quad \left( \frac{d'}{d} \right) = \frac{1}{\sqrt{2}} \]

IES-14. For a power transmission shaft transmitting power \( P \) at \( N \) rpm, its diameter is proportional to:

(a) \( \left( \frac{P}{N} \right)^{\frac{1}{3}} \) (b) \( \left( \frac{P}{N} \right)^{\frac{1}{2}} \) (c) \( \left( \frac{P}{N} \right)^{\frac{2}{3}} \) (d) \( \frac{P}{N} \)

IES-14. Ans. (a)

\[ P = T \times \frac{2\pi N}{60} \quad \text{and} \quad \tau = \frac{16T}{\pi d^3} \quad \text{or} \quad T = \frac{\tau\pi d^3}{16} \]

or \( P = \frac{\tau\pi d^3}{16} \times \frac{2\pi N}{60} \) or \( d^3 = \frac{480P}{\pi^2 J N} \) or \( d \propto \left( \frac{P}{N} \right)^{\frac{1}{3}} \)

IES-15. A shaft can safely transmit 90 kW while rotating at a given speed. If this shaft is replaced by a shaft of diameter double of the previous one and rotated at half the speed of the previous, the power that can be transmitted by the new shaft is:

(a) 90 kW (b) 180 kW (c) 360 kW (d) 720 kW

IES-15. Ans. (c)

IES-16. The diameter of shaft A is twice the diameter or shaft B and both are made of the same material. Assuming both the shafts to rotate at the same speed, the maximum power transmitted by B is:

(a) The same as that of A (b) Half of A (c) 1/8th of A (d) 1/4th of A

IES-16. Ans. (c)
IES-17. When a shaft transmits power through gears, the shaft experiences \([IES-1997]\)
(a) Torsional stresses alone
(b) Bending stresses alone
(c) Constant bending and varying torsional stresses
(d) Varying bending and constant torsional stresses

IES-17. Ans. (d)

**Combined Bending and Torsion**

IES-18. The equivalent bending moment under combined action of bending moment \(M\) and torque \(T\) is:

\[ (a) \sqrt{M^2 + T^2} \quad (b) \frac{1}{2} \left[ M + \sqrt{M^2 + T^2} \right] \]
\[ (c) \frac{1}{2} (M + T) \quad (d) \frac{1}{4} \left[ \sqrt{M^2 + T^2} \right] \]

IES-18. Ans. (b)

IES-19. A solid circular shaft is subjected to a bending moment \(M\) and twisting moment \(T\). What is the equivalent twisting moment \(T_e\) which will produce the same maximum shear stress as the above combination? \([IES-1992; 2007]\)

\[ (a) M^2 + T^2 \quad (b) M + T \quad (c) \sqrt{M^2 + T^2} \quad (d) M - T \]

IES-19. Ans. (c) \(T_e = \sqrt{M^2 + T^2}\)

IES-20. A shaft is subjected to fluctuating loads for which the normal torque \((T)\) and bending moment \((M)\) are 1000 N-m and 500 N-m respectively. If the combined shock and fatigue factor for bending is 1.5 and combined shock and fatigue factor for torsion is 2, then the equivalent twisting moment for the shaft is: \([IES-1994]\)

\[ (a) 2000\text{N-m} \quad (b) 2050\text{N-m} \quad (c) 2100\text{N-m} \quad (d) 2136\text{N-m} \]

IES-20. Ans. (d) \(T_{eq} = \sqrt{(1.5 \times 500)^2 + (2 \times 1000)^2} = 2136\text{Nm}\)

IES-21. A member is subjected to the combined action of bending moment 400 Nm and torque 300 Nm. What respectively are the equivalent bending moment and equivalent torque? \([IES-1994; 2004]\)

\[ (a) 450 \text{Nm and 500 Nm} \quad (b) 900 \text{Nm and 350 Nm} \]
\[ (c) 900 \text{Nm and 500 Nm} \quad (d) 400 \text{Nm and 500 Nm} \]

IES-21. Ans. (a) Equivalent Bending Moment \(M_e\) = \(\frac{M + \sqrt{M^2 + T^2}}{2} = \frac{400 + \sqrt{400^2 + 300^2}}{2} = 450\text{Nm}\)

Equivalent torque \(T_e = \sqrt{M^2 + T^2} = \sqrt{400^2 + 300^2} = 500\text{Nm}\)

IES-22. A shaft was initially subjected to bending moment and then was subjected to torsion. If the magnitude of bending moment is found to be the same as that of the torque, then the ratio of maximum bending stress to shear stress would be: \([IES-1993]\)

\[ (a) 0.25 \quad (b) 0.50 \quad (c) 2.0 \quad (d) 4.0 \]

IES-22. Ans. (c) Use equivalent bending moment formula,

1st case: Equivalent bending moment \((M_e) = M\)

2nd case: Equivalent bending moment \((M_e) = \frac{T}{2}\)
IES-23. A shaft is subjected to simultaneous action of a torque T, bending moment M and an axial thrust F. Which one of the following statements is correct for this situation?

(a) One extreme end of the vertical diametral fibre is subjected to maximum compressive stress only
(b) The opposite extreme end of the vertical diametral fibre is subjected to tensile/compressive stress only
(c) Every point on the surface of the shaft is subjected to maximum shear stress only
(d) Axial longitudinal fibre of the shaft is subjected to compressive stress only

IES-23. Ans. (a)

IES-24. For obtaining the maximum shear stress induced in the shaft shown in the given figure, the torque should be equal to

(a) \(T\) \hspace{1cm} (b) \(TW + T\)
(c) \(\left[ (TW)^2 + \left( \frac{WL}{2} \right)^2 \right]^{\frac{1}{2}}\)
(d) \(\left[ \left( W + \frac{WL^2}{2} \right)^2 + T^2 \right]^{\frac{1}{2}}\)

IES-24. Ans. (d) Bending Moment, \(M = WL + \frac{wL^2}{2}\)

IES-25. Bending moment M and torque is applied on a solid circular shaft. If the maximum bending stress equals to maximum shear stress developed, then M is equal to:

(a) \(\frac{T}{2}\) \hspace{1cm} (b) \(T\) \hspace{1cm} (c) \(2T\) \hspace{1cm} (d) \(4T\)

IES-25. Ans. (a) \(\sigma = \frac{32 \times M}{\pi d^3}\) and \(\tau = \frac{16T}{\pi d^3}\)

IES-26. A circular shaft is subjected to the combined action of bending, twisting and direct axial loading. The maximum bending stress \(\sigma\), maximum shearing force \(\sqrt{3}\sigma\) and a uniform axial stress \(\sigma\) (compressive) are produced. The maximum compressive normal stress produced in the shaft will be:

(a) \(3\sigma\) \hspace{1cm} (b) \(2\sigma\) \hspace{1cm} (c) \(\sigma\) \hspace{1cm} (d) Zero

IES-26. Ans. (a) Maximum normal stress = bending stress \(\sigma\) + axial stress \(\sigma\) = 2 \(\sigma\)

We have to take maximum bending stress \(\sigma\) is (compressive)

The maximum compressive normal stress = \(\sigma_b\) - \(\sqrt{\left( \frac{\sigma_b}{2} \right)^2 + \tau_{xy}^2}\)

\(= \frac{-2\sigma}{2} - \sqrt{\left( \frac{-2\sigma}{2} \right)^2 + \left( \sqrt{3}\sigma \right)^2} = -3\sigma\)

IES-27. Which one of the following statements is correct? Shafts used in heavy duty speed reducers are generally subjected to

(a) Bending stress only
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(b) Shearing stress only
(c) Combined bending and shearing stresses
(d) Bending, shearing and axial thrust simultaneously

IES-27. Ans. (c)

Comparison of Solid and Hollow Shafts

IES-28. The ratio of torque carrying capacity of a solid shaft to that of a hollow shaft is given by: [IES-2008]

(a) \( \left( 1 - K^4 \right) \)  
(b) \( \left( 1 - K^4 \right)^{-1} \)  
(c) \( K^4 \)  
(d) \( 1/K^4 \)

Where \( K = \frac{D_i}{D_o} \); \( D_i \) = Inside diameter of hollow shaft and \( D_o \) = Outside diameter of hollow shaft. Shaft material is the same.

IES-28. Ans. (b) \( \tau \) should be same for both hollow and solid shaft

\[
\frac{T_s}{T_h} = \frac{\pi D_i^4}{32} \left( \frac{D_o^4}{D_o^4 - D_i^4} \right) = \frac{T_s}{T_h} = \frac{D_i^4}{D_o^4 - D_i^4} \Rightarrow \frac{T_s}{T_h} = \left( 1 - \frac{D_i^4}{D_o^4} \right)^{-1}
\]

\[
\therefore \frac{T_s}{T_h} = \left( 1 - K^4 \right)^{-1}
\]

IES-29. A hollow shaft of outer dia 40 mm and inner dia of 20 mm is to be replaced by a solid shaft to transmit the same torque at the same maximum stress. What should be the diameter of the solid shaft? [IES 2007]

(a) 30 mm  
(b) 35 mm  
(c) 10\times(60)^{1/3} mm  
(d) 10\times(20)^{1/3} mm

IES-29. Ans. (c) Section modules will be same

\[
J_h \left( \frac{d^4}{32} \right) = J_s \left( \frac{d^4}{64} \right) \Rightarrow \frac{d^3}{40} = \frac{d^4}{2} \Rightarrow d = 10\sqrt[3]{60} \ mm
\]

IES-30. The diameter of a solid shaft is D. The inside and outside diameters of a hollow shaft of same material and length are \( \frac{D}{\sqrt{3}} \) and \( \frac{2D}{\sqrt{3}} \) respectively. What is the ratio of the weight of the hollow shaft to that of the solid shaft? [IES 2007]

(a) 1:1  
(b) 1: \( \sqrt{3} \)  
(c) 1:2  
(d) 1:3

IES-30. Ans. (a) \( \frac{W_h}{W_s} = \frac{\pi}{4} \left( \frac{4D^2}{3} - \frac{D^3}{3} \right) \times \frac{L \times \rho \times g}{D^2 \times L \times \rho \times g} = 1 \)

IES-31. What is the maximum torque transmitted by a hollow shaft of external radius \( R \) and internal radius \( r \)? [IES-2006]

(a) \( \frac{\pi}{16} \left( R^2 - r^2 \right) f_s \)  
(b) \( \frac{\pi}{2R} \left( R^3 - r^4 \right) f_s \)  
(c) \( \frac{\pi}{8R} \left( R^4 - r^4 \right) f_s \)  
(d) \( \frac{\pi}{32} \left( \frac{R^4 - r^4}{R} \right) f_s \)

\( f_s \) = maximum shear stress in the shaft material

IES-31. Ans. (b) \( \frac{T}{J} = \frac{f_s}{R} \) or \( \frac{T}{R} = \frac{J}{f_s} = \frac{\pi}{2R} \left( \frac{R^4 - r^4}{R} \right) \times f_s = \frac{\pi}{2R} \left( R^4 - r^4 \right) f_s \).

IES-32. A hollow shaft of the same cross-sectional area and material as that of a solid shaft transmits: [IES-2005]
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(a) Same torque  
(b) Lesser torque  
(c) More torque  
(d) Cannot be predicted without more data

IES-32. Ans. (c) \( \frac{T_n}{T_s} = \frac{n^2 + 1}{n^2 - 1} \)  
Where \( n = \frac{D_o}{d_i} \)

IES-33. The outside diameter of a hollow shaft is twice its inside diameter. The ratio of its torque carrying capacity to that of a solid shaft of the same material and the same outside diameter is: [GATE-1993; IES-2001]  
(a) \( \frac{15}{16} \)  
(b) \( \frac{3}{4} \)  
(c) \( \frac{1}{2} \)  
(d) \( \frac{1}{16} \)

IES-33. Ans. (a) \( \frac{T}{J} = \frac{G\theta}{L} = \frac{\tau}{R} \) or \( T = \frac{\tau J}{R} \) if \( \tau \) is const. \( T \propto J \)

\[ \frac{T_n}{T} = \frac{J_n}{J} = \frac{\pi}{32} \left[ D^4 - \left( \frac{D}{2} \right)^4 \right] = \frac{15}{16} \]

IES-34. Two hollow shafts of the same material have the same length and outside diameter. Shaft 1 has internal diameter equal to one-third of the outer diameter and shaft 2 has internal diameter equal to half of the outer diameter. If both the shafts are subjected to the same torque, the ratio of their twists \( \theta_1 / \theta_2 \) will be equal to: [IES-1998]  
(a) 16/81  
(b) 8/27  
(c) 19/27  
(d) 243/256

IES-34. Ans. (d) \( Q \propto \frac{1}{J} \) : \( \frac{Q_1}{Q_2} = \frac{d_i^4 - \left( \frac{d_i}{2} \right)^4}{d_i^4 - \left( \frac{d_i}{3} \right)^4} = \frac{243}{256} \)

IES-35. Maximum shear stress in a solid shaft of diameter \( D \) and length \( L \) twisted through an angle \( \theta \) is \( \tau \). A hollow shaft of same material and length having outside and inside diameters of \( D \) and \( D/2 \) respectively is also twisted through the same angle of twist \( \theta \). The value of maximum shear stress in the hollow shaft will be: [IES-1994; 1997]  
(a) \( \frac{16}{15} \tau \)  
(b) \( \frac{8}{7} \tau \)  
(c) \( \frac{4}{3} \tau \)  
(d) \( \tau \)

IES-35. Ans. (d) \( \frac{T}{J} = \frac{G\theta}{L} = \frac{\tau}{R} \) or \( \tau = \frac{G R \theta}{L} \) if \( \theta \) is const. \( \tau \propto R \) and outer diameter is same in both the cases. 
Note: Required torque will be different.

IES-36. A solid shaft of diameter 'D' carries a twisting moment that develops maximum shear stress \( \tau \). If the shaft is replaced by a hollow one of outside diameter 'D' and inside diameter \( D/2 \), then the maximum shear stress will be: [IES-1994]  
(a) 1.067 \( \tau \)  
(b) 1.143 \( \tau \)  
(c) 1.333 \( \tau \)  
(d) 2 \( \tau \)

IES-36. Ans. (a) \( \frac{\tau_n}{\tau} = \frac{J}{J_n} = \frac{D^4 - \left( \frac{D}{2} \right)^4}{15} = 1.06666 \)

IES-37. A solid shaft of diameter 100 mm, length 1000 mm is subjected to a twisting moment 'T'. The maximum shear stress developed in the shaft is 60 N/mm². A hole of 50 mm diameter is now drilled throughout the length of the shaft. To
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develop a maximum shear stress of 60 N/mm² in the hollow shaft, the torque 'T' must be reduced by:

(a) T/4  
(b) T/8  
(c) T/12  
(d) T/16

IES-37. Ans. (d) \( \tau_s = \frac{T_r}{J} \pi d^2 = \frac{16T}{\pi d^2} = \frac{T'32(d/2)}{d^4-(d/2)^4} \) or \( \frac{T'}{T} = \frac{15}{16} \)

\[ \therefore \text{Reduction} = \frac{1}{16} \]

IES-38. Assertion (A): A hollow shaft will transmit a greater torque than a solid shaft of the same weight and same material. [IES-1994]

Reason (R): The average shear stress in the hollow shaft is smaller than the average shear stress in the solid shaft.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-38. Ans. (a)

IES-39. A hollow shaft is subjected to torsion. The shear stress variation in the shaft along the radius is given by: [IES-1996]

IES-39. Ans. (c)

Shafts in Series

IES-40. What is the total angle of twist of the stepped shaft subject to torque T shown in figure given above?

(a) \( \frac{16T}{\pi Gd^4} \)  
(b) \( \frac{38T}{\pi Gd^4} \)
(c) \( \frac{64T}{\pi Gd^4} \)  
(d) \( \frac{66T}{\pi Gd^4} \)

IES-40. Ans. (d) \( \theta = \theta_1 + \theta_2 = \frac{T \times 2l}{G \times \pi d^4} = \frac{T \times 1}{G \times \frac{\pi}{32} \times (2d)^4} = \frac{Tl}{Gd^4[64 + 2]} = \frac{66T}{Gd^4} \)

Shafts in Parallel

IES-41. For the two shafts connected in parallel, find which statement is true? [IES-1992]

(a) Torque in each shaft is the same
(b) Shear stress in each shaft is the same
(c) Angle of twist of each shaft is the same
(d) Torsional stiffness of each shaft is the same

IES-41. Ans. (c)
IES-42. A circular section rod ABC is fixed at ends A and C. It is subjected to torque T at B. AB = BC = L and the polar moment of inertia of portions AB and BC are 2 J and J respectively. If G is the modulus of rigidity, what is the angle of twist at point B? [IES-2005]

(a) \( \frac{TL}{3GJ} \)  
(b) \( \frac{TL}{2GJ} \)  
(c) \( \frac{TL}{GJ} \)  
(d) \( \frac{2TL}{GJ} \)

IES-42. Ans. (a)

IES-43. A solid circular rod AB of diameter D and length L is fixed at both ends. A torque T is applied at a section X such that AX = L/4 and BX = 3L/4. What is the maximum shear stress developed in the rod? [IES-2004]

(a) \( \frac{16T}{\pi D^3} \)  
(b) \( \frac{12T}{\pi D^3} \)  
(c) \( \frac{8T}{\pi D^3} \)  
(d) \( \frac{4T}{\pi D^3} \)

IES-43. Ans. (b)

IES-44. Two shafts are shown in the above figure. These two shafts will be torsionally equivalent to each other if their
   (a) Polar moment of inertias are the same
   (b) Total angle of twists are the same
   (c) Lengths are the same
   (d) Strain energies are the same

IES-44. Ans. (b)

### Previous 20-Years IAS Questions

#### Torsion Equation

**IAS-1.** Assertion (A): In theory of torsion, shearing strains increase radically away from the longitudinal axis of the bar. [IAS-2001]

Reason (R): Plane transverse sections before loading remain plane after the torque is applied.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-1. Ans. (b)

IAS-2. The shear stress at a point in a shaft subjected to a torque is: [IAS-1995]
(a) Directly proportional to the polar moment of inertia and to the distance of the point
form the axis
(b) Directly proportional to the applied torque and inversely proportional to the polar
moment of inertia.
(c) Directly proportional to the applied torque and polar moment of inertia
(d) inversely proportional to the applied torque and the polar moment of inertia

IAS-2. Ans. (b) \( \frac{T}{J} = \frac{\tau}{R} \)

IAS-3. If two shafts of the same length, one of which is hollow, transmit equal torque
and have equal maximum stress, then they should have equal. [IAS-1994]
(a) Polar moment of inertia
(b) Polar modulus of section
(c) Polar moment of inertia
(d) Angle of twist

IAS-3. Ans. (b) \( \frac{T}{J} = \frac{\tau}{R} \) Here T \& \( \tau \) are same, so \( \frac{J}{R} \) should be same i.e. polar modulus of section will
be same.

**Hollow Circular Shafts**

IAS-4. A hollow circular shaft having outside diameter 'D' and inside diameter 'd'
subjected to a constant twisting moment 'T' along its length. If the maximum
shear stress produced in the shaft is \( \sigma_s \) then the twisting moment 'T' is given
by:
(a) \( \frac{\pi}{8} \sigma_s \frac{D^4 - d^4}{D^4} \)  
(b) \( \frac{\pi}{16} \sigma_s \frac{D^4 - d^4}{D^4} \)  
(c) \( \frac{\pi}{32} \sigma_s \frac{D^4 - d^4}{D^4} \)  
(d) \( \frac{\pi}{64} \sigma_s \frac{D^4 - d^4}{D^4} \)

IAS-4. Ans. (b) \( \frac{T}{J} = \frac{G\theta}{L} = \frac{\tau}{R} \) gives \( T = \tau J = \frac{\sigma_s \times \frac{\pi}{32} (D^4 - d^4)}{\frac{D}{2}} = \frac{\pi}{16} \sigma_s \frac{(D^4 - d^4)}{D} \)

**Torsional Rigidity**

IAS-5. Match List-I with List-II and select the correct answer using the codes given
below the lists: [IAS-1996]

<table>
<thead>
<tr>
<th>List-I (Mechanical Properties)</th>
<th>List-II (Characteristics)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Torsional rigidity</td>
<td>1. Product of young's modulus and second moment of area about the plane of bending</td>
</tr>
<tr>
<td>B. Modulus of resilience</td>
<td>2. Strain energy per unit volume</td>
</tr>
<tr>
<td>C. Bauschinger effect</td>
<td>3. Torque unit angle of twist</td>
</tr>
<tr>
<td>D. Flexural rigidity</td>
<td>4. Loss of mechanical energy due to local yielding</td>
</tr>
</tbody>
</table>

Codes: A B C D  
(a) 1 3 4 2  
(b) 3 2 4 1  
(c) 2 4 1 3  
(d) 3 1 4 2

IAS-5. Ans. (b)

IAS-6. Assertion (A): Angle of twist per unit length of a uniform diameter shaft
depends upon its torsional rigidity. [IAS-2004]
Reason (R): The shafts are subjected to torque only.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
Combined Bending and Torsion

IAS-7. A shaft is subjected to a bending moment $M = 400 \text{ N.m}$ and torque $T = 300 \text{ N.m}$. The equivalent bending moment is: [IAS-2002]

(a) 900 N.m  (b) 700 N.m  (c) 500 N.m  (d) 450 N.m

IAS-7. Ans. (d) $Me = \frac{M + \sqrt{M^2 + T^2}}{2} = \frac{400 + \sqrt{400^2 + 300^2}}{2} = 450 \text{Nm}$

Comparison of Solid and Hollow Shafts

IAS-8. A hollow shaft of length $L$ is fixed at its both ends. It is subjected to torque $T$ at a distance of $\frac{L}{3}$ from one end. What is the reaction torque at the other end of the shaft? [IAS-2007]

(a) $\frac{2T}{3}$  (b) $\frac{T}{2}$  (c) $\frac{T}{3}$  (d) $\frac{T}{4}$

IAS-8. Ans. (e)

IAS-9. A solid shaft of diameter $d$ is replaced by a hollow shaft of the same material and length. The outside diameter of hollow shaft $\frac{2d}{\sqrt{3}}$ while the inside diameter is $\frac{d}{\sqrt{3}}$. What is the ratio of the torsional stiffness of the hollow shaft to that of the solid shaft? [IAS-2007]

(a) $\frac{2}{3}$  (b) $\frac{3}{5}$  (c) $\frac{5}{3}$  (d) 2

IAS-9. Ans. (c) Torsional stiffness $= \frac{\tau}{\theta} = \frac{GJ}{L}$ or $K_h = \frac{\pi}{32} \left( \frac{2d}{\sqrt{3}} \right)^4 - \left( \frac{d}{\sqrt{3}} \right)^4 \frac{\pi}{32} \cdot d^4 = \frac{5}{3}$

IAS-10. Two steel shafts, one solid of diameter $D$ and the other hollow of outside diameter $D$ and inside diameter $D/2$, are twisted to the same angle of twist per unit length. The ratio of maximum shear stress in solid shaft to that in the hollow shaft is: [IAS-1998]

(a) $\frac{4}{9} \tau$  (b) $\frac{8}{7} \tau$  (c) $\frac{16}{15} \tau$  (d) $\tau$

IAS-10. Ans. (d) $\frac{T}{J} = \frac{\tau}{R} = \frac{G\theta}{L}$ or $\tau = \frac{G\theta R}{L}$ as outside diameter of both the shaft is $D$ so $\tau$ is same for both the cases.


Chapter 9  

Shafts in Series

IAS-11. Two shafts having the same length and material are joined in series. If the ratio of the diameter of the first shaft to that of the second shaft is 2, then the ratio of the angle of twist of the first shaft to that of the second shaft is:

(a) 16  
(b) 8  
(c) 4  
(d) 2

IAS-11. Ans. (a) Angle of twist is proportional to \( \frac{1}{J} \) or \( \frac{1}{d^4} \).

IAS-12. A circular shaft fixed at A has diameter D for half of its length and diameter D/2 over the other half. What is the rotation of C relative to B if the rotation of B relative to A is 0.1 radian?

(a) 0.4 radian  
(b) 0.8 radian  
(c) 1.6 radian  
(d) 3.2 radian

(T, L and C remaining same in both cases)

IAS-12. Ans. (c) \( \frac{T}{J} = \frac{G\theta}{L} \) or \( \theta \propto \frac{1}{J} \) or \( \theta \propto \frac{1}{d^4} \) \( \therefore J = \frac{\pi d^4}{32} \)

Here \( \frac{\theta}{0.1} = \frac{d^4}{(d/2)^4} \) or \( \theta = 1.6 \) radian.

Shafts in Parallel

IAS-13. A stepped solid circular shaft shown in the given figure is built-in at its ends and is subjected to a torque \( T_2 \) at the shoulder section. The ratio of reactive torque \( T_1 \) and \( T_2 \) at the ends is (\( J_1 \) and \( J_2 \) are polar moments of inertia):

(a) \( \frac{J_2 \times I_2}{J_1 \times I_1} \)  
(b) \( \frac{J_2 \times I_2}{J_1 \times I_1} \)  
(c) \( \frac{J_2 \times I_2}{J_1 \times I_1} \)  
(d) \( \frac{J_2 \times I_2}{J_1 \times I_1} \)

IAS-13. Ans. (c) \( \theta_1 = \theta_2 \) or \( \frac{T_1 l_1}{GJ_1} = \frac{T_2 l_2}{GJ_2} \) or \( \frac{T_1}{T_2} = \left( \frac{J_1 \times I_2}{J_2 \times I_1} \right) \)

IAS-14. Steel shaft and brass shaft of same length and diameter are connected by a flange coupling. The assembly is rigidity held at its ends and is twisted by a torque through the coupling. Modulus of rigidity of steel is twice that of brass. If torque of the steel shaft is 500 Nm, then the value of the torque in brass shaft will be:

(a) 250 Nm  
(b) 354 Nm  
(c) 500 Nm  
(d) 708 Nm

IAS-14. Ans. (a) \( \frac{T_1}{T_2} = \frac{G_s J_s}{G_b J_b} \) or \( \frac{T_1}{T_2} = \frac{T_b}{G_b} = 1 \) or \( \frac{T_b}{T_2} = \frac{1}{2} \), \( T_b = \frac{T_2}{2} = 250 \) Nm

IAS-15. A steel shaft with built-in ends is subjected to the action of a torque \( M_t \) applied at an intermediate cross-section 'mn' as shown in the given figure.

IAS-2001

IAS-1997
Assertion (A): The magnitude of the twisting moment to which the portion BC is subjected is \[ \frac{M_a a}{a + b} \]

Reason (R): For geometric compatibility, angle of twist at 'mn' is the same for the portions AB and BC.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-15. Ans. (a)

IAS-16. A steel shaft of outside diameter 100 mm is solid over one half of its length and hollow over the other half. Inside diameter of hollow portion is 50 mm. The shaft if held rigidly at two ends and a pulley is mounted at its midsection i.e., at the junction of solid and hollow portions. The shaft is twisted by applying torque on the pulley. If the torque carried by the solid portion of the shaft is 16000 kg-m, then the torque carried by the hollow portion of the shaft will be:

(a) 16000 kg-m  (b) 15000 kg-m  (c) 14000 kg-m  (d) 12000 kg-m

IAS-16. Ans. (b)

\[ T_s = T_h \] or \[ \frac{T_s}{GJ_s} = \frac{T_h}{GJ_h} \]

\[ T_h = T_s \times \frac{J_s}{J_h} = 16000 \times \frac{\pi(100^4 - 50^4)}{32(100^4)} = 15000 \text{kgm} \]
**Conventional Question IES 2010**

Q. A hollow steel rod 200 mm long is to be used as torsional spring. The ratio of inside to outside diameter is 1 : 2. The required stiffness of this spring is 100 Nm/degree. Determine the outside diameter of the rod.

Value of G is $8 \times 10^4$ N/mm$^2$. [10 Marks]

Ans. Length of a hollow steel rod = 200mm
Ratio of inside to outside diameter = 1 : 2
Stiffness of torsional spring = 100 Nm/degree = 5729.578 N m/rad
Rigidity of modulus (G) = $8 \times 10^4$ N / mm$^2$

Find outside diameter of rod:

We know that

$$\frac{T}{J} = \frac{G.0}{L}$$

Where $T =$ Torque

$$\frac{T}{\theta} = \text{Stiffness} \left( \frac{N - M}{\text{rad}} \right)$$

$$J = \text{polar moment}$$

$$\theta = \text{twist angle in rad}$$

$$L = \text{length of rod.}$$

$$d_2 = 2d_1$$

$$J = \frac{\pi}{32} \times \left( d_2^4 - d_1^4 \right)$$

$$J = \frac{\pi}{32} \times \left( 16d_1^4 - d_1^4 \right) \therefore \frac{d_1}{d_2} = \frac{1}{2}$$

$$J = \frac{\pi}{32} \times d_1^4 \times 15$$

$$5729.578 \text{ Nm} / \text{rad} = \frac{8 \times 10^4 \times 10^6 \text{ N} / \text{m}^2 \times \frac{\pi}{32} \times d_1^4 \times 15}{0.2}$$

$$\frac{5729.578 \times 2 \times 32}{8 \times 10^{10} \times \pi \times 15} = d_1^4$$

$$d_1 = 9.93 \times 10^{-3} \text{ m.}$$

$$d_1 = 9.93 \text{ mm.}$$

$$d_2 = 2 \times 9.93 = 19.86 \text{ mm} \quad \text{Ans.}$$

**Conventional Question GATE - 1998**

**Question:** A component used in the Mars pathfinder can be idealized as a circular bar clamped at its ends. The bar should withstand a torque of 1000 Nm. The component is assembled on earth when the temperature is 30°C. Temperature on Mars at the site of landing is -70°C. The material of the bar has an allowable shear stress of 300 MPa and its young’s modulus is 200 GPa. Design the diameter of the bar taking a factor of safety of 1.5 and assuming a coefficient of thermal expansion for the material of the bar as $12 \times 10^{-6}/°C$.

**Answer:** Given:
Diameter of the bar, $D$:

Change in length, $\delta L = L \propto \Delta t$, where $L =$ original length, m.

Change in length at Mars $L = L \times 12 \times 10^{-6} \times \left[30 - (-70) \right] = 12 \times 10^{-4}$ L meters

Linear strain $= \frac{\text{Change in length}}{\text{original length}} = \frac{12 \times 10^{-4} L}{L} = 12 \times 10^{-4}$

$\sigma_a =$ axial stress $= E \times \text{linear strain} = 200 \times 10^6 \times 12 \times 10^{-4} = 2.4 \times 10^8 \text{N/m}^2$

From maximum shear stress equation, we have

$$\tau_{\max} = \sqrt{\left(\frac{16T}{\pi D^3}\right)^2 + \left(\frac{\sigma_a}{2}\right)^2}$$

where, $\tau_{\max} = \frac{\tau_{\text{allowable}}}{\text{F.O.S}} = \frac{300}{1.5} = 200 \text{MPa}$

Substituting the values, we get

$$4 \times 10^{16} = \left(\frac{16 \times 1000}{\pi D^3}\right)^2 + (1.2 \times 10^8)^2$$

or $\frac{16 \times 1000}{\pi D^3} = 1.6 \times 10^8$

or $D = \left(\frac{16 \times 1000}{\pi \times 1.6 \times 10^8}\right)^{\frac{1}{3}} = 0.03169 \text{ m} = 31.69 \text{ mm}$

Conventional Question IES-2009

Q. In a torsion test, the specimen is a hollow shaft with 50 mm external and 30 mm internal diameter. An applied torque of 1.6 kN-m is found to produce an angular twist of 0.4º measured on a length of 0.2 m of the shaft. The Young’s modulus of elasticity obtained from a tensile test has been found to be 200 GPa. Find the values of

(i) Modulus of rigidity.

(ii) Poisson’s ratio.       [10-Marks]

Ans. We have

$$\frac{T}{J} = \frac{\tau}{r} = \frac{G \theta}{L} \quad \text{........ (i)}$$

Where $J =$ polar moment of inertia

$$J = \frac{\pi}{32} \left(D^4 - d^4\right)$$

$$= \frac{\pi}{32} \left(50^4 - 30^4\right) \times 10^{-12}$$

$$= 5.338 \times 10^{-7}$$

$T = 1.6 \text{ kN-m} = 1.6 \times 10^3 \text{ N-m}$

$\theta = 0.4^\circ$

$l = 0.2 \text{ m}$

$E = 200 \times 10^9 \text{ N/m}^2$

From equation (i) $\frac{T}{J} = \frac{G \theta}{L}$
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We also have

\[ G = \frac{1.6 \times 0.2 \times 10^3 \times 180}{0.4 \times \pi \times 5.338 \times 10^{-7}} = 85.92 \text{ GPa} \]

Conventional Question IAS - 1996

**Question:** A solid circular uniformly tapered shaft of length L, with a small angle of taper is subjected to a torque T. The diameter at the two ends of the shaft are D and 1.2D. Determine the error introduced of its angular twist for a given length is determined on the uniform mean diameter of the shaft.

**Answer:** For shaft of tapering's section, we have

\[
\theta = \frac{2TL}{3G\pi} \left[ \frac{R_1^2 + R_2^2 + R_3^2}{R_1^2R_2^2} \right] \]

\[
= \frac{32TL}{3G\pi D^4} \left[ (1.2)^2 + 1.2 \times 1 + (1)^2 \right]
\]

\[
\times \frac{1.2}{(1.2)^3 \times (1)^3}
\]

\[
\therefore \text{D}_1 = D \quad \text{and} \quad \text{D}_2 = 1.2D
\]

\[
\Rightarrow \theta = \frac{32TL}{3G\pi D^4} \times 2.1065
\]

Now,

\[
D_{\text{avg}} = \frac{1.2D + D}{2} = 1.1D
\]

\[
\therefore \theta' = \frac{32TL}{3G\pi} \times \left[ \frac{3(1.1D)^2}{(1.1D)^2} \right] = \frac{32TL}{3G\pi} \times \frac{3}{(1.2)^4D^4} = \frac{32TL}{3G\pi D^4} \times 2.049
\]

\[
\text{Error} = \frac{\theta - \theta'}{\theta} = \frac{2.1065 - 2.049}{2.1065} = 0.0273 \text{ or } 2.73\%
\]

Conventional Question ESE-2008

**Question:** A hollow shaft and a solid shaft construction of the same material have the same length and the same outside radius. The inside radius of the hollow shaft is 0.6 times of the outside radius. Both the shafts are subjected to the same torque.

(i) What is the ratio of maximum shear stress in the hollow shaft to that of solid shaft?

(ii) What is the ratio of angle of twist in the hollow shaft to that of solid shaft?

**Solution:**

Using \[ \frac{T}{J} = \frac{\tau}{R} = \frac{G\theta}{L} \]

Given, \[ \frac{\text{Inside radius (r)}}{\text{Out side (R)}} = 0.6 \] and \[ T_h = T_s = T \]

(i) \[ \tau = \frac{T.R}{J} \] gives ; For hollow shaft \( \tau_h = \frac{T.R}{\pi \left(R^4 - r^4\right)} \)
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and for solid shaft \( \tau_s = \frac{TR}{\pi R^4} \)

Therefore \( \frac{\tau_n}{\tau_s} = \frac{R^4}{R^4 - r^4} = \frac{1}{1 - \left(\frac{r}{R}\right)^4} = \frac{1}{1 - 0.6^4} = 1.15 \)

(ii) \( \theta_TL \) gives \( \theta_n = \frac{TL}{GJ \left(R^4 - r^4\right)} \) and \( \theta_s = \frac{TL}{G \left(\frac{\pi}{2} R^4\right)} \)

Therefore \( \frac{\theta_n}{\theta_s} = \frac{R^4}{R^4 - r^4} = \frac{1}{1 - \left(\frac{r}{R}\right)^4} = \frac{1}{1 - 0.6^4} = 1.15 \)

Conventional Question ESE-2006:

**Question**: Two hollow shafts of the same diameter are used to transmit the same power. One shaft is rotating at 1000 rpm while the other at 1200 rpm. What will be the nature and magnitude of the stress on the surfaces of these shafts? Will it be the same in two cases of different? Justify your answer.

**Answer**: We know power transmitted \( P = \text{Torque} (T) \times \text{rotation speed} (\omega) \)

And shear stress \( \tau = \frac{T.R}{J} = \frac{PR}{\omega J} = \frac{P.D^2}{2 \pi N \left(\frac{32}{60} \frac{\pi}{32} \left(D^4 - d^4\right)\right)} \)

Therefore \( \tau \propto \frac{1}{N} \) as \( P, D \) and \( d \) are constant.

So the shaft rotating at 1000 rpm will experience greater stress than 1200 rpm shaft.

Conventional Question ESE-2002

**Question**: A 5 cm diameter solid shaft is welded to a flat plate by 1 cm filled weld. What will be the maximum torque that the welded joint can sustain if the permissible shear stress in the weld material is not to exceed 8 kN/cm²? Deduce the expression for the shear stress at the throat from the basic theory.

**Answer**: Consider a circular shaft connected to a plate by means of a fillet joint as shown in figure. If the shaft is subjected to a torque, shear stress develops in the weld. Assuming that the weld thickness is very small compared to the diameter of the shaft, the maximum shear stress occurs in the throat area. Thus, for a given torque the maximum shear stress in the weld is

\[
\tau_{\text{max}} = \frac{T \left(\frac{d}{2} + t\right)}{J}
\]

Where \( T = \text{Torque applied.} \)
- \( d = \text{outer diameter of the shaft} \)
- \( t = \text{throat thickness} \)
- \( J = \text{polar moment of area of the throat section} \)

\[
= \frac{\pi}{32} \left(\frac{d}{2} + t\right)^4 - d^4 = \frac{\pi}{4} d^3 \times t
\]

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[As \( t \ll d \) then \( \tau_{\text{max}} = \frac{T d}{\pi d^4 t} = \frac{2T}{\pi td^2} \)]

Given

\[ d = 5 \text{ cm} = 0.05 \text{ m} \quad \& \quad t = 1 \text{ cm} = 0.1 \text{ m} \]

\[ \tau_{\text{max}} = 8 \text{ kN} / \text{cm}^2 = \frac{8000 \text{ N}}{(10^{-4}) \text{ m}^2} = 80 \text{ MPa} = 80 \times 10^6 \text{ N} / \text{m}^2 \]

\[ \therefore T = \frac{\pi d^4 \tau_{\text{max}}}{2} = \frac{\pi \times 0.05^2 \times 0.01 \times 80 \times 10^6}{2} = 3.142 \text{ kNm} \]

**Conventional Question ESE-2000**

**Question:** The ratio of inside to outside diameter of a hollow shaft is 0.6. If there is a solid shaft with same torsional strength, what is the ratio of the outside diameter of hollow shaft to the diameter of the equivalent solid shaft.

**Answer:**

Let \( D \) = external diameter of hollow shaft

So \( d = 0.6D \) internal diameter of hollow shaft

And \( D_s \)= diameter of solid shaft

From torsion equation

\[ \frac{T}{J} = \frac{\tau}{R} \]

\[ \therefore T = \frac{\tau J}{R} = \tau \times \frac{\pi}{32} (D^4 - (0.6D)^4) \quad \text{for hollow shaft} \]

\[ \text{and} \quad T = \frac{\tau J}{R} = J \times \frac{\pi}{32} \frac{D_s^4}{D_s^2} \quad \text{for solid shaft} \]

\[ \tau \frac{\pi D^3}{16} (1 - (0.6)^4) = \tau \frac{\pi D_s^3}{16} \]

\[ \therefore \frac{D}{D_s} = \sqrt[3]{\frac{1}{1 - (0.6)^4}} = 1.072 \]

**Conventional Question ESE-2001**

**Question:** A cantilever tube of length 120 mm is subjected to an axial tension \( P = 9.0 \text{ kN} \), a torsional moment \( T = 72.0 \text{ Nm} \) and a pendant load \( F = 1.75 \text{ kN} \) at the free end. The material is aluminum alloy with an yield strength 276 MPa. Find the thickness of the tube limiting the outside diameter to 50 mm so as to ensure a factor of safety of 4.

**Answer:** Polar moment of inertia \( (J) = 2\pi R^3 t = \frac{\pi D^3 t}{4} \)
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\[
\frac{T}{J} = \frac{\tau}{R} \quad \text{or, } \tau = \frac{T.R}{J} = \frac{TD}{2J} = \frac{TD}{2 \times \pi D^3 t} = \frac{2T}{\pi (0.050)^3 t} = \frac{18335}{t}
\]

Direct stress \(\sigma_1 = \frac{P}{A \pi dt} = \frac{9000}{\pi (0.050)t} = \frac{57296}{t}\)

Maximum bending stress \(\sigma_2 = \frac{My}{l} = \frac{M d/2}{l} = \frac{Md}{J} \quad [J = 2I]\)

\[= \frac{1750 \times 0.120 \times 0.050 \times 4}{\pi (0.050)^3 t} = \frac{106952}{t}\]

\[\therefore \text{Total longitudinal stress } \sigma_b = \sigma_1 + \sigma_2 = \frac{164248}{t}\]

Maximum principal stress

\[\sigma = \frac{\sigma_b}{2} + \sqrt{\left(\frac{\sigma_b}{2}\right)^2 + \tau^2} = \frac{164248}{2t} + \sqrt{\left(\frac{164248}{2t}\right)^2 + \left(\frac{18335}{t}\right)^2} = \left(\frac{276 \times 10^6}{4}\right)\]

or \(t = 2.4 \times 10^{-3} \text{ m} = 2.4 \text{ mm}\)

**Conventional Question ESE-2000 & ESE 2001**

**Question:** A hollow shaft of diameter ratio 3/8 required to transmit 600 kW at 110 rpm, the maximum torque being 20% greater than the mean. The shear stress is not to exceed 63 MPa and the twist in a length of 3 m not to exceed 1.4 degrees. Determine the diameter of the shaft. Assume modulus of rigidity for the shaft material as 84 GN/m².

**Answer:**

Let \(d = \) internal diameter of the hollow shaft

And \(D = \) external diameter of the hollow shaft

(given) \(d = 3/8 \text{ D} = 0.375 \text{ D}\)

Power \((P) = 600 \text{ kW}, \) speed \((N) = 110 \text{ rpm}, \) Shear stress \((\tau) = 63 \text{ MPa, \ Angle of twist } (\theta) = 1.4^\circ, \) Length \((L) = 3 \text{ m, \ modulus of rigidity } (G) = 84 \text{ GPa}\)

We know that, \((P) = T. \omega = T. \frac{2\pi N}{60}\) \([T \text{ is average torque}]\)

or \(T = \frac{60 \times P}{2\pi N} = \frac{60 \times (600 \times 10^3)}{2 \times \pi \times 110} = 52087 \text{ Nm}\)

\(\therefore T_{\text{max}} = 1.2 \times T = 1.2 \times 52087 = 62504 \text{ Nm}\)

First we consider that shear stress is not to exceed 63 MPa

From torsion equation \(\frac{T}{J} = \frac{\tau}{R}\)

or \(J = \frac{T.R}{\tau} = \frac{T.D}{2\tau}\)

or \(\frac{\pi}{32} [D^4 - (0.375D)^4] = \frac{62504 \times D}{2 \times (63 \times 10^6)}\)

or \((D) = 0.1727 m = 172.7 mm \text{ -- -- -- (i)}\)

Second we consider angle of twist is not exceed \(1.4^\circ = \frac{17 \times 1.4}{180} \text{ radian}\)
From torsion equation \( \frac{T}{J} = \frac{G\theta}{\ell} \)
\[ \text{or } \frac{T}{J} = \frac{G\theta}{\ell} \]
\[ \text{or } \frac{\pi}{32} \left[ D^4 - (0.375D)^4 \right] = \frac{62504 \times 3}{(84 \times 10^9) \left( \pi \times 1.5 \right)} \]
\[ \text{or } D = 0.1755m = 175.5mm \quad \text{--- (ii)} \]
So both the condition will satisfy if greater of the two value is adopted
so D=175.5 mm

**Conventional Question ESE-1997**

**Question:** Determine the torsional stiffness of a hollow shaft of length \( L \) and having outside diameter equal to 1.5 times inside diameter \( d \). The shear modulus of the material is \( G \).

**Answer:** Outside diameter \( (D) = 1.5d \)

Polar modulus of the shaft \((J) = \frac{\pi}{32} \left( D^4 - d^4 \right) = \frac{\pi}{32} d^4 (1.5^4 - 1) \)

We know that \( \frac{T}{J} = \frac{G\theta}{\ell} \)
\[ \text{or } T = \frac{G\theta}{J} \frac{\pi}{32} d^4 \frac{1.5^4 - 1}{L} = 0.4G\theta d^4 \]

**Conventional Question AMIE-1996**

**Question:** The maximum normal stress and the maximum shear stress analysed for a shaft of 150 mm diameter under combined bending and torsion, were found to be 120 MN/m\(^2\) and 80 MN/m\(^2\) respectively. Find the bending moment and torque to which the shaft is subjected.

If the maximum shear stress be limited to 100 MN/m\(^2\), find by how much the torque can be increased if the bending moment is kept constant.

**Answer:** Given: \( \sigma_{\text{max}} = 120 \text{MN/m}^2; \tau_{\text{max}} = 80 \text{MN/m}^2; d = 150 \text{mm} = 0.15 \text{m} \)

Part 1: \( M; T \)

We know that for combined bending and torsion, we have the following expressions:

\[ \sigma_{\text{max}} = \frac{16}{\pi d^4} \left[ M + \sqrt{M^2 + T^2} \right] \quad \text{--- (i)} \]

and \[ \tau_{\text{max}} = \frac{16}{\pi d^5} \left[ \sqrt{M^2 + T^2} \right] \quad \text{--- (ii)} \]

Substituting the given values in the above equations, we have

\[ 120 = \frac{16}{\pi \times (0.15)^3} \left[ M + \sqrt{M^2 + T^2} \right] \quad \text{--- (iii)} \]

\[ 80 = \frac{16}{\pi \times (0.15)^3} \left[ \sqrt{M^2 + T^2} \right] \quad \text{--- (iv)} \]

or \[ \sqrt{M^2 + T^2} = \frac{80 \times \pi \times (0.15)^3}{16} = 0.053 \quad \text{--- (v)} \]
Substituting this values in equation (iii), we get
\[
120 = \frac{16}{\pi \times (0.150^3)} [M + 0.053]
\]
\[
\therefore M = 0.0265 \text{MNm}
\]
Substituting for \( M \) in equation (v), we have
\[
\sqrt{(0.0265)^2 + T^2} = 0.053
\]
or
\[
T = 0.0459 \text{MNm}
\]
Part II: \( \therefore \tau_{\text{max}} = 100 \text{MN/m}^2 \)
Increase in torque:
Bending moment (M) to be kept constant = 0.0265 MNm
or
\[
(0.0265)^2 + T^2 = \left[ \frac{100 \times \pi \times (0.15)^3}{16} \right]^2 = 0.004391
\]
\[
\therefore T = 0.0607 \text{MNm}
\]
\[
\therefore \text{The increased torque} = 0.0607 - 0.0459 = 0.0148 \text{MNm}
\]

**Conventional Question ESE-1996**

**Question:** A solid shaft is to transmit 300 kW at 120 rpm. If the shear stress is not to exceed 100 MPa, Find the diameter of the shaft, What percent saving in weight would be obtained if this shaft were replaced by a hollow one whose internal diameter equals 0.6 of the external diameter, the length, material and maximum allowable shear stress being the same?

**Answer:**

Given \( P = 300 \text{ kW}, N = 120 \text{ rpm}, \tau = 100 \text{ MPa}, d_H = 0.6D_H \)

Diameter of solid shaft, \( D_s \):

We know that \( P = \frac{2\pi NT}{60 \times 1000} \) or \( 300 = \frac{2\pi \times 120 \times T}{60 \times 1000} \) or \( T = 23873 \text{ Nm} \)

We know that \( \frac{T}{J} = \frac{\tau}{R} \)

or, \( T = \frac{\tau J}{R} \) or, \( 23873 = \frac{100 \times 10^6 \times \pi}{32} \frac{D_s^4}{2} \)

or, \( D_s = 0.1067 \text{ m} = 106.7 \text{ mm} \)

Percentage saving in weight:

\( T_H = T_s \)
\[
\left( \frac{\tau \times J}{R} \right)_H = \left( \frac{\tau \times J}{R} \right)_s
\]

or, \( \left( \frac{D_H^4 - d_H^4}{D_H} \right) = D_s^3 \)

or, \( \frac{D_H^4 - (0.6D_H)^4}{D_H} = D_s^3 \)

or, \( D_H = \frac{D_s}{\sqrt[3]{1 - 0.6^4}} = \frac{106.7}{\sqrt[3]{0.64}} = 111.8 \text{ mm} \)

Again
\[
\frac{W_H}{W_s} = \frac{A_H L_H \rho_H g}{A_s L_s \rho_s g} = \frac{A_H}{A_s}
\]

\[
\frac{A_H}{A_s} = \frac{\frac{\pi}{4} (D_H^2 - d_H^2)}{\frac{\pi}{4} D_s^2} = \frac{D_H^2 (1 - 0.6^2)}{D_s^2} = \frac{111.8^2}{106.7^2} (1 - 0.6)^2 = 0.702
\]

\[
\therefore \text{Percentage savings in weight} = \left( 1 - \frac{W_H}{W_s} \right) \times 100 = (1 - 0.702) \times 100 = 29.8\% 
\]
1. Thin Rings

Uniformly distributed loading (radial) may be due to either

- Internal pressure or external pressure
- Centrifugal force as in the case of a rotating ring

**Case-I: Internal pressure or external pressure**

- \( s = qr \)  
  Where \( q \) = Intensity of loading in kg/cm of Oce  
  \( r \) = Mean centreline of radius  
  \( s \) = circumferential tension or hoop’s tension  
  (Radial loading ducted outward)

- Unit stress, \( \sigma = \frac{s}{A} = \frac{qr}{A} \)

- Circumferential strain, \( \epsilon_c = \frac{\sigma}{E} = \frac{qr}{AE} \)

- Diametral strain, \( (\epsilon_d) = \) Circumferential strain, \( (\epsilon_c) \)

**Case-II: Centrifugal force**

- Hoop's Tension, \( s = \frac{w\omega^2 r^2}{g} \)  
  Where \( w \) = wt. per unit length of circumferential element  
  \( \omega \) = Angular velocity

- Radial loading, \( q = \frac{s}{r} = \frac{w\omega^2 r}{g} \)

- Hoop's stress, \( \sigma = \frac{s}{A} = \frac{w}{Ag} \cdot \omega^2 r^2 \)

2. Thin Walled Pressure Vessels

For thin cylinders whose thickness may be considered small compared to their diameter.

\[
\frac{\text{Inner dia of the cylinder (d_i)}}{\text{wall thickness (t)}} > 15 \text{ or } 20
\]
Chapter-10 Thin Cylinder

3. General Formula

\[ \sigma_1 + \sigma_2 = \frac{p}{t} \]

Where \( \sigma_1 \) = Meridional stress at A
\( \sigma_2 \) = Circumferential / Hoop's stress

\( P \) = Intensity of internal gas pressure/ fluid pressure
\( t \) = Thickness of pressure vessel.

4. Some cases:

- **Cylindrical vessel**
  \[ \sigma_1 = \frac{pr}{2t} = \frac{pD}{4t} \quad \sigma_2 = \frac{pr}{t} = \frac{pD}{2t} \]
  \[ r_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{pr}{4t} = \frac{pD}{8t} \]

- **Spherical vessel**
  \[ \sigma_1 = \sigma_2 = \frac{pr}{2t} = \frac{pD}{4t} \]
  \( [r_1 = r_2 = r] \)

- **Conical vessel**
  \[ \sigma_1 = \frac{p}{2t} \tan \alpha \quad [r_1 \rightarrow \infty] \quad \text{and} \quad \sigma_2 = \frac{p}{t} \tan \alpha \cos \alpha \]

Notes:

- Volume 'V' of the spherical shell, \( V = \frac{\pi}{6} D_i^3 \)
  \[ \Rightarrow D_i = \left( \frac{6V}{\pi} \right)^{1/3} \]
- Design of thin cylindrical shells is based on hoop's stress

5. Volumetric Strain (Dilation)

- Rectangular block, \( \frac{\Delta V}{V_0} = \epsilon_x + \epsilon_y + \epsilon_z \)
- **Cylindrical pressure vessel**
  \[ \epsilon_1 = \text{Longitudinal strain} = \frac{\sigma_1}{E} - \frac{\mu}{2} \frac{\sigma_2}{E} = \frac{pr}{2Et} [1 - 2\mu] \]
  \[ \epsilon_2 = \text{Circumferential strain} = \frac{\sigma_2}{E} - \frac{\mu}{2} \frac{\sigma_1}{E} = \frac{pr}{2Et} [1 - 2\mu] \]
  Volumetric Strain, \( \frac{\Delta V}{V_0} = \epsilon_1 + 2\epsilon_2 = \frac{pr}{2Et} [5 - 4\mu] = \frac{pD}{4Et} [5 - 4\mu] \)

i.e. Volumetric strain \( \epsilon_v \) = longitudinal strain \( \epsilon_1 \) + 2 × circumferential strain \( \epsilon_2 \)

- **Spherical vessels**
  \[ \epsilon = \epsilon_1 = \epsilon_2 = \frac{pr}{2Et} [1 - \mu] \]
6. Thin cylindrical shell with hemispherical end

Condition for no distortion at the junction of cylindrical and hemispherical portion

\[
\frac{t_2}{t_1} = \frac{1 - \mu}{2 - \mu}
\]

Where, \( t_1 \) = wall thickness of cylindrical portion
\( t_2 \) = wall thickness of hemispherical portion

7. Alternative method

Consider the equilibrium of forces in the z-direction acting on the part cylinder shown in figure.

Force due to internal pressure \( p \) acting on area \( \pi D^2/4 = p \cdot \pi D^2/4 \)

Force due to longitudinal stress \( s_L \) acting on area \( \pi D t = \sigma_1 \cdot \pi D t \)

Equating:

\[
p \cdot \pi D^2/4 = \sigma_1 \cdot \pi D t
\]

or

\[
\sigma_1 = \frac{pd}{4t} = \frac{pr}{2t}
\]

Now consider the equilibrium of forces in the x-direction acting on the sectioned cylinder shown in figure. It is assumed that the circumferential stress \( \sigma_2 \) is constant through the thickness of the cylinder.

Force due to internal pressure \( p \) acting on area \( Dz = pDz \)

Force due to circumferential stress \( \sigma_2 \) acting on area \( 2tz = \sigma_2 2tz \)

Equating:

\[
pDz = \sigma_2 2tz
\]

or

\[
\sigma_2 = \frac{pD}{2t} = \frac{pr}{t}
\]
Objective Questions (GATE, IES, IAS)

Previous 20-Years GATE Questions

Longitudinal stress

GATE-1. The maximum principal strain in a thin cylindrical tank, having a radius of 25 cm and wall thickness of 5 mm when subjected to an internal pressure of 1MPa, is (taking Young's modulus as 200 GPa and Poisson’s ratio as 0.2) [GATE-1998]

(a) $2.25 \times 10^{-4}$  (b) $2.25$  (c) $2.25 \times 10^{-6}$  (d) 22.5

GATE-1. Ans. (a)

Circumferential or Hoop stress ($\sigma_c$) = $\frac{pr}{t} = \frac{1 \times 250}{5} = 50$ MPa

Longitudinal stress ($\sigma_l$) = $\frac{pr}{2t} = 25$ MPa

$e_c = \frac{\sigma_c}{E} - \frac{\sigma_l}{E} = \frac{50 \times 10^6}{200 \times 10^9} - 0.2 \times \frac{25 \times 10^6}{200 \times 10^9} = 2.25 \times 10^{-4}$

Maximum shear stress

GATE-2. A thin walled cylindrical vessel of wall thickness, $t$ and diameter $d$ is fitted with gas to a gauge pressure of $p$. The maximum shear stress on the vessel wall will then be: [GATE-1999]

(a) $\frac{pd}{t}$  (b) $\frac{pd}{2t}$  (c) $\frac{pd}{4t}$  (d) $\frac{pd}{8t}$

GATE-2. Ans. (d) $\sigma_c = \frac{pd}{2t}$, $\sigma_l = \frac{pd}{4t}$, Maximum shear stress $= \frac{\sigma_c - \sigma_l}{2} = \frac{pd}{8t}$

Change in dimensions of a thin cylindrical shell due to an internal pressure

Statement for Linked Answers and Questions 3 and 4

A cylindrical container of radius $R = 1$ m, wall thickness 1 mm is filled with water up to a depth of 2 m and suspended along its upper rim. The density of water is 1000 kg/m$^3$ and acceleration due to gravity is 10 m/s$^2$. The self-weight of the cylinder is negligible. The formula for hoop stress in a thin-walled cylinder can be used at all points along the height of the cylindrical container.

GATE-3. The axial and circumferential stress ($\sigma_a, \sigma_c$) experienced by the cylinder wall at mid-depth (1 m as shown) are

(a) (10,10) MPa  (b) (5,10) MPa  (c) (10,5) MPa  (d) (5,5)MPa

GATE-3. Ans. (a)

Pressure $= h \rho g = 1 \times 1000 \times 10 = 10$ kPa

Axial Stress ($\sigma_a$) $= \sigma_a = 2 \pi RL = \rho g \times \pi R^2 L$

or $\sigma_a = \rho g R L \times t = \frac{1000 \times 10 \times 1 \times 1}{1 \times 10^{-3}} = 10$ MPa

Circumferential Stress($\sigma_c$) = $\frac{PR}{t} = \frac{1 \times 10^{-3}}{1 \times 10^{-3}} = 10$ MPa
GATE-4. If the Young's modulus and Poisson's ratio of the container material are 100 GPa and 0.3, respectively, the axial strain in the cylinder wall at mid-depth is:
(a) $2 \times 10^{-5}$  
(b) $6 \times 10^{-5}$  
(c) $7 \times 10^{-5}$  
(d) $1.2 \times 10^{-5}$

GATE-4. Ans. (c) $\varepsilon_a = \frac{\sigma_a}{E} - \mu \frac{\sigma_c}{E} = \frac{10}{100 \times 10^{-5}} - 0.3 \times \frac{10}{100 \times 10^{-5}} = 7 \times 10^{-5}$

**Previous 20-Years IES Questions**

**Circumferential or hoop stress**

IES-1. Match List-I with List-II and select the correct answer: [IES-2002]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>(2-D Stress system loading)</td>
<td>(Ratio of principal stresses)</td>
</tr>
<tr>
<td>A. Thin cylinder under internal pressure</td>
<td>1. 3.0</td>
</tr>
<tr>
<td>B. Thin sphere under internal pressure</td>
<td>2. 1.0</td>
</tr>
<tr>
<td>C. Shaft subjected to torsion</td>
<td>3. -1.0</td>
</tr>
<tr>
<td></td>
<td>4. 2.0</td>
</tr>
</tbody>
</table>

Codes: A B C   A B C
(a) 4 2 3   (b) 1 3 2
(c) 4 3 2   (d) 1 2 3

IES-1. Ans. (a)

IES-2. A thin cylinder of radius $r$ and thickness $t$ when subjected to an internal hydrostatic pressure $P$ causes a radial displacement $u$, then the tangential strain caused is: [IES-2002]
(a) $\frac{du}{dr}$  
(b) $\frac{1}{r} \frac{du}{dr}$  
(c) $\frac{u}{r}$  
(d) $\frac{2u}{r}$

IES-2. Ans. (c)

IES-3. A thin cylindrical shell is subjected to internal pressure $p$. The Poisson's ratio of the material of the shell is 0.3. Due to internal pressure, the shell is subjected to circumferential strain and axial strain. The ratio of circumferential strain to axial strain is: [IES-2001]
(a) 0.425  
(b) 2.25  
(c) 0.225  
(d) 4.25

IES-3. Ans. (d) Circumferential strain, $\varepsilon_c = \frac{\sigma_c}{E} - \mu \frac{\sigma_t}{E} = \frac{Pr}{2Et}(2 - \mu)$

Longitudinal strain, $\varepsilon_l = \frac{\sigma_t}{E} - \mu \frac{\sigma_c}{E} = \frac{Pr}{2Et}(1 - 2\mu)$

IES-4. A thin cylindrical shell of diameter $d$, length 'l' and thickness $t$ is subjected to an internal pressure $p$. What is the ratio of longitudinal strain to hoop strain in terms of Poisson's ratio (1/m)? [IES-2004]
(a) $\frac{m - 2}{2m + 1}$  
(b) $\frac{m - 2}{2m - 1}$  
(c) $\frac{2m - 1}{m - 2}$  
(d) $\frac{2m + 2}{m - 1}$

IES-4. Ans. (b) longitudinal stress $\left(\sigma_l\right) = \frac{Pr}{2t}$
hoop stress ($\sigma_z$) = $\frac{Pr}{t}$

$\therefore \varepsilon_c = \frac{1}{E} - \frac{1}{m E} = \frac{1}{2} - \frac{1}{m}$

$\therefore \varepsilon_c = -\frac{1}{m E} - \frac{1}{2 m - 1}$

IES-5. When a thin cylinder of diameter 'd' and thickness 't' is pressurized with an internal pressure of 'p', ($1/m = \mu$ is the Poisson's ratio and $E$ is the modulus of elasticity), then [IES-1998]

(a) The circumferential strain will be equal to $\frac{pd}{2tE} \left( \frac{1}{2} - \frac{1}{m} \right)$

(b) The longitudinal strain will be equal to $\frac{pd}{2tE} \left( 1 - \frac{1}{2m} \right)$

(c) The longitudinal stress will be equal to $\frac{pd}{2t}$

(d) The ratio of the longitudinal strain to circumferential strain will be equal to $\frac{m - 2}{2m - 1}$

IES-5. Ans. (d) Ratio of longitudinal strain to circumferential strain

$\sigma_z - \left( \frac{1}{m} \right) \sigma_c = \sigma_z - \left( \frac{1}{m} \right) \left( \frac{2\sigma_z}{1} \right) = \frac{m - 2}{2m - 1}$

Circumferential strain, $\varepsilon_c = \frac{\sigma_c}{E} - \mu \frac{\sigma_z}{E} = \frac{pr}{2Et} (2 - \mu)$

Longitudinal strain, $\varepsilon_l = \frac{\sigma_l}{E} - \mu \frac{\sigma_z}{E} = \frac{pr}{2Et} (1 - 2\mu)$

IES-6. A thin cylinder contains fluid at a pressure of 500 N/m², the internal diameter of the shell is 0.6 m and the tensile stress in the material is to be limited to 9000 N/m². The shell must have a minimum wall thickness of nearly [IES-2000]

(a) 9 mm   (b) 11 mm   (c) 17 mm   (d) 21 mm

IES-6. Ans. (c)

IES-7. A thin cylinder with closed lids is subjected to internal pressure and supported at the ends as shown in figure. The state of stress at point X is as represented in

IES-1999
IES-8. A thin cylinder with both ends closed is subjected to internal pressure $p$. The longitudinal stress at the surface has been calculated as $\sigma_o$. Maximum shear stress at the surface will be equal to:

\[
\text{IES-1999}
\]

(a) $2\sigma_o$  
(b) $1.5\sigma_o$  
(c) $\sigma_o$  
(d) $0.5\sigma_o$

IES-8. Ans. (d)

Longitudinal stress $= \sigma_o$ and hoop stress $= 2\sigma_o$. Max. shear stress $= \frac{2\sigma_o - \sigma_o}{2} = \frac{\sigma_o}{2}$

IES-9. A metal pipe of 1m diameter contains a fluid having a pressure of 10 kgf/cm². If the permissible tensile stress in the metal is 200 kgf/cm², then the thickness of the metal required for making the pipe would be:

\[
\text{IES-1993}
\]

(a) 5 mm  
(b) 10 mm  
(c) 20 mm  
(d) 25 mm

IES-9. Ans. (d)

\[
\text{Hoop stress} = \frac{pd}{2t} \quad \text{or} \quad 200 = \frac{10 \times 100}{2 \times t} \quad \text{or} \quad t = \frac{1000}{400} = 2.5 \text{cm}
\]

IES-10. Circumferential stress in a cylindrical steel boiler shell under internal pressure is 80 MPa. Young's modulus of elasticity and Poisson's ratio are respectively $2 \times 10^5$ MPa and 0.28. The magnitude of circumferential strain in the boiler shell will be:

\[
\text{IES-1999}
\]

(a) $3.44 \times 10^{-4}$  
(b) $3.84 \times 10^{-4}$  
(c) $4 \times 10^{-4}$  
(d) $4.56 \times 10^{-4}$

IES-10. Ans. (a)

\[
\text{Circumferential strain} = \frac{1}{E} \left( \sigma_1 - \mu \sigma_2 \right)
\]

Since circumferential stress $\sigma_1 = 80$ MPa and longitudinal stress $\sigma_2 = 40$ MPa

\[
\therefore \text{Circumferential strain} = \frac{1}{2 \times 10^5 \times 10^6} \left[ 80 - 0.28 \times 40 \right] \times 10^6 = 3.44 \times 10^{-4}
\]

IES-11. A penstock pipe of 10m diameter carries water under a pressure head of 100 m. If the wall thickness is 9 mm, what is the tensile stress in the pipe wall in MPa?

\[
\text{IES-2009}
\]

(a) 2725  
(b) 545 0  
(c) 272 5  
(d) 1090

IES-11. Ans. (b)

\[
\text{Tensile stress in the pipe wall} = \text{Circumferential stress in pipe wall} = \frac{Pd}{2t}
\]

Where, $P = \rho gH = 980000N / m^2$

\[
\therefore \text{Tensile stress} = \frac{980000 \times 10}{2 \times 9 \times 10^{-3}} = 544.44 \times 10^6 N / m^2 = 544.44 MN / m^2 = 544.44 MPa
\]

IES-12. A water main of 1 m diameter contains water at a pressure head of 100 metres. The permissible tensile stress in the material of the water main is 25 MPa. What is the minimum thickness of the water main? (Take $g = 10 m/s^2$).

\[
\text{IES-2009}
\]

(a) 10 mm  
(b) 20mm  
(c) 50 mm  
(d) 60 mm

IES-12. Ans. (b)

\[
\text{Hoop stress} = \sigma_c = \frac{Pd}{2t}
\]

\[
\therefore t = \frac{Pd}{2\sigma_c} = \frac{(10^6)(1)}{2 \times 25 \times 10^6} = \frac{1}{50} \text{m} = 20 \text{ mm}
\]
Longitudinal stress

IES-13. Hoop stress and longitudinal stress in a boiler shell under internal pressure are 100 MN/m² and 50 MN/m² respectively. Young's modulus of elasticity and Poisson's ratio of the shell material are 200 GN/m² and 0.3 respectively. The hoop strain in boiler shell is: \[ \text{IES-1995} \]

(a) \( 0.425 \times 10^{-3} \)  
(b) \( 0.5 \times 10^{-3} \)  
(c) \( 0.585 \times 10^{-3} \)  
(d) \( 0.75 \times 10^{-3} \)

IES-13. Ans. (a) Hoop strain \( \frac{1}{E} (\sigma_h - \mu \sigma_l) = \frac{1}{200 \times 1000} [100 - 0.3 \times 50] = 0.425 \times 10^{-3} \)

IES-14. In strain gauge dynamometers, the use of how many active gauge makes the dynamometer more effective? \[ \text{IES 2007} \]

(a) Four  
(b) Three  
(c) Two  
(d) One

IES-14. Ans. (b)

Volumetric strain

IES-15. Circumferential and longitudinal strains in a cylindrical boiler under internal steam pressure are \( \varepsilon_1 \) and \( \varepsilon_2 \) respectively. Change in volume of the boiler cylinder per unit volume will be: \[ \text{IES-1993; IAS 2003} \]

(a) \( \varepsilon_1 + 2 \varepsilon_2 \)  
(b) \( \varepsilon_1 \varepsilon_2^2 \)  
(c) \( 2 \varepsilon_1 + \varepsilon_2 \)  
(d) \( \varepsilon_1^2 \varepsilon_2 \)

IES-15. Ans. (c) Volumetric strain = \( 2 \times \) circumferential strain + longitudinal strain

IES-16. The volumetric strain in case of a thin cylindrical shell of diameter \( d \), thickness \( t \), subjected to internal pressure \( p \) is: \[ \text{IES-2003; IAS 1997} \]

(a) \( \frac{pd}{2Et} \cdot (3 - 2\mu) \)  
(b) \( \frac{pd}{3Et} \cdot (4 - 3\mu) \)  
(c) \( \frac{pd}{4Et} \cdot (5 - 4\mu) \)  
(d) \( \frac{pd}{4Et} \cdot (4 - 5\mu) \)

(Where \( E \) = Modulus of elasticity, \( \mu \) = Poisson's ratio for the shell material)

IES-16. Ans. (c) Remember it.

Spherical Vessel

IES-17. For the same internal diameter, wall thickness, material and internal pressure, the ratio of maximum stress, induced in a thin cylindrical and in a thin spherical pressure vessel will be: \[ \text{IES-2001} \]

(a) 2  
(b) \( \frac{1}{2} \)  
(c) 4  
(d) \( \frac{1}{4} \)

IES-17. Ans. (a)

IES-18. From design point of view, spherical pressure vessels are preferred over cylindrical pressure vessels because they \[ \text{IES-1997} \]

(a) Are cost effective in fabrication  
(b) Have uniform higher circumferential stress  
(c) Uniform lower circumferential stress  
(d) Have a larger volume for the same quantity of material used

IES-18. Ans. (d)

Previous 20-Years IAS Questions

Circumferential or hoop stress

IAS-1. The ratio of circumferential stress to longitudinal stress in a thin cylinder subjected to internal hydrostatic pressure is: \[ \text{IAS 1994} \]

(a) \( \frac{1}{2} \)  
(b) 1  
(c) 2  
(d) 4

IAS-1. Ans. (c)
IAS-2. A thin walled water pipe carries water under a pressure of 2 N/mm² and discharges water into a tank. Diameter of the pipe is 25 mm and thickness is 2.5 mm. What is the longitudinal stress induced in the pipe? [IAS-2007]
(a) 0  (b) 2 N/mm²  (c) 5 N/mm²  (d) 10 N/mm²
IAS-2. Ans. (c) \[ \sigma = \frac{Pr}{2t} = \frac{2 \times 12.5}{2 \times 2.5} = 5 \text{ N/mm}^2 \]

IAS-3. A thin cylindrical shell of mean diameter 750 mm and wall thickness 10 mm has its ends rigidly closed by flat steel plates. The shell is subjected to internal fluid pressure of 10 N/mm² and an axial external pressure \( P_1 \). If the longitudinal stress in the shell is to be zero, what should be the approximate value of \( P_1 \)? [IAS-2007]
(a) 8 N/mm²  (b) 9 N/mm²  (c) 10 N/mm²  (d) 12 N/mm²
IAS-3. Ans. (c) Tensile longitudinal stress due to internal fluid pressure \( (\delta_1)_t \) = \[ \frac{10 \times \left( \frac{\pi \times 750^2}{4} \right)}{\pi \times 750 \times 10} \] tensile. Compressive longitudinal stress due to external pressure \( p_1 \) \( (\delta_1)_c = \frac{P_1 \times \left( \frac{\pi \times 750^2}{4} \right)}{\pi \times 750 \times 10} \) compressive. For zero longitudinal stress \( (\delta_1)_t = (\delta_1)_c \).

IAS-4. Assertion (A): A thin cylindrical shell is subjected to internal fluid pressure that induces a 2-D stress state in the material along the longitudinal and circumferential directions. [IAS-2000]
Reason (R): The circumferential stress in the thin cylindrical shell is two times the magnitude of longitudinal stress.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IAS-4. Ans. (b) For thin cell \( \sigma_c = \frac{Pr}{t} \), \( \sigma_l = \frac{Pr}{2t} \)

IAS-5. Match List-I (Terms used in thin cylinder stress analysis) with List-II (Mathematical expressions) and select the correct answer using the codes given below the lists: [IAS-1998]

List-I  List-II
A. Hoop stress 1. \( \frac{pd}{4t} \)
B. Maximum shear stress 2. \( \frac{pd}{2t} \)
C. Longitudinal stress 3. \( \frac{pd}{2\sigma} \)
D. Cylinder thickness 4. \( \frac{pd}{8t} \)

Codes: A B C D  A B C D
(a) 2 3 1 4  (b) 2 3 4 1
(c) 2 4 3 1  (d) 2 4 1 3

IAS-5. Ans. (d)
Chapter-10  Thin Cylinder  S K Mondal’s

Reason (R): If the principal stresses directions are not know, the minimum number of strain gauges needed is three in a biaxial field.  [IAS-2001]

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-6. Ans. (d) For thin cylinder, variation of radial strain is zero. So only circumferential and longitudinal strain has to measure so only two strain gauges are needed.

Maximum shear stress

IAS-7. The maximum shear stress is induced in a thin-walled cylindrical shell having an internal diameter 'D' and thickness 't' when subject to an internal pressure 'p' is equal to:  [IAS-1996]

(a) pD/t  (b) pD/2t  (c) pD/4t  (d) pD/8t

IAS-7. Ans. (d) Hoop stress($\sigma_\varepsilon$) = $\frac{PD}{2t}$ and Longitudinal stress($\sigma_\varepsilon$) = $\frac{PD}{4t}$ $\therefore \tau_{\text{max}} = \frac{\sigma_\varepsilon - \sigma_\varepsilon}{2} = \frac{PD}{8t}$

Volumetric strain

IAS-8. Circumferential and longitudinal strains in a cylindrical boiler under internal steam pressure $\varepsilon_1$ and $\varepsilon_2$ respectively. Change in volume of the boiler cylinder per unit volume will be:  [IES-1993; IAS 2003]

(a) $\varepsilon_1 + 2 \varepsilon_2$  (b) $\varepsilon_1 \varepsilon_2^2$  (c) $2 \varepsilon_1 + \varepsilon_2$  (d) $\varepsilon_1^2 \varepsilon_2^2$

IAS-8. Ans. (c) Volumetric strain = 2 x circumferential strain + longitudinal strain.

IAS-9. The volumetric strain in case of a thin cylindrical shell of diameter d, thickness t, subjected to internal pressure p is:  [IES-2003; IAS 1997]

(a) $\frac{pd}{2tE}(3 - 2\mu)$  (b) $\frac{pd}{3tE}(4 - 3\mu)$  (c) $\frac{pd}{4tE}(5 - 4\mu)$  (d) $\frac{pd}{4tE}(4 - 5\mu)$

(Where E = Modulus of elasticity, $\mu$ = Poisson’s ratio for the shell material)

IAS-9. Ans. (c) Remember it.

IAS-10. A thin cylinder of diameter ‘d’ and thickness ‘t’ is subjected to an internal pressure 'p' the change in diameter is (where E is the modulus of elasticity and $\mu$ is the Poisson’s ratio)  [IAS-1998]

(a) $\frac{pd^2}{4tE}(2 - \mu)$  (b) $\frac{pd^2}{2tE}(1 + \mu)$  (c) $\frac{pd^2}{4tE}(2 + \mu)$  (d) $\frac{pd^2}{4tE}(2 + \mu)$

IAS-10. Ans. (a)

IAS-11. The percentage change in volume of a thin cylinder under internal pressure having hoop stress = 200 MPa, E = 200 GPa and Poisson’s ratio = 0.25 is:  [IAS-2002]

(a) 0.40  (b) 0.30  (c) 0.25  (d) 0.20

IAS-11. Ans. (d) Hoop stress($\sigma_t$) = $\frac{Pr}{t} = 200 \times 10^6 P_a$
Chapter-10

Volumetric strain \( (\varepsilon_v) = \frac{Pr}{2Et} (5 - 4\mu) = \frac{\sigma_i}{2E} (5 - 4\mu) \)
\[ = \frac{200 \times 10^6}{2 \times 200 \times 10^9} (5 - 4 \times 0.25) = \frac{2}{1000} \]

IAS-12. A round bar of length \( l \), elastic modulus \( E \) and Poisson's ratio \( \mu \) is subjected to an axial pull 'P'. What would be the change in volume of the bar? [IAS-2007]

\( (a) \frac{Pl}{(1-2\mu)E} \quad (b) \frac{Pl(1-2\mu)}{E} \quad (c) \frac{Pl\mu}{E} \quad (d) \frac{Pl}{\mu E} \)

IAS-12. Ans. (b)

\( \sigma_x = \frac{P}{A} \), \( \sigma_y = 0 \) and \( \sigma_z = 0 \)

or \( \varepsilon_x = \frac{\sigma_x}{E} \), \( \varepsilon_y = -\mu \frac{\sigma_x}{E} \)

and \( \varepsilon_z = -\mu \frac{\sigma_x}{E} \)

or \( \varepsilon_v = \varepsilon_x + \varepsilon_y + \varepsilon_z = \frac{\sigma_x}{E} (1-2\mu) = \frac{P}{AE} (1-2\mu) \)
\[ \delta V = \varepsilon_v \times V = \varepsilon_v \cdot Al = \frac{Pl}{E} (1-2\mu) \]

IAS-13. If a block of material of length 25 cm, breadth 10 cm and height 5 cm undergoes a volumetric strain of 1/5000, then change in volume will be: [IAS-2000]

(a) 0.50 cm³  
(b) 0.25 cm³  
(c) 0.20 cm³  
(d) 0.75 cm³

IAS-13. Ans. (b)

\[ \text{Volumetric strain} (\varepsilon_v) = \frac{\text{Volume change(}\delta V\text{)}}{\text{Initial volume(V)}} \]

or \( (\delta V) = \varepsilon_v \times V = \frac{1}{5000} \times 25 \times 10 \times 5 = 0.25 cm^3 \)
Chapter-10 Thin Cylinder

Previous Conventional Questions with Answers

Conventional Question GATE-1996

Question: A thin cylinder of 100 mm internal diameter and 5 mm thickness is subjected to an internal pressure of 10 MPa and a torque of 2000 Nm. Calculate the magnitudes of the principal stresses.

Answer: Given: \( d = 100 \text{ mm} = 0.1 \text{ m}; \ t = 5 \text{ mm} = 0.005 \text{ m}; \ D = d + 2t = 0.1 + 2 \times 0.005 = 0.11 \text{ m}; \ p = 10 \text{ MPa, } 10 \times 10^6 \text{N/m}^2; \ T= 2000 \text{ Nm.} \)

Longitudinal stress, \( \sigma_l = \sigma_x = \frac{pd}{4t} = \frac{10 \times 10^6 \times 0.1}{4 \times 0.005} = 50 \times 10^6 \text{N/m}^2 = 50 \text{MN/m}^2 \)

Circumferential stress, \( \sigma_c = \sigma_y = \frac{pd}{2t} = \frac{10 \times 10^6 \times 0.1}{2 \times 0.005} = 100 \text{MN/m}^2 \)

To find the shear stress, using Torsional equation,

\[
\tau = \frac{T}{J} = \frac{TR}{J} = \frac{T \times R}{\frac{\pi}{32}(D^4 - d^4)} = \frac{2000 \times (0.05 + 0.005)}{\frac{\pi}{32}(0.11^4 - 0.1^4)} = 24.14 \text{MN/m}^2
\]

Principal stresses are:

\[
\sigma_1 = \frac{\sigma_x + \sigma_y}{2} \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + (\tau)^2} = \frac{50 + 100}{2} \pm \sqrt{\left(\frac{50 - 100}{2}\right)^2 + (24.14)^2} = 75 \pm 34.75 = 109.75 \text{ and } 40.25 \text{MN/m}^2
\]

\( \sigma_1 \) (Major principal stress) = 109.75MN/m\(^2\);

\( \sigma_2 \) (minor principal stress) = 40.25MN/m\(^2\);

Conventional Question IES-2008

Question: A thin cylindrical pressure vessel of inside radius ‘r’ and thickness of metal ‘t’ is subject to an internal fluid pressure p. What are the values of

(i) Maximum normal stress?
(ii) Maximum shear stress?

Answer: Circumferential (Hoop) stress \( \sigma_c = \frac{p \cdot r}{t} \)

Longitudinal stress \( \sigma_l = \frac{p \cdot r}{2t} \)

Therefore (ii) Maximum shear stress, \( \tau_{\text{max}} = \frac{\sigma_c - \sigma_l}{2} = \frac{p \cdot r}{4t} \)

Conventional Question IES-1996

Question: A thin cylindrical vessel of internal diameter \( d \) and thickness \( t \) is closed at both ends is subjected to an internal pressure \( P \). How much would be the hoop and longitudinal stress in the material?

Answer: For thin cylinder we know that
Chapter-10  Thin Cylinder  S K Mondal’s

Hoop or circumferential stress \( (\sigma_c) = \frac{Pd}{2t} \)

And longitudinal stress \( (\sigma_\ell) = \frac{Pd}{4t} \)

Therefore \( \sigma_c = 2\sigma_\ell \)

Conventional Question IES-2009

Q. A cylindrical shell has the following dimensions:
Length = 3 m
Inside diameter = 1 m
Thickness of metal = 10 mm
Internal pressure = 1.5 MPa
Calculate the change in dimensions of the shell and the maximum intensity of shear stress induced. Take \( E = 200 \text{ GPa} \) and Poisson’s ratio \( v = 0.3 \). [15-Marks]

Ans. We can consider this as a thin cylinder.

Hoop stresses, \( \sigma_1 = \frac{pd}{2t} \)

Longitudinal stresses, \( \sigma_2 = \frac{pd}{4t} \)

Shear stress = \( \frac{\sigma_1 - \sigma_2}{2} \)

\( \frac{pd}{8t} \)

Hence from the given data
\( \sigma_1 = \frac{1.5 \times 10^6 \times 1}{2 \times 10 \times 10^{-3}} = 7.5 \times 10^8 \)

\( = 75 \text{ MPa} \)

\( \sigma_2 = \frac{1.5 \times 10^6 \times 1}{4 \times 10 \times 10^{-3}} = 37.5 \times 10^6 \)

\( = 37.5 \text{ MPa} \)

\( \varepsilon_1 \) Hoop strain

\( \varepsilon_1 = \frac{1}{E} \left( \sigma_1 - v\sigma_2 \right) \)

\( = \frac{Pd}{4tE} (2 - v) \)

\( = \frac{1.5 \times 10^6 \times 1}{4 \times 10 \times 10^{-3} \times 200 \times 10^5} (2 - 0.3) \)

\( = \frac{37.5 \times 10^6}{200 \times 10^5} (2 - 0.3) \)

\( = 0.31875 \times 10^{-3} \)

\( \frac{\Delta d}{d} = 0.3187 \times 10^{-3} \)

\( \therefore \) change in diameter,

\( \Delta d = 1 \times 0.31875 \times 10^{-3} \text{ m} \)

\( = 0.31875 \text{ mm} \)
Chapter-10 Thin Cylinder

Logitudinal strain, $\varepsilon_2$

$$\varepsilon_2 = \frac{pd}{4tE} (1-2v)$$

$$= \frac{37.5 \times 10^6}{200 \times 10^9} (1-2 \times 0.3)$$

$$= 7.5 \times 10^{-5}$$

$$\frac{\Delta l}{l} = 7.5 \times 10^{-5}$$

or $\Delta l = 7.5 \times 10^{-5} \times 3$

$$= 2.25 \times 10^{-4} \text{ m} = 0.225 \text{ mm}$$

$\Rightarrow$ Change in length $= 0.225 \text{ mm}$ and maximum shear stress,

$$\sigma = \frac{pd}{8t} = \frac{1.5 \times 10^6 \times 1}{8 \times 10 \times 10^{-3}}$$

$$= 18.75 \text{ MPa}$$

Conventional Question IES-1998

Question: A thin cylinder with closed ends has an internal diameter of 50 mm and a wall thickness of 2.5 mm. It is subjected to an axial pull of 10 kN and a torque of 500 Nm while under an internal pressure of 6 MN/m$^2$.

(i) Determine the principal stresses in the tube and the maximum shear stress.

(ii) Represent the stress configuration on a square element taken in the load direction with direction and magnitude indicated; (schematic).

Answer:

Given: $d = 50 \text{ mm} = 0.05 \text{ m}$

$D = d + 2t = 50 + 2 \times 2.5 = 55 \text{ mm} = 0.055 \text{ m}$;

Axial pull, $P = 10 \text{ kN}$; $T = 500 \text{ Nm}$; $p = 6 \text{ MN/m}^2$

(i) Principal stresses ($\sigma_{xz}$) in the tube and the maximum shear stress ($\tau_{max}$):

$$\sigma_x = \frac{pd + P}{4t} = \frac{6 \times 10^6 \times 0.05}{4 \times 2.5 \times 10^{-3}} + \frac{10 \times 10^3}{\pi \times 0.05 \times 2.5 \times 10^{-3}}$$

$$= 30 \times 10^6 + 25.5 \times 10^6 = 55.5 \times 10^6 \text{ N/m}^2$$

$$\sigma_y = \frac{pd}{2t} = \frac{6 \times 10^6 \times 0.05}{2 \times 2.5 \times 10^{-3}} = 60 \times 10^6$$

Principal stresses are:

$$\sigma_{xz} = \left(\frac{\sigma_x + \sigma_y}{2}\right) \pm \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2} \quad (1)$$

Use Torsional equation, $\frac{T}{J} = \frac{\tau}{R} \quad (i)$

where $J = \frac{\pi}{32} (D^4 - d^4) = \frac{\pi}{32} \left[ (0.055)^4 - (0.05)^4 \right] = 2.848 \times 10^{-7} \text{ m}^4$

$J = \text{polar moment of inertia}$

Substituting the values in (i), we get
\[
\frac{500}{2.848 \times 10^{-7}} = \frac{\tau}{(0.055 / 2)}
\]

or

\[
\tau = \frac{500 \times (0.055 / 2)}{2.848 \times 10^{-7}} = 48.28 \times 10^6 \text{ N/m}^2
\]

Now, substituting the various values in eqn. (i), we have

\[
\sigma_{\nu 2} = \left(\frac{55.5 \times 10^6 + 60 \times 10^6}{2}\right) \pm \sqrt{\left(\frac{55.5 \times 10^6 - 60 \times 10^6}{2}\right)^2 + \left(48.28 \times 10^6 \right)^2}
\]

\[
= \frac{(55.5 + 60) \times 10^6}{2} \pm \sqrt{4.84 \times 10^{12} + 2330.96 \times 10^{12}}
\]

\[
= 57.75 \times 10^6 \pm 48.33 \times 10^6 = 106.08 \text{ MN/m}^2, 9.42 \text{ MN/m}^2
\]

Principal stresses are : \( \sigma_1 = 106.08 \text{ MN/m}^2; \sigma_2 = 9.42 \text{ MN/m}^2 \)

Maximum shear stress, \( \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{106.08 - 9.42}{2} = 48.33 \text{ MN/m}^2 \)

(ii) Stress configuration on a square element:
11. Thick Cylinder

Theory at a Glance (for IES, GATE, PSU)

1. Thick cylinder

\[
\frac{\text{Inner dia of the cylinder (d_i)}}{\text{wall thickness (t)}} < 15 \text{ or } 20
\]

2. General Expression

3. Difference between the analysis of stresses in thin & thick cylinders

- In thin cylinders, it is assumed that the tangential stress \( \sigma_t \) is uniformly distributed over the cylinder wall thickness.

In thick cylinder, the tangential stress \( \sigma_t \) has the highest magnitude at the inner surface of the cylinder & gradually decreases towards the outer surface.

- The radial stress \( \sigma_r \) is neglected in thin cylinders while it is of significant magnitude in case of thick cylinders.

4. Strain

- Radial strain, \( \varepsilon_r = \frac{du}{dr} \).

- Circumferential/Tangential strain \( \varepsilon_t = \frac{u}{r} \).

- Axial strain, \( \varepsilon_z = \frac{\sigma_z}{E} - \mu \left( \frac{\sigma_r}{E} + \frac{\sigma_t}{E} \right) \).
5. Stress

- Axial stress, \( \sigma_z = \frac{p_ir_i^2}{r_o^2 - r_i^2} \)
- Radial stress, \( \sigma_r = A - \frac{B}{r^2} \)
- Circumferential/Tangential stress, \( \sigma_t = A + \frac{B}{r^2} \)

[Note: Radial stress always compressive so its magnitude always –ive. But in some books they assume that compressive radial stress is positive and they use, \( \sigma_r = \frac{B}{r^2} - A \)]

6. Boundary Conditions

At \( r = r_i \), \( \sigma_r = -p_i \)
At \( r = r_o \), \( \sigma_r = -p_o \)

7. \( A = \frac{p_ir_i^2 - p_or_o^2}{r_o^2 - r_i^2} \) and \( B = \frac{(p_i - p_o) - r_i^2r_o^2}{(r_o^2 - r_i^2)} \)

8. Cylinders with internal pressure (\( p_i \)) i.e. \( p_o = 0 \)

- \( \sigma_z = \frac{p_ir_i^2}{r_o^2 - r_i^2} \)
- \( \sigma_r = -\frac{p_ir_i^2}{r_o^2 - r_i^2} \left[ \frac{r_o^2}{r^2} - 1 \right] \) [ive means compressive stress]
- \( \sigma_t = +\frac{p_ir_i^2}{r_o^2 - r_i^2} \left[ \frac{r_o^2}{r^2} + 1 \right] \)

(a) At the inner surface of the cylinder

(i) \( r = r_i \)
(ii) \( \sigma_i = -p_i \)
(iii) \( \sigma_t = +\frac{p_i(r_o^2 + r_i^2)}{r_o^2 - r_i^2} \)
(iv) \( \tau_{\text{max}} = \frac{r_i^2}{r_o^2 - r_i^2} \cdot p_i \)

(b) At the outer surface of the cylinder
(i) \( r = r_i \)
(ii) \( \sigma_r = 0 \)
(iii) \( \sigma_t = \frac{2p_i r_i^2}{r_o^2 - r_i^2} \)

(c) **Radial and circumferential stress distribution within the cylinder wall when only internal pressure acts.**

9. **Cylinders with External Pressure \((p_o)\) i.e. \(\rho = 0\)**

- \( \sigma_t = -\frac{p_o r_o^2}{r_o^2 - r_i^2} \left[ i - \frac{r_i^2}{r^2} \right] \)
- \( \sigma_t = -\frac{p_o r_o^2}{r_o^2 - r_i^2} \left[ i + \frac{r_i^2}{r^2} \right] \)

(a) **At the inner surface of the cylinder**

(i) \( r = r_i \)
(ii) \( \sigma_r = 0 \)
(iii) \( \sigma_t = -\frac{2p_i r_i^2}{r_o^2 - r_i^2} \)

(b) **At the outer surface of the cylinder**

(i) \( r = r_o \)
(ii) \( \sigma_r = -p_o \)
(iii) \( \sigma_t = -\frac{p_o (r_o^2 + r_i^2)}{r_o^2 - r_i^2} \)

(c) **Distribution of radial and circumferential stresses within the cylinder wall when only external pressure acts**
10. Lame's Equation [for Brittle Material, open or closed end]

There is a no of equations for the design of thick cylinders. The choice of equation depends upon two parameters.

- Cylinder Material (Whether brittle or ductile)
- Condition of Cylinder ends (open or closed)

*When the material of the cylinder is brittle, such as cast iron or cast steel, Lame's Equation is used to determine the wall thickness. Condition of cylinder ends may open or closed.*

It is based on maximum principal stress theory of failure.

There principal stresses at the inner surface of the cylinder are as follows: (i) (ii) & (iii)

\[
\begin{align*}
(i) \quad \sigma_r &= -p_i \\
(ii) \quad \sigma_i &= +\frac{p_i (r_i^2 + r_0^2)}{r_0^2 - r_i^2} \\
(iii) \quad \sigma_z &= +\frac{p_i r_i^2}{r_0^2 - r_i^2}
\end{align*}
\]

- \( \sigma_i > \sigma_z > \sigma_r \)
- \( \sigma_i \) is the criterion of design

\[
r_o = \frac{\sigma_i + p_i}{\sigma_i - p_i}
\]

- For \( r_o = r_i + t \)

\[
t = r_i \times \left[ \frac{\sigma_i + p_i}{\sqrt{\sigma_i - p_i}} - 1 \right] \quad \text{(Lame’s Equation)}
\]

- \( \sigma_i = \frac{\sigma_{ult}}{f_{os}} \)

11. Clavarino's Equation [for cylinders with closed end & made of ductile material]

When the material of a cylinder is ductile, such as mild steel or alloy steel, maximum strain theory of failure is used (St. Venant’s theory) is used.

Three principal stresses at the inner surface of the cylinder are as follows (i) (ii) & (iii)
(i) \( \sigma_r = -p_i \)

(ii) \( \sigma_t = \frac{p_i (r_o^2 + r_i^2)}{(r_o^2 - r_i^2)} \)

(iii) \( \sigma_z = \frac{p_i r_i^2}{(r_o^2 - r_i^2)} \)

\( \varepsilon_i = \frac{1}{E} \left[ \sigma_r - \left( \sigma_r + \sigma_z \right) \right] \)

\( \varepsilon_z = \frac{\sigma_{std}}{E} foss \)

- Or \( \sigma = \sigma_t - \mu (\sigma_r + \sigma_z) \). Where \( \sigma = \frac{\sigma_{std}}{foss} \)
- \( \sigma \) is the criterion of design

\[ \frac{r_o}{r_i} = \sqrt{\frac{\sigma + (1 - 2\mu)p_i}{\sigma - (1 + \mu)p_i}} \]

For \( r_o = r_i + t \)

\[ t = r_i \left[ \sqrt{\frac{\sigma + (1 - 2\mu)p_i}{\sigma - (1 + \mu)p_i}} - 1 \right] \] (Clavion's Equation)

12. Birne's Equation [for cylinders with open end & made of ductile material]

When the material of a cylinder is ductile, such as mild steel or alloy steel, maximum strain theory of failure is used (St. Venant's theory) is used.

Three principal stresses at the inner surface of the cylinder are as follows (i) (ii) & (iii)

(i) \( \sigma_r = -p_i \)

(ii) \( \sigma_t = \frac{p_i (r_o^2 + r_i^2)}{(r_o^2 - r_i^2)} \)

(iii) \( \sigma_z = 0 \)

- \( \sigma = \sigma_t - \mu \sigma_r \) where \( \sigma = \frac{\sigma_{std}}{foss} \)
- \( \sigma \) is the criterion of design

\[ \frac{r_o}{r_i} = \sqrt{\frac{\sigma + (1 - \mu)p_i}{\sigma - (1 + \mu)p_i}} \]

For \( r_o = r_i + t \)

\[ t = r_i \times \left[ \sqrt{\frac{\sigma + (1 - \mu)p_i}{\sigma - (1 + \mu)p_i}} - 1 \right] \] (Birnic's Equation)

13. Barlow’s equation: [for high pressure gas pipe brittle or ductile material]
\[ t = r_o \frac{P_i}{\sigma_t} \]

Where \( \sigma_t = \frac{\sigma_y}{f_{os}} \) for ductile material

\( = \frac{\sigma_{ul}}{f_{os}} \) for brittle material

14. Compound Cylinder (A cylinder & A Jacket)

- When two cylindrical parts are assembled by shrinking or press-fitting, a contact pressure is created between the two parts. If the radii of the inner cylinder are \( a \) and \( c \) and that of the outer cylinder are \( (c-\delta) \) and \( b \), \( \delta \) being the radial interference the contact pressure is given by:

\[
P = \frac{E\delta}{c} \left[ \frac{(b^2 - c^2)(c^2 - a^2)}{2c^2(b^2 - a^2)} \right]
\]

Where \( E \) is the Young's modulus of the material

- The inner diameter of the jacket is slightly smaller than the outer diameter of cylinder
- When the jacket is heated, it expands sufficiently to move over the cylinder
- As the jacket cools, it tends to contract onto the inner cylinder, which induces residual compressive stress.
- There is a shrinkage pressure 'P' between the cylinder and the jacket.
- The pressure 'P' tends to contract the cylinder and expand the jacket
- The shrinkage pressure 'P' can be evaluated from the above equation for a given amount of interference \( \delta \)
- The resultant stresses in a compound cylinder are found by supervision losing the 2- stresses
  - stresses due to shrink fit
  - stresses due to internal pressure

**Derivation:**

Due to interference let us assume \( \delta_j \) = increase in inner diameter of jacket and \( \delta_c \) = decrease in outer diameter of cylinder.

so \( \delta = |\delta_j| + |\delta_c| \) i.e. without sign.
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Now $\delta_j = \varepsilon_j c$

$$= \frac{1}{E} [\sigma_i - \mu \sigma_r] c$$

$$= \frac{cP}{E} \left[ \frac{b^2 + c^2}{b^2 - c^2} + \mu \right] \quad \text{--- (i)}$$

$\sigma_i =$circumferential stress

$$\sigma_r = -p \text{ (radial stress)}$$

And in similar way $\delta_c = \varepsilon_c c = \frac{1}{E} [\sigma_i - \mu \sigma_r] c$

$$= -\frac{cP}{E} \left[ \frac{c^2 + a^2}{c^2 - a^2} - \mu \right] \quad \text{--- (ii)}$$

Here -ive sign represents contraction

Adding (i) & (ii)

$$\therefore \delta = |\delta_j| + |\delta_c| = \frac{Pc}{E} \left[ \frac{2c^2(b^2 - a^2)}{(b^2 - c^2)(c^2 - a^2)} \right]$$

or $P = \frac{E\delta}{c} \left[ \frac{(b^2 - c^2)(c^2 - a^2)}{2c^2(b^2 - a^2)} \right]$

15. Autofrettage

Autofrettage is a process of pre-stressing the cylinder before using it in operation.

We know that when the cylinder is subjected to internal pressure, the circumferential stress at the inner surface limits the pressure carrying capacity of the cylinder.

In autofrettage pre-stressing develops a residual compressive stresses at the inner surface. When the cylinder is actually loaded in operation, the residual compressive stresses at the inner surface begin to decrease, become zero and finally become tensile as the pressure is gradually increased. Thus autofrettage increases the pressure carrying capacity of the cylinder.

16. Rotating Disc

The radial & circumferential (tangential) stresses in a rotating disc of uniform thickness are given by

$$\sigma_r = \frac{\rho \omega^2}{8} (3 + \mu) \left( R_0^2 + R_i^2 - \frac{R_0}{r^2} \frac{R_i^2}{r^2} - r^2 \right)$$

$$\sigma_r = \frac{\rho \omega^2}{8} (3 + \mu) \left( R_0^2 + R_i^2 + \frac{R_0}{r^2} \frac{R_i^2}{r^2} - \frac{1 + 3 \mu}{3 + \mu} r^2 \right)$$

Where $R_i =$ Internal radius

$R_o =$ External radius

$\rho =$ Density of the disc material

$\omega =$ Angular speed

$\mu =$ Poisson's ratio.
Or, Hoop's stress, $\sigma_t = \frac{3+\mu}{4} \rho \omega^2 \left[ R_0^2 + \left( \frac{1-\mu}{3+\mu} \right) R_i^2 \right]$.

Radial stress, $\sigma_r = \frac{3+\mu}{8} \rho \omega^2 \left[ R_0^2 - R_i^2 \right]$.
Objective Questions (GATE, IES, IAS)

Previous 20-Years GATE Questions

Lame's theory

GATE-1. A thick cylinder is subjected to an internal pressure of 60 MPa. If the hoop stress on the outer surface is 150 MPa, then the hoop stress on the internal surface is: [GATE-1996; IES-2001]
(a) 105 MPa  (b) 180 MPa  (c) 210 MPa  (d) 135 MPa

GATE-1. Ans. (c)

Circumferential or hoop stress ($\sigma_c$) = $\frac{p_i r^2}{r_0^2 - r_i^2} \left( \frac{r_0^2}{r_i^2} + 1 \right)$

At $p_i = 60$ MPa, $\sigma_c = 150$ MPa and $r = r_0$

$\therefore 150 = 60 \frac{r_1^2}{r_0^2 - r_1^2} \left( \frac{r_0^2}{r_1^2} + 1 \right)$

$\therefore \frac{r_1^2}{r_0^2 - r_1^2} = \frac{150}{120} = \frac{5}{4}$

$\therefore \left( \frac{r_0}{r_1} \right)^2 = \frac{9}{5}$

$\therefore$ at $r = r_1$

$\sigma_c = 60 \frac{r_1^2}{r_0^2 - r_1^2} \left( \frac{r_0^2}{r_1^2} + 1 \right) = 60 \times \frac{5}{4} \times \left( \frac{9}{5} + 1 \right) = 210$ MPa

Previous 20-Years IES Questions

Thick cylinder

IES-1. If a thick cylindrical shell is subjected to internal pressure, then hoop stress, radial stress and longitudinal stress at a point in the thickness will be:
(a) Tensile, compressive and compressive respectively [IES-1999]
(b) All compressive
(c) All tensile
(d) Tensile, compressive and tensile respectively


IES-2. Where does the maximum hoop stress in a thick cylinder under external pressure occur? [IES-2008]
(a) At the outer surface
(b) At the inner surface
(c) At the mid-thickness
(d) At the 2/3rd outer radius

Radial and circumferential stress distribution within the cylinder wall when only internal pressure acts.
Distribution of radial and circumferential stresses within the cylinder wall when only external pressure acts.
In a thick cylinder pressurized from inside, the hoop stress is maximum at 
(a) The centre of the wall thickness  
(b) The outer radius  
(c) The inner radius  
(d) Both the inner and the outer radii  
IES-3. Ans. (c)
Chapter 11

Thick Cylinder

S K Mondal

\[ \varepsilon_r = \frac{\partial u_r}{\partial r} = \frac{1}{E} \left[ \sigma_r - v \sigma_\theta \right] \]

since \( \sigma_\theta = 0 \)

\[ \varepsilon_\theta = \frac{(r + u_\theta) \Delta \theta - r \Delta \theta}{r \Delta \theta} = \frac{u_\theta}{r} = \frac{1}{E} \left[ \sigma_\theta - v \sigma_r \right] \]

Lame's theory

IES-7. A thick cylinder is subjected to an internal pressure of 60 MPa. If the hoop stress on the outer surface is 150 MPa, then the hoop stress on the internal surface is: [GATE-1996; IES-2001]

(a) 105 MPa (b) 180 MPa (c) 210 MPa (d) 135 MPa

IES-7. Ans. (c)

If internal pressure = \( p_1 \); External pressure = zero

Circumferential or hoop stress \( (\sigma_c) = \frac{p r_i^2}{r_o^2 - r_i^2} \left[ \frac{r_o^2}{r_i^2} + 1 \right] \)

At \( p_1 = 60 \text{ MPa, } \sigma_c = 150 \text{ MPa and } r = r_b \)

\[ \Delta \sigma_c = 60 \frac{r_i^2}{r_o^2 - r_i^2} \left[ \frac{r_o^2}{r_i^2} + 1 \right] = 120 \frac{r_i^2}{r_o^2} = 150 \frac{5}{120} = \frac{9}{5} \]

\[ \Delta \sigma_c = 60 \frac{r_i^2}{r_o^2 - r_i^2} \left[ \frac{r_o^2}{r_i^2} + 1 \right] = 60 \frac{5}{4} \left( \frac{9}{5} + 1 \right) = 210 \text{ MPa} \]

IES-8. A hollow pressure vessel is subject to internal pressure. [IES-2005]

Consider the following statements:
1. Radial stress at inner radius is always zero.
2. Radial stress at outer radius is always zero.
3. The tangential stress is always higher than other stresses.
4. The tangential stress is always lower than other stresses.

Which of the statements given above are correct?

(a) 1 and 3 (b) 1 and 4 (c) 2 and 3 (d) 2 and 4

IES-8. Ans. (c)

IES-9. A thick open ended cylinder as shown in the figure is made of a material with permissible normal and shear stresses 200 MPa and 100 MPa respectively. The ratio of permissible pressure based on the normal and shear stress is:

\[ \left[ d_i = 10 \text{ cm; } d_o = 20 \text{ cm} \right] \]

(a) 9/5 (b) 8/5 (c) 7/5 (d) 4/5

IES-9. Ans. (b)

Longitudinal and shear stress

IES-10. A thick cylinder of internal radius and external radius \( a \) and \( b \) is subjected to internal pressure \( p \) as well as external pressure \( p \). Which one of the following statements is correct? [IES-2004]

The magnitude of circumferential stress developed is:

(a) Maximum at radius \( r = a \) (b) Maximum at radius \( r = b \)
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IES-10. Ans. (d)

\[ \sigma_c = A + B \frac{r^2}{r^2} \]
\[ A = \frac{P \rho^2 - P_o \rho^2}{\rho^2 - r^2} = \frac{Pa^2 - Pb^2}{b^2 - a^2} = -P \]
\[ B = \frac{(P - P_o) \rho^2}{r^2} = 0 \]
\[ \therefore \sigma_c = -P \]

IES-11. Consider the following statements:

In a thick walled cylindrical pressure vessel subjected to internal pressure, the Tangential and radial stresses are:

1. Minimum at outer side
2. Minimum at inner side
3. Maximum at inner side and both reduce to zero at outer wall
4. Maximum at inner wall but the radial stress reduces to zero at outer wall

Which of the statements given above is/are correct?

(a) 1 and 2 (b) 1 and 3 (c) 1 and 4 (d) 4 only

IES-11. Ans. (c)

IES-12. Consider the following statements at given point in the case of thick cylinder subjected to fluid pressure:

1. Radial stress is compressive
2. Hoop stress is tensile
3. Hoop stress is compressive
4. Longitudinal stress is tensile and it varies along the length
5. Longitudinal stress is tensile and remains constant along the length of the cylinder

Which of the statements given above are correct?

(a) Only 1, 2 and 4 (b) Only 3 and 4 (c) Only 1,2 and 5 (d) Only 1,3 and 5

IES-12. Ans. (c) 3. For internal fluid pressure Hoop or circumferential stress is tensile. 4. Longitudinal stress is tensile and remains constant along the length of the cylinder.

IES-13. A thick cylinder with internal diameter d and outside diameter 2d is subjected to internal pressure p. Then the maximum hoop stress developed in the cylinder is:

\[ \sigma_{\text{hoop}} = p \times \frac{r_2^2 + r_1^2}{r_2^2 - r_1^2} = p \times \frac{d^2 + \left( \frac{d}{2} \right)^2}{d^2 - \left( \frac{d}{2} \right)^2} = \frac{5}{3} p \]

IES-13. Ans. (c) In thick cylinder, maximum hoop stress

IES-14. Autofrettage is a method of:

(a) Joining thick cylinders  (b) Relieving stresses from thick cylinders  (c) Pre-stressing thick cylinders  (d) Increasing the life of thick cylinders

IES-14. Ans. (c)

IES-15. Match List-I with List-II and select the correct answer using the codes given below the Lists:

List-I
A. Wire winding
B. Lame’s theory
C. Solid sphere subjected to uniform pressure on the surface
D. Autofrettage

List-II
1. Hydrostatic stress
2. Strengthening of thin cylindrical shell
3. Strengthening of thick cylindrical shell
4. Thick cylinders

IES-15. Ans. (c)
IES-15. Ans. (d)

IES-16. If the total radial interference between two cylinders forming a compound cylinder is $\delta$ and Young's modulus of the materials of the cylinders is $E$, then the interface pressure developed at the interface between two cylinders of the same material and same length is:

(a) Directly proportional of $E \times \delta$
(b) Inversely proportional of $\frac{E}{\delta}$
(c) Directly proportional of $\frac{E}{\delta}$
(d) Inversely proportional of $\frac{E}{\delta}$

IES-16. Ans. (a)

\[ \delta = \frac{PD_2}{E} \left( \frac{2D_2^2(D_2^2 - D_1^2)}{(D_2^2 - D_3^2)(D_2^2 - D_1^2)} \right) \]

\[ \therefore P \sim \frac{E}{\delta} \]

Alternatively: if $E \uparrow$ then $P \uparrow$
and if $\delta \uparrow$ then $P \downarrow$ so $P \sim \frac{E}{\delta}$

IES-17. A compound cylinder with inner radius 5 cm and outer radius 7 cm is made by shrinking one cylinder on to the other cylinder. The junction radius is 6 cm and the junction pressure is 11 kgf/cm². The maximum hoop stress developed in the inner cylinder is:

(a) 36 kgf/cm² compression
(b) 36 kgf/cm² tension
(c) 72 kgf/cm² compression
(d) 72 kgf/cm² tension.

IES-17. Ans. (c)

**Thick Spherical Shell**

IES-18. The hemispherical end of a pressure vessel is fastened to the cylindrical portion of the pressure vessel with the help of gasket, bolts and lock nuts. The bolts are subjected to:

(a) Tensile stress
(b) Compressive stress
(c) Shear stress
(d) Bearing stress

IES-18. Ans. (a)

### Previous 20-Years IAS Questions

**Longitudinal and shear stress**

IAS-1. A solid thick cylinder is subjected to an external hydrostatic pressure $p$. The state of stress in the material of the cylinder is represented as:
Distribution of radial and circumferential stresses within the cylinder wall when only external pressure acts.
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Previous Conventional Questions with Answers

Conventional Question IES-1997

Question: The pressure within the cylinder of a hydraulic press is 9 MPa. The inside diameter of the cylinder is 25 mm. Determine the thickness of the cylinder wall, if the permissible tensile stress is 18 N/mm²

Answer: Given: \( P = 9 \text{ MPa} = 9 \text{ N/mm}^2 \), Inside radius, \( r_1 = 12.5 \text{ mm} \);

\( \sigma_1 = 18 \text{ N/mm}^2 \)

Thickness of the cylinder:
Using the equation: \( \sigma_i = P \left( \frac{r_1^2 + r_2^2}{r_2^2 - r_1^2} \right) \), we have

\[
18 = 9 \left( \frac{r_2^2 + 12.5^2}{r_2^2 - 12.5^2} \right)
\]
or

\[
r_2 = 21.65 \text{ mm}
\]

\[
\therefore \text{Thickness of the cylinder} = r_2 - r_1 = 21.65 - 12.5 = 9.15 \text{ mm}
\]

Conventional Question IES-2010

Q. A spherical shell of 150 mm internal diameter has to withstand an internal pressure of 30 MN/m². Calculate the thickness of the shell if the allowable stress is 80 MN/m².

Assume the stress distribution in the shell to follow the law

\[
\sigma_r = a - \frac{2b}{r^3} \quad \text{and} \quad \sigma_\theta = a + \frac{b}{r^3}.
\]

[10 Marks]

Ans. A spherical shell of 150 mm internal diameter internal pressure = 30 MPa.

Allowable stress = 80 MN/m²

Assume radial stress = \( \sigma_r = a - \frac{2b}{r^3} \)

Circumference stress = \( \sigma_\theta = a + \frac{b}{r^3} \)

At internal diameter (r)
\[ \sigma_r = -30 \text{N/mm}^2 \]
\[ \sigma_0 = 80 \text{N/mm}^2 \]
\[-30 = a - \frac{2b}{(75)^3} \] ............(i)
\[80 = a + \frac{b}{(75)^3} \] ............(ii)

Solving eq (i) & (ii)
\[ b = \frac{110 \times 75^3}{3} \quad a = \frac{130}{3} \]

At outer Radius (R) radial stress should be zero
\[ \sigma = a - \frac{2b}{R^3} \]
\[ R^3 = \frac{2b}{a} = \frac{2 \times 110 \times 75^3}{3 \times 130} = 713942.3077 \]

\[ R = 89.376 \text{mm} \]

Therefore thickness of cylinder = (R - r) = 89.376 - 75 = 14.376 mm

**Conventional Question IES-1993**

**Question:** A thick spherical vessel of inner radius 150 mm is subjected to an internal pressure of 80 MPa. Calculate its wall thickness based upon the

(i) Maximum principal stress theory, and

(ii) Total strain energy theory.

**Answer:** Given:

\[ r_1 = 150 \text{mm}; \quad p(\sigma_r) = 80 \text{MPa} = 80 \times 10^6 \text{N/m}^2; \quad \mu = \frac{1}{m} = 0.30; \]
\[ \sigma = 300 \text{MPa} = 300 \times 10^6 \text{N/m}^2 \]

Wall thickness t:

(i) Maximum principal stress theory:

We know that, \[ \sigma \leq \frac{K^2 + 1}{K^2 - 1} \]

\[ \left( \text{Where } K = \frac{r_2}{r_1} \right) \]

or \[ 80 \times 10^6 \left( \frac{K^2 + 1}{K^2 - 1} \right) \leq 300 \times 10^6 \]

or \[ K \geq 1.314 \]

or \[ K = 1.314 \]

i.e. \[ \frac{r_2}{r_1} = 1.314 \quad \text{or} \quad r_2 = r_1 \times 1.314 = 150 \times 1.314 = 197.1 \text{mm} \]

\[ \therefore \text{Metal thickness, } t = r_2 - r_1 = 197.1 - 150 = 47.1 \text{ mm} \]

(ii) Total strain energy theory:

**Use** \[ \sigma_1^2 + \sigma_2^2 - \mu \sigma_1 \sigma_2 \leq \sigma_y^2 \]
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\[ \sigma^2 \geq \frac{2\sigma^2 [K^4 (1+\mu) + (1-\mu)]}{(K^2 - 1)^2} \]
\[ \therefore \left(300 \times 10^6\right)^2 \geq \frac{2 \times \left(80 \times 10^6\right)^2 [K^4 (1+0.3) + (1-0.3)]}{(K^2 - 1)^2} \]

or \[ 300^2 (K^2 - 1)^2 = 2 \times 80^2 \left(1.3K^4 + 0.7\right) \]
gives \( K = 1.86 \) or 0.59
It is clear that \( K > 1 \)
\[ \therefore K = 1.364 \]
or \( \frac{r_2}{r_1} = 1.364 \) or \( r_2 = 150 \times 1.364 = 204.6 \text{ mm} \)
\[ \therefore t = r_2 - r_1 = 204.6 - 150 = 54.6 \text{ mm} \]

Conventional Question ESE-2002

Question: What is the difference in the analysis of think tubes compared to that for thin tubes? State the basic equations describing stress distribution in a thick tube.

Answer: The difference in the analysis of stresses in thin and thick cylinder:
(i) In thin cylinder, it is assumed that the tangential stress is uniformly distributed over the cylinder wall thickness. In thick cylinder, the tangential stress has highest magnitude at the inner surface of the cylinder and gradually decreases towards the outer surface.
(ii) The radial stress is neglected in thin cylinders, while it is of significant magnitude in case of thick cylinders.
Basic equation for describing stress distribution in thick tube is Lame's equation.
\[ \sigma_r = \frac{B}{r^2} - A \text{ and } \sigma_t = \frac{B}{r^2} + A \]

Conventional Question ESE-2006

Question: What is auto frettage?

How does it help in increasing the pressure carrying capacity of a thick cylinder?

Answer: Autofrettage is a process of pre-stressing the cylinder before using it in operation.

We know that when the cylinder is subjected to internal pressure, the circumferential stress at the inner surface limits the pressure carrying capacity of the cylinder.

In autofrettage pre-stressing develops a residual compressive stresses at the inner surface. When the cylinder is actually loaded in operation, the residual compressive stresses at the inner surface begin to decrease, become zero and finally become tensile as the pressure is gradually increased. Thus autofrettage increases the pressure carrying capacity of the cylinder.

Conventional Question ESE-2001

Question: When two cylindrical parts are assembled by shrinking or press-fitting, a contact pressure is created between the two parts. If the radii of the inner cylinder are \( a \) and \( c \) and that of the outer cylinder are \((c-\delta)\) and \( b \), \( \delta \) being the radial interference the contact pressure is given by:

\[ P = \frac{E\delta}{c} \left[ \frac{\left(b^2-c^2\right)(c^2-a^2)}{2c^2\left(b^2-a^2\right)} \right] \]

Where \( E \) is the Young's modulus of the material, Can you outline the steps involved in developing this important design equation?
Answer:

Due to interference let us assume \( \delta_i = \) increase in inner diameter of jacket and \( \delta_c = \) decrease in outer diameter of cylinder.

so \( \delta = |\delta_i| + |\delta_c| \) i.e. without sign.

Now \( \delta_i = \varepsilon_j c \)

\[ \varepsilon_j = \text{tangential strain} \]

\[ \delta_i = \frac{1}{E} \left[ \sigma_r - \mu \sigma_t \right] c \]

\[ \sigma_t = \text{circumferential stress} \]

\[ \sigma_t = \frac{cp}{E} \left[ \frac{b^2 + c^2}{b^2 - c^2 + \mu} \right] \]

\[ \sigma_r = -p \text{ (radial stress)} \]

And in similar way \( \delta_c = \varepsilon_c c \)

\[ \varepsilon_c = \frac{1}{E} \left[ \sigma_r - \mu \sigma_t \right] c \]

\[ \sigma_t = -p \left( \frac{c^2 + a^2}{c^2 - a^2} \right) \]

\[ \sigma_r = -p \]

Adding \((i)\) & \((ii)\)

\[ \delta = |\delta_i| + |\delta_c| = \frac{Pc}{E} \left[ \frac{2c^2(b^2 - a^2)}{(b^2 - c^2)(c^2 - a^2)} \right] \]

or \[ P = \frac{E \delta}{c} \left[ \frac{(b^2 - c^2)(c^2 - a^2)}{2c^2(b^2 - a^2)} \right] \]

Proved
**Chapter-11 Thick Cylinder**

**Conventional Question ESE-2003**

**Question:** A steel rod of diameter 50 mm is forced into a bronze casing of outside diameter 90 mm, producing a tensile hoop stress of 30 MPa at the outside diameter of the casing.

Find (i) The radial pressure between the rod and the casing
(ii) The shrinkage allowance and
(iii) The rise in temperature which would just eliminate the force fit.

Assume the following material properties:

\[
E_s = 2 \times 10^5 \text{ MPa}, \quad \mu_s = 0.25, \quad \alpha_s = 1.2 \times 10^{-5} / ^\circ C
\]

\[
E_b = 1 \times 10^5 \text{ MPa} , \quad \mu_b = 0.3, \quad \mu_b = 1.9 \times 10^{-5} / ^\circ C
\]

**Answer:**

There is a shrinkage pressure \( P \) between the steel rod and the bronze casing. The pressure \( P \) tends to contract the steel rod and expand the bronze casing.

(i) **Consider Bronze casing, According to Lames theory**

\[
\sigma_t = \frac{B}{r_i^2} + A \quad \text{where} \quad A = \frac{Pr_i^2 - P_0r_i^2}{r_0^2 - r_i^2}
\]

and \( B = \frac{(P - P_0)r_0^2r_i^2}{r_0^2 - r_i^2} \)

\( P_0 = P, \quad P_0 = 0 \) and

\[
A = \frac{Pr_i^2}{r_0^2 - r_i^2}, \quad B = \frac{Pr_0^2r_i^2}{r_0^2 - r_i^2} = \frac{2Pr_i^2}{r_0^2 - r_i^2}
\]

\[
\therefore 30 = \frac{B}{r_0^2} + A = \frac{Pr_0^2r_i^2}{r_0^2 - r_i^2} + \frac{Pr_i^2}{r_0^2 - r_i^2} = \frac{2Pr_i^2}{r_0^2 - r_i^2}
\]

\[
or, P = \frac{30(r_0^2 - r_i^2)}{2r_i^2} = 15 \left( \frac{r_0^2}{r_i^2} - 1 \right) = 15 \left( \frac{90}{50} \right)^2 - 1 \text{ MPa} = 33.6 \text{ MPa}
\]

Therefore the radial pressure between the rod and the casing is \( P = 33.6 \text{ MPa} \).

(ii) **The shrinkage allowance:**

Let \( \delta_j = \text{ increase in inert diameter of bronze casing} \)

\( \delta_c = \text{ decrease in outer diameter of steel rod} \)

1st consider bronze casing:

Tangential stress at the inner surface \( (\sigma_t)_j = \frac{B}{r_i^2} + A \)

\[
= \frac{Pr_0^2}{r_0^2 - r_i^2} + \frac{Pr_i^2}{r_0^2 - r_i^2} = \frac{P(r_0^2 + r_i^2)}{(r_0^2 - r_i^2)} = 33.6 \times \left[ \frac{\left( \frac{90}{50} \right)^2 + 1}{\left( \frac{90}{50} \right)^2 - 1} \right] = 63.6 \text{ MPa}
\]
and radial stress \( \sigma_r = -P = -33.6 \text{MPa} \)

longitudinal stress \( \sigma_z = 0 \)

Therefore tangential strain \( (\varepsilon_t)_j = \frac{1}{E} \left[ (\sigma_r)_j - \mu (\sigma_z)_j \right] \)

\[ = \frac{1}{1 \times 10^5} [63.6 + 0.3 \times 33.6] = 7.368 \times 10^{-4} \]

\[ \therefore \delta_j = (\varepsilon_t)_j \times d_j = 7.368 \times 10^{-4} \times 0.050 = 0.03684 \text{mm} \]

2nd Consider steel rod:
Circumferential stress \( (\sigma_t)_s = -P \)
and radial stress \( (\sigma_r)_s = -P \)

\[ \therefore \delta_c = (\varepsilon_t)_s \times d_j = \frac{1}{E_s} \left[ (\sigma_t)_s - \mu (\sigma_r)_s \right] \times d_j \]

\[ = -\frac{P d_j}{E_s} (1 - \mu) = -\frac{33.6 \times 0.050}{2 \times 10^5} [1 - 0.3] = -0.00588 \text{mm} \text{ [reduction]} \]

Total shrinkage = \(|\delta_j| + |\delta_c| = 0.04272 \text{mm} \text{ [it is diametral]} = 0.02136 \text{mm} \text{ [radial]} \]

(iii) Let us temperature rise is \( (\Delta t) \)

As \( \alpha_b > \alpha_s \) due to same temperature rise steel not will expand less than bronze casing. When their difference of expansion will be equal to the shrinkage then force fit will eliminate.

\[ d_i \times \alpha_b \times \Delta t - d_i \times \alpha_s \times \Delta t = 0.04272 \]

\[ or \Delta t = \frac{0.04272}{d_i \left| \alpha_b - \alpha_s \right|} = \frac{0.04272}{50 \times [1.9 \times 10^{-5} - 1.2 \times 10^{-5}]} = 122^\circ \text{C} \]

**Conventional Question AMIE-1998**

**Question:** A thick walled closed-end cylinder is made of an Al-alloy \( (E = 72 \text{ GPa}, \frac{1}{m} = 0.33) \), has inside diameter of 200 mm and outside diameter of 800 mm. \( m \)
The cylinder is subjected to internal fluid pressure of 150 MPa. Determine the principal stresses and maximum shear stress at a point on the inside surface of the cylinder. Also determine the increase in inside diameter due to fluid pressure.

**Answer:**

Given: \( r_1 = \frac{200}{2} = 100 \text{mm} = 0.1 \text{m} ; r_2 = \frac{800}{2} = 400 \text{mm} = 0.4 \text{m} ; p = 150 \text{MPa} = 150 \text{MN/m}^2 \);

\[ E = 72 \text{GPa} = 72 \times 10^9 \text{N/m}^2 ; \frac{1}{m} = 0.33 = \mu \]

**Principal stress and maximum shear stress:**
Using the condition in Lame's equation:

\[ \sigma_r = \frac{b}{r^2} - a \]

At \( r = 0.1 \text{m} \), \( \sigma_2 = +p = 150 \text{MN/m}^2 \)

\[ r = 0.4 \text{m} , \sigma_2 = 0 \]

Substituting the values in the above equation we have
150 = \frac{b}{(0.1)^2} - a \quad (i)

0 = \frac{b}{(0.4)^2} - a \quad (ii)

From (i) and (ii), we get 

a = 10 \quad \text{and} \quad b = 1.6

The circumferential (or hoop) stress by Lame’s equation, is given by

\sigma_c = \frac{b}{r^2} + a

\therefore (\sigma_c)_{max}, \text{at } r = r_1 = 0.1 \text{m} = \frac{1.6}{0.1^2} + 10 = 170 \text{ MN/m}^2 \text{ (tensile), and}

(\sigma_c)_{min}, \text{at } r = r_2 = 0.4 \text{m} = \frac{1.6}{0.4^2} + 10 = 20 \text{ MN/m}^2 \text{ (tensile)}.

\therefore \text{Principal stresses are } 170 \text{ MN/m}^2 \text{ and } 20 \text{ MN/m}^2

Maximum shear stress, \(\tau_{max} = \frac{(\sigma_c)_{max} - (\sigma_c)_{min}}{2}\)

\[\tau_{max} = \frac{170 - 20}{2} = 75 \text{ MN/m}^2\]

Increase in inside diameter, \(\delta d_i\):

We know, longitudinal (or axial) stress, \(\sigma_i = \frac{pr_i^2}{r_i^2 - r_1^2} = \frac{150 \times (0.1)^2}{(0.4)^2 - (0.1)^2} = 10 \text{ MN/m}^2\)

Circumferential (or hoop) strain at the inner radius, is given by:

\[\epsilon_i = \frac{1}{E} \left[ \sigma_i + \mu (\sigma_i - \sigma_1) \right] = \frac{1}{72 \times 10^9} \left[ 170 \times 10^6 + 0.33 (150 - 10) \times 10^6 \right] = 0.003\]

Also, \(\epsilon_i = \frac{\delta d_i}{d_i}\)

or \(0.003 = \frac{\delta d_i}{0.1}\)

\[\delta d_i = 0.003 \times 0.1 = 0.003 \text{m or } 0.3 \text{mm}\]
12. Spring

Theory at a Glance (for IES, GATE, PSU)

1. A spring is a mechanical device which is used for the efficient storage and release of energy.

2. Helical spring – stress equation

Let us a close-coiled helical spring has coil diameter $D$, wire diameter $d$ and number of turn $n$. The spring material has a shearing modulus $G$. The spring index, $C = \frac{D}{d}$. If a force ‘$P$’ is exerted in both ends as shown.

The work done by the axial force ‘$P$’ is converted into strain energy and stored in the spring.

$$U = \text{(average torque)} \times \text{(angular displacement)}$$
$$= \frac{T}{2} \times \theta$$

From the figure we get, $\theta = \frac{TL}{GJ}$

Torque $(T) = \frac{PD}{2}$

Length of wire $(L) = \pi DN$

Polar moment of Inertia $(J) = \frac{\pi d^4}{32}$

Therefore $U = \frac{4P^2D^3n}{32Gd}$

According to Castigliano’s theorem, the displacement corresponding to force $P$ is obtained by partially differentiating strain energy with respect to that force.

Therefore $\delta = \frac{\partial U}{\partial P} = \frac{\partial}{\partial P} \left[ \frac{4P^2D^3n}{32Gd^4} \right] = \frac{8PD^3n}{Gd^4}$

Axial deflection $\delta = \frac{8PD^3n}{Gd^4}$

Spring stiffness or spring constant $(k) = \frac{P}{\delta} = \frac{Gd^4}{8PD^3n}$
Chapter-12

The torsional shear stress in the bar, \( \tau_1 = \frac{16T}{\pi d^3} = \frac{16(PD \pi/2)}{\pi d^3} = \frac{8PD}{\pi d^3} \)

The direct shear stress in the bar, \( \tau_2 = \frac{P}{\pi d^2} = \frac{4P}{\pi d^2} = \frac{8PD}{\pi d^3} \left(\frac{0.5d}{D}\right) \)

Therefore the total shear stress, \( \tau = \tau_1 + \tau_2 = \frac{8PD}{\pi d^3} \left(1 + \frac{0.5d}{D}\right) = K_s \frac{8PD}{\pi d^3} \)

Where \( K_s = 1 + \frac{0.5d}{D} \) is correction factor for direct shear stress.

3. Wahl’s stress correction factor

\[ \tau = K \frac{8PD}{\pi d^3} \]

Where \( K = \left(\frac{4C - 1}{4C - 4}\right) + 0.615 \) is known as Wahl’s stress correction factor.

Here \( K = K_s K_c \); Where \( K_s \) is correction factor for direct shear stress and \( K_c \) is correction factor for stress concentration due to curvature.

Note: When the spring is subjected to a static force, the effect of stress concentration is neglected due to localized yielding. So we will use, \( \tau = K_s \frac{8PD}{\pi d^3} \)

4. Equivalent stiffness \((k_{eq})\)

<table>
<thead>
<tr>
<th>Spring in series ((\delta_e = \delta_1 + \delta_2))</th>
<th>Spring in Parallel ((\delta_e = \delta_1 = \delta_2))</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \frac{1}{K_{eq}} = \frac{1}{K_1} + \frac{1}{K_2} ) or ( K_{eq} = \frac{K_1 K_2}{K_1 + K_2} )</td>
<td>( K_{eq} = K_1 + K_2 )</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Shaft in series ((\theta = \theta_1 + \theta_2))</th>
<th>Shaft in Parallel ((\theta_{eq} = \theta_1 = \theta_2))</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
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</tbody>
</table>
5. Important note

- If a spring is cut into ‘n’ equal lengths then spring constant of each new spring = nk
- When a closed coiled spring is subjected to an axial couple M then the rotation, 
  \[ \phi = \frac{64MDn}{Ed^4} \]

6. Laminated Leaf or Carriage Springs

- Central deflection, \( \delta = \frac{3PL^2}{8Enbt^3} \)
- Maximum bending stress, \( \sigma_{\text{max}} = \frac{3PL}{2nb^2t} \)

Where
- \( P \) = load on spring
- \( b \) = width of each plate
- \( n \) = no of plates
- \( L \) = total length between 2 points
- \( t \) = thickness of one plate.

7. Belleville Springs

Load, \( P = \frac{4E\delta}{(1-\mu^2)k_fD_0^2} \left[ (h-\delta) \left( h - \frac{\delta}{2} \right) t^3 \right] \)

Where
- \( E \) = Modulus of elasticity
- \( \delta \) = Linear deflection
- \( \mu \) = Poisson’s Ratio
- \( k_f \) = factor for Belleville spring
- \( D_0 \) = outside diameter
- \( h \) = Deflection required to flatten Belleville spring
- \( t \) = thickness

Note:
- **Total stiffness** of the springs \( k_{\text{tot}} = \text{stiffness per spring} \times \text{No of springs} \)
- **In a leaf spring** ratio of stress between full length and graduated leaves = 1.5
- **Conical spring** - For application requiring variable stiffness
- **Belleville Springs** - For application requiring high capacity springs into small space
Helical spring

GATE-1. If the wire diameter of a closed coil helical spring subjected to compressive load is increased from 1 cm to 2 cm, other parameters remaining same, then deflection will decrease by a factor of: [GATE-2002]
(a) 16 (b) 8 (c) 4 (d) 2
GATE-1. Ans. (a) \[ \delta = \frac{8PD^3N}{G.d^4} \]

GATE-2. A compression spring is made of music wire of 2 mm diameter having a shear strength and shear modulus of 800 MPa and 80 GPa respectively. The mean coil diameter is 20 mm, free length is 40 mm and the number of active coils is 10. If the mean coil diameter is reduced to 10 mm, the stiffness of the spring is approximately [GATE-2008]
(a) Decreased by 8 times (b) Decreased by 2 times (c) Increased by 2 times (d) Increased by 8 times
GATE-2. Ans. (d) 

\[ K_2 = \left( \frac{D_1}{D_2} \right)^3 = \left( \frac{20}{10} \right)^3 = 8 \]

GATE-3. Two helical tensile springs of the same material and also having identical mean coil diameter and weight, have wire diameters d and d/2. The ratio of their stiffness is: [GATE-2001]
(a) 1 (b) 4 (c) 64 (d) 128
GATE-3. Ans. (c) 

\[ K \propto \frac{d^4}{n} \]

GATE-4. A uniform stiff rod of length 300 mm and having a weight of 300 N is pivoted at one end and connected to a spring at the other end. For keeping the rod vertical in a stable position the minimum value of spring constant K needed is: [GATE-2004]
(a) 300 N/m (b) 400 N/m (c) 500 N/m (d) 1000 N/m
GATE-4. Ans. (c) Inclined it to a very low angle, d\theta

For equilibrium taking moment about ‘hinge’
\[ W \times \left( \frac{1}{2} d\theta \right) - k(d\theta) \times l = 0 \]
\[ k = \frac{W}{2l} = \frac{300}{2 \times 0.3} = 500 \text{ N/m} \]

GATE-5. A weighing machine consists of a 2 kg pan resting on spring. In this condition, with the pan resting on the spring, the length of the spring is 200 mm. When a mass of 20 kg is placed on the pan, the length of the spring becomes 100 mm. For the spring, the un-deformed length L and the spring constant k (stiffness) are: [GATE-2005]
Chapter-12

(a) \( l_0 = 220 \text{ mm}, k = 1862 \text{ N/m} \)
(b) \( l_0 = 210 \text{ mm}, k = 1960 \text{ N/m} \)
(c) \( l_0 = 200 \text{ mm}, k = 1960 \text{ N/m} \)
(d) \( l_0 = 200 \text{ mm}, k = 2156 \text{ N/m} \)

GATE-5. Ans. (b) Initial length = \( l_0 \) m and stiffness = \( k \) N/m

\[
2 \times g = k (l_0 - 0.2)
\]

\[
2 \times g + 20 \times g = k (l_0 - 0.1)
\]

Just solve the above equations.

Springs in Series

GATE-6. The deflection of a spring with 20 active turns under a load of 1000 N is 10 mm. The spring is made into two pieces each of 10 active coils and placed in parallel under the same load. The deflection of this system is: [GATE-1995]

(a) 20 mm  (b) 10 mm  (c) 5 mm  (d) 2.5 mm

GATE-6. Ans. (d) When a spring is cut into two, no. of coils gets halved.

\[ \therefore \] Stiffness of each half gets doubled.

When these are connected in parallel, stiffness = \( 2k + 2k = 4k \)

Therefore deflection will be \( \frac{1}{4} \) times. = 2.5 mm

Previous 20-Years IES Questions

Helical spring

IES-1. A helical coil spring with wire diameter 'd' and coil diameter 'D' is subjected to external load. A constant ratio of d and D has to be maintained, such that the extension of spring is independent of d and D. What is this ratio? [IES-2008]

(a) \( \frac{D^2}{d^4} \)  (b) \( \frac{d^3}{D^4} \)  (c) \( \frac{D^{4/3}}{d} \)  (d) \( \frac{d^{4/3}}{D} \)

IES-1. Ans. (a) \( \delta = \frac{8PD^3N}{Gd^4} \)

\[
T = F \times \frac{D}{2} ; \quad U = \frac{1}{2} T\theta
\]

\[
T = \frac{FD}{2} ; \quad \theta = \frac{TL}{GJ}
\]

\[
L = \pi DN
\]

\[
U = \frac{1}{2} \left( \frac{FD}{2} \right)^2 \left( \frac{L}{GJ} \right) = \frac{4F^2D^3N}{Gd^4}
\]

\[
\delta = \frac{\partial U}{\partial F} = \frac{8F^3D^3N}{Gd^4}
\]

IES-2. Assertion (A): Concentric cylindrical helical springs are used to have greater spring force in a limited space. [IES-2006]

Reason (R): Concentric helical springs are wound in opposite directions to prevent locking of coils under heavy dynamic loading.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IES-2. Ans. (b)

IES-3. Assertion (A): Two concentric helical springs used to provide greater spring force are wound in opposite directions. [IES-1995; IAS-2004]

Reason (R): The winding in opposite directions in the case of helical springs prevents buckling.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
IES-3. Ans. (c) It is for preventing locking not for buckling.

IES-4. Ans. (c) Stiffness of spring \( k = \frac{Gd^4}{8D^2n} \). So \( k \propto \frac{1}{n} \) and will behalf

IES-5. Ans. (b) \( mg(h+x) = \frac{1}{2} kx^2 \)

IES-6. Ans. (c) \( \tau = \frac{8PD}{\pi d^2} \) it is independent of number of turn

IES-7. Ans. (b) Fibres at mean diameter

IES-8. Ans. (c)

IES-9. Ans. (a) Stiffness \( k = \frac{Gd^4}{64R^3N} \). Second spring, stiffness \( k_2 = \frac{Gd^4}{64(2R)^3 \times \frac{N}{2}} = \frac{k}{4} \)

IES-10. Ans. (a) Bending stress
IES-11. Ans. (a)

IES-12. A closely coiled helical spring of 20 cm mean diameter is having 25 coils of 2 cm diameter rod. The modulus of rigidity of the material if $10^7$ N/cm². What is the stiffness for the spring in N/cm? 

(a) 50    (b) 100    (c) 250    (d) 500

IES-12. Ans. (b)

IES-13. Which one of the following expresses the stress factor $K$ used for design of closed coiled helical spring? 

(a) $4C - 4$  
(b) $4C - 1$ , $0.615$  
(c) $4C - 4$ , $C$  
(d) $4C - 1$ , $C$  

Where $C$ = spring index

IES-13. Ans. (b)

IES-14. In the calculation of induced shear stress in helical springs, the Wahl's correction factor is used to take care of: 

(a) Combined effect of transverse shear stress and bending stresses in the wire.  
(b) Combined effect of bending stress and curvature of the wire.  
(c) Combined effect of transverse shear stress and curvature of the wire.  
(d) Combined effect of torsional shear stress and transverse shear stress in the wire.

IES-14. Ans. (c)

IES-15. While calculating the stress induced in a closed coil helical spring, Wahl's factor must be considered to account for: 

(a) The curvature and stress concentration effect  
(b) Shock loading  
(c) Poor service conditions  
(d) Fatigue loading

IES-15. Ans. (a)

IES-16. Cracks in helical springs used in Railway carriages usually start on the inner side of the coil because of the fact that: 

(a) It is subjected to the higher stress than the outer side.  
(b) It is subjected to a higher cyclic loading than the outer side.  
(c) It is more stretched than the outer side during the manufacturing process.  
(d) It has a lower curvature than the outer side.

IES-16. Ans. (a)

IES-17. Two helical springs of the same material and of equal circular cross-section and length and number of turns, but having radii 20 mm and 40 mm, kept concentrically (smaller radius spring within the larger radius spring), are compressed between two parallel planes with a load $P$. The inner spring will carry a load equal to: 

(a) $P/2$  
(b) $2P/3$  
(c) $P/9$  
(d) $8P/9$

IES-17. Ans. (d)

IES-18. A length of 10 mm diameter steel wire is coiled to a close coiled helical spring having 8 coils of 75 mm mean diameter, and the spring has a stiffness $K$. If the same length of wire is coiled to 10 coils of 60 mm mean diameter, then the spring stiffness will be: 

(a) $K$  
(b) $1.25K$  
(c) $1.56K$  
(d) $1.95K$

IES-18. Ans. (c) Stiffness of spring ($k$) = $\frac{Gd^4}{64R^2n}$ Where $G$ and $d$ is same
Therefore \[ \frac{k}{k_2} = \left( \frac{R}{R_2} \right)^3 \left( \frac{n}{n_2} \right) = \frac{1}{1.56} \]

IES-19. A spring with 25 active coils cannot be accommodated within a given space. Hence 5 coils of the spring are cut. What is the stiffness of the new spring?
(a) Same as the original spring  
(b) 1.25 times the original spring  
(c) 0.8 times the original spring  
(d) 0.5 times the original spring

IES-19. Ans. (b) Stiffness of spring \( k \) = \( \frac{Gd^4}{8D^2n} \). ∴ \( k_2 = \frac{1}{n} \), or \( \frac{k_2}{k_1} = \frac{n_1}{n_2} = \frac{25}{20} = 1.25 \)

IES-20. Wire diameter, mean coil diameter and number of turns of a closely-coiled steel spring are \( d \), \( D \) and \( N \) respectively and stiffness of the spring is \( K \). A second spring is made of same steel but with wire diameter, mean coil diameter and number of turns 2\( d \), 2\( D \) and 2\( N \) respectively. The stiffness of the new spring is:
(a) \( K \)  
(b) 2\( K \)  
(c) 4\( K \)  
(d) 8\( K \)

IES-20. Ans. (a) Stiffness of spring \( k \) = \( \frac{Gd^4}{8D^2n} \)

IES-21. When two springs of equal lengths are arranged to form cluster springs which of the following statements are the:
1. Angle of twist in both the springs will be equal
2. Deflection of both the springs will be equal
3. Load taken by each spring will be half the total load
4. Shear stress in each spring will be equal
(a) 1 and 2 only  
(b) 2 and 3 only  
(c) 3 and 4 only  
(d) 1, 2 and 4 only

IES-21. Ans. (a)

IES-22. Consider the following statements:
1. Angle of twist in both the springs will be equal
2. Deflection of both the springs will be equal
3. Load taken by each spring will be half the total load
4. Shear stress in each spring will be equal
Which of the above statements is/are correct?
(a) 1 and 2  
(b) 3 and 4  
(c) 2 only  
(d) 4 only

IES-22. Ans. (a) Same as [IES-1992]
Close-coiled helical spring with axial load

IES-23. Under axial load, each section of a close-coiled helical spring is subjected to
   (a) Tensile stress and shear stress due to load [IES-2003]
   (b) Compressive stress and shear stress due to torque
   (c) Tensile stress and shear stress due to torque
   (d) Torsional and direct shear stresses

IES-23. Ans. (d)

IES-24. When a weight of 100 N falls on a spring of stiffness 1 kN/m from a height of 2 m, the deflection caused in the first fall is: [IES-2000]
   (a) Equal to 0.1 m    (b) Between 0.1 and 0.2 m
   (c) Equal to 0.2 m    (d) More than 0.2 m

IES-24. Ans. (d) use \( mg(h + x) = \frac{1}{2}kx^2 \)

Subjected to 'Axial twist'

IES-25. A closed coil helical spring of mean coil diameter 'D' and made from a wire of diameter 'd' is subjected to a torque 'T' about the axis of the spring. What is the maximum stress developed in the spring wire? [IES-2008]
   (a) \( \frac{8T}{\pi d^3} \)  (b) \( \frac{16T}{\pi d^3} \)  (c) \( \frac{32T}{\pi d^3} \)  (d) \( \frac{64T}{\pi d^3} \)

IES-25. Ans. (b)

Springs in Series

IES-26. When a helical compression spring is cut into two equal halves, the stiffness of each of the result in springs will be: [IES-2002; IAS-2002]
   (a) Unaltered  (b) Double  (c) One-half  (d) One-fourth

IES-26. Ans. (b)

IES-27. If a compression coil spring is cut into two equal parts and the parts are then used in parallel, the ratio of the spring rate to its initial value will be:[IES-1999]
(a) 1    (b) 2    (c) 4    (d) Indeterminable for want of sufficient data

IES-27. Ans. (c) When a spring is cut into two, no. of coils gets halved.
∴ Stiffness of each half gets doubled.
When these are connected in parallel, stiffness = 2k + 2k = 4k

Springs in Parallel

IES-28. The equivalent spring stiffness for the system shown in the given figure (S is the spring stiffness of each of the three springs) is:
(a) S/2    (b) S/3    (c) 2S/3    (d) S

IES-28. Ans. (c) \[
\frac{1}{S_e} = \frac{1}{2S} + \frac{1}{S} \quad \text{or} \quad S_e = \frac{2}{3}S
\]

IES-29. Two coiled springs, each having stiffness K, are placed in parallel. The stiffness of the combination will be:
(a) 4K    (b) 2K    (c) \(\frac{K}{2}\)    (d) \(\frac{K}{4}\)

IES-29. Ans. (b) \[W = k\delta = k_1\delta + k_2\delta\]

IES-30. A mass is suspended at the bottom of two springs in series having stiffness 10 N/mm and 5 N/mm. The equivalent spring stiffness of the two springs is nearly
(a) 0.3 N/mm    (b) 3.3 N/mm    (c) 5 N/mm    (d) 15 N/mm

IES-30. Ans. (b) \[\frac{1}{S_e} = \frac{1}{10} + \frac{1}{5} \quad \text{or} \quad S_e = \frac{10}{3}\]
Chapter-12

IES-31. Figure given above shows a spring-mass system where the mass $m$ is fixed in between two springs of stiffness $S_1$ and $S_2$. What is the equivalent spring stiffness?

(a) $S_1 - S_2$  
(b) $S_1 + S_2$  
(c) $(S_1 + S_2)/S_1 S_2$  
(d) $(S_1 - S_2)/S_1 S_2$

IES-31. Ans. (b)

IES-32. Two identical springs labelled as 1 and 2 are arranged in series and subjected to force $F$ as shown in the given figure. Assume that each spring constant is $K$. The strain energy stored in spring 1 is:

\[
\frac{F^2}{2K}  \quad (a) \quad \frac{F^2}{4K}  \quad (b) \quad \frac{F^2}{8K}  \quad (c) \quad \frac{F^2}{16K}  \quad (d)
\]

IES-32. Ans. (c) The strain energy stored per spring $= \frac{1}{2} k x^2 / 2 = \frac{1}{2} \times k_{eq} \times \left( \frac{F}{k_{eq}} \right)^2 / 2$ and here total force $'F'$ is supported by both the spring 1 and 2 therefore $k_{eq} = k + k = 2k$

IES-33. What is the equivalent stiffness (i.e. spring constant) of the system shown in the given figure?

(a) 24 N/mm  
(b) 16 N/mm  
(c) 4 N/mm  
(d) 5.3 N/mm

IES-33. Ans. (a) Stiffness $K_1$ of 10 coils spring = 8 N/mm  
\[ \therefore \text{Stiffness } K_2 \text{ of 5 coils spring } = 16 \text{ N/mm} \]

Though it looks like in series but they are in parallel combination. They are not subjected to same force. Equivalent stiffness $(k) = k_1 + k_2 = 24 \text{ N/mm}$

Previous 20-Years IAS Questions

Helical spring

IAS-1. Assertion (A): Concentric cylindrical helical springs which are used to have greater spring force in a limited space are wound in opposite directions.
Chapter-12 Spring S K Mondal's

Reason (R): Winding in opposite directions prevents locking of the two coils in case of misalignment or buckling. [IAS-1996]

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-1. Ans. (a)

IAS-2. An open-coiled helical spring of mean diameter D, number of coils N and wire diameter d is subjected to an axial force P. The wire of the spring is subject to: [IAS-1995]

(a) direct shear only
(b) combined shear and bending only
(c) combined shear, bending and twisting
(d) combined shear and twisting only

IAS-2. Ans. (d)

IAS-3. Assertion (A): Two concentric helical springs used to provide greater spring force are wound in opposite directions. [IES-1995; IAS-2004]

Reason (R): The winding in opposite directions in the case of helical springs prevents buckling.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-3. Ans. (c)

It is for preventing locking not for buckling.

IAS-4. Which one of the following statements is correct? [IES-1996; 2007; IAS-1997]

If a helical spring is halved in length, its spring stiffness would be
(a) Remains same
(b) Halves
(c) Doubles
(d) Triples

IAS-4. Ans. (c)

Stiffness of spring $k = \frac{Gd^4}{8D^3n} \Rightarrow k \propto \frac{1}{n}$ and will behave

IAS-5. A closed coil helical spring has 15 coils. If five coils of this spring are removed by cutting, the stiffness of the modified spring will: [IAS-2004]

(a) Increase to 2.5 times
(b) Increase to 1.5 times
(c) Reduce to 0.66 times
(d) Remain unaffected

IAS-5. Ans. (b)

K = \frac{Gd^4}{8D^3 \pi} \quad or \quad K = \frac{1}{N} \quad or \quad K_2 = \frac{N_1}{N_2} = \frac{15}{10} = 1.5

IAS-6. A close-coiled helical spring has wire diameter 10 mm and spring index 5. If the spring contains 10 turns, then the length of the spring wire would be: [IAS-2000]

(a) 100 mm
(b) 157 mm
(c) 500 mm
(d) 1570 mm

IAS-6. Ans. (d)

$l = \pi Dn = \pi (cd)n = \pi \times (5 \times 10) \times 10 = 1570 mm$

IAS-7. Consider the following types of stresses: [IAS-1996]

1. torsional shear
2. Transverse direct shear
3. Bending stress

The stresses, that are produced in the wire of a close-coiled helical spring subjected to an axial load, would include

(a) 1 and 3
(b) 1 and 2
(c) 2 and 3
(d) 1, 2 and 3

IAS-7. Ans. (b)

IAS-8. Two close-coiled springs are subjected to the same axial force. If the second spring has four times the coil diameter, double the wire diameter and double the number of coils of the first spring, then the ratio of deflection of the second spring to that of the first will be: [IAS-1998]

(a) 8
(b) 2
(c) \frac{1}{2}
(d) 1/16

IAS-8. Ans. (d)
Chapter-12  

IAS-8. Ans. (a) \( \delta = \frac{8PD^2N}{Gd^2} \) or \( \delta_2 = \left( \frac{D_2}{D_1} \right) \left( \frac{N_2}{N_1} \right) = \frac{4^2 \times 2}{2^2} = 8 \)

IAS-9. A block of weight 2 N falls from a height of 1m on the top of a spring. If the spring gets compressed by 0.1 m to bring the weight momentarily to rest, then the spring constant would be: \[ \text{[IAS-2000]} \]
(a) 50 N/m  (b) 100 N/m  (c) 200N/m  (d) 400N/m

IAS-9. Ans. (d) Kinetic energy of block = potential energy of spring
or \( W \times h = \frac{1}{2} k \cdot x^2 \) or \( k = \frac{2Wh}{x^2} = \frac{2 \times 2 \times 1}{0.1^2} \frac{N}{m} = 400 \frac{N}{m} \)

IAS-10. The springs of a chest expander are 60 cm long when unstretched. Their stiffness is 10 N/mm. The work done in stretching them to 100 cm is: \[ \text{[IAS-1996]} \]
(a) 600 Nm  (b) 800 Nm  (c) 1000 Nm  (d) 1600 Nm

IAS-10. Ans. (b) \( E = \frac{1}{2} kx^2 = \frac{1}{2} \times \left( \frac{10N}{1 \text{m}} \right) \times (1 - 0.6)^2 \text{m}^2 = 800\text{Nm} \)

IAS-11. A spring of stiffness ‘k’ is extended from a displacement \( x_1 \) to a displacement \( x_2 \), the work done by the spring is: \[ \text{[IAS-1999]} \]
(a) \( \frac{1}{2} k x_1^2 - \frac{1}{2} k x_2^2 \)  (b) \( \frac{1}{2} k (x_1 - x_2)^2 \)  (c) \( \frac{1}{2} k (x_1 + x_2)^2 \)  (d) \( k \left( \frac{x_1 + x_2}{2} \right)^2 \)

IAS-11. Ans. (a) Work done by the spring is \( \frac{1}{2} k x_1^2 - \frac{1}{2} k x_2^2 \)

IAS-12. A spring of stiffness 1000 N/m is stretched initially by 10 cm from the undeformed position. The work required to stretch it by another 10 cm is: \[ \text{[IAS-1995]} \]
(a) 5 Nm  (b) 7 Nm  (c) 10 Nm  (d) 15 Nm

IAS-12. Ans. (d) \( E = \frac{1}{2} k (x_2^2 - x_1^2) = \frac{1}{2} \times 1000 \times (0.20^2 - 0.10^2) = 15\text{Nm} \)

Springs in Series

IAS-13. When a helical compression spring is cut into two equal halves, the stiffness of each of the result in springs will be: \[ \text{[IES-2002; IAS-2002]} \]
(a) Unaltered  (b) Double  (c) One-half  (d) One-fourth

IAS-13. Ans. (b)

IAS-14. The length of the chest-expander spring when it is un-stretched, is 0.6 m and its stiffness is 10 N/mm. The work done in stretching it to 1 m will be: \[ \text{[IAS-2001]} \]
(a) 800 J  (b) 1600 J  (c) 3200 J  (d) 6400 J

IAS-14. Ans. (a)

\[
\text{Work done} = \frac{1}{2} k \cdot x^2 = \frac{1}{2} \times \left( \frac{10N}{1 \text{m}} \right) \times (1 - 0.6)^2 \text{m}^2 = \frac{1}{2} \times \left( \frac{10N}{1 \text{m}} \right) \times 0.4^2 \text{m}^2 = 800 \text{J}
\]
Chapter-12  Springs in Parallel

Springs in Parallel

IAS-15. The equivalent spring stiffness for the system shown in the given figure (S is the spring stiffness of each of the three springs) is:
(a) S/2  (b) S/3
(c) 2S/3  (d) S

IAS-15. Ans. (c) \( S_c = \frac{1}{2S} + \frac{1}{S} \) or \( S_c = \frac{2}{3} S \)

IAS-16. Two identical springs, each of stiffness K, are assembled as shown in the given figure. The combined stiffness of the assembly is:
(a) \( K^2 \)  (b) \( 2K \)
(c) K  (d) \( (1/2)K \)

IAS-16. Ans. (b) Effective stiffness = 2K. Due to applied force one spring will be under tension and another one under compression so total resistance force will double.

Flat spiral Spring

IAS-17. Mach List-I (Type of spring) with List-II (Application) and select the correct answer:

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Leaf/Helical springs</td>
<td>1. Automobiles/Railways coachers</td>
</tr>
<tr>
<td>B. Spiral springs</td>
<td>2. Shearing machines</td>
</tr>
<tr>
<td>C. Belleville springs</td>
<td>3. Watches</td>
</tr>
</tbody>
</table>

Codes: A B C
(a) 1 2 3
(b) 1 3 2
(c) 3 1 2
(d) 2 3 1

IAS-17. Ans. (b)
Semi-elliptical spring

IAS-18. The ends of the leaves of a semi-elliptical leaf spring are made triangular in plan in order to: 
(a) Obtain variable I in each leaf 
(b) Permit each leaf to act as a overhanging beam 
(c) Have variable bending moment in each leaf 
(d) Make Mil constant throughout the length of the leaf.

IAS-18. Ans. (d) The ends of the leaves of a semi-elliptical leaf spring are made rectangular in plan in order to make M/I constant throughout the length of the leaf.
Conventional Question ESE-2008

Question: A close-coiled helical spring has coil diameter D, wire diameter d and number of turn n. The spring material has a shearing modulus G. Derive an expression for the stiffness k of the spring.

Answer: The work done by the axial force 'P' is converted into strain energy and stored in the spring.

\[ U = \text{Torque} \times \text{angular displacement} \]

\[ T = \frac{PD}{2} \]

\[ \theta = \frac{TL}{GJ} \]

Torque \( T = \frac{PD}{2} \)

length of wire \( L = \pi Dn \)

Polar moment of Inertia \( J = \frac{\pi d^4}{32} \)

Therefore \( U = \frac{4P^2D^3n}{Gd^4} \)

According to Castigliano's theorem, the displacement corresponding to force P is obtained by partially differentiating strain energy with respect to that force.

\[ \delta = \frac{\partial U}{\partial P} = \frac{\partial}{\partial P} \left[ \frac{4P^2D^3n}{Gd^4} \right] = \frac{8PD^3n}{Gd^4} \]

So Spring stiffness, \( k = \frac{P}{\delta} = \frac{Gd^4}{8Dn} \)

Conventional Question ESE-2010

Q. A stiff bar of negligible weight transfers a load P to a combination of three helical springs arranged in parallel as shown in the above figure. The springs are made up of the same material and out of rods of equal diameters. They are of same free length before loading. The number of coils in those three springs are 10, 12 and 15 respectively, while the mean coil diameters are in ratio of 1 : 1.2 : 1.4 respectively. Find the distance 'x' as shown in figure, such that the stiff bar remains horizontal after the application of load P. [10 Marks]

Ans. Same free length of spring before loading
The number of coils in the spring 1, 2 and 3 is 10, 12 and 15 mean diameter of spring 1, 2 and 3 in the ratio of 1 : 1.2 : 1.4. Find out distance x so that rod remains horizontal after loading.

Since the rod is rigid and remains horizontal after the load p is applied therefore the deflection of each spring will be same

\[ \delta_1 = \delta_2 = \delta_3 = \delta \]  
(say)

Spring are made of same material and out of the rods of equal diameter

\[ G_1 = G_2 = G_3 = G \quad \text{and} \quad d_1 = d_2 = d_3 = d \]

Load in spring 1

\[ P_1 = \frac{Gd^4 \delta}{64R_1^3 n_1} = \frac{Gd^4 \delta}{64R_1^3 \times 10} = \frac{Gd^4 \delta}{640R_1^3} \] ....(1)

Load in spring 2

\[ P_2 = \frac{Gd^4 \delta}{64R_2^3 n_2} = \frac{Gd^4 \delta}{64 \times (1.2)^3 \times 12R_1^3} = \frac{Gd^4 \delta}{1327.10R_1^3} \] ....(2)

Load in spring 3

\[ P_3 = \frac{Gd^4 \delta}{64R_3^3 n_3} = \frac{Gd^4 \delta}{64 \times (1.4)^3 \times 15R_1^3} = \frac{Gd^4 \delta}{2634.2R_1^3} \] ....(3)

From eqn (1) & (2)

\[ P_2 = \frac{640}{1327.1} P_1 \]

\[ P_2 = 0.482 P_1 \]

from eqn (1) & (3)

\[ P_3 = \frac{640}{2634.2} P_1 = 0.2430 P_1 \]

Taking moment about the line of action \( P_1 \)

\[ P_2 \times L + P_3 \times 2L = P \times x \]

\[ 0.4823 P_1 L + 0.2430 P_1 \times 2L = P \times x \]

\[ x = \frac{(0.4823 + 0.486)P_1 L}{P} \] .......(4)

total load in the rod is

\[ P = P_1 + P_2 + P_3 \]

\[ P = P_1 + 0.4823P_1 + 0.2430P_1 \]

\[ P = 1.725 P_1 \] .......(5)

Equation (4) & (5)

\[ x = \frac{0.9683L}{1.725 P_1 / P_1} = \frac{0.9683L}{1.725} = 0.5613L \]

\[ x = 0.5613 \text{ L} \]

**Conventional Question ESE-2008**

**Question:** A close-coiled helical spring has coil diameter to wire diameter ratio of 6. The spring deflects 3 cm under an axial load of 500N and the maximum shear stress is not to exceed 300 MPa. Find the diameter and the length of the spring wire required. Shearing modulus of wire material = 80 GPa.

**Answer:**

\[ \text{Stiffness}, K = \frac{P}{\delta} = \frac{Gd^4}{8D^3 n} \]
or \( \frac{500}{0.03} = \frac{(80 \times 10^3) \times d}{8 \times 6^3 \times n} \)  
\[ \text{[given } \frac{D}{d} = 6] \]

or \( d = 3.6 \times 10^{-4} n \) \( i \)

For static loading correcting factor (k)

\[ k = \left(1 + \frac{0.5}{c} \right) = \left(1 + \frac{0.5}{6} \right) = 1.0833 \]

We know that \( (\tau) = k \frac{8PD}{\pi d^3} \)

\[ d^2 = \frac{8kPC}{\pi \tau} \]
\[ \therefore c = \frac{D}{d} = 6 \]

\[ d = \sqrt{\frac{1.0833 \times 8 \times 500 \times 6}{\pi \times 300 \times 10^6}} = 5.252 \times 10^{-3} m = 5.252 mm \]

So \( D = cd = 6 \times 5.252 mm = 31.513 mm \)

From equation (i) \( n = 14.59 \approx 15 \)

Now length of spring wire (L) = \( \pi Dn = \pi \times 31.513 \times 15 \) mm = 1.485 m

**Conventional Question ESE-2007**

**Question:** A coil spring of stiffness ‘k’ is cut to two halves and these two springs are assembled in parallel to support a heavy machine. What is the combined stiffness provided by these two springs in the modified arrangement?

**Answer:**

When it cut to two halves stiffness of each half will be 2k. Springs in parallel.

Total load will be shared so

\[ \text{Total load} = W + W \]

or \( \delta K_{eq} = \delta (2k) + \delta (2k) \)

or \( K_{eq} = 4k \).

**Conventional Question ESE-2001**

**Question:** A helical spring B is placed inside the coils of a second helical spring A, having the same number of coils and free axial length and of same material. The two springs are compressed by an axial load of 210 N which is shared between them. The mean coil diameters of A and B are 90 mm and 60 mm and the wire diameters are 12 mm and 7 mm respectively. Calculate the load shared by individual springs and the maximum stress in each spring.

**Answer:** The stiffness of the spring \( k = \frac{Gd^4}{8D^3N} \)

Here load shared the springs are arranged in parallel

Equivalent stiffness \( k_e = k_A + k_B \)

\[ \text{Hear } \frac{K_A}{K_B} = \left( \frac{d_A}{d_B} \right)^4 \left( \frac{D_B}{D_A} \right)^3 \]  
\[ \text{[As } N_A = N_B \]  
\[ = \left( \frac{12}{7} \right)^4 \times \left( \frac{60}{90} \right)^3 = 2.559 \]

Let total deflection is ‘x’ m

\[ x = \frac{\text{Total load}}{\text{Equivaleat stiffness}} = \frac{210 N}{K_A + K_B} \]
Spring

Load shared by spring 'A' \( F_A = \frac{210}{1 + \frac{k_A}{k}} \) = 151 N

Load shared by spring 'A' \( F_B = (210 - 151) = 59 \) N

For static load: \( \tau = \left( 1 + \frac{0.5}{C} \right) \frac{8PD}{\pi d^3} \)

\[
\left( \tau_A \right)_{\text{max}} = \left[ 1 + \frac{0.5}{\frac{90}{12}} \right] \frac{8 \times 151 \times 0.090}{\pi \times (0.012)^3} = 21.362 \text{ MPa}
\]

\[
\left( \tau_B \right)_{\text{max}} = \left[ 1 + \frac{0.5}{\frac{60}{7}} \right] \frac{8 \times 59 \times 0.060}{\pi \times (0.007)^3} = 27.816 \text{ MPa}
\]

Conventional Question AMIE-1997

**Question:** A close-coiled spring has mean diameter of 75 mm and spring constant of 90 kN/m. It has 8 coils. What is the suitable diameter of the spring wire if maximum shear stress is not to exceed 250 MN/m²? Modulus of rigidity of the spring wire material is 80 GN/m². What is the maximum axial load the spring can carry?

**Answer:**

Given \( D = 75 \text{ mm; } k = 80 \text{ kN/m; } n = 8 \)

\( \tau = 250 \text{ MN/m}^2; G = 80 \text{ GN/m}^2 = 80 \times 10^6 \text{ N/m}^2 \)

Diameter of the spring wire, \( d \):

\[ T = \tau \times \frac{\pi}{16} d^3 \quad \text{(where} \ T = P \times R) \]

We know, \( P \times 0.0375 = \left(250 \times 10^6\right) \times \frac{\pi}{16} d^3 \quad - - - (i) \)

Also \( P = k \delta \)

or \( P = 80 \times 10^3 \times \delta \quad - - - (ii) \)

Using the relation:

\[ \delta = \frac{8PD^3 n}{Gd^4} = \frac{8 \times (0.075)^3 \times 8}{80 \times 10^6 \times d^4} = 33.75 \times 10^{-14} \times \frac{P}{d^4} \]

Substituting for \( \delta \) in equation (ii), we get

\[ P = 80 \times 10^3 \times 33.75 \times 10^{-14} \times \frac{P}{d^4} \quad \text{or} \quad d = 0.0128 \text{ m or 12.8 mm} \]

Maximum axial load the spring can carry \( P \):

From equation (i), we get

\[ P \times 0.0375 = \left(250 \times 10^6\right) \times \frac{\pi}{16} \times (0.0128)^3; \quad : \quad P = 2745.2 \text{ N} = 2.745 \text{ kN} \]
13. Theories of Column

Theory at a Glance (for IES, GATE, PSU)

1. Introduction

- **Strut**: A member of structure which carries an axial compressive load.
- **Column**: If the strut is vertical it is known as column.
- A long, slender column becomes unstable when its axial compressive load reaches a value called the critical buckling load.
- If a beam element is under a compressive load and its length is an order of magnitude larger than either of its other dimensions such a beam is called a *columns*.
- Due to its size its axial displacement is going to be very small compared to its lateral deflection called *buckling*.
- *Buckling* does not vary linearly with load it occurs suddenly and is therefore dangerous.
- **Slenderness Ratio**: The ratio between the length and least radius of gyration.
- **Elastic Buckling**: Buckling with no permanent deformation.
- Euler buckling is only valid for long, slender objects in the elastic region.
- For short columns, a different set of equations must be used.

2. Which is the critical load?

- At this value the structure is in equilibrium regardless of the magnitude of the angle (provided it stays small)
- Critical load is the only load for which the structure will be in equilibrium in the disturbed position.
- At this value, restoring effect of the moment in the spring matches the buckling effect of the axial load represents the boundary between the stable and unstable conditions.
- If the axial load is less than $P_{cr}$ the effect of the moment in the spring dominates and the structure returns to the vertical position after a small disturbance – stable condition.
- If the axial load is larger than $P_{cr}$ the effect of the axial force predominates and the structure buckles – unstable condition.
- Because of the large deflection caused by buckling, the least moment of inertia $I$ can be expressed as, $I = A \kappa^2$
- Where: $A$ is the cross sectional area and $r$ is the *radius of gyration* of the cross sectional area, i.e. $k_{\text{min}} = \sqrt{\frac{I_{\text{min}}}{A}}$
3. Euler’s Critical Load for Long Column

**Assumptions:**

(i) The column is perfectly straight and of uniform cross-section
(ii) The material is homogenous and isotropic
(iii) The material behaves elastically
(iv) The load is perfectly axial and passes through the centroid of the column section.
(v) The weight of the column is neglected.

Euler’s critical load, 

\[ P_{cr} = \frac{\pi^2 EI}{l_e^2} \]

Where \( l_e \) = Equivalent length of column (1st mode of bending)

4. Remember the following table

<table>
<thead>
<tr>
<th>Case</th>
<th>Diagram</th>
<th>( P_{cr} )</th>
<th>Equivalent length(( l_e ))</th>
</tr>
</thead>
<tbody>
<tr>
<td>Both ends hinged/pinned</td>
<td><img src="image1" alt="Diagram" /></td>
<td>( \frac{\pi^2 EI}{l_e^2} )</td>
<td>( l )</td>
</tr>
<tr>
<td>Both ends fixed</td>
<td><img src="image2" alt="Diagram" /></td>
<td>( \frac{4\pi^2 EI}{l_e^2} )</td>
<td>( \frac{l}{2} )</td>
</tr>
<tr>
<td>One end fixed &amp; other end free</td>
<td><img src="image3" alt="Diagram" /></td>
<td>( \frac{\pi^2 EI}{4l^2} )</td>
<td>( 2l )</td>
</tr>
</tbody>
</table>
5. Slenderness Ratio of Column

\[ P_{cr} = \frac{\pi^2 EI}{L_e^2} \]  
where \( L = A \) 

\[ k_{\text{min}} = \frac{\ell_e}{k_{\text{min}}} \] 

\[ k_{\text{min}} = \text{least radius of gyration} \]

\[ \therefore \text{Slenderness Ratio} = \frac{\ell_e}{k_{\text{min}}} \]

6. Rankine’s Crippling Load

Rankine theory is applied to both

- Short strut / column (valid upto SR-40)
- Long Column (Valid upto SR 120)

- Slenderness ratio

\[ \frac{\ell_e}{k} = \sqrt{\frac{\pi^2 E}{\sigma_c}} \]  

(\( \sigma_c \) = critical stress) \( P_{cr} = \frac{P_e}{A} \)

- Crippling Load, \( P \)

\[ P = \frac{\sigma_c A}{1 + K' \left( \frac{\ell_e}{k} \right)^2} \]

where \( k' = \text{Rankine constant} = \frac{\sigma_c}{\pi^2 E} \)

depends on material & end conditions
Chapter-13 Theories of Column

\( \sigma_c = \text{crushing stress} \)

- For steel columns

\[
K' = \frac{1}{25000} \quad \text{for both ends fixed}
\]

\[
= \frac{1}{12500} \quad \text{for one end fixed & other hinged} \quad 20 \leq \frac{\ell_c}{k} \leq 100
\]

7. Other formulas for crippling load (P)

- Gordon’s formula,

\[
P = \frac{\sigma_c}{1 + b \left( \frac{\ell_c}{d} \right)}
\]

\( b = \text{a constant, } d = \text{least diameter or breadth of bar} \)

- Johnson Straight line formula,

\[
P = \sigma_c A \left[ 1 - c \left( \frac{\ell_c}{k} \right) \right]
\]

\( c = \text{a constant depending on material} \)

- Johnson parabolic formulae:

\[
P = \sigma_c A \left[ 1 - \left( \frac{N^2}{\ell_c} \right) \right]
\]

where the value of index ‘b’ depends on the end conditions.

- Fiddler’s formula,

\[
P = \frac{A}{C} \left[ (\sigma_c + \sigma_e) - \sqrt{(\sigma_c + \sigma_e)^2 - 2c \sigma_e \sigma_c} \right]
\]

where, \( \sigma_e = \frac{\pi^2 E}{(\frac{\ell_c}{k})^2} \)

8. Eccentrically Loaded Columns

- Secant formula

\[
\sigma_{\text{max}} = \frac{P}{A} \left[ 1 + \frac{ev_c}{k^2} \sec \left( \frac{\ell_c}{2k} \right) \sqrt{\frac{P}{EA}} \right]
\]

Where \( \sigma_{\text{max}} = \text{maximum compressive stress} \)

\( P = \text{load} \)
A = Area of c/s

$y_c =$ Distance of the outermost fiber in compression from the NA

e = Eccentricity of the load

$l_e =$ Equivalent length

$k =$ Radius of gyration $= \sqrt{\frac{I}{A}}$

$E =$ Modulus of elasticity of the material

$M = P . e . S e c \left( \frac{\ell_e}{2k} \sqrt{\frac{P}{EA}} \right) \frac{1}{k^2}$

Where $M =$ Moment introduced.

- **Prof. Perry’s Formula**

  \[
  \frac{\sigma_{\text{max}}}{\sigma_d} - 1 \left( 1 - \frac{\sigma_d}{\sigma_e} \right) = \frac{e_i y_c}{k^2}
  \]

  Where $\sigma_{\text{max}} =$ maximum compressive stress

  \[
  \sigma_d = \frac{P}{A} = \text{Load} \quad \text{c/s area}
  \]

  \[
  \sigma_e = \frac{P}{A} = \text{Euler’s load} \quad \text{c/s area}
  \]

  \[
  p_e = \text{Euler’s load} = \frac{\pi^2 EI}{\ell_e^2}
  \]

  $e'$ = Versine at mid-length of column due to initial curvature

  e = Eccentricity of the load

  $e_i = e' + 1.2e$

  $y_c =$ distance of outer most fiber in compression form the NA

  $k =$ Radius of gyration

  If $\sigma_{\text{max}}$ is allowed to go up to $\sigma_1$(permissible stress)

  Then, $\eta = \frac{e_i y_c}{k^2}$

  \[
  \sigma_d = \frac{\sigma_f + \sigma_e (1 + \eta)}{2} - \sqrt{\left( \frac{\sigma_f + \sigma_e (1 + \eta)}{2} \right)^2 - \sigma_e \sigma_f}
  \]

- **Perry-Robertson Formula**

  \[
  \eta = 0.003 \left( \frac{\ell_e}{k} \right)
  \]

  \[
  \sigma_d = \frac{\sigma_f + \sigma_e \left( 1 + 0.003 \frac{\ell_e}{k} \right)}{2} - \sqrt{\left( \frac{\sigma_f + \sigma_e \left( 1 + 0.003 \frac{\ell_e}{k} \right)}{2} \right)^2 - \sigma_e \sigma_f}
  \]
9. ISI’s Formula for Columns and Struts

For \( \frac{\ell}{k} = 0 \) to 160

\[
P_c = \frac{\sigma_y f_{os}}{1 + 0.2 \sec\left(\frac{\ell}{k} \sqrt{\frac{f_{os} \times P_c}{4E}}\right)}
\]

Where, \( P_c \) = Permissible axial compressive stress

\( P_c' \) = A value obtained from above Secant formula

\( \sigma_y \) = Guaranteed minimum yield stress = 2600 kg/cm² for mild steel

\( f_{os} \) = factor of safety = 1.68

\( \frac{\ell}{k} \) = Slenderness ratio

\( E \) = Modulus of elasticity = \( 2.045 \times 10^6 \) kg/cm² for mild steel

For \( \frac{\ell}{k} > 160 \)
Chapter-13 Theories of Column S K Mondal’s

OBJECTIVE QUESTIONS (GATE, IES, IAS)

Previous 20-Years GATE Questions

Strength of Column

GATE-1. The rod PQ of length \( L \) and with flexural rigidity EI is hinged at both ends. For what minimum force \( F \) is it expected to buckle?

\[
\begin{align*}
(a) \quad & \frac{\pi^2 EI}{L^2} \\
(b) \quad & \frac{\sqrt{2}\pi^2 EI}{L^2} \\
(c) \quad & \frac{\pi^2 EI}{\sqrt{2}L^2} \\(b) \quad & \frac{\pi^2 EI}{2L^2}
\end{align*}
\]

GATE-1. Ans. (b) Axial component of the force \( F_{PQ} = F \sin 45^\circ \)

We know for both end fixed column buckling load \( P = \frac{\pi^2 EI}{L^2} \)

and \( F \sin 45^\circ = P \) or \( F = \frac{\sqrt{2}\pi^2 EI}{L^2} \)

Equivalent Length

GATE-2. The ratio of Euler's buckling loads of columns with the same parameters having (i) both ends fixed, and (ii) both ends hinged is:

\[(a) 2 \quad (b) 4 \quad (c) 6 \quad (d) 8\]

GATE-2. Ans. (b) Euler's buckling loads of columns

(1) both ends fixed = \( \frac{4\pi^2 EI}{P} \)

(2) both ends hinged = \( \frac{\pi^2 EI}{P} \)

Euler's Theory (For long column)

GATE-3. A pin-ended column of length \( L \), modulus of elasticity \( E \) and second moment of the cross-sectional area \( I \) is loaded centrically by a compressive load \( P \). The critical buckling load \( P_{cr} \) is given by:

\[
\begin{align*}
(a) \quad & P_{cr} = \frac{EI}{\pi^2 L^2} \\
(b) \quad & P_{cr} = \frac{\pi^2 EI}{3L^2} \\
(c) \quad & P_{cr} = \frac{\pi EI}{L^2} \\(d) \quad & P_{cr} = \frac{\pi^2 EI}{L^2}
\end{align*}
\]

GATE-3. Ans. (d)

GATE-4. What is the expression for the crippling load for a column of length \( L \) with one end fixed and other end free?

\[
\begin{align*}
(a) \quad & P = \frac{2\pi^2 EI}{L^2} \\
(b) \quad & P = \frac{\pi^2 EI}{4L^2} \\
(c) \quad & P = 4\pi^2 EI \quad \text{(IES-2006; GATE-1994)} \\
(d) \quad & P = \frac{\pi^2 EI}{L^2}
\end{align*}
\]
21. The piston rod of diameter 20 mm and length 700 mm in a hydraulic cylinder is subjected to a compressive force of 10 KN due to the internal pressure. The end conditions for the rod may be assumed as guided at the piston end and hinged at the other end. The Young’s modulus is 200 GPa. The factor of safety for the piston rod is (a) 0.68 (b) 2.75 (c) 5.62 (d) 11.0 [GATE-2007]

21. Ans. (c)

Assuming guided end to be fixed and other end given as hinged, the crippling load according to Euler’s equation,

\[ P_c = \frac{2\pi^2 E l}{L^2}, \quad l = \frac{\pi}{64} (20)^4 \]

\[ = \frac{2\pi^2 \times 200 \times 10^3 \times 7853.9}{(700)^2} \]

\[ = 63.27 \text{kN} \]

Factor of safety = \( \frac{Crippling \ load}{Working \ load} = \frac{63.27}{10} = 6.32 \)

### Previous 20-Years IES Questions

#### Classification of Column

IES-1. A structural member subjected to an axial compressive force is called (a) Beam (b) Column (c) Frame (d) Strut

IES-1. Ans. (d) A machine part subjected to an axial compressive force is called a **strut**. A strut may be horizontal, inclined or even vertical. But a vertical strut is known as a **column**, **pillar** or **stanchion**.

The term **column** is applied to all such members except those in which failure would be by simple or pure compression. Columns can be categorized then as:

1. Long column with central loading
2. Intermediate-length columns with central loading
3. Columns with eccentric loading
4. Struts or short columns with eccentric loading

IES-2. Which one of the following loadings is considered for design of axles?

(a) Bending moment only (b) Twisting moment only (c) Combined bending moment and torsion (d) Combined action of bending moment, twisting moment and axial thrust.

IES-2. Ans. (a) Axle is a non-rotating member used for supporting rotating wheels etc. and do not transmit any torque. Axle must resist forces applied laterally or transversely to their axes. Such members are called beams.
Chapter-13 Theories of Column

IES-3. The curve $ABC$ is the Euler's curve for stability of column. The horizontal line $DEF$ is the strength limit. With reference to this figure Match List-I with List-II and select the correct answer using the codes given below the lists:

<table>
<thead>
<tr>
<th>List-I (Regions)</th>
<th>List-II (Column specification)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. $R_1$</td>
<td>1. Long, stable</td>
</tr>
<tr>
<td>B. $R_2$</td>
<td>2. Short</td>
</tr>
<tr>
<td>C. $R_3$</td>
<td>3. Medium</td>
</tr>
<tr>
<td>D. $R_4$</td>
<td>4. Long, unstable</td>
</tr>
</tbody>
</table>

Codes: 
(a) 2 4 3 1  
(b) 2 3 1 4  
(c) 1 2 4 3  
(d) 2 1 3 4  

IES-3. Ans. (b)

IES-4. Match List-I with List-II and select the correct answer using the codes given below the lists:

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Polar moment of inertia of section</td>
<td>1. Thin cylindrical shell</td>
</tr>
<tr>
<td>B. Buckling</td>
<td>2. Torsion of shafts</td>
</tr>
<tr>
<td>C. Neutral axis</td>
<td>3. Columns</td>
</tr>
<tr>
<td>D. Hoop stress</td>
<td>4. Bending of beams</td>
</tr>
</tbody>
</table>

Codes: 
(a) 3 2 1 4  
(b) 2 3 4 1  
(c) 3 2 4 1  
(d) 2 3 1 4  

IES-4. Ans. (b)

**Strength of Column**

IES-5. Slenderness ratio of a column is defined as the ratio of its length to its  
(a) Least radius of gyration  
(b) Least lateral dimension  
(c) Maximum lateral dimension  
(d) Maximum radius of gyration  

IES-5. Ans. (a)

IES-6. Assertion (A): A long column of square cross section has greater buckling stability than a similar column of circular cross-section of same length, same material and same area of cross-section with same end conditions.  
Reason (R): A circular cross-section has a smaller second moment of area than a square cross-section of same area.  
IES-1999; IES-1996  
(a) Both A and R are individually true and R is the correct explanation of A  
(b) Both A and R are individually true but R is NOT the correct explanation of A  
(c) A is true but R is false  
(d) A is false but R is true  

IES-6. Ans. (a)

**Equivalent Length**

IES-7. Four columns of same material and same length are of rectangular cross-section of same breadth $b$. The depth of the cross-section and the end conditions are, however different are given as follows:  

<table>
<thead>
<tr>
<th>Column</th>
<th>Depth</th>
<th>End conditions</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0.6 $b$</td>
<td>Fixed-Fixed</td>
</tr>
<tr>
<td>2</td>
<td>0.8 $b$</td>
<td>Fixed-hinged</td>
</tr>
<tr>
<td>3</td>
<td>1.0 $b$</td>
<td>Hinged-Hinged</td>
</tr>
<tr>
<td>4</td>
<td>2.6 $b$</td>
<td>Fixed-Free</td>
</tr>
</tbody>
</table>

Which of the above columns Euler buckling load maximum?  
(a) Column 1  
(b) Column 2  
(c) Column 3  
(d) Column 4  

IES-7. Ans. (b)
### Chapter-13 Theories of Column

IES-8. Match List-I (End conditions of columns) with List-II (Equivalent length in terms of length of hinged-hinged column) and select the correct answer using the codes given below the Lists: **[IES-2000]**

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Both ends hinged</td>
<td>1. $L$</td>
</tr>
<tr>
<td>B. One end fixed and other end free</td>
<td>2. $L/\sqrt{2}$</td>
</tr>
<tr>
<td>C. One end fixed and the other pin-pointed</td>
<td>3. $2L$</td>
</tr>
<tr>
<td>D. Both ends fixed</td>
<td>4. $L/2$</td>
</tr>
</tbody>
</table>

**Code:**

(a) 1 3 4 2  (b) 1 3 2 4  (c) 3 1 2 4  (d) 3 1 4 2

IES-8. Ans. (b)

IES-9. The ratio of Euler's buckling loads of columns with the same parameters having (i) both ends fixed, and (ii) both ends hinged is: **[GATE-1998; 2002; IES-2001]**

(a) 2  (b) 4  (c) 6  (d) 8

IES-9. Ans. (b) Euler's buckling loads of columns

- (1) both ends fixed = $\frac{4\pi^2EI}{l^2}$
- (2) both ends hinged = $\frac{\pi^2EI}{l^2}$

### Euler's Theory (For long column)

IES-10. What is the expression for the crippling load for a column of length ‘l’ with one end fixed and other end free? **[IES-2006; GATE-1994]**

(a) $P = \frac{2\pi^2EI}{l^2}$  (b) $P = \frac{\pi^2EI}{4l^2}$  (c) $P = \frac{4\pi^2EI}{l^2}$  (d) $P = \frac{\pi^2EI}{l^2}$

IES-10. Ans. (b)

IES-11. Euler's formula gives 5 to 10% error in crippling load as compared to experimental results in practice because: **[IES-1998]**

(a) Effect of direct stress is neglected
(b) Pin joints are not free from friction
(c) The assumptions made in using the formula are not met in practice
(d) The material does not behave in an ideal elastic way in tension and compression

IES-11. Ans. (c)

IES-12. Euler's formula can be used for obtaining crippling load for a M.S. column with hinged ends.

Which one of the following conditions for the slenderness ratio $\frac{l}{k}$ is to be satisfied? **[IES-2000]**

(a) $5 < \frac{l}{k} < 8$  (b) $9 < \frac{l}{k} < 18$  (c) $19 < \frac{l}{k} < 40$  (d) $\frac{l}{k} \geq 80$

IES-12. Ans. (d)

IES-13. If one end of a hinged column is made fixed and the other free, how much is the critical load compared to the original value? **[IES-2008]**

(a) $\frac{1}{4}$  (b) $\frac{1}{2}$  (c) Twice  (d) Four times

IES-13. Ans. (a) Critical Load for both ends hinged = $\frac{\pi^2EI}{l^2}$

And Critical Load for one end fixed, and other end free = $\frac{\pi^2EI}{4l^2}$

IES-14. If one end of a hinged column is made fixed and the other free, how much is the critical load compared to the original value? **[IES-2008]**

(a) $\frac{1}{4}$  (b) $\frac{1}{2}$  (c) Twice  (d) Four times

IES-14. Ans. (a) Original load = $\frac{\pi^2EI}{l^2}$
When one end of hinged column is fixed and other free. New \( L_e = 2L \)

\[ \therefore \text{New load} = \frac{\pi^2 EI}{(2L)^2} = \frac{\pi^2 EI}{4L^2} = \frac{1}{4}\times \text{Original value} \]


<table>
<thead>
<tr>
<th>List-I (Long Column)</th>
<th>List-II (Critical Load)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Both ends hinged</td>
<td>1. ( \pi^2 EI/4l^2 )</td>
</tr>
<tr>
<td>B. One end fixed, and other end free</td>
<td>2. ( 4 \pi^2 EI/l^2 )</td>
</tr>
<tr>
<td>C. Both ends fixed</td>
<td>3. ( 2 \pi^2 EI/l^2 )</td>
</tr>
<tr>
<td>D. One end fixed, and other end hinged</td>
<td>4. ( \pi^2 EI/l^2 )</td>
</tr>
</tbody>
</table>

Code:  
(a) 2 1 4 3  
(b) 4 1 2 3  
(c) 2 3 4 1  
(d) 4 3 2 1  
IES-15. Ans. (b)

IES-16. The ratio of the compressive critical load for a long column fixed at both the ends and a column with one end fixed and the other end free is: [IES-1997]

(a) 1 : 2  
(b) 1 : 4  
(c) 1 : 8  
(d) 1 : 16  
IES-16. Ans. (d) Critical Load for one end fixed, and other end free is \( \pi^2 EI/4l^2 \) and both ends fixed is \( 4 \pi^2 EI/l^2 \)

IES-17. The buckling load will be maximum for a column, if [IES-1993]

(a) One end of the column is clamped and the other end is free  
(b) Both ends of the column are clamped  
(c) Both ends of the column are hinged  
(d) One end of the column is hinged and the other end is free  
IES-17. Ans. (b) Buckling load of a column will be maximum when both ends are fixed

IES-18. If diameter of a long column is reduced by 20%, the percentage of reduction in Euler buckling load is: [IES-2001]

(a) 4  
(b) 36  
(c) 49  
(d) 59  
IES-18. Ans. (d) \( P = \frac{\pi^2 EI}{L^2} \) or \( P = \pi^2 EI/L^2 \) as \( P - P' = \frac{d^2 - (d')^2}{d} = 1 - \left( \frac{0.8d}{d} \right)^4 = 0.59 \)

IES-19. A long slender bar having uniform rectangular cross-section 'B x H' is acted upon by an axial compressive force. The sides B and H are parallel to x- and y-axes respectively. The ends of the bar are fixed such that they behave as pin-jointed when the bar buckles in a plane normal to x-axis, and they behave as built-in when the bar buckles in a plane normal to y-axis. If load capacity in either mode of buckling is same, then the value of H/B will be: [IES-2000]

(a) 2  
(b) 4  
(c) 8  
(d) 16  
IES-19. Ans. (a) \( P_{xx} = \frac{\pi^2 EI}{L^2} \) and \( P_{yy} = \frac{4\pi^2 EI'}{L^2} \) as \( P_{xx} = P_{yy} \) then \( l = 4l' \) or \( \frac{BH^3}{12} = 4 \times \frac{HB^3}{12} \) or \( H = 2B \)

IES-20. The Euler's crippling load for a 2m long slender steel rod of uniform cross-section hinged at both the ends is 1 kN. The Euler's crippling load for 1 m long steel rod of the same cross-section and hinged at both ends will be: [IES-1998]

(a) 0.25 kN  
(b) 0.5 kN  
(c) 2 kN  
(d) 4 kN  
IES-20. Ans. (d) For column with both ends hinged, \( P = \frac{\pi^2 EI}{L^2} \). If 'T' is halved, P will be 4 times.

IES-21. If \( \sigma_c \) and E denote the crushing stress and Young's modulus for the material of a column, then the Euler formula can be applied for determination of crippling load of a column made of this material only, if its slenderness ratio is:

(a) More than \( \sqrt[3]{\frac{E}{\sigma_c}} \)  
(b) Less than \( \sqrt[3]{\frac{E}{\sigma_c}} \)  
IES-21. Ans. (a)
(c) More than \( \pi^2 \left( \frac{E}{\sigma_c} \right) \)
(d) Less than \( \pi^2 \left( \frac{E}{\sigma_c} \right) \)

IES-21. Ans. (a) For long column \( P_{\text{Euler}} < P_{\text{crushing}} \)

or \( \frac{\pi^2 E I}{l_0^2} < \sigma_e A \)

or \( \frac{\pi^2 E A k^2}{l_0^2} < \sigma_e A \)

or \( \frac{E}{k} > \frac{\pi^2 E}{\sigma_e} \)

or \( \frac{E}{k} > \pi \sqrt{E/\sigma_e} \)

IES-22. Four vertical columns of same material, height and weight have the same end conditions. Which cross-section will carry the maximum load? [IES-2009]

(a) Solid circular section  
(b) Thin hollow circular section  
(c) Solid square section  
(d) I-section

IES-22. Ans. (b)

Rankine's Hypothesis for Struts/Columns

IES-23. Rankine Gordon formula for buckling is valid for [IES-1994]

(a) Long column  
(b) Short column  
(c) Short and long column  
(d) Very long column

IES-23. Ans. (c)

Prof. Perry's formula

IES-24. Match List-I with List-II and select the correct answer using the code given below the lists: [IES-2008]

<table>
<thead>
<tr>
<th>List-I (Formula/theorem/method)</th>
<th>List-II (Deals with topic)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Clapeyron's theorem</td>
<td>1. Deflection of beam</td>
</tr>
<tr>
<td>B. Macaulay's method</td>
<td>2. Eccentrically loaded column</td>
</tr>
<tr>
<td>C. Perry's formula</td>
<td>3. Riveted joints</td>
</tr>
<tr>
<td>4. Continuous beam</td>
<td></td>
</tr>
</tbody>
</table>

Code: A B C  A B C
(a) 3 2 1  (b) 4 1 2
(c) 4 1 3  (d) 2 4 3

IES-24. Ans. (b)

Previous 20-Years IAS Questions

Classification of Column

IAS-1. Mach List-I with List-II and select the correct answer using the codes given below the lists: [IAS-1999]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Polar moment of inertia of section</td>
<td>1. Thin cylindrical shell</td>
</tr>
<tr>
<td>B. Buckling</td>
<td>2. Torsion of shafts</td>
</tr>
<tr>
<td>C. Neutral axis</td>
<td>3. Columns</td>
</tr>
<tr>
<td>D. Hoop stress</td>
<td>4. Bending of beams</td>
</tr>
</tbody>
</table>

Codes: A B C D  A B C D
(a) 3 2 1 4  (b) 2 3 4 1
(c) 3 2 4 1  (d) 2 3 1 4

IAS-1. Ans. (b)

Strength of Column

IAS-2. Assertion (A): A long column of square cross-section has greater buckling stability than that of a column of circular cross-section of same length, same material, same end conditions and same area of cross-section. [IAS-1998]

Reason (R): The second moment of area of a column of circular cross-section is smaller than that of a column of square cross section having the same area.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-2. Ans. (a)

IAS-3. Which one of the following pairs is not correctly matched? [IAS-2003]
(a) Slenderness ratio : The ratio of length of the column to the least radius of gyration
(b) Buckling factor : The ratio of maximum load to the permissible axial load on the column
(c) Short column : A column for which slenderness ratio < 32
(d) Strut : A member of a structure in any position and carrying an axial compressive load

IAS-3. Ans. (b) Buckling factor: The ratio of equivalent length of the column to the least radius of gyration.

Equivalent Length

IAS-4. A column of length 'l' is fixed at its both ends. The equivalent length of the column is: [IAS-1995]
(a) 2l
(b) 0.5l
(c) 2l
(d) l

IAS-4. Ans. (b)

IAS-5. Which one of the following statements is correct? [IAS-2000]
(a) Euler's formula holds good only for short columns
(b) A short column is one which has the ratio of its length to least radius of gyration greater than 100
(c) A column with both ends fixed has minimum equivalent or effective length
(d) The equivalent length of a column with one end fixed and other end hinged is half of its actual length

IAS-5. Ans. (c) A column with both ends fixed has minimum equivalent effective length (l/2)

Euler's Theory (For long column)

IAS-6. For which one of the following columns, Euler buckling load = \(\frac{4\pi^2 EI}{l^2}\)? [IAS-1999; 2004]
(a) Column with both hinged ends
(b) Column with one end fixed and other end free
(c) Column with both ends fixed
(d) Column with one end fixed and other hinged

IAS-6. Ans. (c)

Reason (R): In a buckled column, the stresses do not exceed the yield stress.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true

IAS-7. Ans. (d) And Critical Load for one end fixed, and other end free = \(\pi^2EI/4l^2\)

List-I (Long Column) List-II (Critical Load)
A. Both ends hinged 1. \(\frac{\pi^2EI}{4l^2}\)
B. One end fixed, and other end free 2. \(4\ \pi^2EI/ l^2\)
Chapter-13

Theories of Column

C. Both ends fixed
3. $\frac{\pi^2EI}{l^2}$

D. One end fixed, and other end hinged
4. $\frac{\pi^2EI}{l^2}$

Code:   A  B  C  D  A  B  C  D

(a)  2  1  4  3   (b)  4  1  2  3
(c)  2  3  4  1   (d)  4  3  2  1

IAS-8. Ans. (b)
Chapter-13 Theories of Column

Previous Conventional Questions with Answers

Conventional Question ESE-2001, ESE 2000

**Question:** Differentiate between strut and column. What is the general expression used for determining of their critical load?

**Answer:**

**Strut:** A member of structure which carries an axial compressive load.

**Column:** If the strut is vertical it is known as column.

For strut failure due to compression or \( \sigma_c = \frac{\text{Compressive force}}{\text{Area}} \)

If \( \sigma_c > \sigma_{yc} \) it fails.

Euler's formula for column \( \left(P_c\right) = \frac{\pi^2 EI}{L_c^2} \)

Conventional Question ESE-2009

**Q.** Two long columns are made of identical lengths 'I' and flexural rigidities 'EI'. Column 1 is hinged at both ends whereas for column 2 one end is fixed and the other end is free.

(i) Write the expression for Euler's buckling load for column 1.
(ii) What is the ratio of Euler's buckling load of column 1 to that column 2? [2 Marks]

**Ans.**

(i) \( P_1 = \frac{\pi^2 EI}{L^2} ; P_2 = \frac{\pi^2 EI}{4L^2} \) (right)

For column 1, both end hinged \( [e = L] \)

(ii) \( \frac{P_1}{P_2} = 4 \)

Conventional Question ESE-2010

**Q.** The piston rod of diameter 20 mm and length 700 mm in a hydraulic cylinder is subjected to a compressive force of 10 kN due to internal pressure. The piston end of the rod is guided along the cylinder and the other end of the rod is hinged at the cross-head. The modulus of elasticity for piston rod material is 200 GPa. Estimate the factor of safety taken for the piston rod design. [2 Marks]

**Ans.**

\[
\sigma = \frac{P}{A} \quad \delta = \frac{PL}{AE} \quad \ell_c = \frac{l}{\sqrt{2}} \quad P_e = \frac{\pi^2 EI}{L_c^2} \quad (\text{considering one end of the column is fixed and other end is hinged})
\]

\( P_e = \text{Euler Crippling load} \)

Compressive load, \( P_e = \sigma_c \times \text{Area} = 10 \text{ kN} \)

Euler's load, \( P_e = \frac{2\pi^2 \times (200 \times 10^9) \times \left(\pi \times 0.020^4 / 64\right)}{(0.7)^2} = 63.278 \text{ kN} \)

F.S = \frac{\text{Euler's load}}{\text{Compressive load}}

F.S = \frac{63.278}{10} = 6.3
Chapter-13 Theories of Column S K Mondal's

Conventional Question ESE-1999
Question: State the limitation of Euler's formula for calculating critical load on columns
Answer: Assumptions:
(i) The column is perfectly straight and of uniform cross-section
(ii) The material is homogenous and isotropic
(iii) The material behaves elastically
(iv) The load is perfectly axial and passes through the centroid of the column section.
(v) The weight of the column is neglected.

Conventional Question ESE-2007
Question: What is the value of Euler's buckling load for an axially loaded pin-ended (hinged at both ends) strut of length 'l' and flexural rigidity 'EI'? What would be order of Euler's buckling load carrying capacity of a similar strut but fixed at both ends in terms of the load carrying capacity of the earlier one?
Answer: From Euler's buckling load formula,
\[
P_{e} = \frac{\pi^2 EI}{\ell^2}
\]
Equivalent length \( \ell_e \) for both end hinged = \( \ell \)/2 for both end fixed.
So for both end hinged \( P_{e,beh} = \frac{\pi^2 EI}{(\ell/2)^2} \)
and for both fixed \( P_{e,bf} = \frac{4\pi^2 EI}{(\ell/2)^2} \)

Conventional Question ESE-1996
Question: Euler's critical load for a column with both ends hinged is found as 40 kN. What would be the change in the critical load if both ends are fixed?
Answer: We know that Euler's critical load,
\[
P_{Euler} = \frac{\pi^2 EI}{\ell^2}
\]  [Where E = modulus of elasticity, I = least moment of inertia \( \ell_e = \) equivalent length ]
For both end hinged (\( \ell_e = \ell \))
And For both end fixed (\( \ell_e = \ell /2 \))
\[
\therefore (P_{Euler})_{b.e.h.} = \frac{\pi^2 EI}{(\ell/2)^2} = 40 kN \text{(Given)}
\]
and \( (P_{Euler})_{b.e.f.} = \frac{\pi^2 EI}{(\ell/2)^2} = 4 \times \frac{\pi^2 EI}{\ell^2} = 4 \times 40 = 160 kN \)

Conventional Question ESE-1999
Question: A hollow cast iron column of 300 mm external diameter and 220 mm internal diameter is used as a column 4 m long with both ends hinged. Determine the safe compressive load the column can carry without buckling using Euler's formula and Rankine's formula
\( E = 0.7 \times 10^5 \text{ N/mm}^2 \), FOS = 4, Rankine constant \((a) = 1/1600 \)
Crushing Stress \( (\sigma_c) = 567 \text{ N/mm}^2 \)
Answer: Given outer diameter of column \( (D) = 300 \text{ mm} = 0.3 \text{ m} \).
Inner diameter of the column \( (d) = 220 \text{ mm} = 0.22 \text{ m} \).
Length of the column \( (\ell) = 4 \text{ m} \).
End conditions is both ends hinged. Therefore equivalent length \( (\ell_e) = \ell = 4 \text{ m} \).
Yield crushing stress \( (\sigma_c) = 567 \text{ MPa} = 567 \times 10^6 \text{ N/m}^2 \)
Rankine constant \((a) = 1/1600 \)

\[
\text{Safe compressive load} = \frac{\pi^2 EI}{\ell^2} = \frac{4\pi^2 EI}{(\ell/2)^2}
\]

\[
\text{Safe compressive load} = 4 \times \frac{\pi^2 EI}{\ell^2} = 4 \times 40 = 160 kN
\]
### Chapter-13 Theories of Column  
S K Mondal’s

Moment of Inertia \( I = \frac{\pi}{64} (D^4 - d^4) = \frac{\pi}{64} [0.3^4 - 0.22^4] = 2.826 \times 10^{-4} \, m^4 \)

Slenderness ratio \( k = \sqrt{\frac{I}{A}} = \sqrt{\frac{\frac{\pi}{64} (D^4 - d^4)}{\frac{\pi}{4} (D^2 - d^2)}} = \sqrt{\frac{D^2 + d^2}{16}} = \sqrt{\frac{0.3^2 + 0.22^2}{16}} = 0.093 m \)

Area \( A = \frac{\pi}{4} (D^2 - d^2) = \frac{\pi}{4} (0.3^2 - 0.22^2) = 0.03267 \, m^2 \)

(i) Euler’s buckling load, \( P_{Euler} = \frac{\pi^2 EI}{k^2} = \frac{\pi^2 \times (70 \times 10^6) \times (2.826 \times 10^{-4})}{4^2} = 12.2 \, MN \)

:. Safe load \( = \frac{P_{Euler}}{f_{os}} = 12.2 \times \frac{4}{4} = 3.05 \, MN \)

(ii) Rankine’s buckling load, \( P_{Rankine} = \frac{\sigma_{c} A}{(1 + \frac{k}{a} \frac{e}{L})^2} = \frac{(567 \times 10^6) \times 0.03267}{1 + \frac{1}{1600} \times \frac{4}{0.093}} = 8.59 \, MN \)

:. Safe load \( = \frac{P_{Rankine}}{f_{os}} = \frac{8.59}{4} = 2.148 \, MPa \)

**Conventional Question ESE-2008**

**Question:** A both ends hinged cast iron hollow cylindrical column 3 m in length has a critical buckling load of \( P \) kN. When the column is fixed at both the ends, its critical buckling load raise by 300 kN more. If ratio of external diameter to internal diameter is 1.25 and \( E = 100 \, GPa \) determine the external diameter of column.

**Answer:**  
\[ P_c = \frac{\pi^2 EI}{L^2} \]

For both end hinged column

\[ P = \frac{\pi^2 EI}{L^2} \quad \quad \quad \quad \quad (i) \]

For both end fixed column

\[ P + 300 = \frac{\pi^2 EI}{L^2} = \frac{4 \pi^2 EI}{L^2} \quad \quad \quad \quad \quad (ii) \]

**Dividing (ii) by (i) we get**

\[ \frac{P + 300}{P} = 4 \quad \text{or} \quad P = 100kN \]

Moment of inertia of a hollow cylinder c/s is

\[ I = \frac{\pi}{64} (D^4 - d^4) = \frac{PL^2}{\pi^2 E} \]

or \( D^4 - d^4 = \frac{64 \left(100 \times 10^3\right)^2}{\pi \left(\frac{100 \times 10^3}{\pi}\right)^2} = 1.8577 \times 10^{-5} \)
Conventional Question AMIE-1996

Question: A piston rod of steam engine 80 cm long is subjected to a maximum load of 60 kN. Determine the diameter of the rod using Rankine's formula with permissible compressive stress of 100 N/mm². Take constant in Rankine's formula as \( \frac{1}{7500} \) for hinged ends. The rod may be assumed partially fixed with length coefficient of 0.6.

Answer: Given: \( l = 80 \) cm = 800 mm; \( P = 60 \) kN = 60 \times 10³ N, \( \sigma_c = 100 \) N/mm²; 
\( a = \frac{1}{7500} \) for hinged ends; length coefficient = 0.6

To find diameter of the rod, \( d \):

Use Rankine's formula

\[
P = \frac{\sigma_c A}{1 + a \left( \frac{b}{k} \right)}
\]

Here \( l = 0.6l = 0.6 \times 800 = 480 \) mm [\( \because \) length coefficient = 0.6]

\[
k = \sqrt{\frac{1}{A}} = \sqrt{\frac{\pi d^4}{\frac{64}{\pi} d^2}} = \frac{d}{4}
\]

\[
\therefore \quad 60 \times 10^3 = \frac{100 \times \left( \frac{\pi}{4} d^2 \right)}{1 + \frac{1}{7500} \left[ \frac{480}{d/4} \right]^2}
\]

Solving the above equation we get the value of ‘\( d \)’

Note: Unit of \( d \) comes out from the equation will be mm as we put the equivalent length in mm.

or \( d = 33.23 \) mm

Conventional Question ESE-2005

Question: A hollow cylinder CI column, 3 m long its internal and external diameters as 80 mm and 100 mm respectively. Calculate the safe load using Rankine formula: if

(i) Both ends are hinged and
(ii) Both ends are fixed.

Take crushing strength of material as 600 N/mm², Rankine constant 1/1600 and factor of safety = 3.

Answer: Moment of Inertia (I)\( = \frac{\pi}{64}(0.1^4 - 0.08^4)m^4 = 2.898 \times 10^{-6} m^4 \)
Area \( (A) = \frac{\pi}{4}(0.1^2 - 0.08^2) = 2.8274 \times 10^{-3} \text{m}^2 \)

Radius of gyration \( (k) = \sqrt{\frac{I}{A}} = \sqrt{\frac{2.898 \times 10^{-6}}{2.8274 \times 10^{-3}}} = 0.032 \text{m} \)

\[
P_{\text{Rankine}} = \frac{\sigma_c \cdot A}{1 + \alpha \left(\frac{\ell_e}{k}\right)^2}; \quad [\ell_e = \text{equivalent length}]
\]

(i) \[
= \left(\frac{600 \times 10^6}{1 + \left(\frac{1}{1600}\right) \times \left(\frac{3}{0.032}\right)^2}\right) = 2.61026 \text{kN}
\]

Safe load \( (P) = \frac{P_{\text{Rankine}}}{\text{FOS}} = \frac{26126}{3} = 87.09 \text{kN} \)

(ii) For both end fixed, \( \ell_e = \frac{\ell}{2} = 1.5 \text{m} \)

\[
P_{\text{Rankine}} = \left(\frac{600 \times 10^6}{1 + \left(\frac{1}{1600}\right) \times \left(\frac{1.5}{0.032}\right)^2}\right) = 714.8 \text{kN}
\]

Safe load \( (P) = \frac{P_{\text{Rankine}}}{\text{FOS}} = \frac{714.8}{3} = 238.27 \text{kN} \)

**Conventional Question AMIE-1997**

**Question:** A slender column is built-in at one end and an eccentric load is applied at the free end. Working from the first principles find the expression for the maximum length of column such that the deflection of the free end does not exceed the eccentricity of loading.

**Answer:** Above figure shows a slender column of length 'l'. The column is built in at one end B and eccentric load P is applied at the free end A. Let \( y \) be the deflection at any section XX distant x from the fixed end B. Let \( \delta \) be the deflection at A.

The bending moment at the section XX is given by
The solution to the above differential equation is

\[ y = C_1 \cos \left( \frac{P}{\sqrt{EI}} \right) + C_2 \sin \left( \frac{P}{\sqrt{EI}} \right) + (\delta + e) \]  

Where \( C_1 \) and \( C_2 \) are the constants.

At the end B, \( x = 0 \) and \( y = 0 \)

\[ 0 = C_1 \cos 0 + C_2 \sin 0 + (\delta + e) \]

or

\[ C_1 = -(\delta + e) \]

Differentiating equation (ii) we get

\[ \frac{dy}{dx} = -C_1 \frac{P}{\sqrt{EI}} \sin \left( \frac{P}{\sqrt{EI}} \right) + C_2 \frac{P}{\sqrt{EI}} \cos \left( \frac{P}{\sqrt{EI}} \right) \]

Again, at the fixed end B,

When \( x = 0, \frac{dy}{dx} = 0 \)

\[ 0 = (\delta + e) \frac{P}{\sqrt{EI}} \times 0 + C_2 \frac{P}{\sqrt{EI}} \cos 0 \]

or

\[ C_2 = 0 \]

At the free end A, \( x = \ell, y = \delta \)

Substituting for \( x \) and \( y \) in equation (ii), we have

\[ \delta = -(\delta + e) \cos \left( \frac{P}{\sqrt{EI}} \right) = (\delta + e) \]

\[ \therefore \quad \cos \left( \frac{P}{\sqrt{EI}} \right) = \frac{e}{\delta + e} \]

It is mentioned in the problem that the deflection of the free end does not exceed the eccentricity. It means that \( \delta = e \)

Substituting this value in equation (iii), we have

\[ \cos \left( \frac{P}{\sqrt{EI}} \right) = \frac{1}{2} \]

\[ \therefore \quad \frac{P}{\sqrt{EI}} = \cos^{-1} \left( \frac{1}{2} \right) = \frac{\pi}{3} \]

\[ \ell = \frac{\pi}{3} \sqrt{\frac{EI}{P}} \]

Conventional Question ESE-2005

Question: A long strut AB of length \( '\ell' \) is of uniform section throughout. A thrust \( P \) is applied at the ends eccentrically on the same side of the centre line with eccentricity at the end B twice than that at the end A. Show that the maximum bending moment occurs at a distance \( x \) from the end A,

Where, \( \tan(kx) = \frac{2 - \cos k\ell}{\sin k\ell} \) and \( k = \frac{P}{\sqrt{EI}} \)
Chapter-13  

**Theories of Column**

**Answer:** Let at a distance 'x' from end A deflection of the beam is y

\[ \therefore EI \frac{d^2y}{dx^2} = -Py \]

or \[ \frac{d^2y}{dx^2} + \frac{P}{EI}y = 0 \]

or \[ \frac{d^2y}{dx^2} + k^2y = 0 \]

\[ \therefore k = \frac{P}{\sqrt{EI}} \text{ given} \]

C.F of this differential equation

\[ y = Ae^x \cos kx + Be^x \sin kx \]

Where A & B constant.

It is clear at \( x = 0 \), \( y = e \)

And at \( x = \ell \), \( y = 2e \)

\[ \therefore e = A \ldots \ldots \ldots (i) \]

\[ 2e = Acosk\ell + Bsink\ell \quad \text{or} \quad B = \frac{2e - e\cos k\ell}{\sin k\ell} \]

\[ \therefore y = e\cos kx + \left[ \frac{2e - e\cos k\ell}{\sin k\ell} \right] \sin kx \]

Where bending moment is maximum,

the deflection will be maximum so \( \frac{dy}{dx} = 0 \)

\[ \therefore \frac{dy}{dx} = -ek\sin kx + k\left[ \frac{2e - e\cos k\ell}{\sin k\ell} \right] \cos kx = 0 \]

or \( \tan kx = \frac{2 - \cos k\ell}{\sin k\ell} \)

**Conventional Question ESE-1996**

**Question:** The link of a mechanism is subjected to axial compressive force. It has solid circular cross-section with diameter 9 mm and length 200 mm. The two ends of the link are hinged. It is made of steel having yield strength = 400 N/mm² and elastic modulus = 200 kN/mm². Calculate the critical load that the link can carry. Use Johnson's equation.

**Answer:** According to Johnson's equation

\[ P_\sigma = \sigma_y A \left[ 1 - \frac{\sigma_y}{4n\pi^2E} \frac{(\ell)^2}{k^2} \right] \]

Hear A=area of cross section\(= \frac{\pi d^2}{4} = 63.62 \text{mm}^2 \)

least radius of gyration \( (k) = \sqrt{\frac{l}{A}} = \sqrt{\frac{\frac{\pi d^4}{64}}{\frac{d^4}{4}}} = \frac{d}{4} = 2.55 \text{mm} \)

For both end hinged \( n=1 \)

\[ \therefore P_\sigma = 400 \times 63.62 \left[ 1 - \frac{400}{4 \times 1 \times \pi^2 \times (200 \times 10^3) \times \left( \frac{200}{2.25} \right)^2} \right] = 15.262 \text{kN} \]

**Conventional Question GATE-1995**

**Question:** Find the shortest length of a hinged steel column having a rectangular cross-section 600 mm x 100 mm, for which the elastic Euler formula applies. Take
Chapter-13 Theories of Column S K Mondal's

yield strength and modulus of elasticity value for steel as 250 MPa and 200 GPa respectively.

Answer: Given: Cross-section, (= b x d) = 600 mm x 100 mm = 0.6 m x 0.1 m = 0.06 m²;

Yield strength = \( \frac{P}{A} = 250 \text{MPa} = 250 \text{MN/m}^2; \) \( E = 200 \text{GPa} = 200 \times 10^{12} \text{N/m}^2 \)

Length of the column, \( L \):

Least area moment of Inertia, \( I = \frac{bd^3}{12} = \frac{0.6 \times 0.1^3}{12} = 5 \times 10^{-5} \text{m}^4 \)

Also, \( k^2 = \frac{I}{A} = \frac{5 \times 10^{-5}}{0.6 \times 0.1} = 8.333 \times 10^{-4} \text{m}^2 \)

[ \therefore \] \( I = AK^2 \) (where \( A = \) area of cross-section, \( k = \) radius of gyration])

From Euler's formula for column, we have

Crushing load, \( P_{cr} = \frac{\pi^2 EI}{L_o^2} = \frac{\pi^2 E I}{L^2} \)

For both end hinged type of column, \( L_o = L \)

or \( P_{cr} = \frac{\pi^2 EA k^2}{L^2} \)

or \( \text{Yield stress} \left( \frac{P_{cr}}{A} \right) = \frac{\pi^2 E I}{L^2} \)

or \( L^2 = \frac{\pi^2 Ek^2}{\left( \frac{P_{cr}}{A} \right)} \)

Substituting the value, we get

\( L^2 = \frac{\pi^2 \times 200 \times 10^9 \times 0.0008333}{250 \times 10^6} = 6.58 \)

\( L = 2.565 \text{ m} \)

Conventional Question GATE-1993

Question: Determine the temperature rise necessary to induce buckling in a 1m long circular rod of diameter 40 mm shown in the Figure below. Assume the rod to be pinned at its ends and the coefficient of thermal expansion as 20 \( \times 10^{-6} /° \text{C} \). Assume uniform heating of the bar.

Answer: Let us assume the buckling load be'\( P'\).
\[ \delta L = L \cdot \infty \cdot \Delta t, \quad \text{Where} \quad \Delta t \quad \text{is the temperature rise.} \]

or

\[ \Delta t = \frac{\delta L}{L \cdot \infty} \]

Also,

\[ \delta L = \frac{PL}{AE} \quad \text{or} \quad P = \frac{\delta LAE}{L} \]

\[ P_{\varphi} = \frac{\pi^2 EI}{L^2_{\varphi}} \quad \text{(where} \quad L_{\varphi} \quad \text{= equivalent length)} \]

or

\[ \frac{\pi^2 EI}{L^2} = \frac{\delta LAE}{L} \quad \text{[QL}_{\varphi} = L \quad \text{For both endhinged]} \]

or

\[ \delta L = \frac{\pi^2 I}{LA} \]

\[ \Delta t = \frac{\delta L}{L \cdot \infty} = \frac{\pi^2 I}{L \cdot \infty \cdot L \cdot \infty} = \frac{\pi^2 I}{L^2 A \cdot \infty} \]

Substituting the values, we get

Temperature rise \[ \Delta t = \frac{\pi^2 \times \pi \times (0.040)^4}{64 \times (1)^2 \times \pi \times (0.040)^4 \times 20 \times 10^{-6}} = 49.35^0 \text{C} \]

So the rod will buckle when the temperature rises more than 49.35°C.
14. Strain Energy Method

Theory at a Glance (for IES, GATE, PSU)

1. Resilience (U)
   - Resilience is an ability of a material to absorb energy when elastically deformed and to return it when unloaded.
   - The strain energy stored in a specimen when strained within the elastic limit is known as resilience.
   \[
   U = \frac{\sigma^2}{2E} \times \text{Volume} \quad \text{or} \quad U = \frac{\varepsilon^2}{2} \times \text{Volume}
   \]

2. Proof Resilience
   - Maximum strain energy stored at elastic limit. i.e. the strain energy stored in the body up to elastic limit.
   - This is the property of the material that enables it to resist shock and impact by storing energy. The measure of proof resilience is the strain energy absorbed per unit volume.

3. Modulus of Resilience (u)
   The proof resilience per unit volume is known as modulus of resilience. If \( \sigma \) is the stress due to gradually applied load, then
   \[
   u = \frac{\sigma^2}{2E} \quad \text{or} \quad u = \frac{\varepsilon^2}{2} \times \frac{E}{E}
   \]

4. Application
   \[
   U = \frac{p^2L}{2AE} = \frac{p^2}{4} \left( \frac{3L}{4} \right) + \frac{p^2}{4} \left( \frac{L}{4} \right)
   \]
   \[
   U = \frac{p^2}{2} \left( \frac{\pi}{4} \right) \left( \frac{2d + \pi d^2}{4} \right) E
   \]

Strain energy becomes smaller & smaller as the cross sectional area of bar is increased over more & more of its length i.e. \( A \uparrow, U \downarrow \)

5. Toughness
   - This is the property which enables a material to be twisted, bent or stretched under impact load or high stress before rupture. It may be considered to be the ability of the material to
Chapter-14  
**Strain Energy Method**

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absorb energy in the plastic zone. The measure of toughness is the amount of energy absorbed after being stressed up to the point of fracture.

- Toughness is an ability to absorb energy in the plastic range.
- The ability to withstand occasional stresses above the yield stress without fracture.
- Toughness = strength + ductility
- The materials with higher modulus of toughness are used to make components and structures that will be exposed to sudden and impact loads.

**Modulus of Toughness**

- The ability of unit volume of material to absorb energy in the plastic range.
- The amount of work per unit volume that the material can withstand without failure.
- The area under the entire stress strain diagram is called *modulus of toughness*, which is a measure of energy that can be absorbed by the unit volume of material due to impact loading before it fractures.

6. **Strain energy in shear and torsion**

- Strain energy per unit volume, \( u_s \)

\[
  u_s = \frac{\tau^2}{2G} \quad \text{or} \quad u_s = \frac{G\gamma^2}{2}
\]

- Total Strain Energy (U) for a Shaft in Torsion

\[
  U_s = \frac{1}{2} T \phi
\]

\[\therefore U_s = \frac{1}{2} \left( \frac{T^2 L}{GJ} \right) \quad \text{or} \quad \frac{1}{2} \frac{GJ\phi^2}{L} \]

or

\[
  U_s = \frac{\tau_{\text{max}}^2}{2G} \frac{2\pi L}{r^2} \int \rho^3 d\rho
\]

- **Cases**

  - **Solid shaft**, \( U_s = \frac{\tau_{\text{max}}^2}{4G} \times \pi r^2 L \)

  - **Hollow shaft**, \( U_s = \frac{\tau_{\text{max}}^2}{4G} \times \frac{\pi (D^4 - d^4)}{D^2} L = \frac{\tau_{\text{max}}^2}{4G} \times \frac{(D^2 + d^2)}{D^2} \times \text{Volume} \)
• Thin walled tube, \( U_s = \frac{\tau^2}{4G} \times sL t \)
  
  where \( s \) = Length of mean centre line

• Conical spring, \( U_s = \frac{GJ}{2} \int \left( \frac{d\phi}{dx} \right)^2 dx = \frac{GJ}{2} \int_0^{2\pi/h} \left( \frac{PR}{GJ} \right)^2 R \, d\alpha \) (\( R = \text{Radius} \))
  
  \[ = \frac{p^2}{2GJ} \int_0^{2\pi} R^3 \, d\alpha \] (\( R \) varies with \( \alpha \))

• Cantilever beam with load 'p' at end, \( U_s = \frac{3}{5} \left( \frac{P^2L}{bhG} \right) \)

• Helical spring, \( U_s = \frac{\pi P^2 R^3 n}{GJ} \) (\( \therefore L = 2\pi Rn \))

7. Strain energy in bending.

• Angle subtended by arc, \( \theta = \int \frac{M_x}{EI} \, dx \)

• Strain energy stored in beam.

  \[ U_b = \int_0^L \frac{M_x^2}{2EI} \, dx \]

  or \( U_b = \frac{EI}{2} \int_0^L \left( \frac{d^2 y}{dx^2} \right)^2 dx \)

  \( \because \frac{d^2 y}{dx^2} = -\frac{M}{EI} \)

• Cases

  o Cantilever beam with a end load \( P \), \( U_b = \frac{P^2L^3}{6EI} \)

  o Simply supported with a load \( P \) at centre, \( U_b = \frac{P^2L^3}{96EI} \)

• Important Note

  o For pure bending

    • \( M \) is constant along the length 'L'

    • \( \theta = \frac{ML}{EI} \)

    • \( U = \frac{M^2L}{2EI} \) if \( M \) is known = \( \frac{EL\theta^2}{2L} \) if curvature \( \theta / L \) is known

  o For non-uniform bending

    • Strain energy in shear is neglected

    • Strain energy in bending is only considered.

8. Castiglione’s theorem

\[ \frac{\partial U}{\partial P_n} = \delta_n \]
\[ \frac{\partial U}{\partial p} = \frac{1}{EI} \int M_x \left( \frac{\partial M_x}{\partial p} \right) dx \]

- **Note:**
  o Strain energy, stored due to direct stress in 3 coordinates
    \[ U = \frac{1}{2E} \left[ \sum (\sigma_x)^3 - 2\mu \sum \sigma_x \sigma_y \right] \]
  o If \( \sigma_x = \sigma_y = \sigma_z \), in case of equal stress in 3 direction then
    \[ U = \frac{3\sigma^2}{2E} \left[ 1 - 2\mu \right] = \frac{\sigma^2}{2k} \] (volume strain energy)
Strain Energy or Resilience

GATE-1. The strain energy stored in the beam with flexural rigidity $EI$ and loaded as shown in the figure is: [GATE-2008]

\[
\begin{align*}
(a) & \quad \frac{P^2L^3}{3EI} \\
(b) & \quad \frac{2P^2L^3}{3EI} \\
(c) & \quad \frac{4P^2L^3}{3EI} \\
(d) & \quad \frac{8P^2L^3}{3EI}
\end{align*}
\]

GATE-1. Ans. (c) \[
\int_0^L \frac{M^2}{EI} dx = \int_0^\frac{L}{4} \frac{M^2}{EI} dx + \int_\frac{L}{4}^\frac{3L}{4} \frac{M^2}{EI} dx + \int_\frac{3L}{4}^L \frac{M^2}{EI} dx \\
= 2 \int_0^{\frac{L}{4}} \frac{M^2}{EI} dx \quad \text{By symmetry} \int_0^L \frac{M^2}{EI} dx = \frac{4}{3} \int_0^L \frac{M^2}{EI} dx
\]

\[
= 2 \int_0^L \left(\frac{P}{E} \right)^2 \frac{L}{2} dx = \frac{4P^2L^3}{3EI}
\]

GATE-2. $\frac{PL^3}{3EI}$ is the deflection under the load $P$ of a cantilever beam [length $L$, modulus of elasticity, $E$, moment of inertia-$I$]. The strain energy due to bending is: [GATE-1993]

\[
\begin{align*}
(a) & \quad \frac{P^2L^3}{3EI} \\
(b) & \quad \frac{P^2L^3}{6EI} \\
(c) & \quad \frac{P^2L^3}{4EI} \\
(d) & \quad \frac{P^2L^3}{48EI}
\end{align*}
\]

GATE-2. Ans. (b) We may do it taking average

\[
\text{Strain energy} = \text{Average force} \times \text{displacement} = \left(\frac{P}{2}\right) \times \frac{PL^3}{3EI} = \frac{P^2L^3}{6EI}
\]

Alternative method: In a funny way you may use Castiglione's theorem, $\delta = \delta \frac{\partial U}{\partial P}$. Then

\[
\delta = \frac{\partial U}{\partial P} = \frac{PL^3}{3EI} \quad \text{or} \quad U = \int \partial U = \int \frac{PL^3}{3EI} \partial P \quad \text{Partially integrating with respect to P we get}
\]

\[
U = \frac{P^2L^3}{6EI}
\]
GATE-3. The stress-strain behaviour of a material is shown in figure. Its resilience and toughness, in Nm/m^3, are respectively:
(a) 28 \times 10^4, 76 \times 10^4
(b) 28 \times 10^4, 48 \times 10^4
(c) 14 \times 10^4, 90 \times 10^4
(d) 76 \times 10^4

GATE-3. Ans. (c) Resilience = area under this curve up to 0.004 strain
= \frac{1}{2} \times 0.004 \times 70 \times 10^6 = 14 \times 10^4 \text{ Nm/m}^3

Toughness = area under this curve up to 0.012 strain
= 14 \times 10^4 + 70 \times 10^6 \times (0.012 - 0.004) + \frac{1}{2} \times (0.012 - 0.004) \times (120 - 70) \times 10^6 \text{ Nm/m}^3
= 90 \times 10^4 \text{ Nm/m}^3

GATE-4. A square bar of side 4 cm and length 100 cm is subjected to an axial load P. The same bar is then used as a cantilever beam and subjected to all end load P. The ratio of the strain energies, stored in the bar in the second case to that stored in the first case, is:
(a) 16 (b) 400 (c) 1000 (d) 2500

GATE-4. Ans. (d) \[ U_1 = \frac{W^2}{2E} \] \[ U_2 = \frac{W^2L^3}{6EI} = \frac{W^2L^3}{2W^2L^3} = \frac{12}{1}a^4 \] \[ \sigma \]

\[ a^2 \]

or \[ \frac{U_2}{U_1} = \frac{4L^2}{a^2} = 4 \left( \frac{100}{4} \right)^2 = 2500 \]

Toughness
GATE-5. The total area under the stress-strain curve of a mild steel specimen tested up to failure under tension is a measure of:
(a) Ductility (b) Ultimate strength (c) Stiffness (d) Toughness

GATE-5. Ans. (d)

Previous 20-Years IES Questions

Strain Energy or Resilience
IES-1. What is the strain energy stored in a body of volume V with stress \( \sigma \) due to gradually applied load?

(a) \( \frac{\sigma E}{V} \) (b) \( \frac{\sigma E^2}{V} \) (c) \( \frac{\sigma V^2}{E} \) (d) \( \frac{\sigma^2 V}{2E} \)

Where, \( E \) = Modulus of elasticity

IES-1. Ans. (d) Strain Energy = \( \frac{1}{2} \frac{\sigma^2}{E} \times V \)

IES-2. A bar having length L and uniform cross-section with area A is subjected to both tensile force P and torque T. If G is the shear modulus and E is the Young's modulus, the internal strain energy stored in the bar is:

IES-2. A bar having length L and uniform cross-section with area A is subjected to both tensile force P and torque T. If G is the shear modulus and E is the Young's modulus, the internal strain energy stored in the bar is:
Chapter-14 Strain Energy Method

(а) \( \frac{T^2L}{2GJ} + \frac{P^2L}{AE} \)  \hspace{1cm} (b) \( \frac{T^2L}{GJ} + \frac{P^2L}{2AE} \)  \hspace{1cm} (c) \( \frac{T^2L}{2GJ} + \frac{P^2L}{2AE} \)  \hspace{1cm} (d) \( \frac{T^2L}{GJ} + \frac{P^2L}{AE} \)

IES-2. Ans. (c) Internal strain energy = \( \frac{1}{2}P\delta + \frac{1}{2}T\theta = \frac{1}{2}P\frac{PL}{AE} + \frac{1}{2}T\frac{TL}{GJ} \)

IES-3. Strain energy stored in a body of volume \( V \) subjected to uniform stress \( s \) is:

(a) \( s\frac{E}{V} \)  \hspace{1cm} (b) \( s\frac{E^2}{V} \)  \hspace{1cm} (c) \( s\frac{V^2}{E} \)  \hspace{1cm} (d) \( s^2\frac{V}{2E} \)

IES-3. Ans. (d)

IES-4. A bar of length \( L \) and of uniform cross-sectional area \( A \) and second moment of area \( T \) is subjected to a pull \( P \). If Young's modulus of elasticity of the bar material is \( E \), the expression for strain energy stored in the bar will be:

(a) \( \frac{P^2L}{2AE} \)  \hspace{1cm} (b) \( \frac{PL^2}{2EI} \)  \hspace{1cm} (c) \( \frac{PL^2}{AE} \)  \hspace{1cm} (d) \( \frac{P^2L}{AE} \)

IES-4. Ans. (a) Strain energy = \( \frac{1}{2} \times \text{stress} \times \text{strain} \times \text{volume} = \frac{1}{2} \times \left( \frac{P}{A} \right) \times \left( \frac{P}{A} \frac{L}{E} \right) \times (AL) = \frac{PL^2}{2AE} \)

IES-5. Which one of the following gives the correct expression for strain energy stored in a beam of length \( L \) and of uniform cross-section having moment of inertia \( T \) and subjected to constant bending moment \( M \)?

(a) \( \frac{ML}{EI} \)  \hspace{1cm} (b) \( \frac{2ML}{EI} \)  \hspace{1cm} (c) \( \frac{M^2L}{EI} \)  \hspace{1cm} (d) \( \frac{M^2L}{2EI} \)

IES-5. Ans. (d)

IES-6. A steel specimen 150 \( mm^2 \) in cross-section stretches by 0.05 mm over a 50 mm gauge length under an axial load of 30 kN. What is the strain energy stored in the specimen? (Take \( E = 200 \) GPa)

(a) 0.75 N-m  \hspace{1cm} (b) 1.00 N-m  \hspace{1cm} (c) 1.50 N-m  \hspace{1cm} (d) 3.00 N-m

IES-6. Ans. (a) Strain Energy stored in the specimen

\[
\frac{1}{2}P\delta = \frac{1}{2}P\frac{PL}{AE} = \frac{P^2L}{2AE} = \frac{(30000)^2 \times 50 \times 10^{-3}}{2 \times 150 \times 10^{-6} \times 200 \times 10^{-6}} = 0.75 \text{ N-m}
\]

IES-7. What is the expression for the strain energy due to bending of a cantilever beam (length \( L \), modulus of elasticity \( E \) and moment of inertia \( I \))?  

(a) \( \frac{P^2L^3}{3EI} \)  \hspace{1cm} (b) \( \frac{P^2L^3}{6EI} \)  \hspace{1cm} (c) \( \frac{P^2L^3}{4EI} \)  \hspace{1cm} (d) \( \frac{P^2L^3}{48EI} \)

IES-7. Ans. (b) Strain Energy Stored \( \int_0^L \frac{(Px)^2}{2E} \, dx = \frac{P^2}{2EI} \left( \frac{x^3}{3} \right)^L_0 = \frac{P^2L^3}{6EI} \)

IES-8. The property by which an amount of energy is absorbed by a material without plastic deformation, is called:

(a) Toughness  \hspace{1cm} (b) Impact strength  \hspace{1cm} (c) Ductility  \hspace{1cm} (d) Resilience

IES-8. Ans. (d)

IES-9. 30 C 8 steel has its yield strength of 400 N/mm\(^2\) and modulus of elasticity of 2 \( \times \) \( 10^5 \) MPa. Assuming the material to obey Hooke’s law up to yielding, what is its proof resilience?

(a) 0.8 N/mm\(^2\)  \hspace{1cm} (b) 0.4 N/mm\(^2\)  \hspace{1cm} (c) 0.6 N/mm\(^2\)  \hspace{1cm} (d) 0.7 N/mm\(^2\)

IES-9. Ans. (b) Proof resilience \( (R_p) = \frac{1}{2} \frac{\sigma^2}{E} = \frac{1}{2} \frac{\left(400\right)^2}{2 \times 2 \times 10^5} = 0.4 N / mm^2 \)
Chapter-14  Strain Energy Method  S K Mondal's

**Toughness**

IES-10. Toughness for mild steel under uni-axial tensile loading is given by the shaded portion of the stress-strain diagram as shown in [IES-2003]

(a) ![Stress-Strain Diagram](image)

(b) ![Stress-Strain Diagram](image)

(c) ![Stress-Strain Diagram](image)

(d) ![Stress-Strain Diagram](image)

IES-10. Ans. (d) Toughness of material is the total area under stress-strain curve.

---

**Previous 20-Years IAS Questions**

**Strain Energy or Resilience**

**IAS-1.** Total strain energy stored in a simply supported beam of span, 'L' and flexural rigidity 'EI' subjected to a concentrated load 'W' at the centre is equal to:

(a) \(\frac{W^2L^3}{40EI}\)  
(b) \(\frac{W^2L^3}{60EI}\)  
(c) \(\frac{W^2L^3}{96EI}\)  
(d) \(\frac{W^2L^3}{240EI}\)

IAS-1. Ans. (c) Strain energy = \(\frac{1}{2} \int_0^L \sigma^2 \varepsilon dx = \frac{1}{2} \int_0^L \left( \frac{M}{EI} \right)^2 dx = \frac{W^2L^3}{96EI}\)

Alternative method: In a funny way you may use Castiglione's theorem, \(\delta = \frac{\partial U}{\partial P} = \frac{\partial U}{\partial W}\)

We know that \(\delta = \frac{WL^3}{48EI}\) for simply supported beam in concentrated load at mid span.

Then \(\delta = \frac{\partial U}{\partial P} = \frac{W^2L^2}{48EI}\) or \(U = \int \frac{W^2L^2}{48EI} dW\) partially integrating with respect to \(W\) we get \(U = \frac{W^2L^3}{96EI}\)

**IAS-2.** If the cross-section of a member is subjected to a uniform shear stress of intensity 'q' then the strain energy stored per unit volume is equal to (\(G =\) modulus of rigidity).

(a) \(2q^2/G\)  
(b) \(2G / q^2\)  
(c) \(q^2 /2G\)  
(d) \(G/2 q^2\)

IAS-2. Ans. (c)

**IAS-3.** The strain energy stored in the beam with flexural rigidity EI and loaded as shown in the figure is:

[GATE-2008]
IAS-3. Ans. (c) \[
\int_0^L \frac{M^2}{EI} \, dx = \int_0^L \frac{L^2}{EI} \, dx + \int_0^L \frac{M^2}{EI} \, dx + \int_0^L \frac{4L^2}{EI} \, dx
\]
\[
= 2 \int_0^L \frac{M^2}{EI} \, dx + \int_0^L \frac{4L^2}{EI} \, dx \quad \text{By symmetry} \int_0^L \frac{M^2}{EI} \, dx = \int_0^{3L} \frac{M^2}{EI} \, dx
\]
\[
= 2 \int_0^L \frac{(Px)^2}{EI} \, dx + \int_0^L \frac{(PL)^2}{EI} \, dx = \frac{4P^2L^3}{3EI}
\]

IAS-4. Which one of the following statements is correct? [IAS-2004]
The work done in stretching an elastic string varies
(a) As the square of the extension  
(b) As the square root of the extension  
(c) Linearly with the extension  
(d) As the cube root of the extension
IAS-4. Ans. (a) \[
\frac{\sigma^2}{2E} = \frac{1}{2} \frac{\varepsilon^2}{E} = \frac{1}{2} \left( \frac{\delta l}{L} \right)^2 E
\]

**Toughness**

IAS-5. Match List-I with List-II and select the correct answer using the codes given below the lists: [IAS-1996]

<table>
<thead>
<tr>
<th>List-I (Mechanical properties)</th>
<th>List-II (Meaning of properties)</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Ductility</td>
<td>1. Resistance to indentation</td>
</tr>
<tr>
<td>B. Hardness</td>
<td>2. Ability to absorb energy during plastic deformation</td>
</tr>
<tr>
<td>C. Malleability</td>
<td>3. Percentage of elongation</td>
</tr>
<tr>
<td>D. Toughness</td>
<td>4. Ability to be rolled into flat product</td>
</tr>
</tbody>
</table>

Codes: A B C D  A B C D  
(a) 1 4 3 2  (b) 3 2 4 1  
(c) 2 3 4 1  (d) 3 1 4 2
IAS-5. Ans. (d)

IAS-6. Match List-I (Material properties) with List-II (Technical definition/requirement) and select the correct answer using the codes below the lists: [IAS-1999]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Hardness</td>
<td>1. Percentage of elongation</td>
</tr>
<tr>
<td>B. Toughness</td>
<td>2. Resistance to indentation</td>
</tr>
<tr>
<td>C. Malleability</td>
<td>3. Ability to absorb energy during plastic deformation</td>
</tr>
<tr>
<td>D. Ductility</td>
<td>4. Ability to be rolled into plates</td>
</tr>
</tbody>
</table>

Codes: A B C D  A B C D  
(a) 3 2 1 4  (b) 2 3 4 1  
(c) 2 4 3 1  (d) 1 3 4 2
IAS-6. Ans. (b)

IAS-7. A truck weighing 150 kN and travelling at 2m/sec impacts which a buffer spring which compresses 1.25cm per 10 kN. The maximum compression of the spring is: [IAS-1995]
(a) 20.00 cm  
(b) 22.85 cm  
(c) 27.66 cm  
(d) 30.00 cm

IAS-7. Ans. (c) Kinetic energy of the truck = strain energy of the spring

\[ \frac{1}{2}mv^2 = \frac{1}{2}kx^2 \text{ or } x = \sqrt{\frac{mv^2}{k}} = \sqrt{\left(\frac{150 \times 10^3}{9.81}\right) \times \left(\frac{10 \times 1000}{0.0125}\right)^2} = 0.2766 \text{ m} = 27.66 \text{ cm} \]
Conventional Question IES 2009
Q. A close coiled helical spring made of wire diameter $d$ has mean coil radius $R$, number of turns $n$ and modulus of rigidity $G$. The spring is subjected to an axial compression $W$.
(1) Write the expression for the stiffness of the spring.
(2) What is the magnitude of the maximum shear stress induced in the spring wire neglecting the curvature effect? [2 Marks]

Ans. (1) Spring stiffness, $K = \frac{W}{X} = \frac{Gd^4}{8nD^3}$
(2) Maximum shear stress, $\tau = \frac{8WD}{\pi d^3}$

Conventional Question IES 2010
Q. A semicircular steel ring of mean radius $300$ mm is suspended vertically with the top end fixed as shown in the above figure and carries a vertical load of $200$ N at the lowest point. Calculate the vertical deflection of the lower end if the ring is of rectangular cross-section $20$ mm thick and $30$ mm wide. Value of Elastic modulus is $2 \times 10^5$ N/mm$^2$. Influence of circumferential and shearing forces may be neglected. [10 Marks]

Ans. Load applied, $F = 200$ N
Mean Radius, $R = 300$ mm
Elastic modules, $E = 2 \times 10^5$ N/mm$^2$
$I = \text{Inertia of moment of cross-section}$

\[ I = \frac{bd^3}{12} \]
\[ b = 20 \text{ mm} \]
\[ d = 30 \text{ mm} \]
\[ = \frac{20 \times (30)^3}{12} = 45,000 \text{ mm}^4 \]

$\Rightarrow$ Influence of circumferential and shearing force are neglected strain energy at the section.
Chapter-14 Strain Energy Method

Strain Energy stored by beam AB,

\[ U = \text{Strain energy stored by AC} (U_{AC}) + \text{strain energy stored by BC} (U_{BC}) \]

\[ = \int_0^a \left( \frac{P_b}{L} x \right)^2 \frac{dx}{2EI} + \int_a^L \left( \frac{P_a}{L} x \right)^2 \frac{dx}{2EI} = \frac{P^2 b^2 a^3}{6EI L^2} + \frac{P^2 b^2 a^3}{6EI L^2} \]

\[ = \frac{P^2 b^2 a^2}{6EI L^2} (a + b) = \frac{P^2 b^2 a^2}{6EI L^2} = \frac{P^2 (L - b)^2 b^2}{6EI L} \]

\[ \therefore (a + b) = L \]

Deflection under the load \( P \), \( \delta = y = \frac{\partial U}{\partial P} = \frac{2P(L - b)^2 b^2}{6EI L} = \frac{P(L - b)^2 b^2}{3EI L} \)

Deflection at the mid-span of the beam can be found by Macaulay's method.

By Macaulay's method, deflection at any section is given by
Where $y$ is deflection at any distance $x$ from the support.

At $x = \frac{L}{2}$, i.e. at mid-span,

$$EIy = \frac{Pbx^3}{6L} - \frac{Pb}{6L}(L^2 - b^2)x - \frac{P(x - a)^3}{6}$$

or,

$$EIy = \frac{Pb\times(L/2)^3}{6L} - \frac{Pb}{6L}(L^2 - b^2)\times\frac{L}{2} - \frac{P\left(\frac{L}{2} - a\right)^3}{6}$$

$$y = \frac{P}{48EI}\left[bL^2 - 4b(L^2 - b^2) - (L - 2a)^3\right]$$
**15. Theories of Failure**

**Theory at a Glance (for IES, GATE, PSU)**

1. **Introduction**
   - **Failure**: Every material has certain strength, expressed in terms of stress or strain, beyond which it fractures or fails to carry the load.
   - **Failure Criterion**: A criterion used to hypothesize the failure.
   - **Failure Theory**: A Theory behind a failure criterion.

**Why Need Failure Theories?**
- To design structural components and calculate margin of safety.
- To guide in materials development.
- To determine weak and strong directions.

**Failure Mode**
- **Yielding**: a process of global permanent plastic deformation. Change in the geometry of the object.
- **Low stiffness**: excessive elastic deflection.
- **Fracture**: a process in which cracks grow to the extent that the component breaks apart.
- **Buckling**: the loss of stable equilibrium. Compressive loading can lead to bucking in columns.
- **Creep**: a high-temperature effect. Load carrying capacity drops.

<table>
<thead>
<tr>
<th>Failure Modes:</th>
<th>Yielding</th>
<th>Fracture</th>
</tr>
</thead>
<tbody>
<tr>
<td>Excessive elastic deformation</td>
<td>• Plastic deformation at room temperature&lt;br&gt;• Creep at elevated temperatures&lt;br&gt;• Yield stress is the important design factor</td>
<td>• Sudden fracture of brittle materials&lt;br&gt;• Fatigue (progressive fracture)&lt;br&gt;• Stress rupture at elevated temperatures&lt;br&gt;• Ultimate stress is the important design factor</td>
</tr>
</tbody>
</table>

1. **Stretch, twist, or bending**
2. **Buckling**
3. **Vibration**

2. **Maximum Principal Stress Theory**
   - **(W. Rankin’s Theory - 1850) – Brittle Material**
   - The maximum principal stress criterion:
Chapter-15  Theories of Failure  S K Mondal’s

- Rankin stated max principal stress theory as follows- a material fails by fracturing when the largest principal stress exceeds the ultimate strength $\sigma_u$ in a simple tension test. That is, at the onset of fracture, $|\sigma_1| = \sigma_u$ OR $|\sigma_3| = \sigma_u$
- Crack will start at the most highly stressed point in a brittle material when the largest principal stress at that point reaches $\sigma_u$
- Criterion has good experimental verification, even though it assumes ultimate strength is same in compression and tension

![Failure surface according to maximum principal stress theory](image)

- This theory of yielding has very poor agreement with experiment. However, the theory has been used successfully for brittle materials.
- Used to describe fracture of **brittle materials** such as cast iron
- **Limitations**
  - Doesn’t distinguish between tension or compression
  - Doesn’t depend on orientation of principal planes so only applicable to isotropic materials
- Generalization to 3-D stress case is easy:

![3-D stress case](image)

3. Maximum Shear Stress or Stress difference theory  
(Guest’s or Tresca’s Theory-1868)- Ductile Material

**The Tresca Criterion:**

- Also known as the **Maximum Shear Stress** criterion.
- Yielding will occur when the maximum shear stress reaches that which caused yielding in a simple tension test.
Chapter-15  Theories of Failure  S K Mondal’s

- Recall that yielding of a material occurred by slippage between planes oriented at 45° to principal stresses. This should indicate to you that yielding of a material depends on the maximum shear stress in the material rather than the maximum normal stress.
  
  If \( \sigma_1 > \sigma_2 > \sigma_3 \) Then \( \sigma_1 - \sigma_3 = \sigma_y \)

- Failure by slip (yielding) occurs when the maximum shearing stress, \( \tau_{\text{max}} \) exceeds the yield stress \( \tau_y \) as determined in a uniaxial tension test.

- This theory gives satisfactory result for ductile material.

![Failure surface according to maximum shear stress theory](image)

4. Strain Energy Theory (Haigh’s Theory)

The theory associated with Haigh

This theory is based on the assumption that strains are recoverable up to the elastic limit, and the energy absorbed by the material at failure up to this point is a single valued function independent of the stress system causing it. The strain energy per unit volume causing failure is equal to the strain energy at the elastic limit in simple tension.

\[
U = \frac{1}{2E} \left[ \sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\mu (\sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_3 \sigma_1) \right] = \frac{\sigma_y^2}{2E}
\]

\[
\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\mu (\sigma_1 \sigma_2 + \sigma_2 \sigma_3 + \sigma_3 \sigma_1) = \sigma_y^2 \quad \text{For 3D- stress}
\]

\[
\sigma_1^2 + \sigma_2^2 - 2\mu (\sigma_1 \sigma_2) = \sigma_y^2 \quad \text{For 2D- stress}
\]

5. Shear Strain Energy Theory (Distortion Energy Theory or Mises-Henky Theory or Von-Misses Theory)-Ductile Material

Von-Mises Criterion:

- Also known as the Maximum Energy of Distortion criterion
- Based on a more complex view of the role of the principal stress differences.
Chapter-15  Theories of Failure  S K Mondal’s

- In simple terms, the von Mises criterion considers the diameters of all three Mohr’s circles as contributing to the characterization of yield onset in isotropic materials.
- When the criterion is applied, its relationship to the uniaxial tensile yield strength is:

\[(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_1 - \sigma_3)^2 = 2\sigma_y^2\]

- For a state of plane stress \((\sigma_3 = 0)\)

\[\sigma_1^2 - \sigma_1\sigma_2 + \sigma_2^2 = \sigma_y^2\]

- It is often convenient to express this as an equivalent stress, \(\sigma_e\):

\[\sigma_e = \frac{1}{\sqrt{2}} \left[ (\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \right]^{1/2}\]

\[or \sigma_e = \frac{1}{\sqrt{2}} \left[ (\sigma_x - \sigma_y)^2 + (\sigma_y - \sigma_z)^2 + (\sigma_z - \sigma_x)^2 + 6(\tau_{xy}^2 + \tau_{yx}^2 + \tau_{zx}^2) \right]^{1/2}\]

- In formulating this failure theory we used generalized Hooke’s law for an isotropic material so the theory given is only applicable to those materials but it can be generalized to anisotropic materials.
- The von Mises theory is a little less conservative than the Tresca theory but in most cases there is little difference in their predictions of failure. Most experimental results tend to fall on or between these two theories.
- It gives very good result in ductile material.

6. Maximum Principal Strain Theory (St. Venant Theory)
According to this theory, yielding will occur when the maximum principal strain just exceeds the strain at the tensile yield point in either simple tension or compression. If \(\varepsilon_1\) and \(\varepsilon_2\) are maximum and minimum principal strains corresponding to \(\sigma_1\) and \(\sigma_2\), in the limiting case

\[\varepsilon_1 = \frac{1}{E}(\sigma_1 - \nu\sigma_2) \quad |\sigma_1| > |\sigma_2|\]

\[\varepsilon_2 = \frac{1}{E}(\sigma_2 - \nu\sigma_1) \quad |\sigma_2| > |\sigma_1|\]

This gives, \(E\varepsilon_1 = \sigma_1 - \nu\sigma_2 = \pm\sigma_y\)
\(E\varepsilon_2 = \sigma_2 - \nu\sigma_1 = \pm\sigma_y\)
7. Mohr’s theory- Brittle Material

Mohr’s Theory

- Mohr’s theory is used to predict the fracture of a material having different properties in tension and compression. Criterion makes use of Mohr’s circle
- In Mohr’s circle, we note that $\tau$ depends on $\sigma$, or $\tau = f(\sigma)$. Note the vertical line $PC$ represents states of stress on planes with same $\sigma$ but differing $\tau$, which means the weakest plane is the one with maximum $\tau$, point $P$.
- Points on the outer circle are the weakest planes. On these planes the maximum and minimum principal stresses are sufficient to decide whether or not failure will occur.
- Experiments are done on a given material to determine the states of stress that result in failure. Each state defines a Mohr’s circle. If the data are obtained from simple tension, simple compression, and pure shear, the three resulting circles are adequate to construct an envelope ($AB$ & $A'B'$)
- Mohr’s envelope thus represents the locus of all possible failure states.

![Yield surface corresponding to maximum principal strain theory](image)

Higher shear stresses are to the left of origin, since most brittle materials have higher strength in compression

8. Comparison

A comparison among the different failure theories can be made by superposing the yield surfaces as shown in figure
Previous 20-Years GATE Questions

Maximum Shear stress or Stress Difference Theory

GATE-1. Match 4 correct pairs between list I and List II for the questions [GATE-1994]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>(a) Hooke's law</td>
<td>1. Planetary motion</td>
</tr>
<tr>
<td>(b) St. Venant's law</td>
<td>2. Conservation Energy</td>
</tr>
<tr>
<td>(c) Kepler's laws</td>
<td>3. Elasticity</td>
</tr>
<tr>
<td>(d) Tresca's criterion</td>
<td>4. Plasticity</td>
</tr>
<tr>
<td>(e) Coulomb's laws</td>
<td>5. Fracture</td>
</tr>
<tr>
<td>(f) Griffith's law</td>
<td>6. Inertia</td>
</tr>
</tbody>
</table>

GATE-1. Ans. (a) - 3, (c) -1, (d) -5, (e) -2

St. Venant's law: Maximum principal strain theory

GATE-2. Which theory of failure will you use for aluminium components under steady loading? [GATE-1999]

- (a) Principal stress theory
- (b) Principal strain theory
- (c) Strain energy theory
- (d) Maximum shear stress theory

GATE-2. Ans. (d) Aluminium is a ductile material so use maximum shear stress theory

Shear Strain Energy Theory (Distortion energy theory)

GATE-3. According to Von-Mises' distortion energy theory, the distortion energy under three dimensional stress state is represented by [GATE-2006]

\[
\frac{1}{2E}\left[\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - 2\nu(\sigma_1\sigma_2 + \sigma_3\sigma_2 + \sigma_1\sigma_3)\right]
\]

GATE-3. Ans. (c)

\[
V_s = \frac{1}{12G}\left((\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2\right)
\]

Where \(E = 2G(1 + \mu)\) simplify and get result.

GATE-4. A small element at the critical section of a component is in a bi-axial state of stress with the two principal stresses being 360 MPa and 140 MPa. The maximum working stress according to Distortion Energy Theory is: [GATE-1997]

- (a) 220 MPa
- (b) 110 MPa
- (c) 314 MPa
- (d) 330 MPa

GATE-4. Ans. (c) According to distortion energy theory if maximum stress (\(\sigma_1\)) then

- or \(\sigma_1^2 = \sigma_1^2 + \sigma_2^2 - \sigma_1\sigma_2\)
- or \(\sigma_1^2 = 360^2 + 140^2 - 360 \times 140\)
- or \(\sigma_1 = 314\) MPa
Maximum Principal Stress Theory

IES-1. Match List-I (Theory of Failure) with List-II (Predicted Ratio of Shear Stress to Direct Stress at Yield Condition for Steel Specimen) and select the correct answer using the code given below the Lists: [IES-2006]

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>A. Maximum shear stress theory</td>
<td>1. 1 0</td>
</tr>
<tr>
<td>B. Maximum distortion energy theory</td>
<td>2. 0 577</td>
</tr>
<tr>
<td>C. Maximum principal stress theory</td>
<td>3. 0 62</td>
</tr>
<tr>
<td>D. Maximum principal strain theory</td>
<td>4. 0 50</td>
</tr>
</tbody>
</table>

Codes: A B C D
(a) 1 2 4 3 (b) 4 3 1 2 (c) 1 3 4 2 (d) 4 2 1 3

IES-1. Ans. (d)

IES-2. From a tension test, the yield strength of steel is found to be 200 N/mm². Using a factor of safety of 2 and applying maximum principal stress theory of failure, the permissible stress in the steel shaft subjected to torque will be: [IES-2000]

(a) 50 N/mm² (b) 57.7 N/mm² (c) 86.6 N/mm² (d) 100 N/mm²

IES-2. Ans. (d) For pure shear \( \tau = \pm \sigma_y \)

IES-3. A circular solid shaft is subjected to a bending moment of 400 kNm and a twisting moment of 300 kNm. On the basis of the maximum principal stress theory, the direct stress is \( \sigma \) and according to the maximum shear stress theory, the shear stress is \( \tau \). The ratio of \( \tau / \sigma \) is: [IES-2000]

(a) \( \frac{1}{5} \) (b) \( \frac{3}{9} \) (c) \( \frac{9}{5} \) (d) \( \frac{11}{6} \)

IES-3. Ans. (c) \( \sigma = \frac{16}{\pi d^2} \left( M + \sqrt{M^2 + T^2} \right) \) and \( \tau = \frac{16}{\pi d^2} \left( \sqrt{M^2 + T^2} \right) \)

Therefore \( \frac{\sigma}{\tau} = \frac{M + \sqrt{M^2 + T^2}}{\sqrt{M^2 + T^2}} = \frac{4 + \sqrt{4^2 + 3^2}}{\sqrt{4^2 + 3^2}} = \frac{9}{5} \)

IES-4. A transmission shaft subjected to bending loads must be designed on the basis of [IES-1996]

(a) Maximum normal stress theory
(b) Maximum shear stress theory
(c) Maximum normal stress and maximum shear stress theories
(d) Fatigue strength

IES-4. Ans. (a)

IES-5. Design of shafts made of brittle materials is based on [IES-1993]

(a) Guest’s theory (b) Rankine’s theory (c) St. Venant’s theory (d) Von Mises theory

IES-5. Ans. (b) Rankine’s theory or maximum principle stress theory is most commonly used for brittle materials.

Maximum Shear stress or Stress Difference Theory

IES-6. Which one of the following figures represents the maximum shear stress theory or Tresca criterion? [IES-1999]
IES-7. According to the maximum shear stress theory of failure, permissible twisting moment in a circular shaft is 'T'. The permissible twisting moment will be the same as per the maximum principal stress theory of failure will be: [IES-1998: ISRO-2008]

(a) T/2   (b) T   (c) \( \sqrt{2T} \)   (d) 2T

IES-7. Ans. (d) Given \( \tau = \frac{16T}{\pi d^3} = \frac{\sigma_y}{2} \) principal stresses for only this shear stress are

\[
\sigma_{ts} = \sqrt{\tau^2} = \pm \tau \text{ maximum principal stress theory of failure gives}
\]

\[
\max[\sigma_1, \sigma_2] = \sigma_{st} = \frac{16(2T)}{\pi d^3}
\]

IES-8. Permissible bending moment in a circular shaft under pure bending is M according to maximum principal stress theory of failure. According to maximum shear stress theory of failure, the permissible bending moment in the same shaft is: [IES-1995]

(a) 1/2 M   (b) M   (c) \( \sqrt{2} M \)   (d) 2M

IES-8. Ans. (b) \( \sigma = \frac{16}{\pi d^3} \left( M + \sqrt{M^2 + T^2} \right) \) and \( \tau = \frac{16}{\pi d^3} \left( \sqrt{M^2 + T^2} \right) \) put \( T = 0 \)

or \( \sigma_{yy} = \frac{32M}{\pi d^3} \) and \( \tau = \frac{16M}{\pi d^3} = \frac{\sigma_{yy}}{2} \)

Therefore \( M' = M \)

IES-9. A rod having cross-sectional area 100 x 10^{-6} m^2 is subjected to a tensile load. Based on the Tresca failure criterion, if the uniaxial yield stress of the material is 200 MPa, the failure load is: [IES-2001]

(a) 10 kN   (b) 20 kN   (c) 100 kN   (d) 200 kN

IES-9. Ans. (b) Tresca failure criterion is maximum shear stress theory.

We know that, \( \tau = \frac{P \sin 2\theta}{A} \) or \( \tau_{max} = \frac{P}{2A} = \frac{\sigma_{yy}}{2} \) or \( P = \sigma_{yy} \times A \)

IES-10. A cold roller steel shaft is designed on the basis of maximum shear stress theory. The principal stresses induced at its critical section are 60 MPa and - 60 MPa respectively. If the yield stress for the shaft material is 360 MPa, the factor of safety of the design is: [IES-2002]

(a) 2   (b) 3   (c) 4   (d) 6

IES-10. Ans. (b)

IES-11. A shaft is subjected to a maximum bending stress of 80 N/mm^2 and maximum shearing stress equal to 30 N/mm^2 at a particular section. If the yield point in tension of the material is 280 N/mm^2, and the maximum shear stress theory of failure is used, then the factor of safety obtained will be: [IES-1994]

(a) 2.5   (b) 2.8   (c) 3.0   (d) 3.5

IES-11. Ans. (b) Maximum shear stress = \( \sqrt{\left( \frac{80 - 0}{2} \right)^2 + 30^2} = 50 \text{ N/mm}^2 \)

According to maximum shear stress theory, \( \tau = \frac{\sigma y}{2} \); \( \therefore F.S. = \frac{280}{2 \times 50} = 2.8 \)

IES-12. For a two-dimensional state stress \( (\sigma_1 > \sigma_2, \sigma_1 > 0, \sigma_2 < 0) \) the designed values are most conservative if which one of the following failure theories were used? [IES-1998]

(a) Maximum principal strain theory   (b) Maximum distortion energy theory
(c) Maximum shear stress theory   (d) Maximum principal stress theory

IES-12. Ans. (c)
Graphical comparison of different failure theories
Above diagram shows that $\sigma_x > 0, \sigma_z < 0$ will occur at 4th quadrant and most conservative design will be maximum shear stress theory.

Shear Strain Energy Theory (Distortion energy theory)

IES-13. Who postulated the maximum distortion energy theory? [IES-2008]
(a) Tresca (b) Rankine (c) St. Venant (d) Mises-Henky
IES-13. Ans. (d)

IES-14. Who postulated the maximum distortion energy theory? [IES-2008]
(a) Tresca (b) Rankine (c) St. Venant (d) Mises-Henky
IES-14. Ans. (d)
Maximum shear stress theory $\rightarrow$ Tresca
Maximum principal stress theory $\rightarrow$ Rankine
Maximum principal strain theory $\rightarrow$ St. Venant
Maximum shear strain energy theory $\rightarrow$ Mises – Henky

IES-15. The maximum distortion energy theory of failure is suitable to predict the failure of which one of the following types of materials? [IES-2004]
(a) Brittle materials (b) Ductile materials (c) Plastics (d) Composite materials
IES-15. Ans. (b)

IES-16. If $\sigma_y$ is the yield strength of a particular material, then the distortion energy theory is expressed as [IES-1994]
(a) $\left( \sigma_1 - \sigma_2 \right)^2 + \left( \sigma_2 - \sigma_3 \right)^2 + \left( \sigma_3 - \sigma_1 \right)^2 = 2\sigma_y^2$
(b) $\left( \sigma_1^2 - \sigma_2^2 + \sigma_3^2 \right) - 2\mu(\sigma_1\sigma_2 + \sigma_2\sigma_3 + \sigma_3\sigma_1) = \sigma_y^2$
(c) $\left( \sigma_1 - \sigma_2 \right)^2 + \left( \sigma_2 - \sigma_3 \right)^2 + \left( \sigma_3 - \sigma_1 \right)^2 = 3\sigma_y^2$
(d) $(1-2\mu)\left( \sigma_1 + \sigma_2 + \sigma_3 \right)^2 = 2(1+\mu)\sigma_y^2$
IES-16. Ans. (a)

IES-17. If a shaft made from ductile material is subjected to combined bending and twisting moments, calculations based on which one of the following failure theories would give the most conservative value? [IES-1996]
(a) Maximum principal stress theory (b) Maximum shear stress theory.
(d) Maximum strain energy theory (d) Maximum distortion energy theory.
IES-17. Ans. (b)
Maximum Principal Strain Theory

IES-18. Match List-I (Failure theories) with List-II (Figures representing boundaries of these theories) and select the correct answer using the codes given below the Lists:

List-I
A. Maximum principal stress theory
B. Maximum shear stress theory
C. Maximum octahedral stress theory
D. Maximum shear strain energy theory

List-II
1. 
2. 
3. 
4. 

Code: A B C D
(a) 2 1 3 4 (b) 2 4 3 1
(c) 4 2 3 1 (d) 2 4 1 3

IES-18. Ans. (d)

Previous 20-Years IAS Questions

Maximum Principal Stress Theory

IAS-1. For $\sigma_1 \neq \sigma_2$ and $\sigma_3 = 0$, what is the physical boundary for Rankine failure theory? 
(a) A rectangle  (b) An ellipse  (c) A square  (d) A parabola
Theories of Failure

Chapter-15

IAS-1. Ans. (c) Rankine failure theory or Maximum principle stress theory.

IAS-2. Consider the following statements: 
1. Experiments have shown that the distortion-energy theory gives an accurate prediction about failure of a ductile component than any other theory of failure.
2. According to the distortion-energy theory, the yield strength in shear is less than the yield strength in tension.

Which of the statements given above is/are correct?
(a) 1 only  (b) 2 only  (c) Both 1 and 2 (d) Neither 1 nor 2

IAS-2. Ans. (c) $\tau_y = \frac{\sigma_y}{\sqrt{3}} = 0.577\sigma_y$

IAS-3. Consider the following statements:
1. Distortion-energy theory is in better agreement for predicting the failure of ductile materials.
3. Module of elasticity in tension and compression are assumed to be different

Which of these statements is/are correct?
(a) 1, 2 and 3   (b) 1 and 2  (c) 3 only   (d) 1 and 3

IAS-3. Ans. (b)

IAS-4. Which one of the following graphs represents Mises yield criterion? 

IAS-4. Ans. (d)

Maximum Principal Strain Theory

IAS-5. Given that the principal stresses $\sigma_1 > \sigma_2 > \sigma_3$ and $\sigma_E$ is the elastic limit stress in simple tension; which one of the following must be satisfied such that the elastic failure does not occur in accordance with the maximum principal strain theory?

(a) $\frac{\sigma_E}{E} < \left(\frac{\sigma_1}{E} - \mu \frac{\sigma_2}{E} - \mu \frac{\sigma_3}{E}\right)$
(b) $\frac{\sigma_E}{E} > \left(\frac{\sigma_1}{E} - \mu \frac{\sigma_2}{E} - \mu \frac{\sigma_3}{E}\right)$

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(c) \( \frac{\sigma_e}{E} \geq \left( \frac{\sigma_1}{E} + \mu \frac{\sigma_2}{E} + \mu \frac{\sigma_3}{E} \right) \) 

(d) \( \frac{\sigma_e}{E} < \left( \frac{\sigma_1}{E} + \mu \frac{\sigma_2}{E} - \mu \frac{\sigma_3}{E} \right) \)

IAS-5. Ans. (b) Strain at yield point > principal strain

\( \frac{\sigma_e}{E} > \frac{\sigma_1}{E} - \mu \frac{\sigma_2}{E} - \mu \frac{\sigma_3}{E} \)
Conventional Question ESE-2010

Q. The stress state at a point in a body is plane with
\[ \sigma_1 = 60 \text{ N/mm}^2 \quad \text{and} \quad \sigma_2 = -36 \text{ N/mm}^2 \]
If the allowable stress for the material in simple tension or compression is 100 N/mm\(^2\) calculate the value of factor of safety with each of the following criteria for failure
(i) Max Stress Criteria
(ii) Max Shear Stress Criteria
(iii) Max strain criteria
(iv) Max Distortion energy criteria

[10 Marks]

Ans. The stress at a point in a body is plane
\[ \sigma_1 = 60 \text{ N/mm}^2 \quad \text{and} \quad \sigma_2 = -36 \text{ N/mm}^2 \]
Allowable stress for the material in simple tension or compression is 100 N/mm\(^2\)

Find out factor of safety for

(i) **Maximum stress Criteria**: In this failure point occurs when max principal stress reaches the limiting strength of material.

Therefore. Let F.S factor of safety

\[ F.S = \frac{\sigma (allowable)}{\sigma} \]

\[ F.S = \frac{100 \text{ N/mm}^2}{60 \text{ N/mm}^2} = 1.67 \quad \text{Ans.} \]

(ii) **Maximum Shear stress criteria**: According to this failure point occurs at a point in a member when maximum shear stress reaches to shear at yield point

\[ \gamma_{\text{max}} = \frac{\sigma_{\text{yt}}}{2 F.S} \quad \sigma_{\text{yt}} = 100 \text{ N/mm}^2 \]

\[ \gamma_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{60 + 36}{2} = \frac{96}{2} = 48 \text{ N/mm}^2 \]

\[ 48 = \frac{100}{2 \times F.S} \]

\[ F.S = \frac{100}{2 \times 48} = \frac{100}{96} = 1.042 \quad \text{Ans.} \]

(iii) **Maximum Strain Criteria**! In this failure point occurs at a point in a member when maximum strain in a bi-axial stress system reaches the limiting value of strain (i.e. strain at yield point)

\[ \sigma_1^2 + \sigma_2^2 - 2\mu \sigma_1 \sigma_2 = \left( \frac{\sigma_{\text{allowable}}}{F.O.S} \right)^2 \]

\[ \text{F.O.S} = 1.27 \]

(\( \mu = 0.3 \) assume)

(iv) **Maximum Distortion energy criteria**! In this failure point occurs at a point in a member when distortion strain energy per unit volume in a bi-axial system reaches the limiting distortion strain energy at the of yield
\[ \sigma_1^2 + \sigma_2^2 - \sigma_1 \times \sigma_2 = \left( \frac{\sigma_{yt}}{F.S} \right)^2 \]

\[ 60^2 + (36)^2 - 60 \times 36 = \left( \frac{100}{F.S} \right)^2 \]

F.S = 1.19

**Conventional Question ESE-2006**

**Question:** A mild steel shaft of 50 mm diameter is subjected to a bending moment of 1.5 kNm and torque \( T \). If the yield point of steel in tension is 210 MPa, find the maximum value of the torque without causing yielding of the shaft material according to

(i) Maximum principal stress theory
(ii) Maximum shear stress theory.

**Answer:** We know that, Maximum bending stress \( (\sigma_b) = \frac{32M}{\pi d^3} \)

and Maximum shear stress \( (\tau) = \frac{16T}{\pi d^3} \)

Principal stresses are given by:

\[ \sigma_{1,2} = \frac{\sigma_b}{2} \pm \sqrt{\frac{\sigma_b}{2}^2 + \tau^2} = \frac{16}{\pi d^3} \left[ M \pm \sqrt{M^2 + T^2} \right] \]

(i) According to Maximum principal stress theory

Maximum principal stress=Maximum stress at elastic limit \( (\sigma_y) \)

\[ \text{or} \quad \frac{16}{\pi d^3} \left[ M + \sqrt{M^2 + T^2} \right] = 210 \times 10^6 \]

\[ \text{or} \quad \frac{16}{\pi (0.050)^3} \left[ 1500 + \sqrt{1500^2 + T^2} \right] = 210 \times 10^6 \]

or \( T = 3332 \text{ Nm} = 3.332 \text{ kNm} \)

(ii) According to Maximum shear stress theory

\[ \tau_{\text{max}} = \frac{\sigma_1 - \sigma_2}{2} = \frac{\sigma_y}{2} \]

or, \( \sigma_1 - \sigma_2 = \sigma_y \)

\[ \text{or, } 2 \times \frac{16}{\pi d^3} \sqrt{M^2 + T^2} = 210 \times 10^6 \]

or, \( T = 2096 \text{ N m} = 2.096 \text{ kNm} \)

**Conventional Question ESE-2005**

**Question:** Illustrate the graphical comparison of following theories of failures for two-dimensional stress system:

(i) Maximum normal stress theory
(ii) Maximum shear stress theory
(iii) Distortion energy theory

**Answer:**
**Conventional Question ESE-2004**

**Question:** State the Von-Mises's theory. Also give the naturally expression.

**Answer:** According to this theory yielding would occur when total distortion energy absorbed per unit volume due to applied loads exceeds the distortion energy absorbed per unit volume at the tensile yield point. The failure criterion is

\[
\left(\sigma_1 - \sigma_2\right)^2 + \left(\sigma_2 - \sigma_3\right)^2 + \left(\sigma_3 - \sigma_1\right)^2 = 2\sigma_y^2
\]

[symbols has usual meaning]

**Conventional Question ESE-2002**

**Question:** Derive an expression for the distortion energy per unit volume for a body subjected to a uniform stress state, given by the \(\sigma_1\) and \(\sigma_2\) with the third principal stress \(\sigma_3\) being zero.

**Answer:** According to this theory yielding would occur when total distortion energy absorbed per unit volume due to applied loads exceeds the distortion energy absorbed per unit volume at the tensile yield point. Total strain energy \(E_T\) and strain energy for volume change \(E_V\) can be given as

\[
E_T = \frac{1}{2} \left(\sigma_1 \varepsilon_1 + \sigma_2 \varepsilon_2 + \sigma_3 \varepsilon_3\right) \quad \text{and} \quad E_V = \frac{3}{2} \sigma_{av} \varepsilon_{av}
\]

Substituting strains in terms of stresses the distortion energy can be given as

\[
E_d = E_T - E_V = \frac{2(1+\nu)}{6E} \left(\sigma_1^2 + \sigma_2^2 + \sigma_3^2 - \sigma_1 \sigma_2 - \sigma_2 \sigma_3 - \sigma_3 \sigma_1\right)
\]

At the tensile yield point, \(\sigma_1 = \sigma_0\), \(\sigma_2 = \sigma_3 = 0\) which gives

\[
E_{dy} = \frac{2(1+\nu)}{6E} \left(\sigma_0^2\right)
\]

The failure criterion is thus obtained by equating \(E_d\) and \(E_{dy}\), which gives

\[
\left(\sigma_1 - \sigma_2\right)^2 + \left(\sigma_2 - \sigma_3\right)^2 + \left(\sigma_3 - \sigma_1\right)^2 = 2\sigma_y^2
\]

In a 2-D situation if \(\sigma_3\) = 0, the criterion reduces to

\[
\sigma_1^2 + \sigma_2^2 - \sigma_1 \sigma_2 = \sigma_y^2
\]

**Conventional Question GATE-1996**

**Question:** A cube of 5mm side is loaded as shown in figure below.

(i) Determine the principal stresses \(\sigma_1, \sigma_2, \sigma_3\).

(ii) Will the cube yield if the yield strength of the material is 70 MPa? Use Von-Mises theory.

**Answer:** Yield strength of the material \(\sigma_w = 70\) MPa = 70 MN/m² or 70 N/mm².
Chapter-15 Theories of Failure

(i) Principal stress $\sigma_1, \sigma_2, \sigma_3$:

\[ \sigma_1 = \frac{2000}{5 \times 5} = 80 \text{ N/mm}^2; \quad \sigma_2 = \frac{1000}{5 \times 5} = 40 \text{ N/mm}^2 \]
\[ \sigma_3 = \frac{500}{5 \times 5} = 20 \text{ N/mm}^2; \quad \tau_{xy} = \frac{800}{5 \times 5} = 32 \text{ N/mm}^2 \]

\[ \sigma = \frac{\sigma_1 + \sigma_2}{2} \pm \sqrt{\left(\frac{\sigma_1 - \sigma_2}{2}\right)^2 + \tau_{xy}^2} = \frac{80 + 40}{2} \pm \sqrt{\frac{80 - 40}{2}^2 + (32)^2} \]

\[ = 60 \pm \sqrt{(20)^2 + (32)^2} = 97.74, 22.26 \]

\[ \therefore \sigma_1 = 97.74 \text{ N/mm}^2, \text{ or } 97.74 \text{ MPa} \]

and $\sigma_2 = 22.96 \text{ N/mm}^2$ or $22.96 \text{ MPa}$

$\sigma_3 = \sigma_z = 20 \text{ N/mm}^2$ or $22 \text{ MPa}$

(ii) Will the cube yield or not?

According to Von-Mises yield criteria, yielding will occur if

\[ (\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \geq 2\sigma_y^2 \]

Now

\[ (\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2 \]
\[ = (97.74 - 22.96)^2 + (22.96 - 20)^2 + (20 - 97.74)^2 \]
\[ = 11745.8 \quad (i) \]

\[ 2\sigma_y^2 = 2 \times (70)^2 = 9800 \quad (ii) \]

Since 11745.8 > 9800 so yielding will occur.

Conventional Question GATE-1995

Question: A thin-walled circular tube of wall thickness $t$ and mean radius $r$ is subjected to an axial load $P$ and torque $T$ in a combined tension-torsion experiment.

(i) Determine the state of stress existing in the tube in terms of $P$ and $T$.

(ii) Using Von-Mises - Henky failure criteria show that failure takes place when

\[ \sqrt{\sigma^2 + 3\tau^2} = \sigma_0, \text{ where } \sigma_0 \text{ is the yield stress in uniaxial tension}, \]

\[ \sigma \text{ and } \tau \text{ are respectively the axial and torsional stresses in the tube}. \]

Answer: Mean radius of the tube = $r$,
Wall thickness of the tube = $t$,
Axial load = $P$, and
Torque = $T$.

(i) The state of stress in the tube:
Due to axial load, the axial stress in the tube $\sigma_x = \frac{P}{2\pi rt}$

Due to torque, shear stress,
$$\tau_{xy} = \frac{Tr}{J} = \frac{Tr}{2\pi r^3 t} = \frac{T}{2\pi r^3 t}$$

$$J = \frac{\pi}{2} \left( (r + t)^4 - r^4 \right) = 2\pi r^3 t$$ - neglecting $t^2$ higher power of $t$.

\[
\sigma_x = \frac{P}{2\pi rt}, \sigma_y = 0, \tau_{xy} = \frac{T}{2\pi r^3 t}
\]

(ii) Von Mises-Henky failure in tension for 2-dimensional stress is
$$\sigma_0^2 = \sigma_1^2 + \sigma_2^2 - \sigma_1 \sigma_2$$
$$\sigma_1 = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}$$
$$\sigma_2 = \frac{\sigma_x + \sigma_y}{2} - \sqrt{\left(\frac{\sigma_x - \sigma_y}{2}\right)^2 + \tau_{xy}^2}$$

In this case, $\sigma_1 = \frac{\sigma_x + \sigma_y}{2} + \sqrt{\frac{\sigma_x^2 + \sigma_y^2}{4} + \tau_{xy}^2}$, and
$$\sigma_2 = \frac{\sigma_x + \sigma_y}{2} - \sqrt{\frac{\sigma_x^2 + \sigma_y^2}{4} + \tau_{xy}^2} \quad (\therefore \sigma_y = 0)$$

\[
\sigma_0^2 = \left[\frac{\sigma_x + \sigma_y}{2} + \sqrt{\frac{\sigma_x^2 + \sigma_y^2}{4} + \tau_{xy}^2}\right]^2 - \frac{\sigma_x}{2} + \left[\frac{\sigma_x + \sigma_y}{2} + \sqrt{\frac{\sigma_x^2 + \sigma_y^2}{4} + \tau_{xy}^2}\right] - \frac{\sigma_x}{2} + \frac{\sigma_x^2 + \sigma_y^2}{4} + \tau_{xy}^2)
\]

\[
\sigma_0^2 = \frac{\sigma_x^2 + \sigma_y^2}{4} + 3\tau_{xy}^2
\]

\[
\sigma_0 = \sqrt{\sigma_0^2 + 3\tau_{xy}^2}
\]

**Conventional Question GATE-1994**

**Question:** Find the maximum principal stress developed in a cylindrical shaft, 8 cm in diameter and subjected to a bending moment of 2.5 kNm and a twisting moment of 4.2 kNm. If the yield stress of the shaft material is 300 MPa. Determine the factor of safety of the shaft according to the maximum shearing stress theory of failure.

**Answer:**

Given: $d = 8 \text{ cm} = 0.08 \text{ m}$; $M = 2.5 \text{ kNm} = 2500 \text{ Nm}$; $T = 4.2 \text{ kNm} = 4200 \text{ Nm}$

$\sigma_{\text{yield}} = 300 \text{ MPa} = 300 \text{ MN/m}^2$

Equivalent torque, $T_e = \sqrt{M^2 + T^2} = \sqrt{(2.5)^2 + (4.2)^2} = 4.888 \text{ kNm}$

Maximum shear stress developed in the shaft,
$$\tau_{\text{max}} = \frac{16T}{\pi d^3} = \frac{16 \times 4.888 \times 10^3}{\pi \times (0.08)^3} \times 10^{-6} \text{ MN/m}^2 = 48.62 \text{ MN/m}^2$$

Permissible shear stress $= \frac{300}{2} = 150 \text{ MN/m}^2$

\[\therefore \text{ Factor of safety} = \frac{150}{48.62} = 3.085\]
### 16. Riveted and Welded Joint

**Theory at a Glance (for IES, GATE, PSU)**

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<th>FIGURE</th>
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<td><img src="image1" alt="Figure" /></td>
<td>HEXAGON THREADED FLAT HEAD</td>
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<td><img src="image2" alt="Figure" /></td>
<td>HEXAGON CLOSE END THREADED FLAT HEAD</td>
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<td><img src="image3" alt="Figure" /></td>
<td>THREADED HEXAGON FOR AUTOMATED ASSEMBLY</td>
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<td><img src="image4" alt="Figure" /></td>
<td>SQUARE THREADED FLAT HEAD</td>
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<td><img src="image5" alt="Figure" /></td>
<td>BUTTON HEAD, TAPPING</td>
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Failure of riveted joint

GATE-1. Bolts in the flanged end of pressure vessel are usually pre-tensioned to seal the pressure vessel. Indicate which of the following statements is NOT TRUE? [GATE-1999]

(a) Pre-tensioning helps to seal the pressure vessel
(b) Pre-tensioning increases the fatigue life of the bolts
(c) Pre-tensioning reduces the maximum tensile stress in the bolts
(d) Pre-tensioning helps to reduce the effect of pressure pulsations in the pressure vessel

GATE-1. Ans. (c)

Statement for Linked Answers and Questions Q2 and Q3

A steel bar of 10 × 50 mm is cantilevered with two M12 bolts (P and Q) to support a static load of 4 kN as shown in the figure.

GATE-2. The primary and secondary shear loads on bolt P, respectively, are:

[GATE-2008]

(A) 2 kN, 20 kN   (B) 20 kN, 2kN   (C) 20kN,0kN   (D) 0kN, 20 kN

GATE-2. Ans. (a) Primary (Direct) Shear load = \( \frac{4kN}{2} = 2 \) kN

GATE-3. The resultant stress on bolt P is closest to

[GATE-2008]

(A) 132 MPa   (B) 159 MPa   (C) 178 MPa   (D) 195 MPa

GATE-3. Ans. (b)

GATE-4. A bolted joint is shown below. The maximum shear stress, in MPa, in the bolts at A and B, respectively are:

[GATE-2007]
GATE-4. Ans. (a)

GATE-5. A bracket (shown in figure) is rigidly mounted on wall using four rivets. Each rivet is 6 mm in diameter and has an effective length of 12 mm. [GATE-2010]

GATE-5. Ans. (b)

\[ F = \frac{1000}{4} = 250 \text{ N} \]
\[ z = \frac{F}{\pi} = \frac{250}{\pi (6)^2} = 8.8 \text{ MPa} \]

**Efficiency of a riveted joint**

GATE-6. If the ratio of the diameter of rivet hole to the pitch of rivets is 0.25, then the tearing efficiency of the joint is: [GATE-1996]

GATE-6. Ans. (b)
A manufacturer of rivets claims that the failure load in shear of his product is 500 ± 25 N. This specification implies that:

(a) No rivet is weaker than 475 N and stronger than 525 N
(b) The standard deviation of strength of random sample of rivets is 25 N
(c) There is an equal probability of failure strength to be either 475 N or 525 N
(d) There is approximately two-to-one chance that the strength of a rivet lies between 475 N to 525 N

GATE-7. Ans. (a)
\[ P = 2F_z = 2 \times 3 = 6 \text{ kN} \]

\[ \text{and} \quad P \cdot L = F_1 l + F_2 l = 2 F_1 l \]

or \[ 6L = 2 \times 4l = 8l \]

or \[ \frac{L}{l} = \frac{8}{6} \]

Resultant force on rivet, \[ R = \sqrt{F_1^2 + F_2^2 + 2F_1 F_2 \cos \theta} \]

\[ = \sqrt{(4)^2 + (3)^2 + 2 \times 4 \times 3 \cos \theta} \]

\[ = 5 \text{ kN} \]

\[ \therefore \text{Shear stress on rivet,} \]

\[ \tau = \frac{R}{\text{Area}} = \frac{5 \times 10^3}{500} = 10 \text{ N/mm}^2 \]

IES-3. If permissible stress in plates of joint through a pin as shown in the given figure is 200 MPa, then the width \( w \) will be

(a) 15 mm
(b) 18 mm
(c) 20 mm
(d) 25 mm

IES-3. Ans. (a) \((w - 10) \times 2 \times 10^{-6} \times 200 \times 10^6 = 2000 \text{ N}; \) or \( w = 15 \text{ mm}. \)

IES-4. For the bracket bolted as shown in the figure, the bolts will develop

(a) Primary tensile stresses and secondary shear stresses
(b) Primary shear stresses and secondary shear stresses
(c) Primary shear stresses and secondary tensile stresses
(d) Primary tensile stresses and secondary compressive stresses

IES-4. Ans. (a)

IES-5. Assertion (A): In pre-loaded bolted joints, there is a tendency for failure to occur in the gross plate section rather than through holes. [IES-2000]

Reason (R): The effect of pre-loading is to create sufficient friction between the assembled parts so that no slippage occurs.

(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
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IES-5. Ans. (a)

IES-6. Two rigid plates are clamped by means of bolt and nut with an initial force N. After tightening, a separating force P (P < N) is applied to the lower plate, which in turn acts on nut. The tension in the bolt after this is: [IES-1996]
(a) (N + P)  
(b) (N – P)  
(c) P  
(d) N
IES-6. Ans. (a)

Efficiency of a riveted joint

IES-7. Which one of the following structural joints with 10 rivets and same size of plate and material will be the most efficient? [IES-1994]

IES-7. Ans. (b)

IES-8. The most efficient riveted joint possible is one which would be as strong in tension, shear and bearing as the original plates to be joined. But this can never be achieved because: [IES-1993]
(a) Rivets cannot be made with the same material
(b) Rivets are weak in compression
(c) There should be at least one hole in the plate reducing its strength
(d) Clearance is present between the plate and the rivet
IES-8. Ans. (c) Riveted joint can't be as strong as original plates, because there should be at least one hole in the plate reducing its strength.

Advantages and disadvantages of welded joints

IES-9. Assertion (A): In a boiler shell with riveted construction, the longitudinal seam is, jointed by butt joint. [IES-2001]
Reason (R): A butt joint is stronger than a lap joint in a riveted construction.
(a) Both A and R are individually true and R is the correct explanation of A
(b) Both A and R are individually true but R is NOT the correct explanation of A
(c) A is true but R is false
(d) A is false but R is true
IES-9. Ans. (c)
Failure of riveted joint

IAS-1. Two identical planks of wood are connected by bolts at a pitch distance of 20 cm. The beam is subjected to a bending moment of 12 kNm, the shear force in the bolts will be:
(a) Zero         (b) 0.1 kN
(c) 0.2 kN      (d) 4 kN

IAS-1. Ans. (a)

IAS-2. Match List-I with List-II and select the correct answer using the code given below the Lists:

<table>
<thead>
<tr>
<th>List-I</th>
<th>List-II</th>
</tr>
</thead>
<tbody>
<tr>
<td>(Stress Induced)</td>
<td>(Situation/ Location)</td>
</tr>
<tr>
<td>A. Membrane stress</td>
<td>1. Neutral axis of beam</td>
</tr>
<tr>
<td>B. Torsional shear stress</td>
<td>2. Closed coil helical spring under axial load</td>
</tr>
<tr>
<td>C. Double shear stress</td>
<td>3. Cylindrical shell subject to fluid pressure</td>
</tr>
<tr>
<td>D. Maximum shear stress</td>
<td>4. Rivets of double strap butt joint</td>
</tr>
</tbody>
</table>

Code: A B C D  A B C D
(a) 3 1 4 2  (b) 4 2 3 1
(c) 3 2 4 1  (d) 4 1 3 2

IAS-2. Ans. (c)
Conventional Question GATE-1994

Question: The longitudinal joint of a thin cylindrical pressure vessel, 6 m internal diameter and 16 mm plate thickness, is double riveted lap joint with no staggering between the rows. The rivets are of 20 mm nominal (diameter with a pitch of 72 mm. What is the efficiency of the joint and what would be the safe pressure inside the vessel? Allowable stresses for the plate and rivet materials are; 145 MN/m² in shear and 230 MN/m² in bearing. Take rivet hole diameter as 1.5 mm more than the rivet diameter.

Answer:

Given:
- Diameter of rivet = 20 mm
- Diameter of hole = 20 + 1.5 = 21.5 mm
- Diameter the pressure vessel, d = 6 m
- Thickness of the plate, t = 16 mm
- Type of the joint: Double riveted lap joint
- Allowable stresses:
  \[ \sigma_t = 145 \text{MN/m}^2; \tau = 120 \text{MN/m}^2; \sigma_c = 230 \text{MN/m}^2 \]

Strength of plate in tearing/pitch, \( R_t = \frac{72-(2 \times 21.5)}{1000} \times \frac{16}{1000} \times 145 \)

\[ = 0.06728 \text{ MN} \]

Strength of rivet in tearing/pitch, \( R_t = 2 \times \frac{\pi}{4} \left( \frac{20}{1000} \right)^2 \times 120 \)

\[ = 0.0754 \text{ MN} \]

Strength of plate in crushing/pitch, \( R_c = 2 \times \left( \frac{20}{1000} \times \frac{16}{1000} \right) \times 230 \)

\[ = 0.1472 \text{ MN} \]

From the above three modes of failure it can be seen that the weakest element is the plate as it will have tear failure at 0.06728 MN/pitch load itself.

Stresses acting on the plate for an inside pressure of \( p \text{MN/m}^2 \) is shown in figure.

Hoop stress \( = \frac{pd}{2t} = \frac{p \times 6}{2 	imes (0.016)} = 187.5p \)

Longitudinal stress \( = \frac{pd}{4t} = \frac{p \times 6}{4 \times (0.016)} = 93.75p \)

Maximum principal stress acting on the plate \( = \frac{pd}{2t} \) only (i.e. 187.5p) as there is no shear stress.

or \( 187.5p \leq \frac{0.06728}{(0.016) \times \left( \frac{72-(2 \times 21.5)}{1000} \right)} \leq 145 \)

or \( p \leq 0.7733 \text{ MN/m}^2 \) or 0.7733 MPa

\[ \eta_{\text{joint}} = \frac{R_t}{p \times \sigma_t} = \frac{0.06728}{(0.072) \times (0.016) \times 145} = 0.4028 = 40.28\% \]
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**Conventional Question GATE-1995**

**Question:** Determine the shaft diameter and bolt size for a marine flange-coupling transmitting 3.75 MW at 150 r.p.m. The allowable shear stress in the shaft and bolts may be taken as 50 MPa. The number of bolts may be taken as 10 and bolt pitch circle diameter as 1.6 times the shaft diameter.

**Answer:**

Given, \( P = 3.75 \text{MW} \); \( N = 150 \text{ r.p.m.} \);
\( \tau_s = \tau_b = 50 \text{ MPa} \); \( n = 10 \), \( D_b = 1.6D \)

Shaft diameter, \( D \):

\[
P = \frac{2\pi NT}{60}
\]
\[
E = 3.78 \times 10^6 = \frac{2\pi \times 150 \times T}{60}
\]

or
\[
T = \frac{3.75 \times 10^6 \times 60}{2\pi \times 150} = 238732 \text{ Nm}
\]

Also,
\[
T = \tau_s \times \frac{\pi}{16} \times D^3
\]

or
\[
238732 = 50 \times 10^6 \times \frac{\pi}{16} \times D^3
\]

\[
\therefore \quad D = \left( \frac{238732 \times 16}{50 \times 10^6 \times \pi} \right) = 0.28 \text{ m or 290 mm}
\]

Bolt size, \( d_b \):

Bolt pitch circle diameter, \( D_b = 1.6D = 1.6 \times 0.29 = 0.464 \text{ m} \)

Now,
\[
T = n \times \frac{\pi}{4} d_b^2 \times \tau_b \times \left( \frac{D_b}{2} \right)
\]

or
\[
238732 = 10 \times \frac{\pi}{4} d_b^2 \times 50 \times 10^6 \times \left( \frac{0.464}{2} \right)
\]

or
\[
d_b = 0.0512 \text{ m or 51.2 mm}
\]